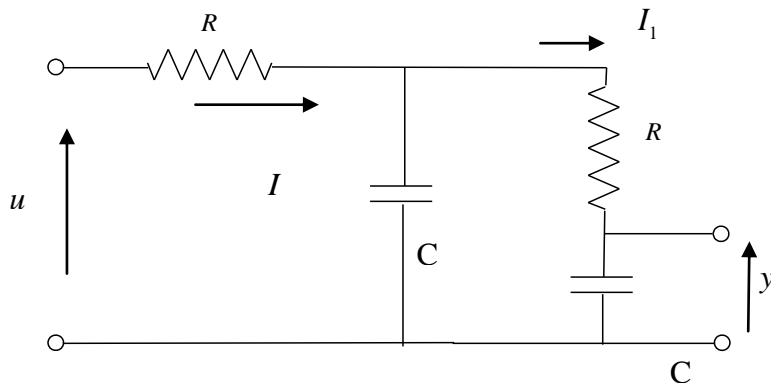


Tracce delle soluzioni

1.
1)



$$U = ZI$$

$$Z = R + \frac{RCs + 1}{Cs(RCs + 2)}$$

$$Y = \frac{1}{Cs} \cdot I_1 = \frac{1}{Cs} \cdot I \frac{\frac{1}{Cs}}{\frac{1}{Cs} + R + \frac{1}{Cs}} = \frac{1}{Cs} \cdot \frac{U}{Z} \frac{\frac{1}{Cs}}{\frac{1}{Cs} + R + \frac{1}{Cs}}$$

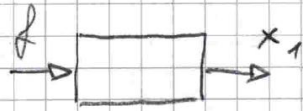
$$G(s) := \frac{Y}{U} = \frac{1}{T^2 s^2 + 3Ts + 1}$$

2) I poli del sistema sono $\frac{-3-\sqrt{5}}{2T}$, $\frac{-3+\sqrt{5}}{2T}$ e quindi i corrispondenti modi sono $\exp\left(\frac{-3-\sqrt{5}}{2T} \cdot t\right)$, $\exp\left(\frac{-3+\sqrt{5}}{2T} \cdot t\right)$.

3) L'equazione differenziale associata a $G(s)$ è

$$T^2 D^2 y + 3TDy + y = u$$

2.



$$\begin{cases} m D^2 x_1 = f - k(x_1 - x_2) \Rightarrow k x_2 = m D^2 x_1 + k x_1 - f \\ m D^2 x_2 = k(x_1 - x_2) - k(x_2 - x_3) \\ m D^2 x_3 = k(x_2 - x_3) \end{cases}$$

$$\begin{cases} k x_3 = m D^2 x_2 + 2k x_2 - k x_1 \\ m D^2 x_3 + k x_3 = k x_2 \end{cases} \quad (m D^2 + k) x_3 = k x_2$$

$$(m D^2 + k)(m D^2 x_2 + 2k x_2 - k x_1) = k^2 x_2$$

$$(m D^2 + k)(m D^2 + 2k) x_2 - k(m D^2 + k) x_1 = k^2 x_2$$

$$(m^2 D^4 + 2k m D^2 + k m D^2 + 2k^2 - k^2) x_2 = k(m D^2 + k) x_1$$

$$(m^2 D^4 + 3k m D^2 + k^2) x_2 = k(m D^2 + k) x_1$$

$$(m^2 D^4 + 3k m D^2 + k^2)(m D^2 x_1 + k x_1 - f) = k^2(m D^2 + k) x_1$$

$$(m^2 D^4 + 3k m D^2 + k^2)(m D^2 + k) x_1 - k^2(m D^2 + k) x_1 = (m^2 D^4 + 3k m D^2 + k^2) f$$

$$(m^2 D^4 + 3k m D^2)(m D^2 + k) x_1 = (m^2 D^4 + 3k m D^2 + k^2) f$$

$$\text{f.d.t. } G(s) = \frac{m^2 s^4 + 3k m s^2 + k^2}{(m^2 s^4 + 3k m s^2)(m s^2 + k)} = \frac{m^2 s^4 + 3k m s^2 + k^2}{m \cdot s^2 (m s^2 + 3k)(m s^2 + k)}$$

3.

Le dimostrazioni della prima e terza proprietà sono riportate sulle dispense del corso. La seconda dimostrazione richiesta si deduce facilmente a partire dalla prima proprietà.

4.

Vedi le dispense del corso.

5.

1° metodo: $u(t) = 1(t) - 1(t-1)$

$$U(s) = \frac{1}{s} - \frac{1}{s} e^{-s} \quad Y(s) = G(s)U(s) = \frac{1}{s(s+1)^2} - \frac{1}{s(s+1)^2} e^{-s}$$

$$y(t) = \mathcal{L}^{-1} \left[\frac{1}{s(s+1)^2} \right] - \mathcal{L}^{-1} \left[\frac{1}{s(s+1)^2} \cdot e^{-s} \right]$$

$$\frac{1}{s(s+1)^2} = \frac{K_1}{s} + \frac{K_{21}}{(s+1)^2} + \frac{K_{12}}{s+1}$$

$$K_1 = \frac{1}{(s+1)^2} \Big|_{s=0} = 1 \quad K_{21} = \frac{1}{s} \Big|_{s=-1} = -1 \quad K_1 + K_{12} = 0$$

$$K_{12} = -1$$

$$\mathcal{L}^{-1} \left[\frac{1}{s(s+1)^2} e^{-s} \right] = \mathcal{L}^{-1} \left[\frac{1}{s(s+1)^2} \right] (t-1) \cdot 1(t-1)$$

$$y(t) = 1 - t e^{-t} - e^{-t} - \left[1 - (t-1) e^{-(t-1)} - e^{-(t-1)} \right] \cdot 1(t-1)$$

$$\text{Per } t \in [0, 1) \quad y(t) = 1 - t e^{-t} - e^{-t}$$

$$\text{Per } t \in [1, +\infty) \quad y(t) = \cancel{1 - t e^{-t} - e^{-t}} - \cancel{1} + (t-1) e^{-(t-1)} \cdot e + \cancel{e^{-(t-1)} \cdot e}$$

$$y(t) = -e^{-t} + (e-1) t e^{-t}$$

2° metodo: Per $t \in [0, 1)$ vale $u(t) = 1(t)$

$$\text{e quindi } y(t) = 1 - t e^{-t} - e^{-t}$$

$$\text{Per } t \in [1, +\infty) \quad y(t) = c_1 e^{-t} + c_2 t e^{-t}$$

 $u(t)$ è discontinua su $(-\infty, +\infty)$, quindi $y(t) \in C^{0-1}(\mathbb{R})$
ovvero $y(t) \in C^1(\mathbb{R})$

$$\begin{cases} y(1-) = y(1+) \\ D y(1-) = D y(1+) \end{cases}$$

$$\begin{cases} y(1-) = y(1+) \\ D y(1-) = D y(1+) \end{cases}$$

$$\text{Für } t \in [0, 1) \quad y(t) = 1 - te^{-t} - e^{-t}$$

$$Dy(t) = -e^{-t} + te^{-t} + e^{-t}$$

$$\text{Für } t \in [1, +\infty) \quad y(t) = C_1 e^{-t} + C_2 t e^{-t}$$

$$Dy(t) = -C_1 e^{-t} + C_2 (e^{-t} - t e^{-t})$$

$$y(1-) = 1 - e^{-1} - e^{-1} = 1 - 2e^{-1}$$

$$Dy(1-) = -\cancel{e^{-1}} + \cancel{e^{-1}} + e^{-1} = e^{-1}$$

$$\begin{cases} C_1 e^{-1} + C_2 e^{-1} = 1 - 2e^{-1} \\ -C_1 e^{-1} + C_2 (e^{-1} - e^{-1}) = e^{-1} \end{cases} \Rightarrow C_1 = -1$$

$$-e^{-1} + C_2 e^{-1} = 1 - 2e^{-1} \quad -1 + C_2 = e - 2$$

$$\Rightarrow C_2 = e - 1$$

$$y(t) = -e^{-t} + (e-1)te^{-t}$$

6.

Soluzioni

Metodo dei modi: $y(t) = C_1 e^{-t} + C_2 e^{-2t}$

$$Dy(t) = -C_1 e^{-t} - 2C_2 e^{-2t}$$

$$\begin{cases} C_1 + C_2 = 0 \\ -C_1 - 2C_2 = 1 \end{cases} \quad \begin{aligned} C_2 &= -C_1 \\ -C_1 - 2(-C_1) &= 1 \end{aligned} \quad \begin{aligned} C_2 &= -1 \\ C_1 &= 1 \end{aligned}$$

Quindi $y(t) = e^{-t} - e^{-2t}$

Metodo dell'eq. differenziale: $G(s) = \frac{s+3}{s^2+3s+2}$

$$D^2 y(t) + 3Dy(t) + 2y(t) = Du(t) + 3u(t)$$

Applichiamo la Trasformata di Laplace

$$s^2 Y - y(0+)s - Dy(0+) + 3(sY - y(0+)) + 2Y = 0$$

$$(s^2 + 3s + 2)Y - 1 = 0 \quad Y = \frac{1}{s^2 + 3s + 2}$$

$$Y(s) = \frac{1}{(s+1)(s+2)} = \frac{K_1}{s+1} + \frac{K_2}{s+2} = \frac{1}{s+1} - \frac{1}{s+2}$$

$$K_1 = \frac{1}{s+2} \Big|_{s=-1} = 1 \quad K_1 + K_2 = 0 \quad K_2 = -1$$

$$y(t) = \mathcal{L}^{-1}[Y(s)] = e^{-t} - e^{-2t}$$