

# Building Socially Intelligent AI systems

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Wu, Jason Xianghua, et al. "Building socially intelligent AI systems: Evidence from the trust game using artificial agents with deep learning." *Management Science* 69.12 (2023): 7236-7252.

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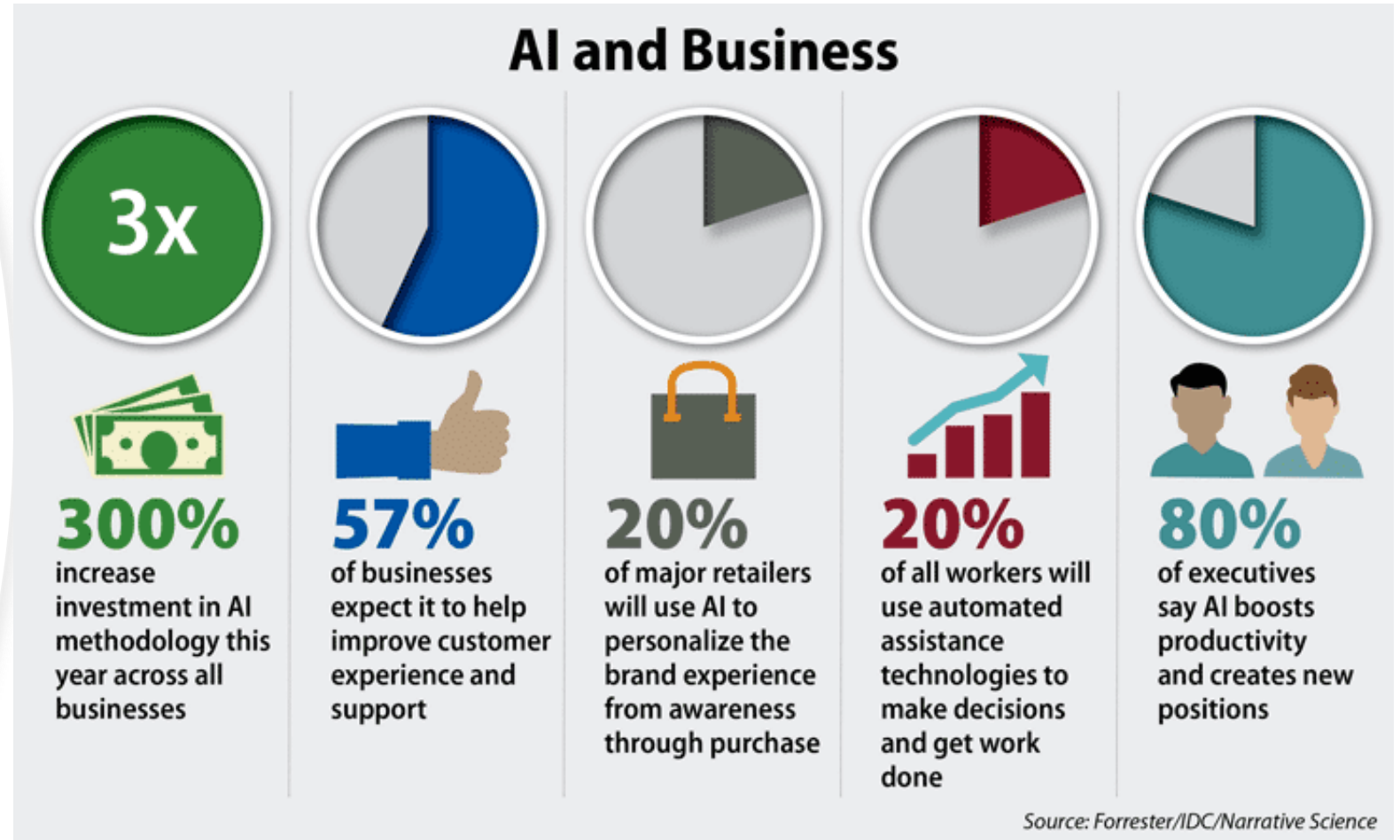
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## Introduction

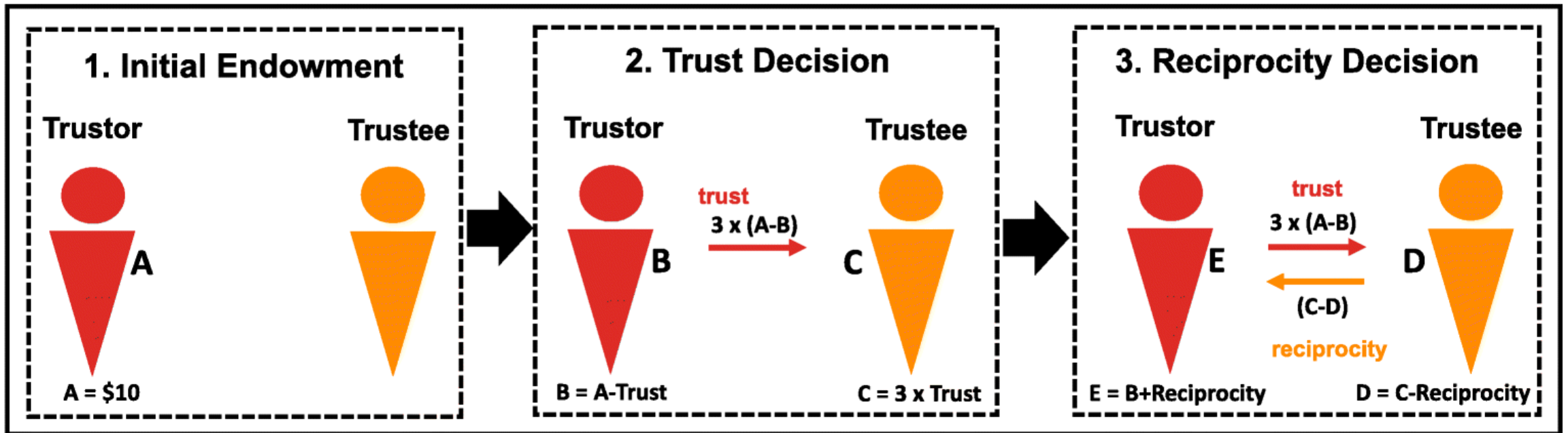
- Trend of implementing AI technologies in business
- New Challenges: Deeper understanding of AI behaviors within a social context



# Trust Game

- Non-zero-sum game
- Quantifiable measure of trust and trustworthiness
- One-sided incentive problem

## One-Round Trust Game



# Objectives



Explore the possibilities and conditions to mimic social behaviors of humans: trust and be trustworthy



Develop trusting and cooperative behavior purely from an interactive trial-and-error learning

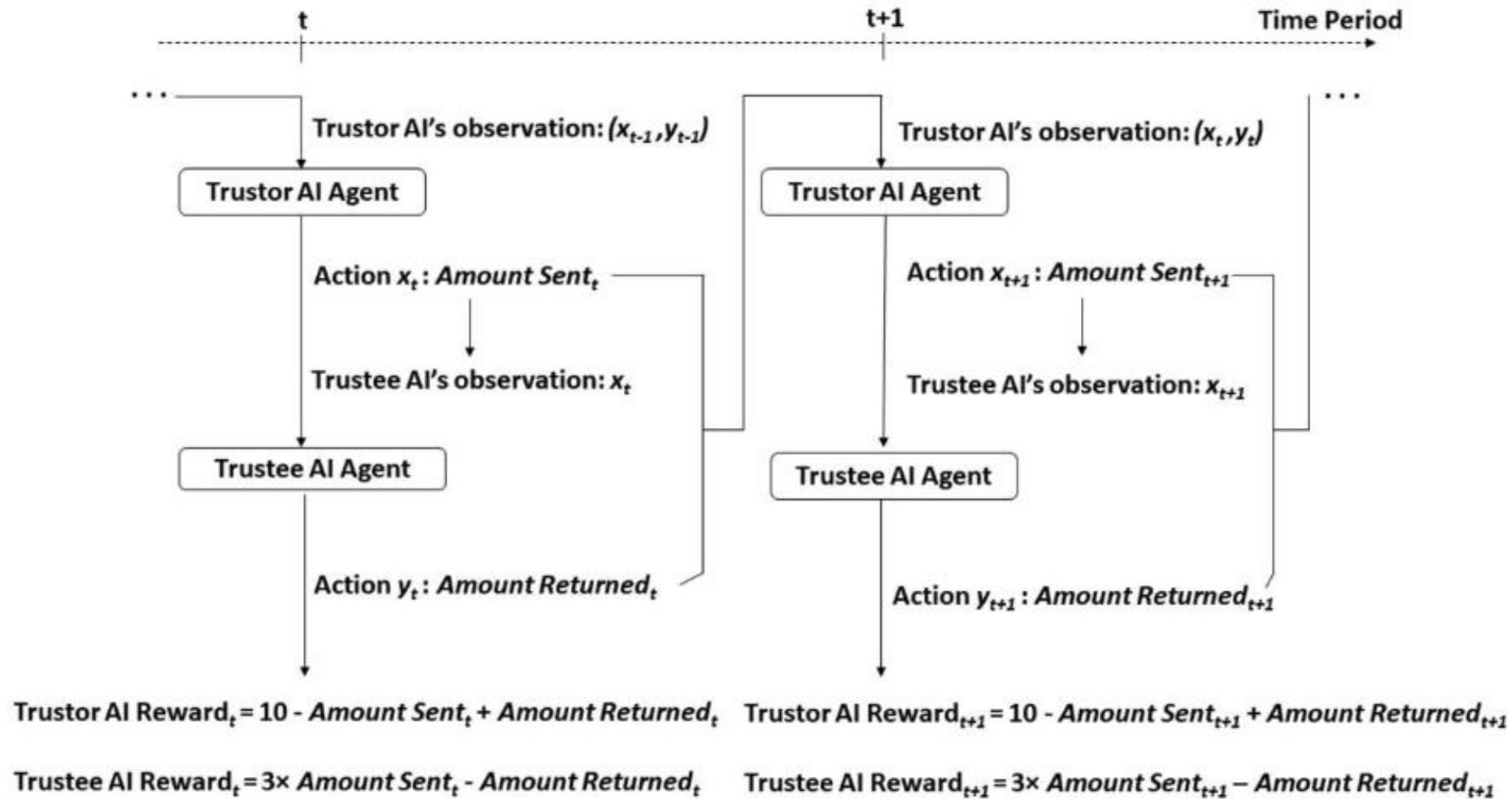


Build decision support systems: Artificial agents can leverage social intelligence to achieve better outcomes

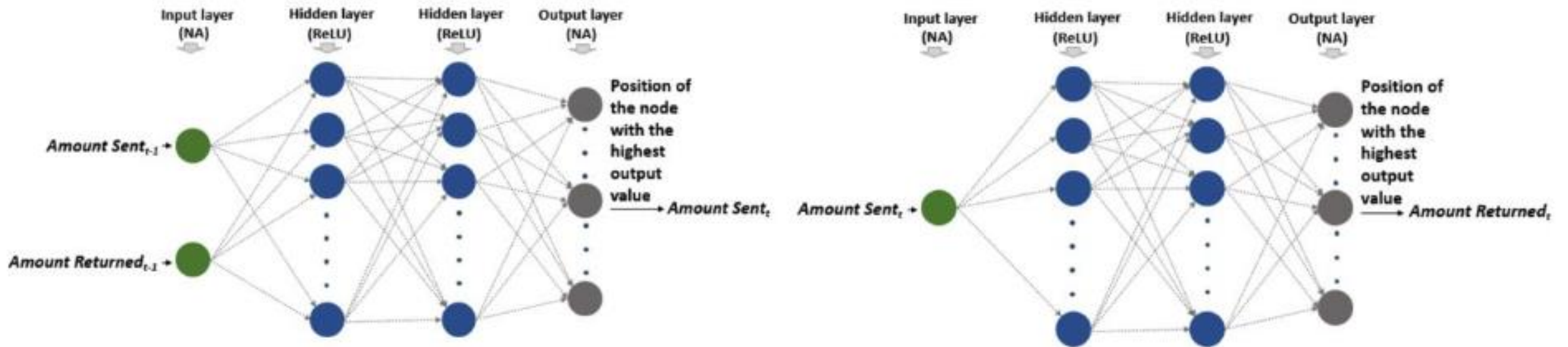
# Methodology

- Deep-Q-network (DQN): Deep reinforcement learning method
  - Build the artificial agents: Trustor and trustee
  - Optimize actions through interactions with the environment in order to maximize the expected cumulative reward
  - $\epsilon$ -greedy policy
- Analysis: Randomization test, polynomial regressions on the length of memory and the discount rate; Robustness check

# Reinforcement Learning Process



# Schematic Neural Network



**Table A.2.** Structural Details of the Neural Network

Layer	Activation function	Number of nodes in the neural network	
		Trustor AI	Trustee AI
Input layer	NA	2	1
Hidden layer 1	ReLU $\max(0, x)$	800	800
Hidden layer 2	ReLU $\max(0, x)$	1,000	1,000
Output layer	NA	11	31



# Objective Function

- Bellman Equation:

$$\begin{aligned} Q_{trustor}^*((x_{t-1}, y_{t-1}), x_t) \\ = \mathbf{E}\{R - x_t + y_t + \gamma \cdot \mathbf{max}_{x_{t+1}} Q_{trustor}^*((x_t, y_t), x_{t+1}) \mid (x_{t-1}, y_{t-1}), x_t\}. \end{aligned}$$

$$Q_{trustee}^*(x_t, y_t) = \mathbf{E}\{\alpha x_t - y_t + \gamma \cdot \mathbf{max}_{y_{t+1}} Q_{trustee}^*(x_{t+1}, y_{t+1}) \mid x_t, y_t\}$$

- Minimize the mean-squared error in the Bellman Equation

$$\begin{aligned} L(\theta_{trustor}) = \mathbf{E}_{x_{t-1}, y_{t-1}, x_t, y_t} (R - x_t + y_t + \gamma \cdot \mathbf{max}_{x_{t+1}} Q_{trustor}((x_t, y_t), \\ x_{t+1}, \theta_{trustor}^{-1}) - Q_{trustor}((x_{t-1}, y_{t-1}), x_t, \theta_{trustor}))^2, \end{aligned}$$

$$\begin{aligned} L(\theta_{trustee}) = \mathbf{E}_{x_t, y_t, x_{t+1}} (\alpha x_t - y_t + \gamma \cdot \mathbf{max}_{y_{t+1}} Q_{trustee}(x_{t+1}, y_{t+1}, \theta_{trustee}^{-1}) \\ - Q_{trustee}(x_t, y_t, \theta_{trustee}))^2, \end{aligned}$$

# Experimental Setting

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The same parameter settings as the trust game Berg et al. (1995)

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Built 20 trustors and 20 trustees

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Training stage for 1,000,000 periods; playing stage for 10,000 periods

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The discount rate:  $\gamma = 0.75$

# Experimental Design



## First set of experiments

- Two matching protocols: fixed partners versus random stranger
- 2 x 2 factorial design



## Second set of experiments

- The availability and the length of memory
- Discount rate
- Robustness check

# Result 1

## DQN agents can develop trust and trustworthiness purely from an interactive trial-and-error learning process.

**Table 1.** Summary Statistics for the  $2 \times 2$  Factorial Design of AI-Agent Experiments

Average over 10,000 playing periods	Trustor AI agents ( $N = 20$ )		Trustee AI agents ( $N = 20$ )	
	Amount sent	Transfer rate: $\frac{\text{Amount Sent}}{10}, \%$	Amount returned	Return rate: $\frac{\text{Amount Returned}}{3 \times \text{Amount Sent}}, \%$
Partner training, partner playing	5.45 (2.54)	54.50 (25.44)	6.20 (2.98)	39.77 (15.42)
Partner training, stranger playing	3.78 (2.10)	37.84 (20.99)	3.25 (0.62)	41.12 (46.14)
Cochard et al. (2004)	7.47 (NA)	74.70 (NA)	NA (NA)	56.14 (NA)
Repeated game ( $N = 16$ )				
Cochard et al. (2004)	5.00 (NA)	50.00 (NA)	NA (NA)	38.21 (NA)
One-shot game ( $N = 20$ )				
Berg et al. (1995)	5.36 (3.53)	53.57 (35.29)	6.46 (6.19)	37.08 (24.83)
One-shot game ( $N = 28$ )				

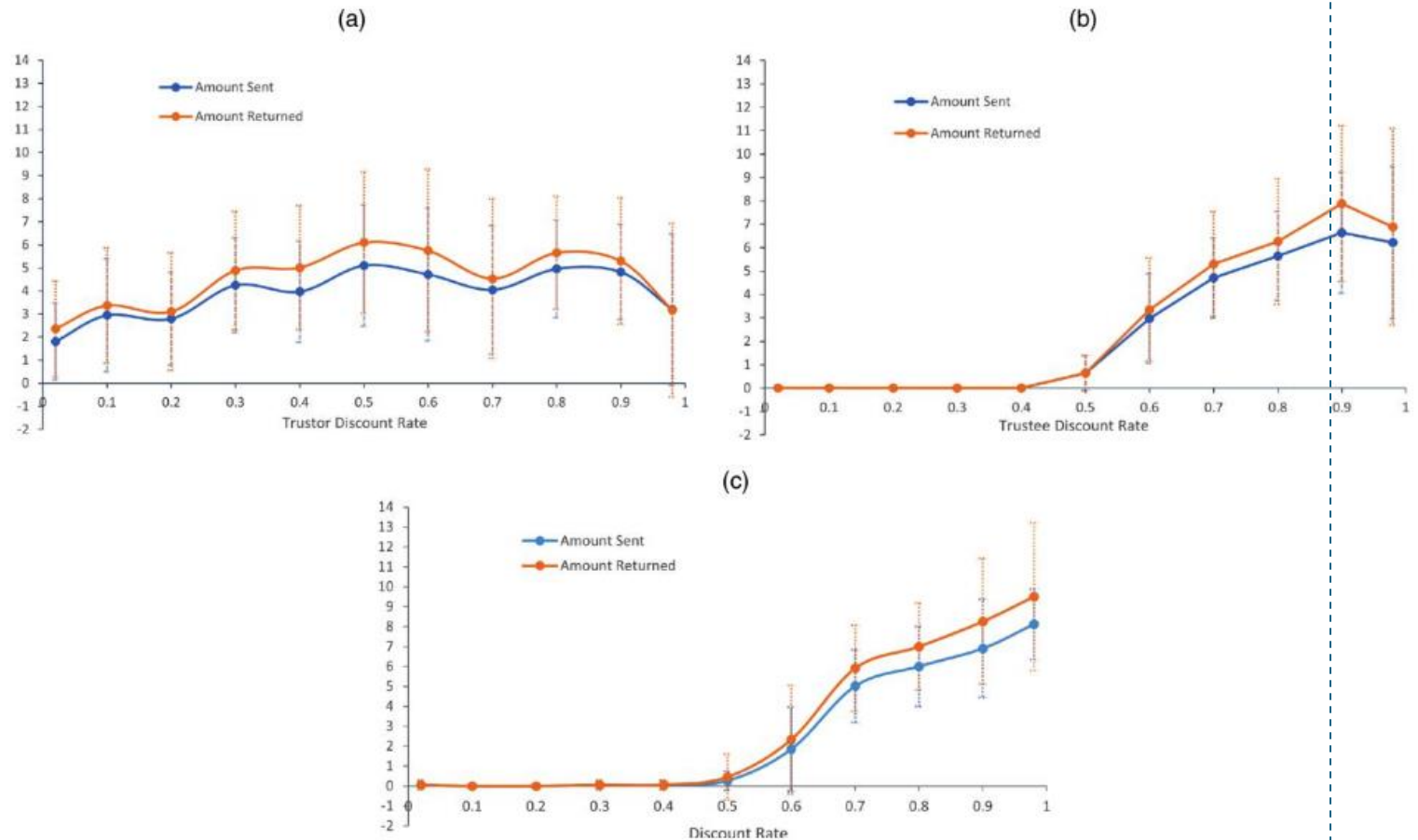
## Result 2

Under partner training, memory of past experience by the trustor AI is required for DQN agents to establish trusting and cooperative behaviors.

		Training stage	
Playing stage	Stranger playing	Memory	No memory
	Partner playing	Memory	No memory
	Stranger playing	Memory	No memory
Playing stage	Memory	Baseline: 5.45, 6.20 (2.54, 2.98) 3.78, 3.25 (2.10, 0.62)	0.00, 0.00 (0.00, 0.00) 0.00, 0.00 (0.00, 0.00)
	No memory	4.23, 4.05 (1.78, 2.00) 4.23, 3.40 (1.77, 0.72)	0.00, 0.00 (0.00, 0.00) 0.00, 0.00 (0.00, 0.00)

## Result 3

- The discount rate plays a dominant role in the emergence of cooperative behaviors
- Higher incentives for future rewards, controlled by the discount rate, generally increase their levels of trust and trustworthiness





# Future Works

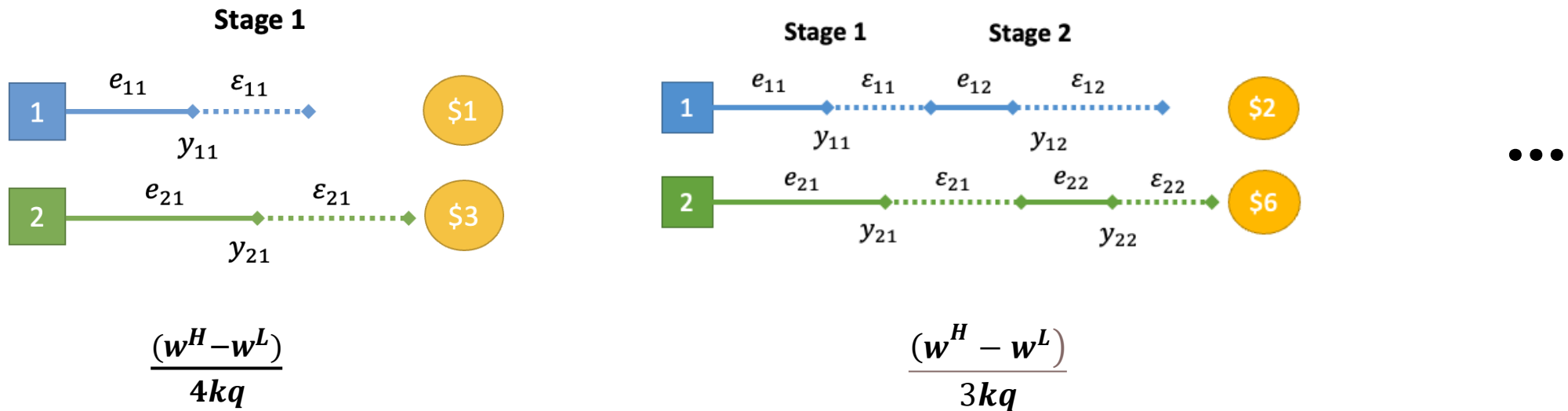
- Cooperation with two-sided incentives
- More than two players
- Asymmetric information
- Behavioral uncertainties



# Research in-progress

Exploring Equilibrium for Multi-period Sales Tournament

- Output:  $y_{it} = e_{it} + \varepsilon_{it}$ ,  $\varepsilon_{it}$  iid, uniformly distributed on the interval  $[-q, q]$
- Cost function:  $c(e_{it}) = ke_{it}^2$
- 2 contestant, and each contestant can view her own output and that of her competitor after each round





# Objectives

- Learning to find the equilibrium: one period and two periods
  - Without data
  - With limited data
- Multi-period sales tournament
  - Exploring the effort equilibrium for more than three periods
  - Insights for incentive strategies



Thank you!

