Os 300 (Hyper)Parâmetros



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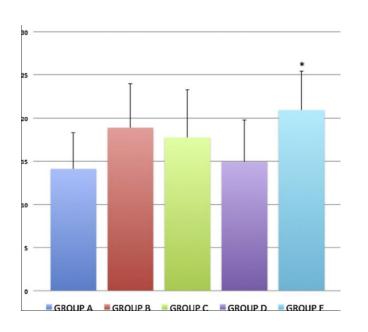


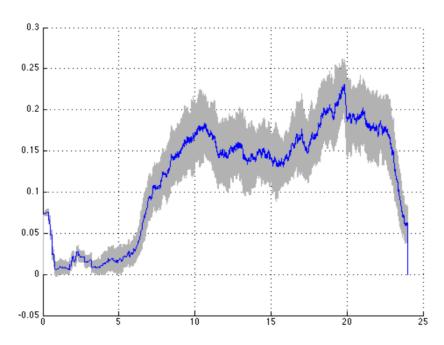
Tópicos:

- Preparação dos Dados
- Definição das Funções Custo e Métrica (classificação vs regressão)
- Interpretação e Correção de Resultados (Ciclo Vicioso de ML)
- Estudo de Caso: RSNA Bone Age Challenge 2017

Visualização



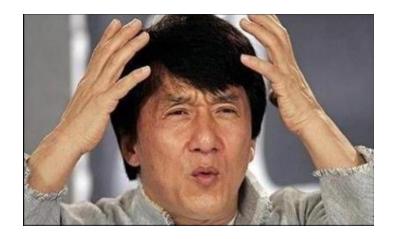


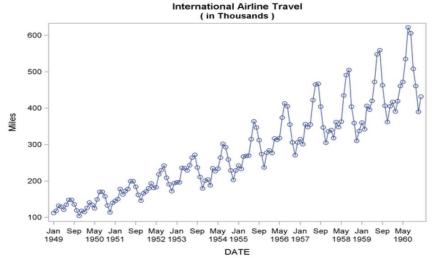


Diferentes Tipos de Dados



+	C1	C2	C3
	length	success	Recoded length
1	2	93.3	0
2	3	83.1	0
3	4	74.1	0
4	5	58.9	0
5	6	54.8	0
6	7	53.1	0
7	8	46.3	0
8	9	31.8	0
9	10	33.5	1
10	11	31.6	1
11	12	25.7	1
12	13	24.0	1
13	14	31.0	1



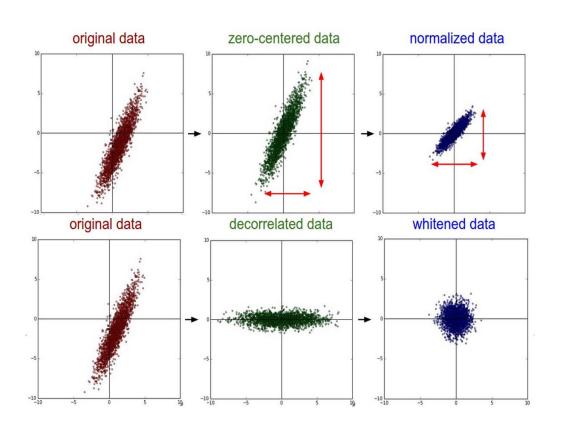


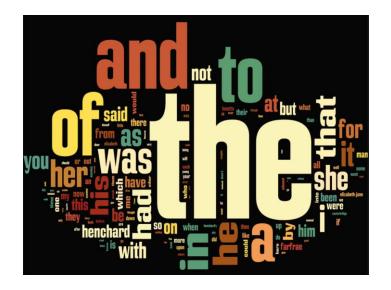
ID	Gender	
1	Male	
2	Female	
3	Not Specified	
4	Not Specified	
5	Female	



ID	Male	Female	Not Specified
1	1	0	0
2	0	1	0
3	0	0	1
4	0	0	1
5	0	1	0

Preprocessamento







Divisão treino/validação/teste

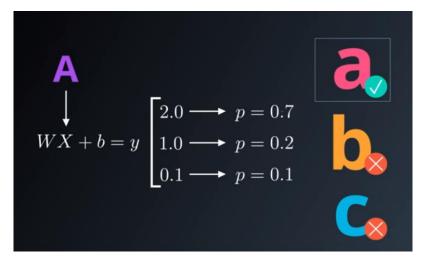
```
>>> import numpy as np
>>> from sklearn.model_selection import train_test_split
>>> from sklearn import datasets
>>> from sklearn import svm

>>> iris = datasets.load_iris()
>>> iris.data.shape, iris.target.shape
((150, 4), (150,))
>>> X_train, X_test, y_train, y_test = train_test_split(
... iris.data, iris.target, test_size=0.4, random_state=0)

>>> X_train.shape, y_train.shape
((90, 4), (90,))
>>> X_test.shape, y_test.shape
((60, 4), (60,))
```

Definição da Função Custo:

Classificação



LOGITS SCORES • SOFTMAX PROBABILITIES
$$y \begin{bmatrix} 2.0 \longrightarrow \\ 1.0 \longrightarrow \\ 0.1 \longrightarrow \end{bmatrix} S(y_i) = \frac{e^{y_i}}{\sum_j e^{y_j}} \begin{bmatrix} \longrightarrow p = 0.7 \\ \longrightarrow p = 0.2 \\ \longrightarrow p = 0.1 \end{bmatrix}$$

Entropia Cruzada:
$$H(p,q) = -\sum_x p(x) \log q(x)$$
, $H(p,q) \neq H(q,p)$

Outros exemplos menos usados: Hinge, divergência de Kullback-Leibler, cosseno do ângulo entre os vetores, etc. (Google is your friend! :))

Definição da Função Custo:

Regressão

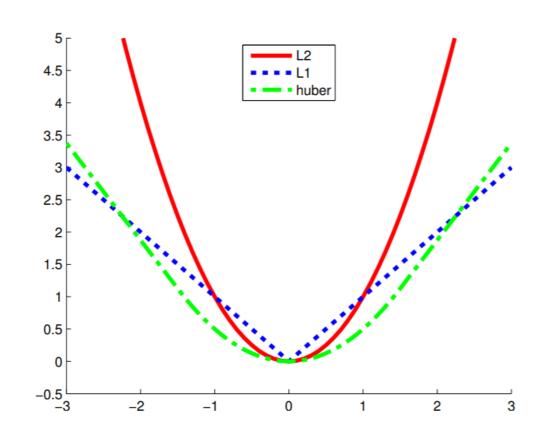
As mais usadas são:

$$L2 = \mathbb{E}_{\mathbf{x}, \mathbf{y} \sim p_{\text{data}}} ||\mathbf{y} - f(\mathbf{x})||^2$$

$$S=\sum_{i=0}^n (y_i-h(x_i))^2$$

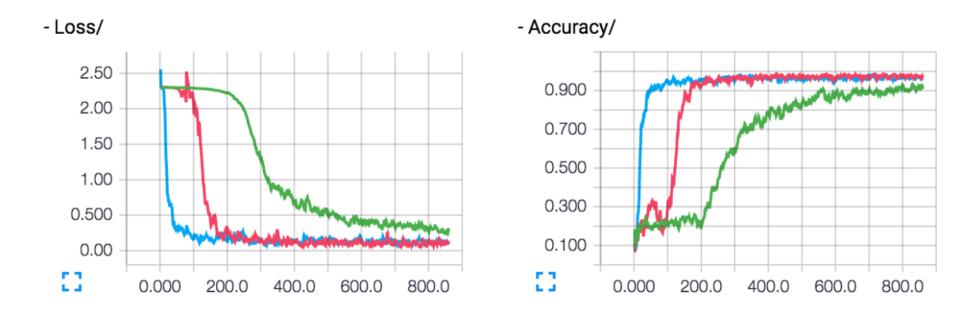
$$L1 = \mathbb{E}_{\mathbf{x}, \mathbf{y} \sim p_{\text{data}}} || \mathbf{y} - f(\mathbf{x}) ||_1$$

$$S = \sum_{i=0}^n |y_i - h(x_i)|$$



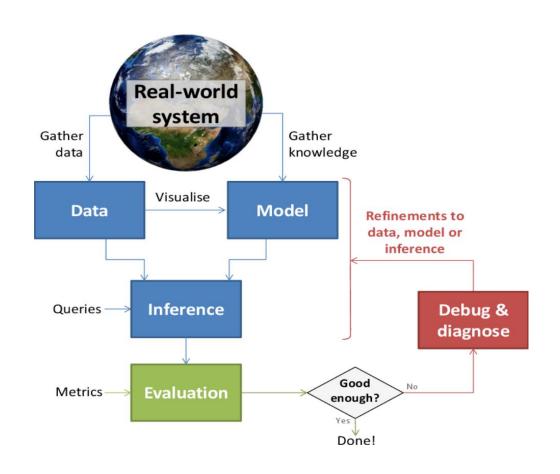
Definição da Métrica:

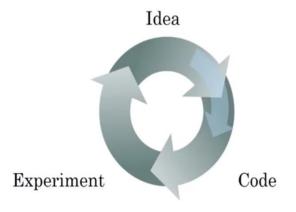
Diferença entre Custo e Métrica



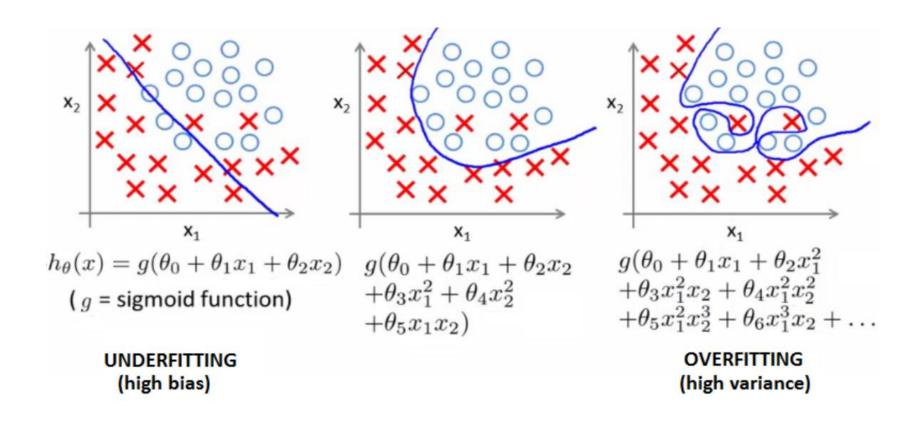
 Exemplos de métricas: acurácia, precisão, recall, F1 score, IoU, MAP, etc.

Ciclo (Vicioso) de ML

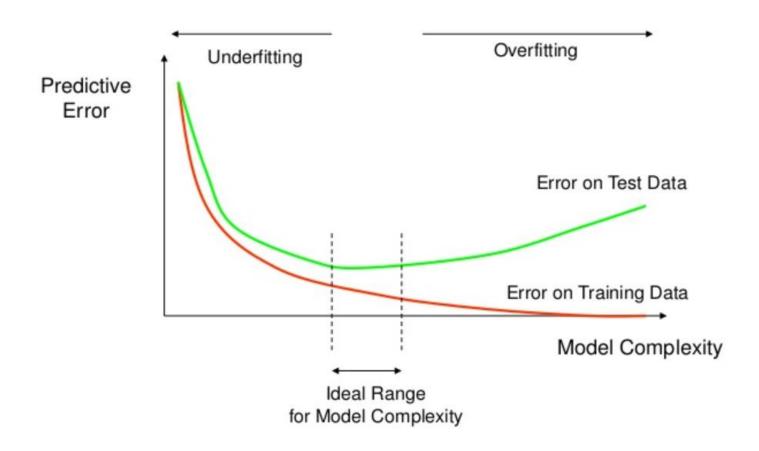




Underfit vs Overfit



Underfit vs Overfit



- Parâmetros: $W^{[1]}$, $b^{[1]}$, $W^{[2]}$, $b^{[2]}$, $W^{[3]}$, $b^{[3]}$...
- Hyperparâmetros:
 - Arquitetura da rede (MLP, CNN, RNN, ...)
 - Número de camadas e número de unidades por camada (profundidade e largura da rede)
 - Função de ativação
 - Algoritmos de Otimização
 - Taxa de aprendizado
 - Técnicas de regularização
 - [...] (sempre tem um que vc tá esquecendo... --')

- Inicialização de Parâmetros
 - Iniciar tudo com 0
 - Iniciar tudo com o mesmo valor > 0
 - Iniciar tudo com o mesmo valor < 0
 - Iniciar com valores aleatórios com variância alta
 - Iniciar com valores aleatórios com variância baixa

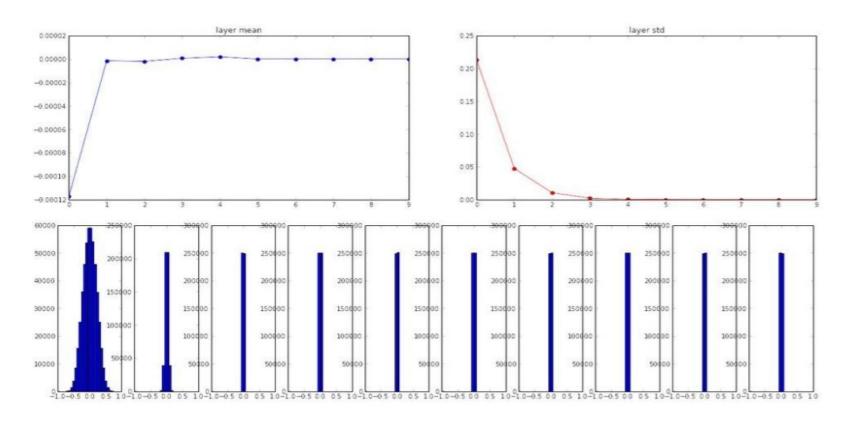
- Inicialização de Parâmetros
 - Iniciar tudo com 0
 - Iniciar tudo com o mesmo valor > 0
 - Iniciar tudo com o mesmo valor < 0
 - Iniciar com valores aleatórios com variância alta





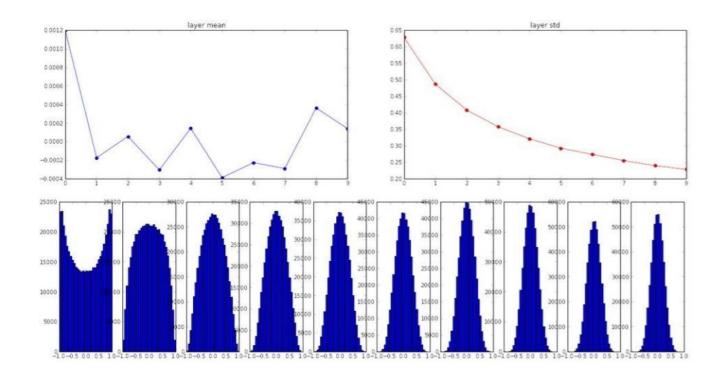


- Inicialização de Parâmetros
 - -W = 0.01*np.random.randn(D, H)



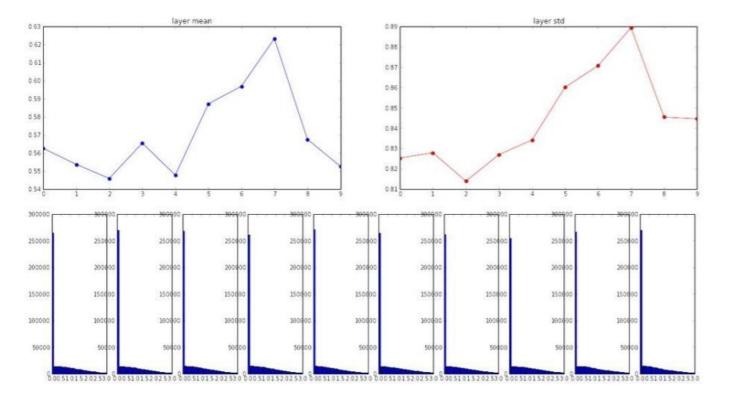
- Inicialização de Parâmetros
 - Xavier Glorot (2010):

W = 0.01*np.random.randn(D, H) / np.sqrt((D+H)/2)

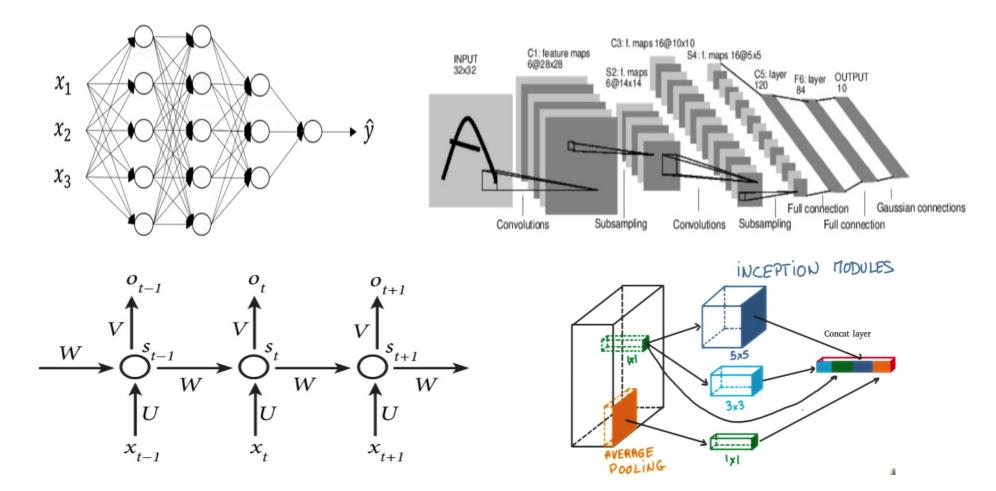


- Inicialização de Parâmetros
 - Kaiming He (2015):

W = 0.01*np.random.randn(D, H) / np.sqrt(D/2)



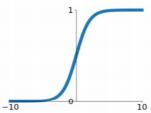
- Hyperparâmetros
 - Escolha da Arquitetura e das Dimensões



- Hyperparâmetros
 - Função de Ativação

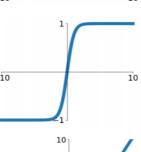
Sigmoid

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$



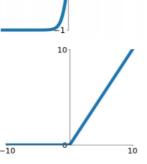
tanh

tanh(x)



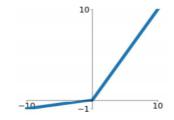
ReLU

 $\max(0,x)$



Leaky ReLU

 $\max(0.1x, x)$

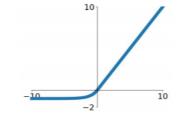


Maxout

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

ELU

$$\begin{cases} x & x \ge 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$



- Hyperparâmetros
 - Algoritmos de Otimização

Stochastic Gradient Descent (SGD):

Batch < len(dataset)

Gradient Descent com Momento

```
v = mu * v - learning_rate * dx # integrate velocity
x += v # integrate position
```

Adagrad

```
cache += dx**2
x += - learning_rate * dx / (np.sqrt(cache) + eps)
```

- Hyperparâmetros
 - Algoritmos de Otimização

RMSprop

```
cache = decay_rate * cache + (1 - decay_rate) * dx**2
x += - learning_rate * dx / (np.sqrt(cache) + eps)
```

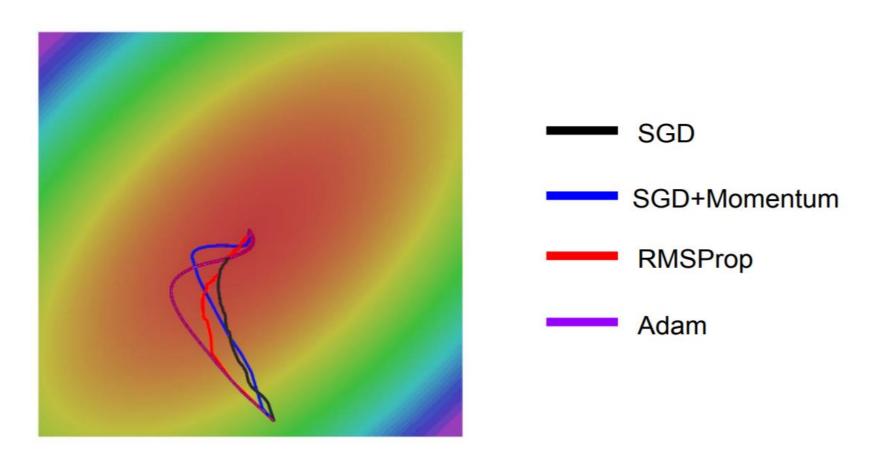
Adam

```
m = beta1*m + (1-beta1)*dx
v = beta2*v + (1-beta2)*(dx**2)
x += - learning_rate * m / (np.sqrt(v) + eps)
```

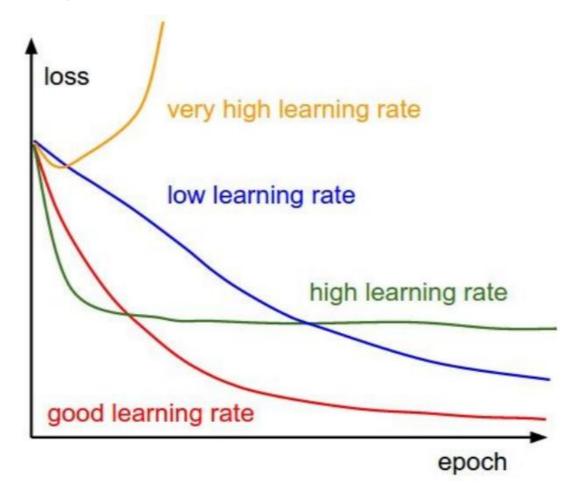
Métodos de 2^a ordem: BFGS e L-BFGS (mais comuns)

$$\boldsymbol{\theta}^* = \boldsymbol{\theta}_0 - \boldsymbol{H}^{-1} \nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}_0)$$

- Hyperparâmetros
 - Algoritmos de Otimização



- Hyperparâmetros
 - Taxa de Aprendizado



Hyperparâmetros

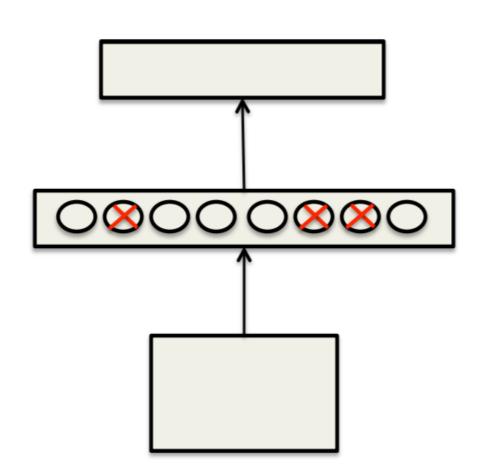
Regularização (weight-decay)

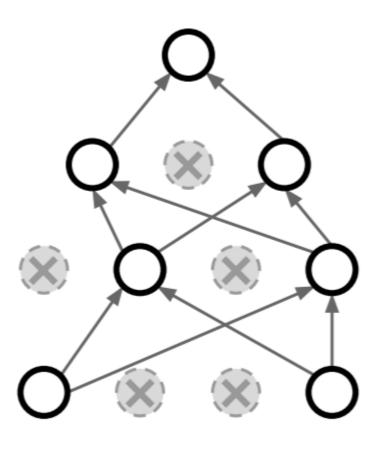
$$L = \frac{1}{N} \sum_{i} L_{i} + \underbrace{\lambda R(W)}_{ ext{regularization loss}}$$

$$-$$
 L2: $R(W) = \sum_k \sum_l W_{k,l}^2$

$$-$$
 L1: $R(W) = \sum_{k} \sum_{l} |W_{k,l}|$

- Hyperparâmetros
 - Dropout



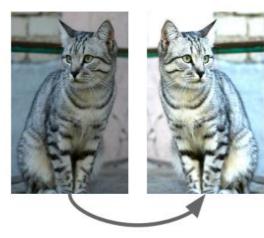


- Hyperparâmetros
 - Batch (Re)Normalization

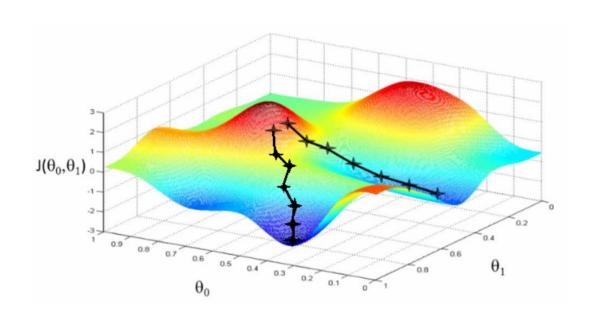
```
Input: Values of x over a mini-batch: \mathcal{B} = \{x_{1...m}\};
                 Parameters to be learned: \gamma, \beta
Output: \{y_i = BN_{\gamma,\beta}(x_i)\}
 \mu_{\mathcal{B}} \leftarrow \frac{1}{m} \sum_{i=1}^{m} x_i // mini-batch mean \sigma_{\mathcal{B}}^2 \leftarrow \frac{1}{m} \sum_{i=1}^{m} (x_i - \mu_{\mathcal{B}})^2 // mini-batch variance
   \widehat{x}_i \leftarrow \frac{x_i - \mu_{\mathcal{B}}}{\sqrt{\sigma_{\mathcal{B}}^2 + \epsilon}}
                                                                                                 // normalize
      y_i \leftarrow \gamma \hat{x}_i + \beta \equiv BN_{\gamma,\beta}(x_i)
                                                                                       // scale and shift
```

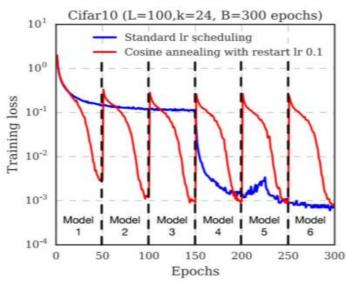
- Hyperparâmetros
 - Data Augmentation



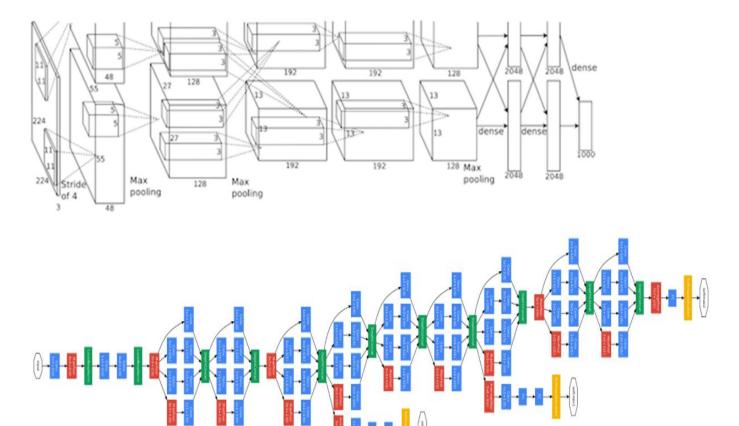


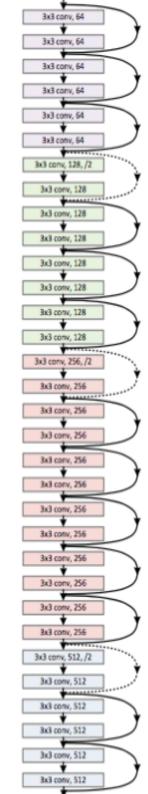
- Hyperparâmetros
 - Ensembles





- Hyperparâmetros
 - Transfer Learning





- Hyperparâmetros
 - Transfer Learning

	Datasets Similares	Datasets Distintos
Muitos dados disponíveis	Treine algumas camadas do modelo base e o classificador de saída	Treine um número maior de camadas (ou todas elas) da rede
Poucos dados disponíveis	Treine apenas o classificador de saída	É Houston, we have a problem

Estudo de Caso: RSNA Bone Age Challenge 2017

RSNA 2017 – Pediatric Bone Age Challenge

Objetivo:

- Identificar idade óssea a partir de radiografias infantis.

Solução proposta:

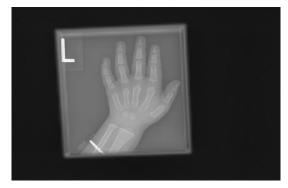
- Deep Learning

Time:

____- UFG + Unifesp

Resumo do Problema







Entradas:

- Radiografia
- Sexo

Idades:

• 1 mês a 19 anos

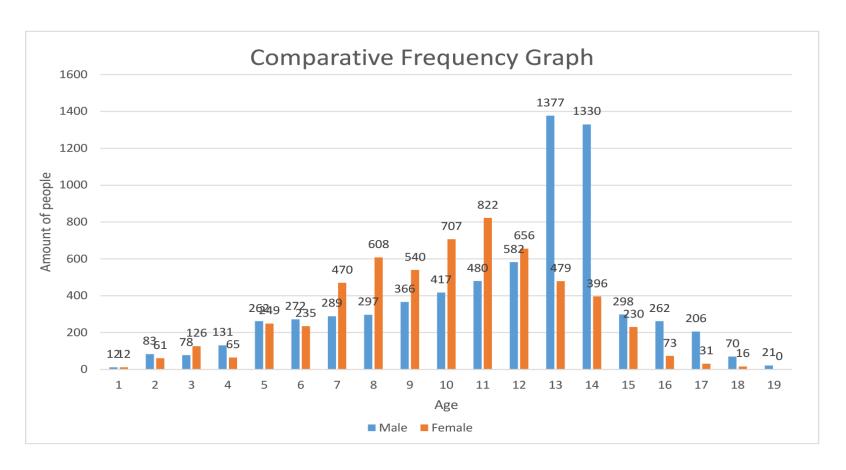
Métrica:

Erro médio absoluto (MAE)

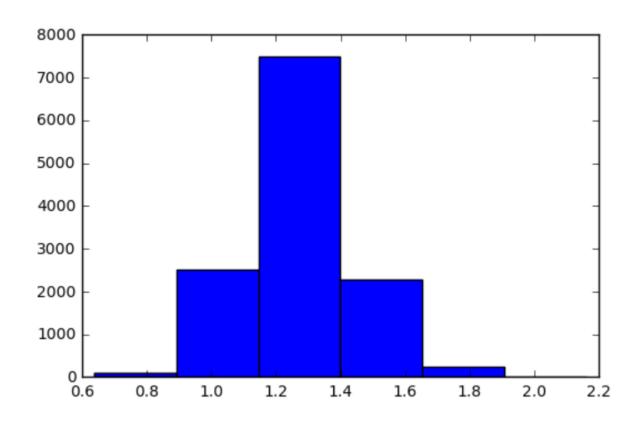
Restrição:

 Proibido usar dados privados ou redes prétreinadas em dados privados

Distribuição das radiografias em relação ao sexo



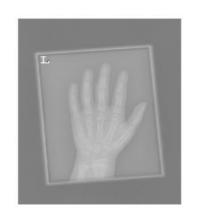
 Distribuição dos formatos (aspect ratio) das radiografias



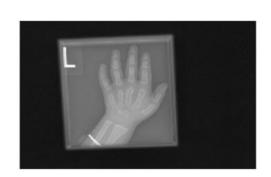
 Variação de Brilho e Contraste entre as radiografias













 Variação estrutural dos dados (ângulo das mãos, presença de outros objetos, presença de duas mãos, etc.)







• Exemplo inacreditável...





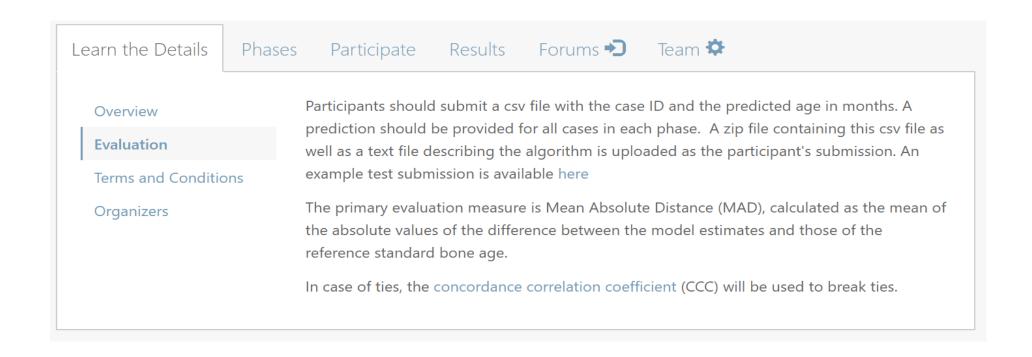






Função Custo e Métrica

Erro Absoluto Médio



Exploração de Arquiteturas

Inception v4

Inception-v4, Inception-ResNet and the Impact of Residual Connections on Learning

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Abstract

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Alex Alemi

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Very deep convolutional networks have been central to the largest advances in image recognition performance in recent years. One example is the Inception architecture that has been shown to achieve very good performance at relatively low computational cost. Recently, the introduction of residual connections in conjunction with a more traditional architecture has yielded state-of-the-art performance in the 2015 ILSVRC challenge; its performance was similar to the latest generation Inception-v3 network. This raises the question of whether there are any benefit in combining the Inception architecture with residual connections. Here we give clear empirical evidence that training with residual connections accelerates the training of Inception networks significantly. There is also some evidence of residual Inception networks outperforming similarly expensive Inception networks without residual connections by a thin margin. We also present several new streamlined architectures for both residual and non-residual Inception networks. These variations improve the single-frame recognition performance on the ILSVRC 2012 classification task significantly. We further demonstrate how proper activation scaling stabilizes the training of very wide residual Inception networks. With

tion [7], object tracking [18], and superresolution [3]. These examples are but a few of all the applications to which deep convolutional networks have been very successfully applied ever since.

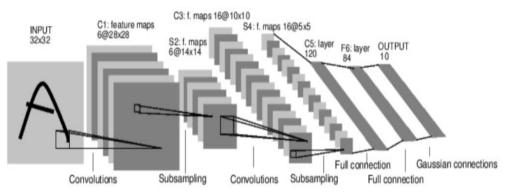
In this work we study the combination of the two most recent ideas: Residual connections introduced by He et al. in [5] and the latest revised version of the Inception architecture [15]. In [5], it is argued that residual connections are of inherent importance for training very deep architectures. Since Inception networks tend to be very deep, it is natural to replace the filter concatenation stage of the Inception architecture with residual connections. This would allow Inception to reap all the benefits of the residual approach while retaining its computational efficiency.

Besides a straightforward integration, we have also studied whether Inception itself can be made more efficient by making it deeper and wider. For that purpose, we designed a new version named Inception-v4 which has a more uniform simplified architecture and more inception modules than Inception-v3. Historically, Inception-v3 had inherited a lot of the baggage of the earlier incarnations. The technical constraints chiefly came from the need for partitioning the model for distributed training using DistBelief [2]. Now, after migrating our training setup to TensorFlow [1] these

```
from keras.models import Sequential
from keras import optimizers
from keras.layers.core import Dense, Dropout
from keras.layers.convolutional import Conv2D
from keras.layers.pooling import MaxPool2D, GlobalAveragePooling2D
from keras.models import Model
from keras.layers import Input, Concatenate
import inception v4
# define cnn model
def inceptionv4():
    #Carrega Incpetion v4
    model = inception v4.create model(include top=False)
    return model
imgs = Input(shape=(598, 598, 1))
gender = Input(shape=(1,))
x = Conv2D(3, 3, padding='same', activation='relu')(imgs)
x = MaxPool2D()(x)
x = inceptionv4()(x)
x = GlobalAveragePooling2D()(x)
x = Concatenate(axis=-1)([x,qender])
x = Dense(32, activation='relu')(x)
outputs = Dense (1) (x)
inputs = [imgs, gender]
icptv4 model = Model(inputs=inputs, outputs=outputs)
# escolha o modelo a ser treinado:
model = icptv4 model
#model.summarv()
```

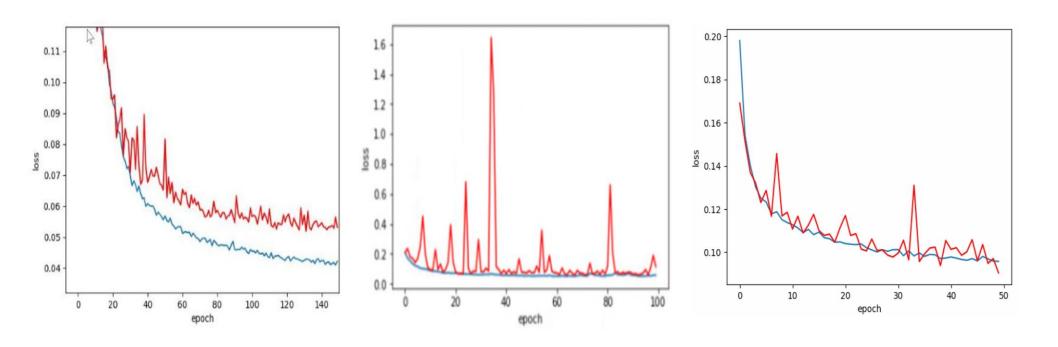
Exploração de Arquiteturas

Variação da LeNet



```
from keras.models import Sequential
from keras import optimizers
from keras.layers.core import Dense, Dropout
from keras.layers.convolutional import Conv2D
from keras.layers.pooling import MaxPool2D, GlobalAveragePooling2D
from keras.models import Model
from keras.layers import Input, Concatenate
# define cnn model
cnn model = Sequential()
cnn model.add(Conv2D(16, 3, input shape=(550, 550, 1), padding='same', activation='relu'))
cnn model.add(MaxPool2D())
cnn model.add(Conv2D(32, 3, padding='same', activation='relu'))
cnn model.add(MaxPool2D())
cnn model.add(Dropout(0.5))
cnn model.add(Conv2D(32, 3, padding='same', activation='relu'))
cnn model.add(MaxPool2D())
cnn model.add(Conv2D(64, 3, padding='same', activation='relu'))
cnn model.add(MaxPool2D())
cnn model.add(Conv2D(64, 3, padding='same', activation='relu'))
cnn model.add(Dropout(0.5))
cnn model.add(GlobalAveragePooling2D(name='ft x layer'))
cnn model.add(Dense(64, activation='relu'))
cnn model.add(Dense(1))
# define ft. extractor + gender based on cnn model
base model = Model(inputs=cnn model.input, outputs=cnn model.get layer('ft x layer').output)
imgs = base model.input
gender = Input(shape=(1,))
x = base model.output
x = Concatenate(axis=-1)([x,gender])
x = Dense(32, activation='relu')(x)
outputs = Dense(1)(x)
inputs = [imgs, gender]
ft x cnn model = Model(inputs=inputs, outputs=outputs)
# escolha o modelo a ser treinado:
model = ft x cnn model
#model.summary()
```

Resultados



Resultados



