



The Stanford 3D Scanning Repository

The "Stanford Bunny"

In recent years, the number of range scanners and surface reconstruction algorithms has been growing rapidly. Many researchers, however, do not have access to scanning facilities or dense polygonal models. The purpose of this repository is to make some range data and detailed reconstructions available to the public. Here's how the models in this repository were created:

Scanning and surface reconstruction

The first set of models below, called "The Stanford Models", were scanned with a [Cyberware](#) 3030 MS scanner, with the exception of Lucy, who was scanned with the [Stanford Large Statue Scanner](#), designed for the [Digital Michelangelo Project](#). Both scanners are swept-stripe, laser triangulation range scanners. The triangulation calculations all the Stanford models except the Happy Buddha and Dragon were performed in hardware by the Cyberware scanner(s). These last two models were acquired using Brian Curless's [spacetime analysis](#). Each scan takes the form of a range image, described in the local coordinate system of the scanner. To merge these range images, we must first align them together. For all the Stanford models, alignment was done using a modified ICP algorithm, as described in [this paper](#). These alignments are stored in ".conf" files, which list each range image in the model along with a translation and a quaternion rotation. Finally, the aligned range images are combined to produce a single triangle mesh (a process sometimes called surface reconstruction) using either [zippering](#) or [volumetric merging](#), two methods developed at Stanford. The entry for each model indicates which method was used. Implementations of both methods are currently available for download, respectively, at [ZipPack](#) and [VripPack](#). The second method is the surface reconstruction method invoked by the [Scanalyze](#) software package used in the [Digital Michelangelo Project](#). Another software package that might be of interest is [Volfill](#), our diffusion-based hole filler for large polygon meshes.

The second set of models below were acquired at a XY scan resolution of 100 microns using the [XYZ RGB](#) auto-synchronized camera, which is based on technology developed in the [Visual Information Technology group](#) of the Canadian National Research Council (NRC). This camera has an accuracy (3 Sigma) of $\pm 0.025\text{mm}$ ($\pm 0.001''$), and X, Y, and Z-axis resolutions of 0.1mm (0.004"), 0.002mm (0.00008"), and 0.003mm (0.0001"), respectively, as determined using a DEA Scirocco coordinate measuring machine. All post-processing, including alignment, merging, editing, and polygon reduction, were done using [Innovmetric's](#) Polyworks software. These models come to us courtesy of Helmut Kungl.

File format

Unless otherwise noted, the range data and reconstructed models in this repository are stored in PLY files. This format was developed at Stanford University, and the source code is available for [download](#). For convenience, we have represented most of these PLY files in their ASCII formats. Choosing ASCII makes it possible for someone unfamiliar with it to get a feel for the file format, and it avoids the problem of using the correct big-endian vs. little-endian byte orders. To view PLY files, you can download our [Scanalyze](#) software package. For converting PLY files to other formats, here are some converters we have or know about:

- Our utility for converting PLY files to Inventor files. Click [here](#) to download the executable.
- [Richard Harding](#) of the Sony Playstation group has contributed a [ply-to-Maya plugin](#). It supports import from PLY to Maya, and export from Maya to PLY, for versions 6.0 and 7.0 of Maya. Starting with Maya 8.5, this exporter can be downloaded from [http://sites.google.com/site/mayaplugin/](#)
- [Bruce Merry](#) of South Africa has written a script to import PLY files to Blender. Click [here](#) to download it.
- A [shareware program](#) written by Zoltan Karpati for converting between many 3D formats, including PLY.
- For converting PLY to OBJ/3DS formats, there used to be a free demo version of Deep Exploration, available [here](#), but we hear it is no longer available.
- Diego Nehab (Princeton) has also written a [toolkit for manipulating PLY files](#).
- Another site with information about PLY files is the [PLY File Format page](#) of the Georgia Institute of Technology's [Large Geometric Models Archive](#).
- Jo o Oliveira of University College London has modified the Georgia Tech libraries so that reading of PLY files is robust to the line breaks inserted when editing them on various platforms. Here is his [package](#).
- Okino's PolyTrans package includes a PLY [importer](#) and [exporter](#).
- Paolo Cignoni's MeshLab system, available from [SourceForge](#).
- A C++ library for parsing PLY files, written by Ares Lagae, is available [here](#).

We have not tested any of these converters ourselves. Feedback or bug reports should be sent directly to the authors of these packages.

Contacting us

For questions and comments about our archive, send mail to:

scanrep-question at graphics dot stanford dot edu

To subscribe to the 3D Scanning Repository's email list, send mail to:

majordomo@lists.stanford.edu

with the message body:

subscribe graphics-scanrep-announce

Please acknowledge...

Please be sure to acknowledge the source of the data and models you take from this repository. In each of the listings below, we have cited the source of the range data and reconstructed models. You are welcome to use the data and models for research purposes. You are also welcome to mirror or redistribute them for free. Finally, you may publish images made using these models, or the images on this web site, in a scholarly article or book - as long as credit is given to the Stanford Computer Graphics Laboratory. However, such models or images are not to be used for commercial purposes, nor should they appear in a product for sale (with the exception of scholarly journals or books), without our permission.

Inappropriate uses of these models

As you browse this repository and think about how you might use our 3D models and range datasets, please remember that several of these artifacts have religious or cultural significance. Aside from the buddha, statues like her are commonly seen in Italian churches. Keep your renderings and other uses of these particular models in good taste. Don't animate or morph them, don't apply Boolean operators to them, and don't simulate nasty things happening to them (like breaking, exploding, melting, etc.). Choose another model for these sorts of experiments. (You can do anything you want to the Stanford bunny or the armadillo.)

Range data versus 3D models - a caveat on the use of these models

The models in this archive are fairly widely used in the graphics, visualization, and vision communities. Things people have done with these models include simplification, multi-resolution representation, curved surface fitting, compression, texture mapping, modeling, deformation, animation, physically-based simulation, texture synthesis, and rendering. The Stanford Bunny is particularly widely used, as surveyed by Greg Turk on this entertaining [web page](#).

One use people have made of these models is as input for surface reconstruction algorithms, typically by stripping away the mesh connectivity and treating the vertices as an unorganized point cloud. We caution against this approach. Our [zippering](#) and [volumetric](#) range image merging methods produce smooth, (usually) manifold surfaces. More specifically, they eliminate outliers in the range data, reduce noise, mask misalignments between range images, and generally hide many of the errors that arise naturally during 3D scanning. In this sense, our reconstructed models do not constitute realistic input data for a surface reconstruction algorithm.

If you want to experiment with a new reconstruction algorithm, and especially if you want to compare its performance against existing methods, then you should start with real range data. For many of the models in this archive, we have made this raw data available. For larger datasets, see the [Stanford Digital Michelangelo Project Archive](#).

Even if you start with real range data, if your goal is surface reconstruction, you should think twice about stripping away the mesh connectivity and treating the vertices as an unorganized point cloud. While this strategy may be appropriate for the data produced by some 3D capture technologies - such as time-of-flight scanners, it may be inappropriate for others - such as swept-plane laser triangulation systems. In these systems, the scanner typically examines a high-resolution image of the reflected laser line, deciding from its profile in this image whether two adjacent vertices should be connected by a surface or not. Cyberware laser scanners do this. Thus, if you discard mesh connectivity, you are discarding real and possibly useful information about the underlying surface.

-Notes by Marc Levoy

The Stanford Models



Stanford Bunny
Source: Stanford University Computer Graphics Laboratory
Scanner: Cyberware 3030 MS

Number of scans: 10
Total size of scans: 362,272 points (about 725,000 triangles)
Reconstruction: zipper

Size of reconstruction: 35947 vertices, 69451 triangles
Comments: contains 5 holes in the bottom

Range data + zippered reconstruction:

[bunny.tar.gz](#) (4.9 MB compressed, 22 MB uncompressed)

Inventor and VRML versions of this model are available from Georgia Tech's [large models archive](#).

A QSplat version of this model is available in the [QSplat models archive](#).

Believe it or not, we also have a [CT scan](#) of the bunny. Check it out!

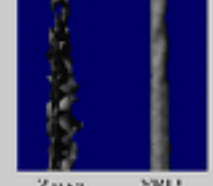
If you want to fly around the bunny, but don't need the model, try [ScanView](#), our client / server rendering system.

We have also captured a [light field](#) of the bunny, using a gantry made from [Lego Mindstorm](#).

This dataset was scanned in 1994 using the zippering technique described in [Turk94].

Here is longer, illustrated [history of the Stanford bunny](#), from [Greg Turk's](#) web pages at Georgia Tech.

Note about the bunny photograph: The bunny was bought and scanned in 1993-94. The color photograph (above) was taken on April 1, 2003. The bits of gray plaster on the sides of the bunny's feet somehow appeared since the bunny was scanned; they are not present in the 3D model. The chip on his left ear, however, is present in the model as well, although degraded in resolution.



Drill bit
Source: Stanford University Computer Graphics Laboratory
Scanner: Cyberware 3030 MS

Number of scans: 12
Total size of scans: 50643 points (about 101,000 triangles)
Reconstruction: zipper and vrip

Size of zippered reconstruction: 881 vertices, 1288 triangles
Size of vrippd reconstruction: 1961 vertices, 3855 triangles

Range data + zippered and vrippd reconstructions:

[drill.tar.gz](#) (0.6 MB compressed, 3.5 MB uncompressed)

This dataset first appeared in [Curless96].



Happy Buddha
Source: Stanford University Computer Graphics Laboratory
Scanner: Cyberware 3030 MS + spacetime analysis

Number of scans: ~60
Total size of scans: 4,586,124 points (about 9,200,000 triangles)
Reconstruction: vrip (conservatively decimated)

Size of reconstruction: 343,652 vertices, 1,087,716 triangles
Comments: hole-free, but contains small bridges due to space carving, so its topological genus is larger than it appears

Range data:

[happy_stand.tar.gz](#) (14 MB compressed, 51 MB uncompressed)
[happy_side.tar.gz](#) (8.9 MB compressed, 35 MB uncompressed)
[happy_back.tar.gz](#) (8.1 MB compressed, 32 MB uncompressed)
[happy_fillers.tar.gz](#) (2.2 MB compressed, 9.0 MB uncompressed)
[happy_backdrop.tar.gz](#) (22 MB compressed, 89 MB uncompressed)

Vrippd reconstruction:
[happy_recon.tar.gz](#) (14 MB compressed, 56 MB uncompressed)

Inventor and VRML versions of this model are available from Georgia Tech's [large models archive](#).

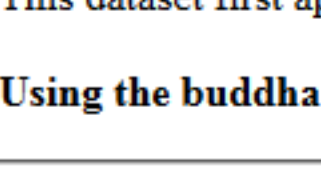
A QSplat version of this model is available in the [QSplat models archive](#).

A voxel array representation of this model (i.e. a Stanford VRI file) is available on the web page of our [Volfill](#) software package.

If you want to fly around the buddha, but don't need the model, try [ScanView](#), our client / server rendering system.

This dataset first appeared in [Curless96].

Using the buddha model: Please remember that the buddha is a religious symbol. See our reminder above about [inappropriate uses](#) of this model.



Dragon
Source: Stanford University Computer Graphics Laboratory
Scanner: Cyberware 3030 MS + spacetime analysis

Number of scans: ~70
Total size of scans: 2,748,318 points (about 5,500,000 triangles)
Reconstruction: vrip (conservatively decimated)

Size of reconstruction: 566,098 vertices, 1,132,830 triangles
Comments: contains numerous small holes

Range data:

[dragon_stand.tar.gz](#) (6.1 MB compressed, 23 MB uncompressed)
[dragon_side.tar.gz](#) (4.2 MB compressed, 16 MB uncompressed)
[dragon_up.tar.gz](#) (5.7 MB compressed, 24 MB uncompressed)
[dragon_fillers.tar.gz](#) (6.7 MB compressed, 26 MB uncompressed)
[dragon_backdrop.tar.gz](#) (11 MB compressed, 44 MB uncompressed)

Vrippd reconstruction:
[dragon_recon.tar.gz](#) (11 MB compressed, 43 MB uncompressed)

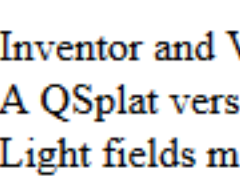
Inventor and VRML versions of this model are available from Georgia Tech's [large models archive](#).

A QSplat version of this model is available in the [QSplat models archive](#).

Light fields made from renderings of this model are available in the [Stanford Light Fields Archive](#).

This dataset first appeared in [Curless96].

Using the dragon: Please remember that the dragon is a symbol of Chinese culture. See our reminder above about [inappropriate uses](#) of this model.



Armadillo
Source: Stanford University Computer Graphics Laboratory
Scanner: Cyberware 3030 MS

Number of scans: 114 (but only 60-70 were used in vrippd model)
Total size of scans: 3,390,515 points (about 7,500,000 triangles)
Reconstruction: vrip (conservatively decimated)

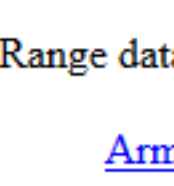
Size of reconstruction: 345,944 triangles

Range data:

[Armadillo_scans.tar.gz](#) (30 MB compressed)

Vrippd reconstruction:
[Armadillo.ply.gz](#) (4 MB compressed, 7 MB uncompressed)

This dataset first appeared in [Krishnamurthy96].



Lucy
Source: Stanford University Computer Graphics Laboratory
Scanner: [Stanford Large Statue Scanner](#)

Number of scans: 47
Total size of scans: 58,241,932 points (approx 116 million triangles)
Reconstruction: vrip at 0.5 mm, holefilling

Size of reconstruction: 14,027,872 vertices, 28,055,742 triangles
Comments: hole-free, but contains small bridges due to space carving, so its topological genus is larger than it appears.

It may also have a few topological problems, making it not a proper manifold. Thanks to the [Chaos Group](#) for the rendering above.

Range data:

[lucy_scans.tar.gz](#) (SD format: 155 MB compressed, 325 MB uncompressed)

Note about this range dataset: Lucy was scanned on two separate occasions. The raw range data (lucy_scans.tar.gz) and the VRIPped reconstruction (lucy.tar.gz) unfortunately do not correspond to the same scan of the statue. Moreover, the raw range data was never aligned, so the *.xf transform files in lucy_scans.tar.gz (as well as those in lucysd.tar.gz in the same directory) do not register the scans together.

Vrippd reconstruction:

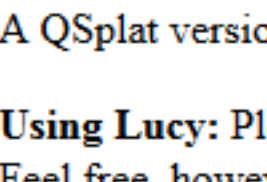
[lucy.tar.gz](#) (307 MB compressed, 508 MB uncompressed)

A QSplat version of this model is available in the [QSplat models archive](#).

Feeling Lucy: Please remember that Lucy is a Christian angel. See our reminder above about [inappropriate uses](#) of this model.

Use free, however, to build a [lego replica](#) of Lucy, as David Winkler has done. Check out his explanation of the [conversion process](#). You can also download the [plans](#) and build it yourself.

The XYZ RGB models



Asian Dragon

Scan data of a dragon sculpture constructed from wood pulp resin. Approx. 20cm x 8cm x 9cm.
Source: [XYZ RGB Inc.](#)

Scanner: XYZ RGB
Number of scans: 18

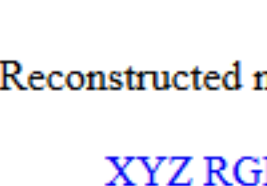
Scan Resolution: 100 um
Total size of scans: 6,300,000 points (about 12,600,000 triangles)

Size of merged model: 3,609,435 vertices, 7,218,906 triangles
Comments: watertight & uncompressed

Reconstructed model:

[XYZ RGB dragon.ply.gz](#) (69 MB compressed, 133 MB uncompressed)

Using the dragon: Please remember that the dragon is a symbol of Chinese culture. See our reminder above about [inappropriate uses](#) of this model.



Vellum manuscript

Vellum manuscript. Approx. 22 cm x 30 cm.

Source: [XYZ RGB Inc.](#)
Scanner: XYZ RGB

Number of scans: 3
Scan Resolution: 100 um

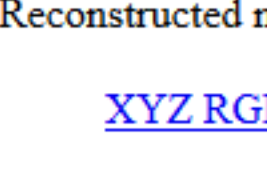
Total size of scans: 3,368,123 points (about 4,750, 000 triangles)
Size of merged model: 2,152,840 vertices, 4,305,679 triangles

Comments: watertight & uncompressed

Reconstructed model:

[XYZ RGB manuscript.ply.gz](#) (41 MB Compressed 86 MB uncompressed)

This illuminated manuscript is a page in Latin from the Book of Hours, Rouen, c. 1460. The scan was made for the paper [Gardner03].



Thai Statue

Scan data of a resin statue. Approx. 40cm x 8cm x 8cm.

Source: [XYZ RGB Inc.](#)
Scanner: XYZ RGB

Number of scans: 36
Scan Resolution: 100 um

Total Size of scans: 34,500,000 points (about 69,000,000 triangles)
Size of merged model: 19,400,000 vertices (38,800,000 triangles)

Size of model provided: 5,000,000 vertices (10,000,000 triangles)
Comments: This model is provided in its decimated form of 10 million polygons

Reconstructed model:

[XYZ RGB statuette.ply.gz](#) (122 MB compressed, 220 MB uncompressed)

Using this model: This statue includes elements of Hindu religious significance. See our reminder above about [inappropriate uses](#) of this model.

Models from the [Stanford Digital Michelangelo Project](#) are available [here](#).
Models in QSplat format, including many of the models listed above, are available [here](#).

Another site with a collection of large geometric models is Greg Turk's [Large Geometric Models Archive](#) at the Georgia Institute of Technology. Links to various pages of that archive are sprinkled throughout this web page.

Citations

[Curless96] [A Volumetric Method for Building Complex Models from Range Images](#)
[Brian Curless](#) and [Marc Levoy](#)
Computer Graphics (SIGGRAPH 1996 Proceedings)

[Gardner03] [Linear Light Source Reflectometry](#)
Andrew Gardner, Chris Tchou, Tim Hawkins, Paul Debevec
Computer Graphics (SIGGRAPH 2003 Proceedings)

[Krishnamurthy96] [Fitting Smooth Surfaces to Dense Polygon Meshes](#)
[Venkat Krishnamurthy](#) and [Marc Levoy](#)
Computer Graphics (SIGGRAPH 1996 Proceedings)

[Turk94] [Zippered Polygon Meshes from Range Images](#)
[Greg Turk](#) and [Marc Levoy](#)
Computer Graphics (SIGGRAPH 1996 Proceedings)