

*)

satellites[i].a += OrbitCalculator::b

* satellites[a].m

satellites[b].pos = satellites[i].pos

^2) { ... }

satellites[i].v += satellites[i].a * delta

satellites[i].pos = satellites[i].a

* delta * delta / 2

+ satellites[i].v

* delta

+ satellites[i].pos

satellites[i].a = [0, 0, 0]

}

}

satellites[i] satellites[i].header

OrbitCalculator::ready() {

OrbitCalculator::process() {

for (int i = 0; i < satellites.length();

{ for (int b = 0; b < i; i = satellites.length();

{ if (i == b) continue;

OrbitCalculator::new_body(satellites[i].

OrbitCalculator::append(satellites, sat);

Obstacle

sataat[] satellites

struct sataat {

int[] pos = [0, 0, 0];

int[] v! = [0, 0, 0];

int[] acc = [0, 0, 0];

int[] collisionArea = [-1000, -1

1, 1, 1];

int m

int[] posn = [0, 0, 0]

}