

GRACeFUL WP4 - DSL

Domain-Specific Language for System Dynamics Models

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Introduction



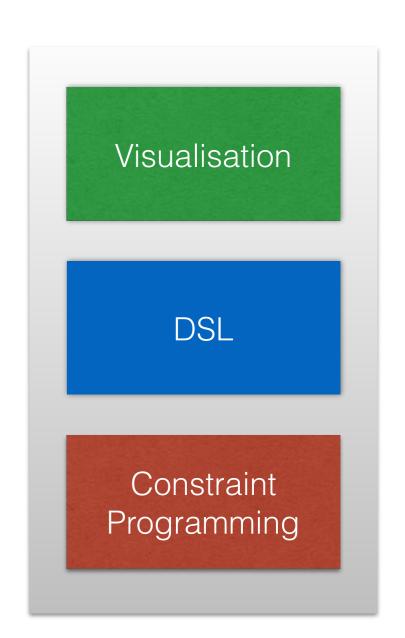
- What is the purpose of GRACeFUL?
- What is a GRACeFUL Concept Map?
- Use Concept Maps and Constraint Programming instead of simulation



Domain specific language



- Use a DSL to express Concept Maps
- Why use a DSL (and not directly translate to CP)?
 - Simple interface for Visualisation Layer
 - Abstract away from Constraint Programming layer
 - Validate correctness of generated model



Haskell



- We have implemented the DSL in Haskell
- Haskell serves as the host language
- Haskell is a functional programming language
 - Algebraic datatypes
 - Strongly typed
 - Good compiler: GHC



GRACe DSL



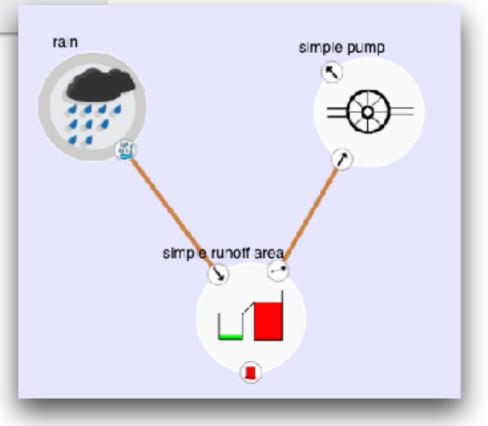
- GRACe: a DSL for GRACeFUL Concept Maps in Haskell
 - Expressive
 - Composable
- Translated to Constraint Programs
- Expose components to Visualisation Layer via libraries



```
example :: GCM ()
example = do
  (inflowP, outflowP) <- pump 5
  (inflowS, outletS, overflowS) <- runoffArea 5
  rainflow <- rain 10

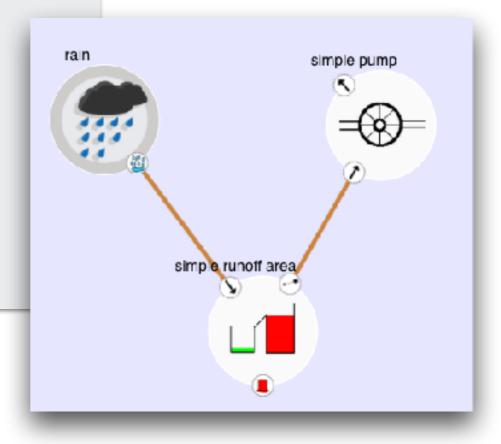
link inflowP outletS
  link inflowS rainflow

output overflowS "Overflow"</pre>
```



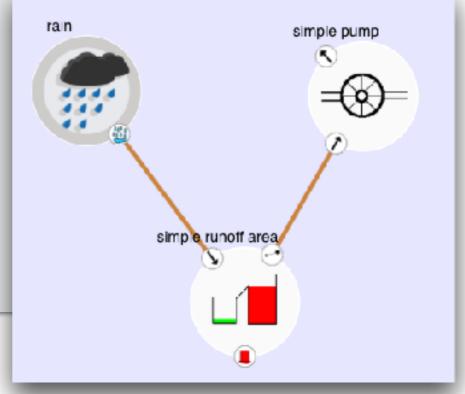


```
rain :: Float -> GCM (Port Float)
rain amount = do
  port <- createPort</pre>
  set port amount
  return port
pump :: Float -> GCM (Port Float, Port Float)
pump maxCap = do
  inPort <- createPort</pre>
  outPort <- createPort</pre>
  constrain $ do
    inflow <- value inPort</pre>
    outflow <- value outPort
    assert $ inflow === outflow
    assert $ inflow `inRange` (0, maxCap)
  return (inPort, outPort)
```





```
runoffArea :: Float -> GCM (Port Float, Port Float, Port Float)
runoffArea cap = do
  inflow <- createPort</pre>
  outlet <- createPort
 overflow <- createPort
  constrain $ do
    currentStored <- createLVar</pre>
    inf <- value inflow
    out <- value outlet
    ovf <- value overflow
    sto <- value currentStored
                                                   ra n
    assert $ sto === inf - out - ovf
    assert $ sto `inRange` (0, cap)
    assert $ (ovf .> 0) ==> (sto === cap)
    assert $ ovf >= 0
  return (inflow, outlet, overflow)
```



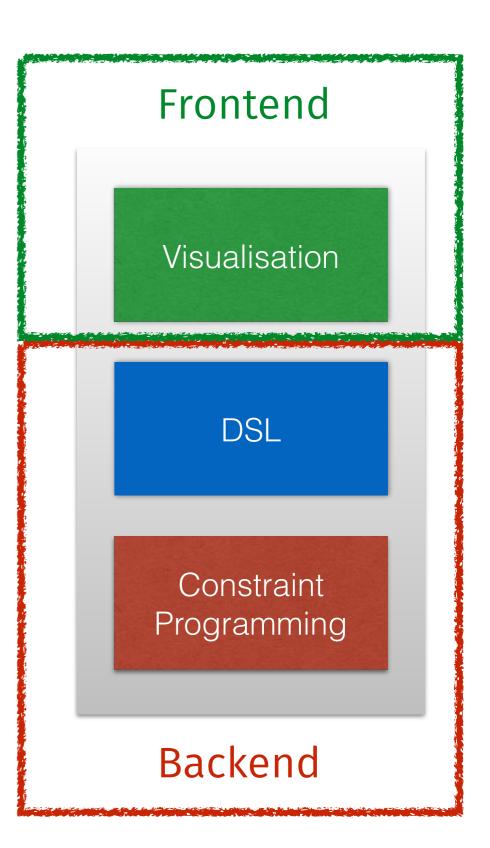


```
var float: v6;
var float: v5;
                              > runGCM example
var float: v4;
                              "{\"Overflow\" : 0.0}\n"
var float: v3;
var float: v2;
var float: v1;
var float: v0;
constraint ((v0) == (v1));
constraint (((0.0) \le (v0)) / ((v0) \le (5.0)));
constraint ((v5) == (((v2) - (v3)) - (v4)));
constraint (((0.0) \le (v5)) / ((v5) \le (5.0)));
constraint ((not ((not ((not ((0.0) < (v4)))))) /\
           ((not ((v5) == (5.0))))));
constraint ((0.0) \le (v4));
constraint ((v6) == (10.0));
constraint ((v0) == (v3));
constraint ((v2) == (v6));
solve satisfy;
output ["{\"Overflow\" : \(v4)}"]
```

GRACeServer



- Expose GRACe DSL via webservices:
 - Query libraries
 - Evaluate DSL programs
 - Exchange format in JSON
- We use the Servant library
- Deployed via Docker
- Typed -> untyped -> typed



TypedValues



- Combine value with its type representation
- Hide type using existential quantification
- Tags for annotating meta data (such as names and images)

Example library



```
library :: Library
library = Library "crud"
    [ item "rain" $
       rain ::: "amount" #
         tFloat .-> tGCM
                                  (tPort $ "rainfall" # tFloat)
    , item "pump" $
       pump ::: "capacity" #
         tFloat .-> tGCM (tPair (tPort $ "inflow" # tFloat)
                                  (tPort $ "outflow" # tFloat))
    , item "runoff area" $
       runoffArea ::: "storage capacity" #
         tFloat .-> tGCM (tTuple3 (tPort $ "inflow" # tFloat)
                                  (tPort $ "outlet" # tFloat)
                                  (tPort $ "overflow" # tFloat))
```

Conclusions



- We have constructed a DSL for GRACeFUL Concept Maps
- We can define libraries of components
- Using the GRACeServer the Visualisation Layer can construct and evaluate GRACeFUL Concept Maps