

INTERVAL ESTIMATION

• Goal. Confidence interval.

In interval estimation, we want to find the range $\theta_a \leq \theta \leq \theta_b$ which contains the true value θ_0 with probability β .

Such interval is called "confidence interval" with probability content β .

Typically, we choose $\beta = 68.3\%$ and call it 1 standard deviation error. However, the 68% interval corresponds to ± 1 STD only for a Gaussian distrib.

Given an observation x from a PDF $f(x|\theta)$, the probability content β of the ~~the~~ region $[a, b]$ in x -space is:

$$\beta = P(a \leq x \leq b) = \int_a^b f(x|\theta) dx$$

If $f(x|\theta)$ and the parameter θ are known, one can always compute β given a and b .

If the parameter ~~θ~~ is unknown, we need to find another variable $z = z(x, \theta)$

such that the PDF of z is independent of θ : ~~$f(z|\theta) = f(z)$~~

$$f(z|x, \theta) = f(z|x)$$

If this can be found, we can find the optimal range $[\theta_a, \theta_b]$ in θ -space

such that:

$$P(\theta_a < \theta < \theta_b) = \beta$$

This interval $[\theta_a, \theta_b]$ is called "confidence interval".

A method which yields ~~an~~ such an interval $[\theta_a, \theta_b]$ is said to possess the property of coverage.

Notice that: $\rightarrow \theta_0$ is an unknown constant

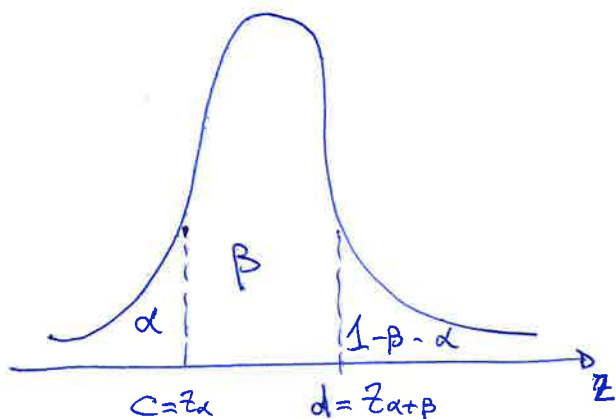
$\rightarrow \theta_a$ and θ_b are functions of x , not of θ .

• Confidence intervals for the mean of a Gaussian

For any Gaussian, we can re-define: $z = \frac{x - \mu}{\sigma}$

which is a standard-normal variable: $f(z) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{z^2}{2}\right)$

Estimating the interval $[c, d]$ so that $P(c \leq z \leq d) = \beta$ is equivalent to finding $[z_\alpha, z_{1-\alpha}]$:



→ There's infinite choices of the interval!

→ A standard choice is the central interval symmetric around zero, so that:

$$\alpha = \frac{1-\beta}{2}$$

$\beta = \frac{1-\alpha}{2}$	z_α	$z_{1-\alpha}$	
0.6827	-1	+1	→ ±1σ
0.9	-1.65	+1.65	
0.95	-1.96	+1.96	
0.9545	-2	+2	→ ±2σ
0.9973	-3	+3	→ ±3σ

• Confidence intervals for several parameters

Suppose we have an n-dimensional Gaussian:

$$f(\vec{\pi} | \vec{\theta}) = \frac{1}{(2\pi)^{n/2} \sqrt{|C|}} \exp\left(-\frac{1}{2}(\vec{\pi} - \vec{\theta})^T C^{-1} (\vec{\pi} - \vec{\theta})\right)$$

Each π_i is normal, Therefore $Q(\vec{\pi}, \vec{\theta}) = (\vec{\pi} - \vec{\theta})^T C^{-1} (\vec{\pi} - \vec{\theta})$ is a $\chi^2(n)$ distribution, and does not depend on $\vec{\theta}$:

$$Q(\vec{\pi}, \vec{\theta}) = Q(\vec{\pi})$$

• Second derivative matrix

Assume $\vec{\pi}$ has an n-dim Gaussian PDF.

One can prove that the n-dim covariance matrix C can be obtained from the inverse of the 2^{nd} order partial derivative matrix of $-\ln L$:

$$C_{ij}^{-1} = - \frac{\partial^2 \ln L(\vec{\pi} | \vec{\theta})}{\partial \theta_i \partial \theta_j}$$

This covariance matrix gives an n-dim elliptic contour with the correct coverage only if the PDF is exactly Gaussian!

This is the "standard" classical method used to compute uncertainties in common fitting algorithms, e.g. Tigrad/Hesse of Minuit/ROOT.

• Log-Likelihood scan

Another common method consists in taking a scan of $-2 \ln L$ around its minimum value, $-2 \ln L_{\text{max}}$.

→ For a Gaussian 1-dim distribution:

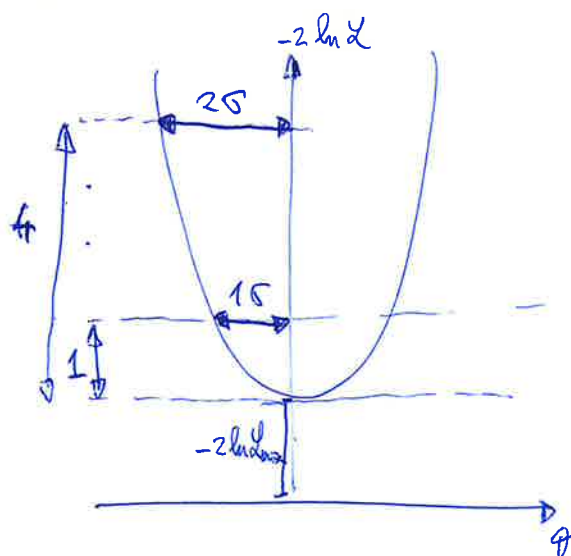
$$\ln L(\mu | n) = \ln C - \frac{(\mu - n)^2}{2\sigma^2}$$

⇒ parabola in μ

$$-2 \ln L = -2 \ln L_{\text{max}} + \frac{(\mu - n)^2}{\sigma^2}$$

The intercept at $-2 \ln L = -2 \ln L_{\text{max}} + 1$ provides the $\pm 1\sigma$ interval.

The intercept at $+4$ provides the $\pm 2\sigma$, and so on

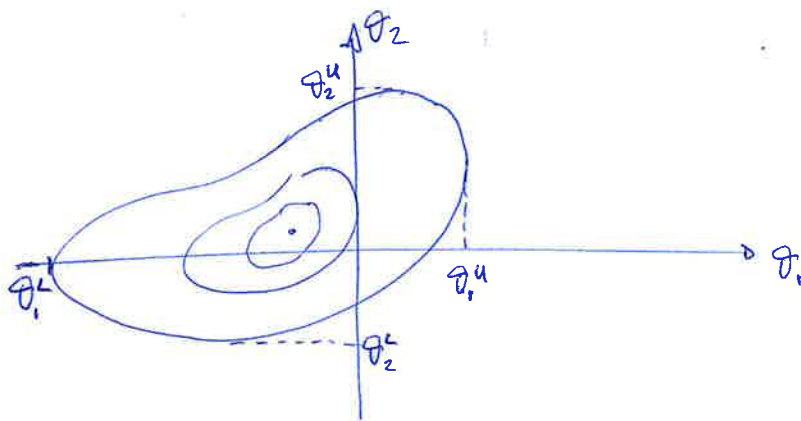


- \mathcal{L} non in $\dim > 1$: Profile likelihood

For $\dim > 1$ we have: $\ln \mathcal{L}_{\vec{\theta}}(\vec{n} | \vec{\theta}) = \ln \mathcal{L}_{\max} - \frac{1}{2} \chi^2_{\vec{\theta}}(\mathbf{K})$

$$\ln \mathcal{L}_{\vec{\theta}}(\vec{n} | \vec{\theta}) = -2 \ln \mathcal{L}_{\max} + \chi^2_{\vec{\theta}}(\mathbf{K})$$

In principle, we can compute the contours:



- Notice that:
- The inner contour is more nearly elliptical than the outer ones
 - The coverage is improved with respect to the Gaussian approximation
 - This is still an approximation valid for large n .

- Variance of Transformed variables, aka Error propagation

Suppose we have a variable \vec{n} with a given PDF $p_{\vec{n}}$ and mean $\vec{\mu}$ and variance $V(\vec{n})$

Suppose we want to compute the variance of the transformed variable $y = y(\vec{n})$,

and that the function can be expanded in Taylor series around $\vec{\mu}$:

$$y(\vec{n}) = y(\vec{\mu}) + \sum_i (\kappa_i - \mu_i) \frac{\partial y}{\partial \mu_i} + \dots$$

The expectation value of y is: $\bar{y} = y(\vec{\mu})$

The variance is: $V(y) = E[(y - E(y))^2]$

$$\approx E \left[\sum_i (\kappa_i - \mu_i) \frac{\partial y}{\partial \mu_i} \right]^2$$

$$\approx \sum_i \sum_j \frac{\partial y}{\partial \mu_i} \frac{\partial y}{\partial \mu_j} E[(\kappa_i - \mu_i)(\kappa_j - \mu_j)]$$

$$\approx \sum_{i,j} \frac{\partial y}{\partial \mu_i} \frac{\partial y}{\partial \mu_j} \text{Cov}(\kappa_i, \kappa_j)$$

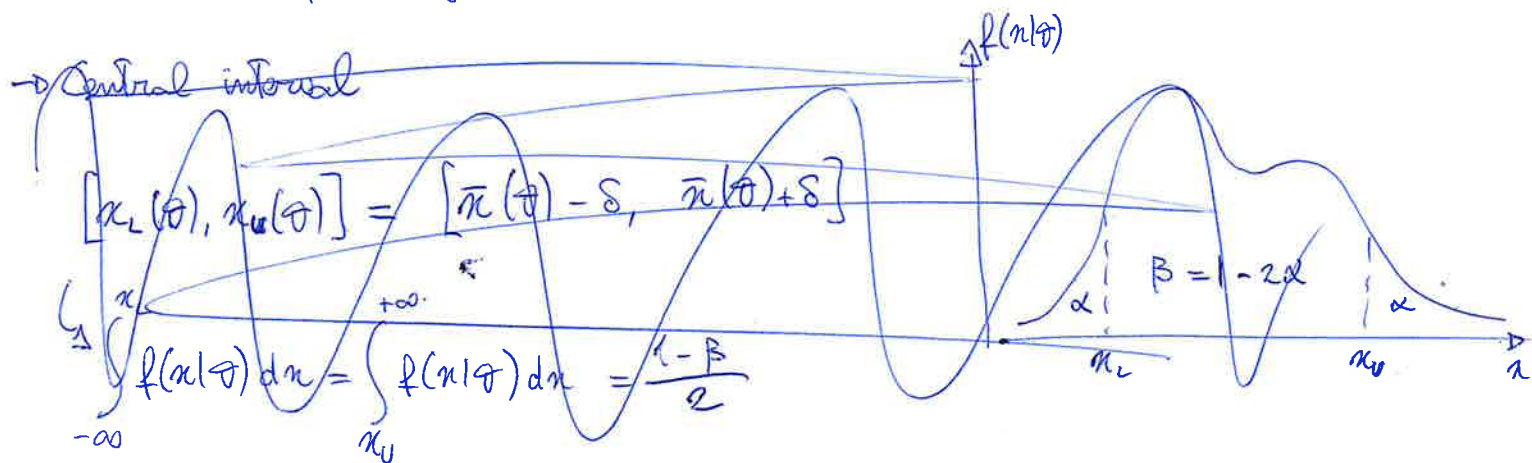
- Confidence intervals for any PDF: Ordering rules

The approximation of $-2\ln L$ with a Gaussian or its excursion around its minimum guarantee an exact coverage only for a small set of cases, and in particular for large n .

Here we'll see a general approach.

Suppose we have a variable κ with PDF $f(\kappa|\theta)$.

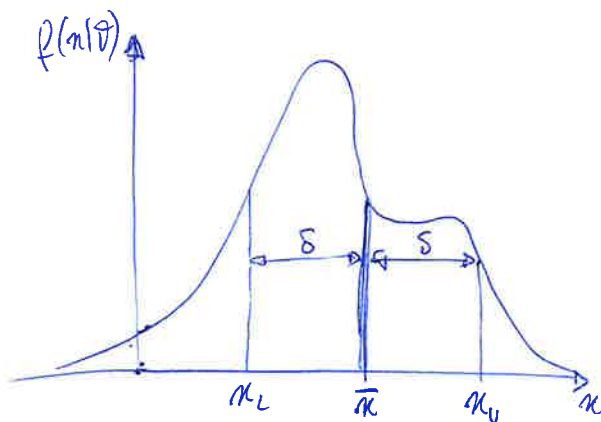
In general, f is not symmetric, so we need to decide how to compute an interval corresponding to some predefined probability content β .



→ Central interval

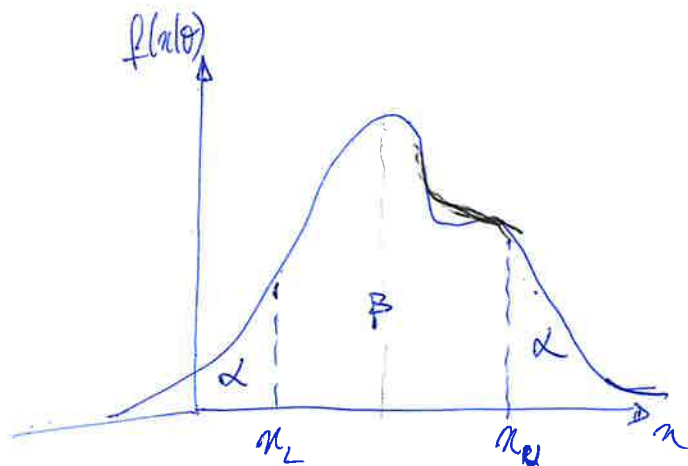
$$[\kappa_L(\theta), \kappa_U(\theta)] = [\bar{\kappa}(\theta) - \delta, \bar{\kappa}(\theta) + \delta]$$

$\bar{\kappa}$ could be the mean or the mode



→ Equal areas

$$\int_{-\infty}^{\kappa_L} f(\kappa|\theta) d\kappa = \int_{\kappa_U}^{+\infty} f(\kappa|\theta) d\kappa = \frac{1-\beta}{2}$$



• Neyman confidence belt

Take a variable x with PDF $f(x|\theta)$ and θ unknown.

~~Assume x could be an estimator of the parameter θ .~~

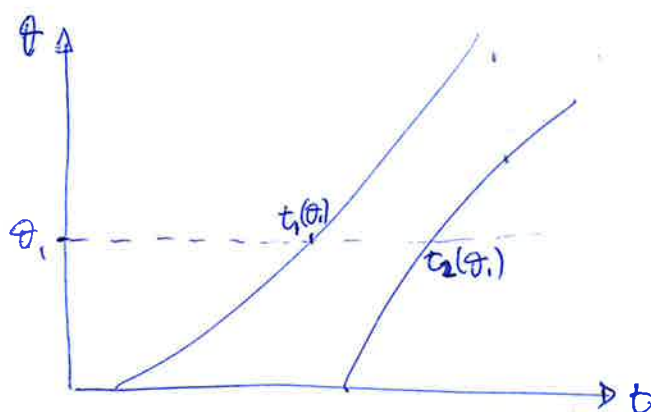
Suppose $t(x)$ is some function of the data.

We can write - $B = P(t_1 \leq t \leq t_2) = P(t_1(\theta) \leq t \leq t_2(\theta))$.

$$= \int_{t_1}^{t_2} f(t|\theta) dt$$

Assume that we have a way to determine t_1 and t_2 for each value of θ .

Such values form two curves in the (t, θ) space: ~~Then~~



From the PDF
of t :

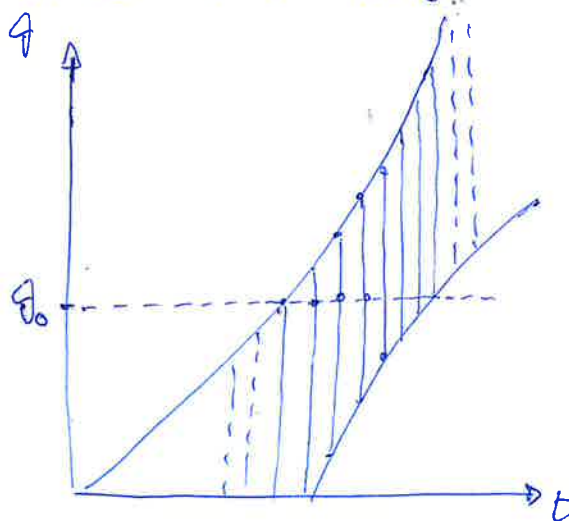
$f(t(x)|\theta)$ we get
 t_1 and t_2

The ~~area~~ space between these curves is called the "Neyman confidence belt".

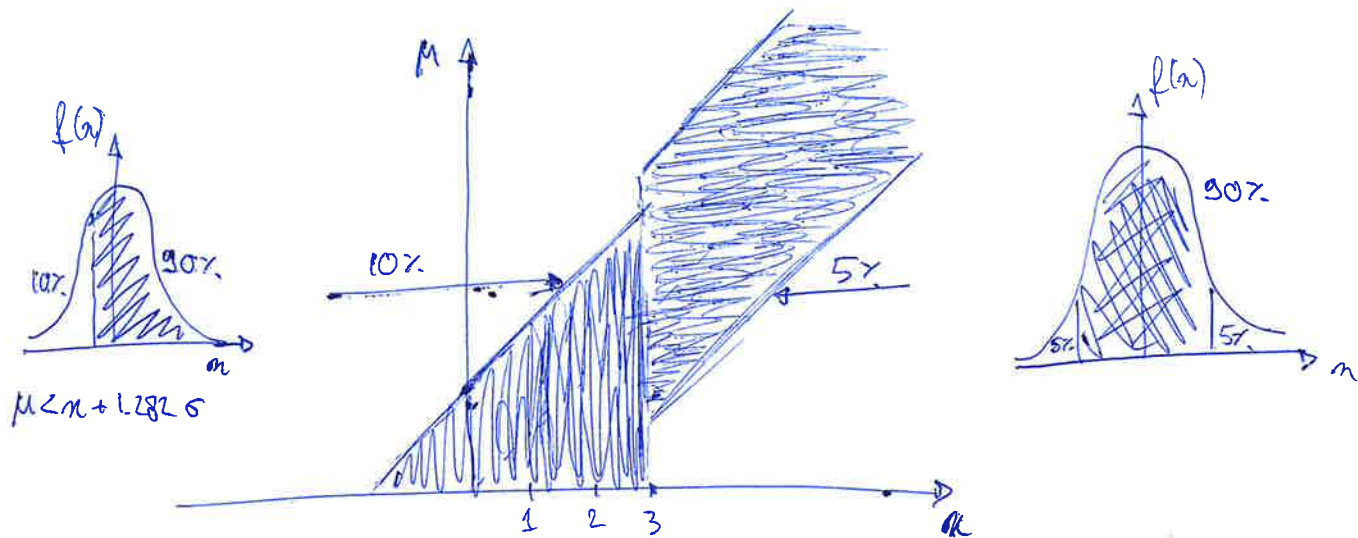
From this belt, ~~we want to~~ given a specific measured value t_0 , we want to extract an interval on the parameter θ .

Suppose θ_0 is the true, unknown value of θ .

If we repeat the measurement many times, a fraction B of the measurements will fall ~~in~~ in $[t_1(\theta_0), t_2(\theta_0)]$ by definition:



The corresponding belt would be:



For some values of μ , e.g. $\mu = 2.5$, we have a coverage of 85% only!

Notice That: \rightarrow The coverage is a property of the method, not of the particular interval

\rightarrow The flip-flopping issue arises from the fact that our ordering rule depends on the outcome of the measurement.

Feldman and Cousins showed that this should not be done!

Example: Flip-flopping

• Example → FC Belt for Gaussian

→ FC belt for electron neutrino mass

• ~~Analytical~~ ~~Numerical~~ FC belt calculation for Gaussian

Recall The flip-flopping zone, where we had x with a PDF:

$$f(x|\mu) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(x-\mu)^2}{2}\right)$$

The value ~~that~~ $\hat{\mu}$ that maximizes $f(x|\mu)$ given some measured x is:

$$\hat{\mu}(x) = \max\{x, 0\}$$

The PDF for x , using the max-L estimate for μ is:

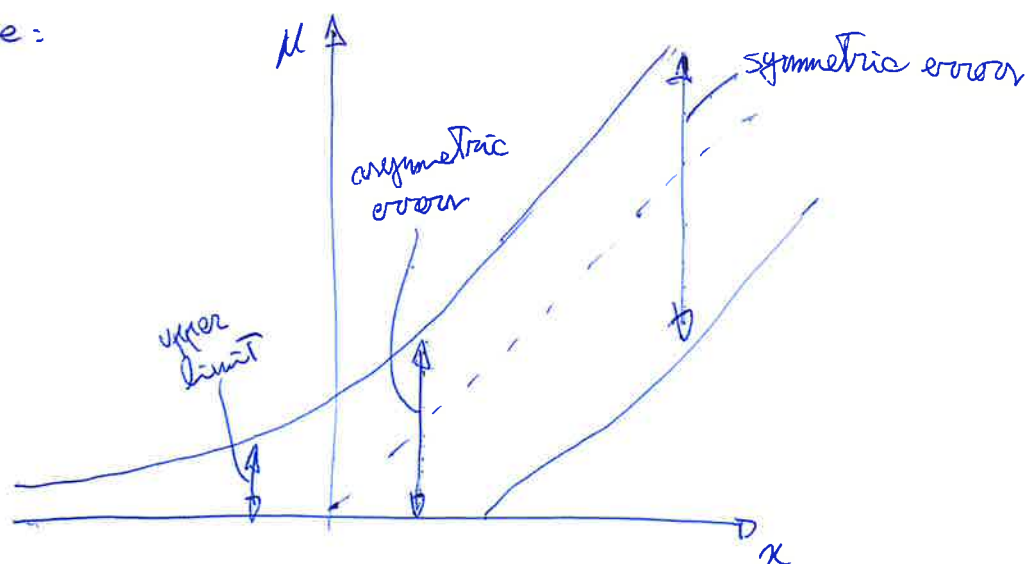
$$f(x|\hat{\mu}(x)) = \begin{cases} \frac{1}{\sqrt{2\pi}} & \text{if } x \geq 0 \\ \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) & \text{if } x < 0 \end{cases}$$

The likelihood ratio becomes:

$$\lambda(x|\mu) = \frac{f(x|\mu)}{f(x|\hat{\mu}(x))} = \begin{cases} \exp\left(-\frac{(x-\mu)^2}{2}\right) & \text{if } x \geq 0 \\ \exp\left(x\mu - \frac{\mu^2}{2}\right) & \text{if } x < 0 \end{cases}$$

At this point, we can find the interval $[\mu_1, \mu_2]$ numerically for any value of x .

The result will be:



If (1) and (2) give different results:

→ If The number of parameters is small (~ 2), Feldman-Cousins is easy to implement.

→ If The number of parameters is ≥ 3 , then FC might become very complicated or CPU intensive, but in this situations typically the profile- χ^2 method provides good coverage.

→ Coverage calculation

In any case, one should make sure the method provides the desired coverage!

This can be done as follows:

- 1) Assume values for each parameter, generate $\geq 10^4$ Toy-MC experiments, count how many times the confidence interval covers the true value of each parameter.
- 2) Repeat for different values of the parameters.