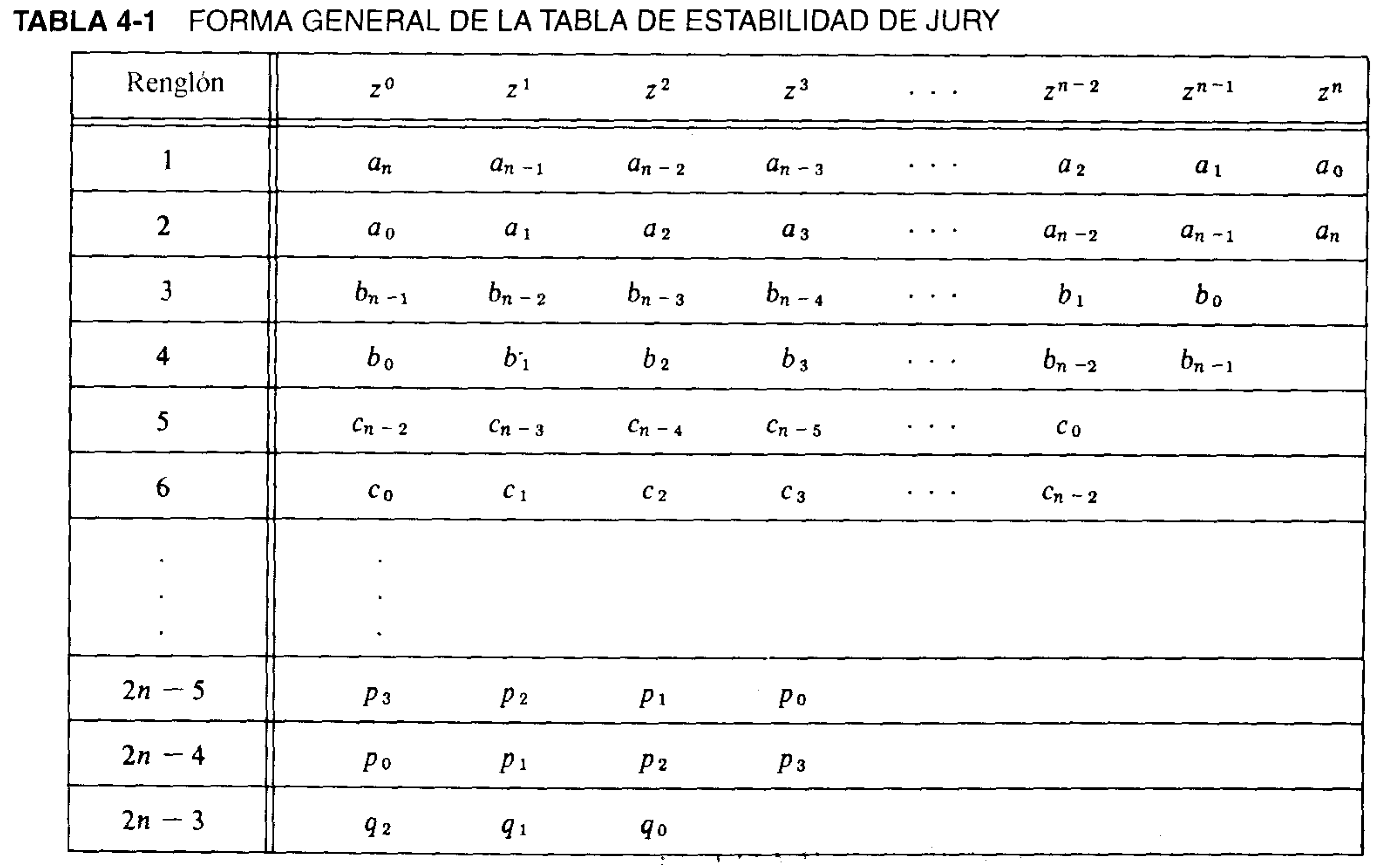
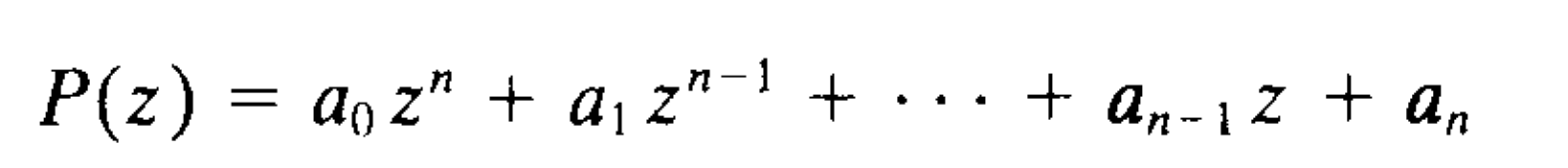
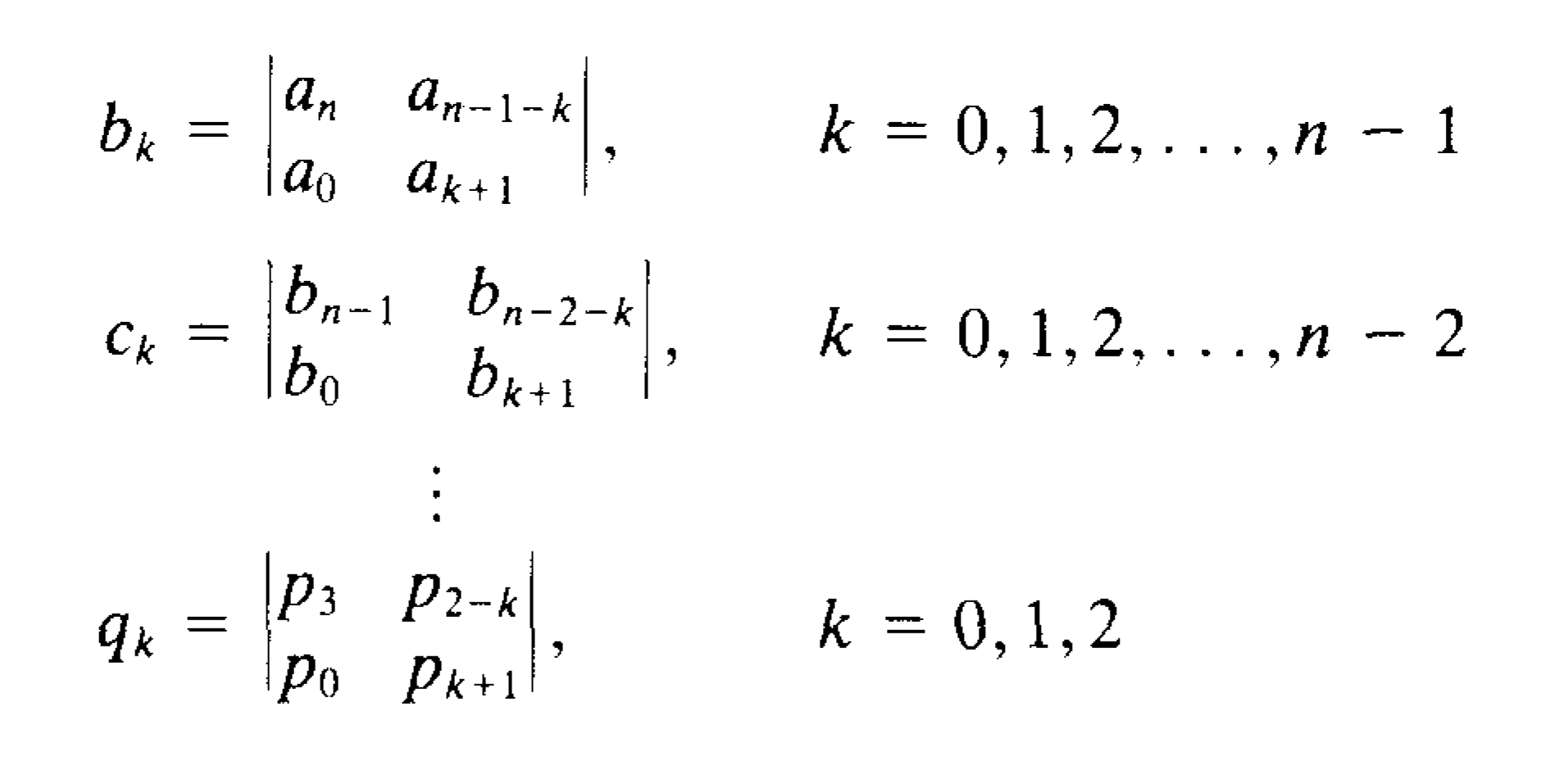
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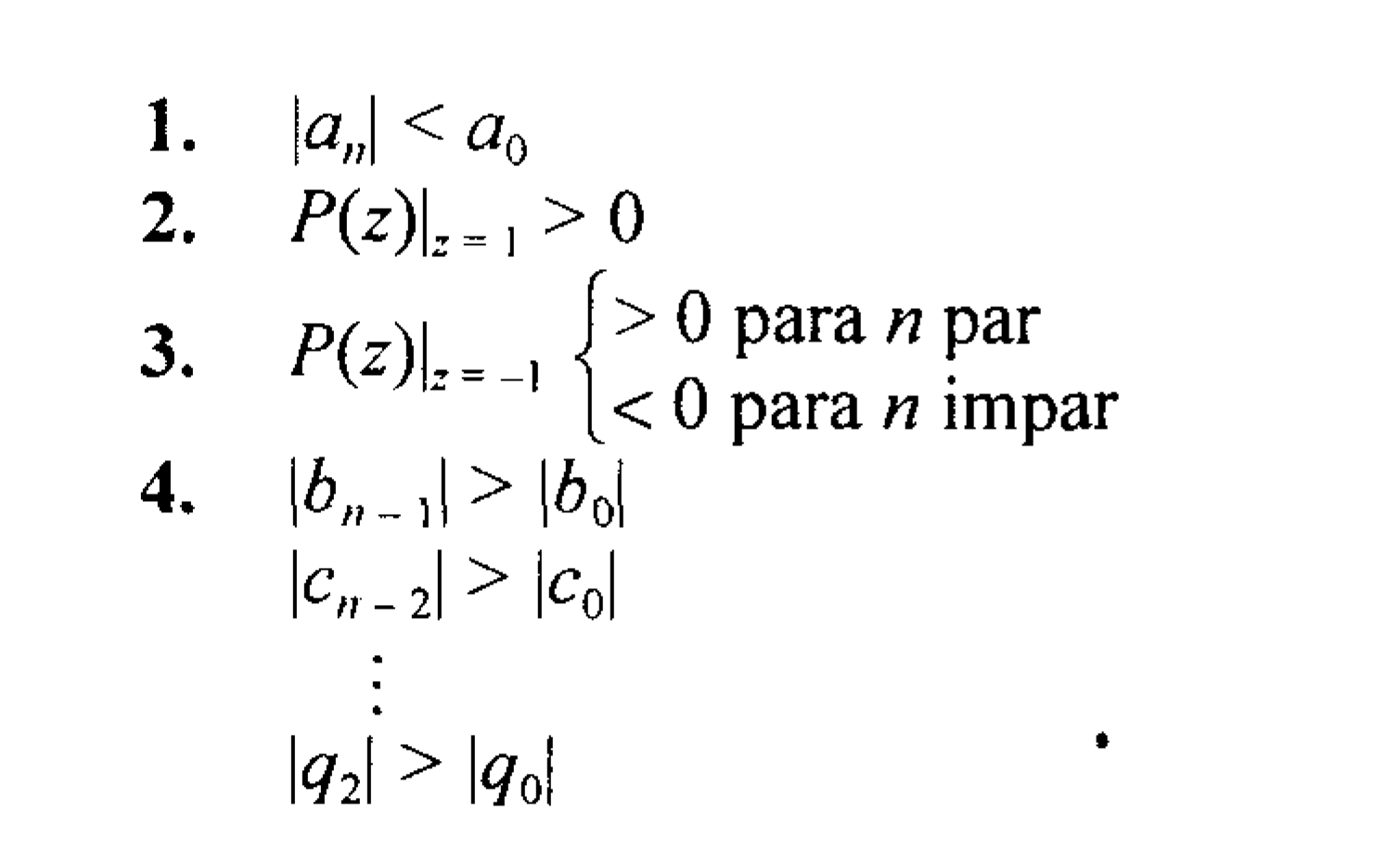




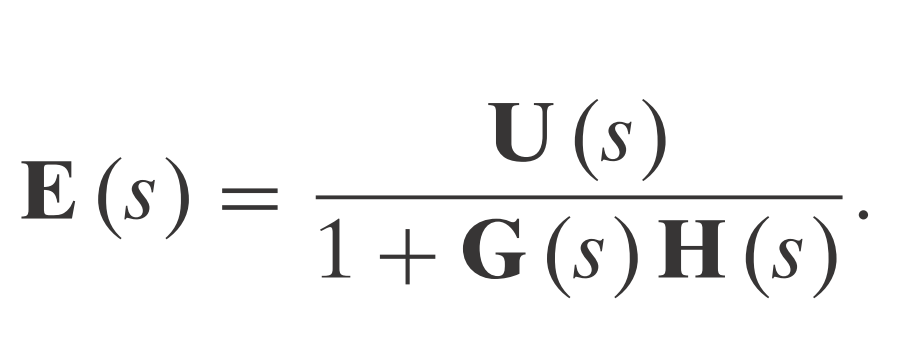
Jury





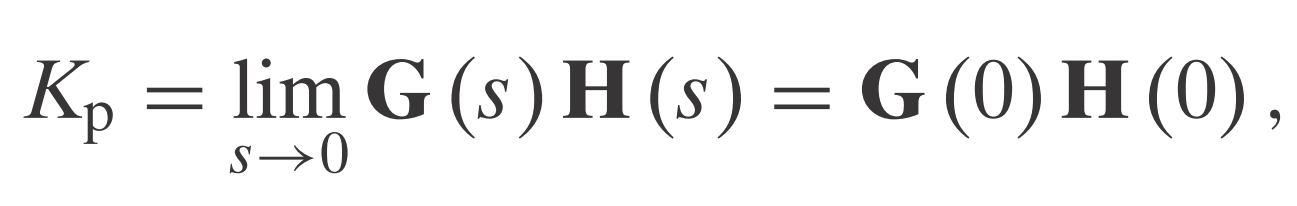
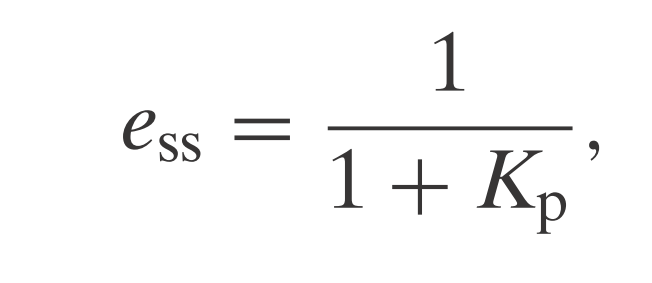


Error de estado

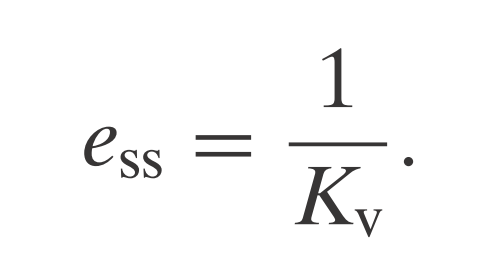
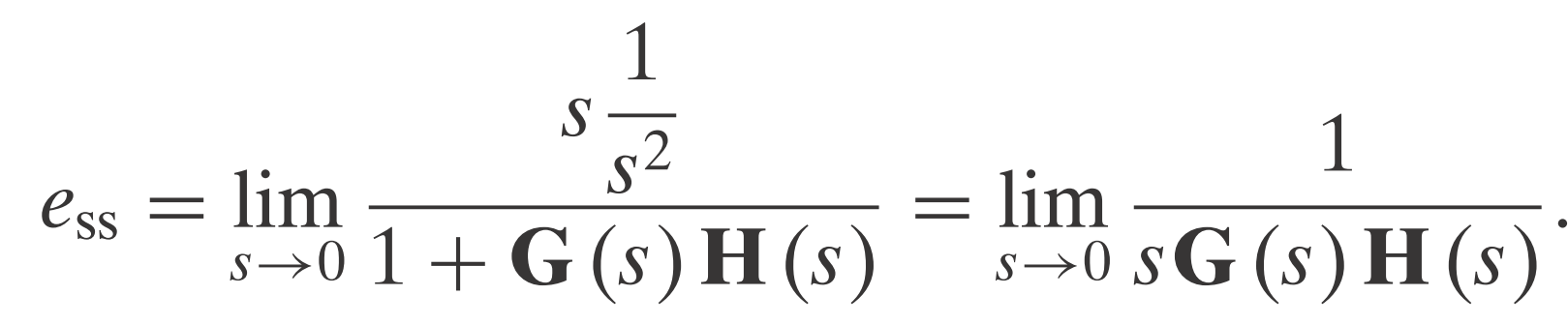
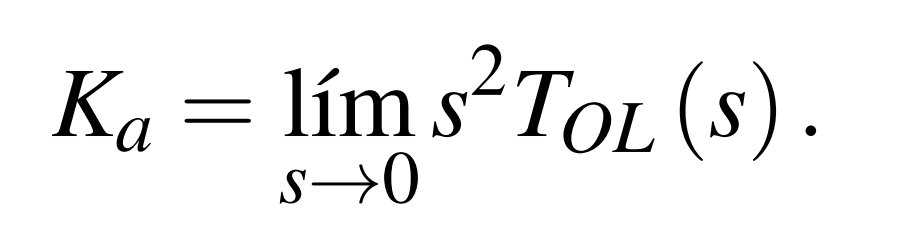


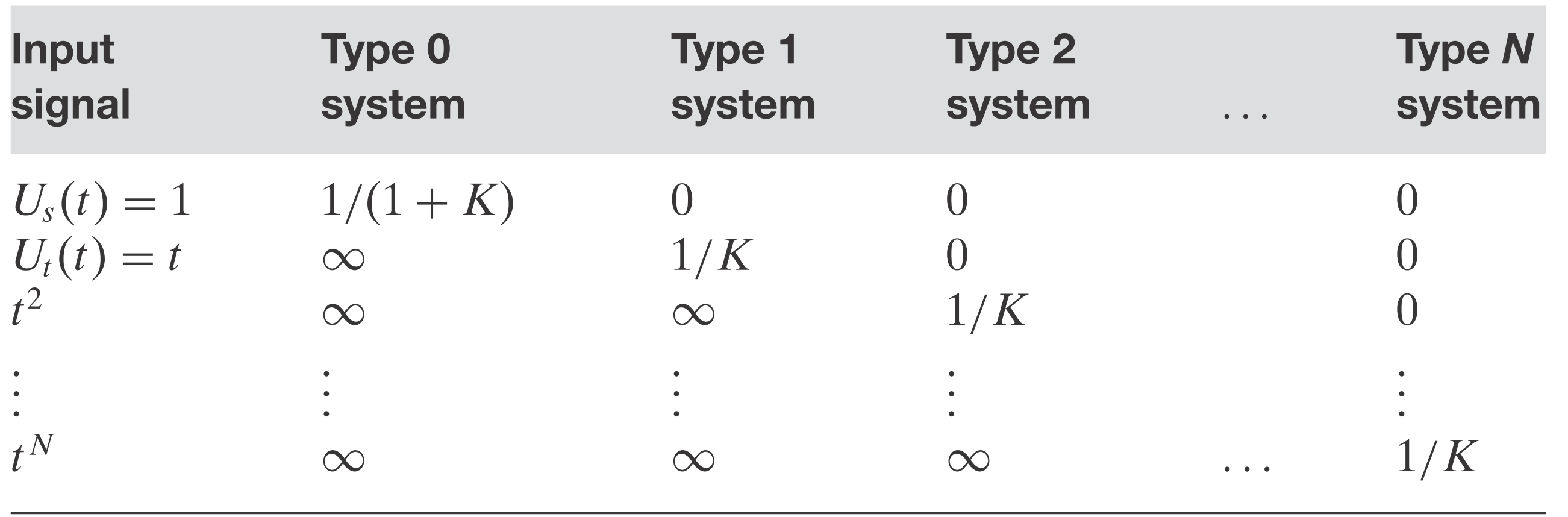
Ess = 

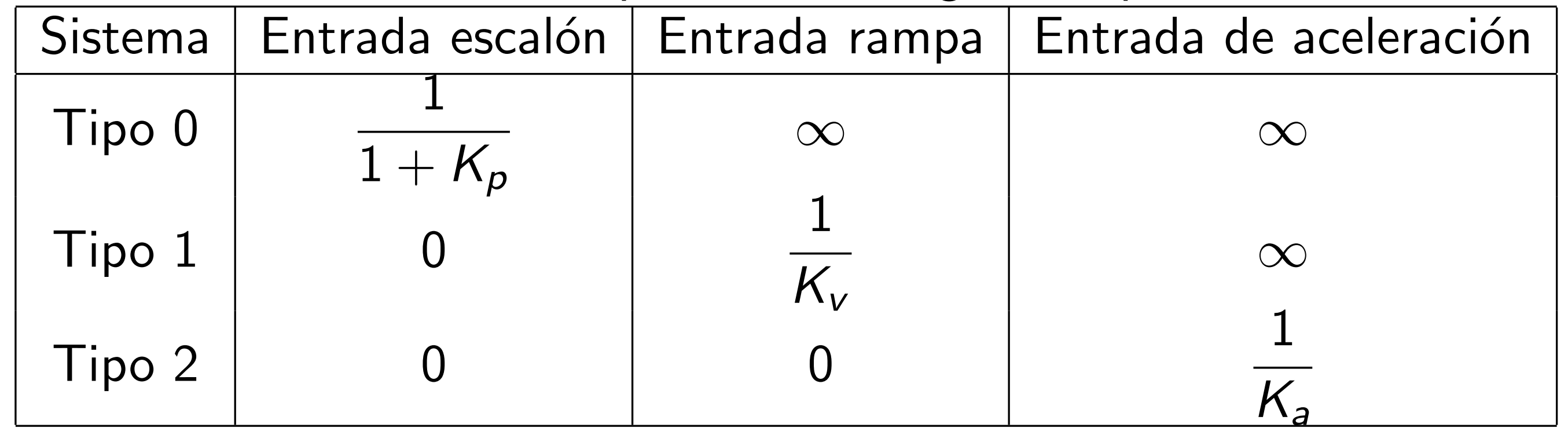
Step response

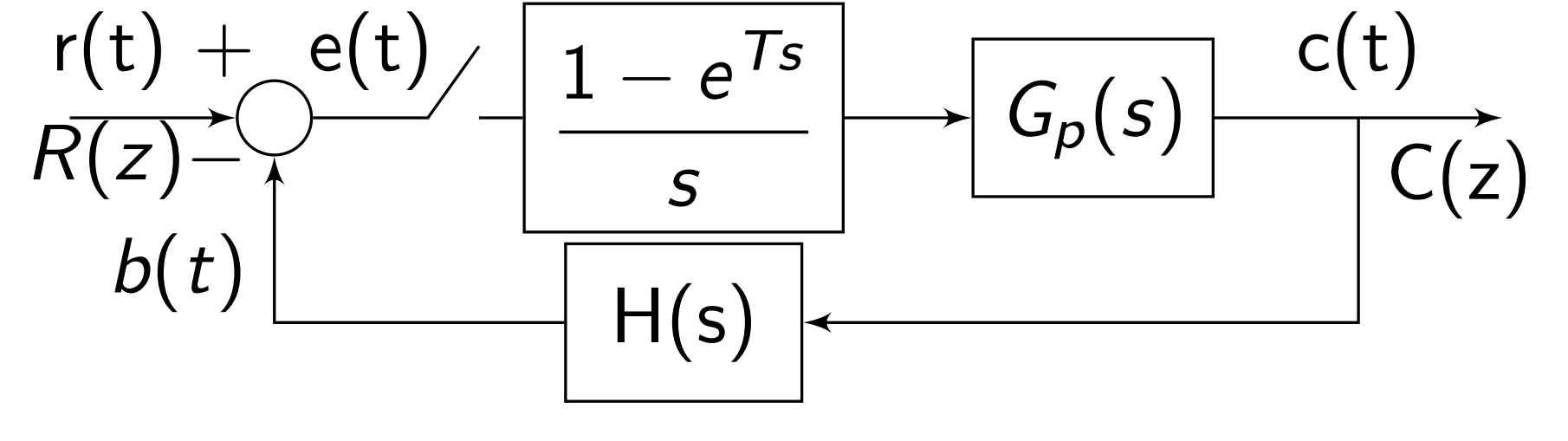


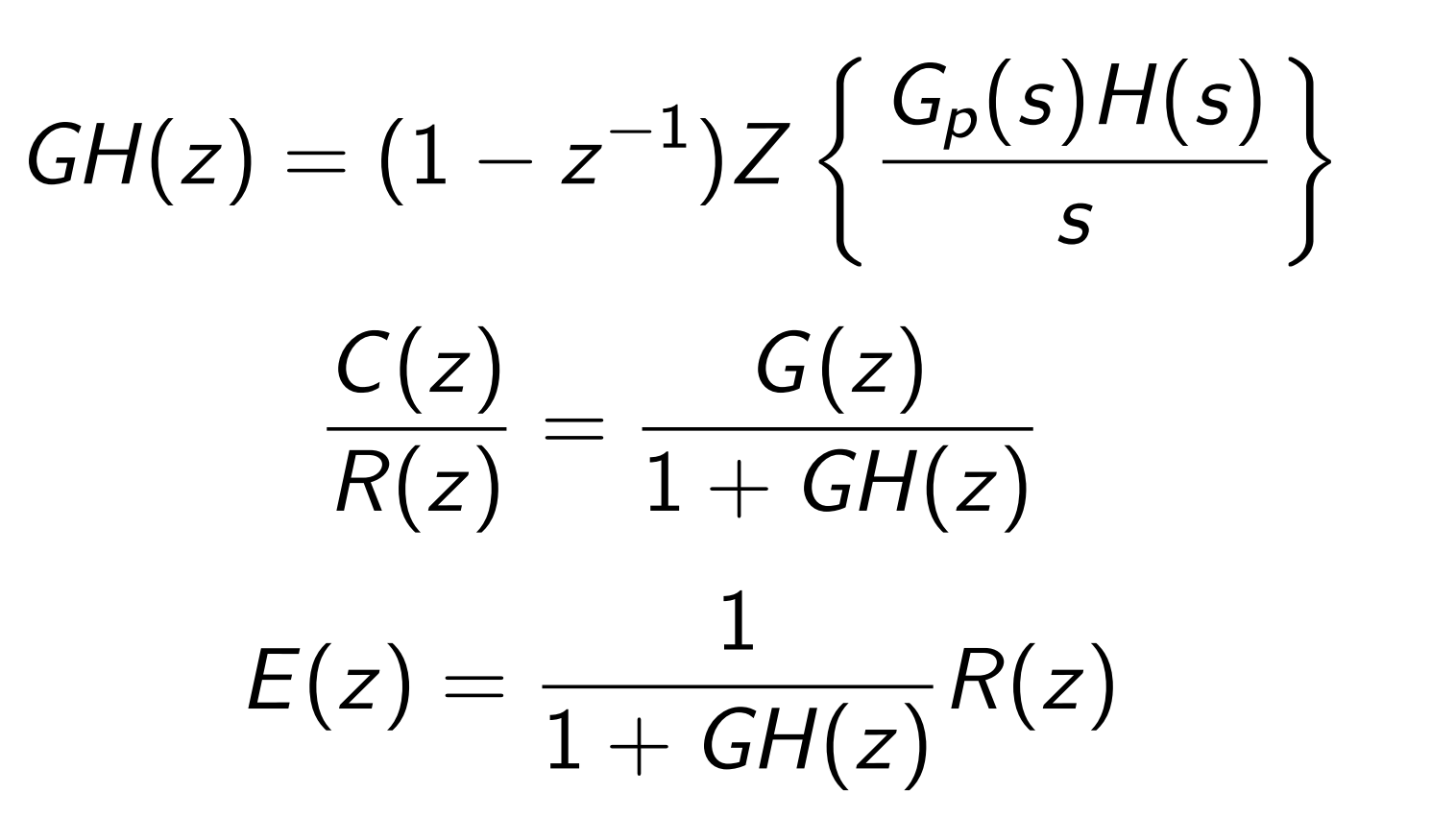
Unit ramp

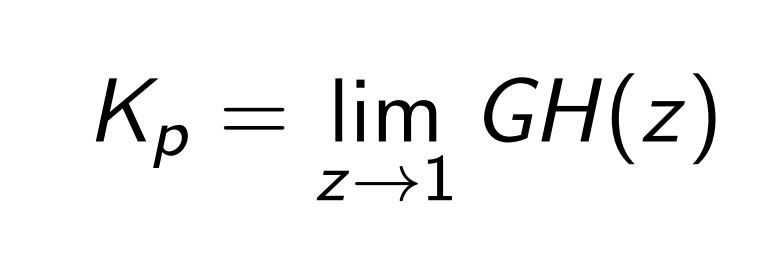
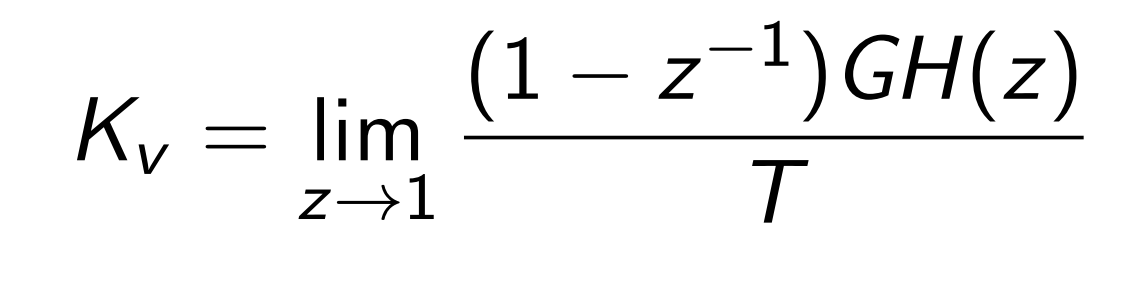
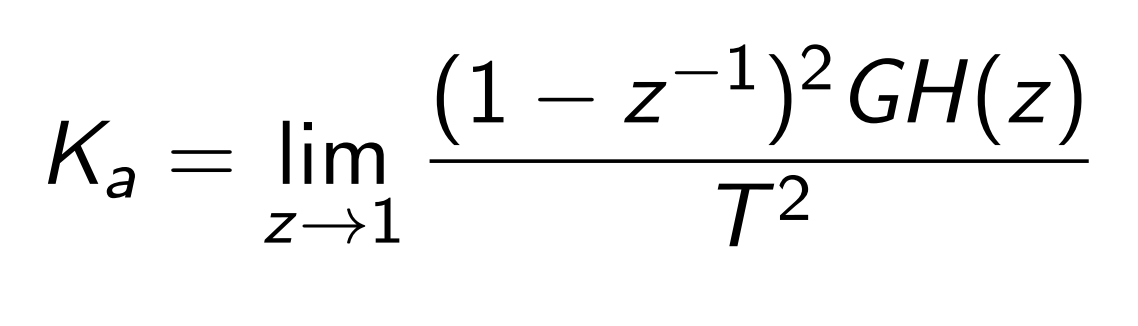
 

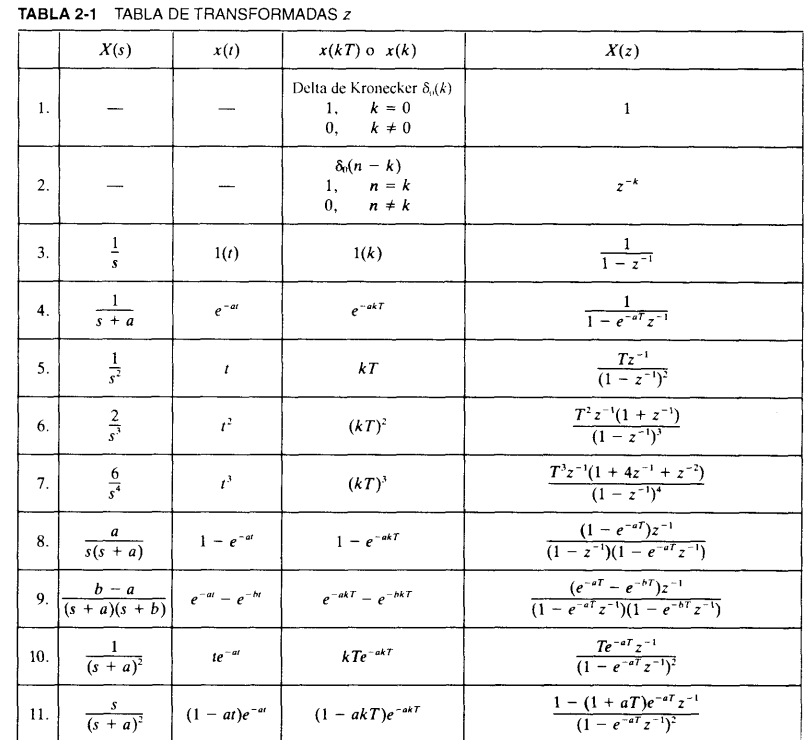


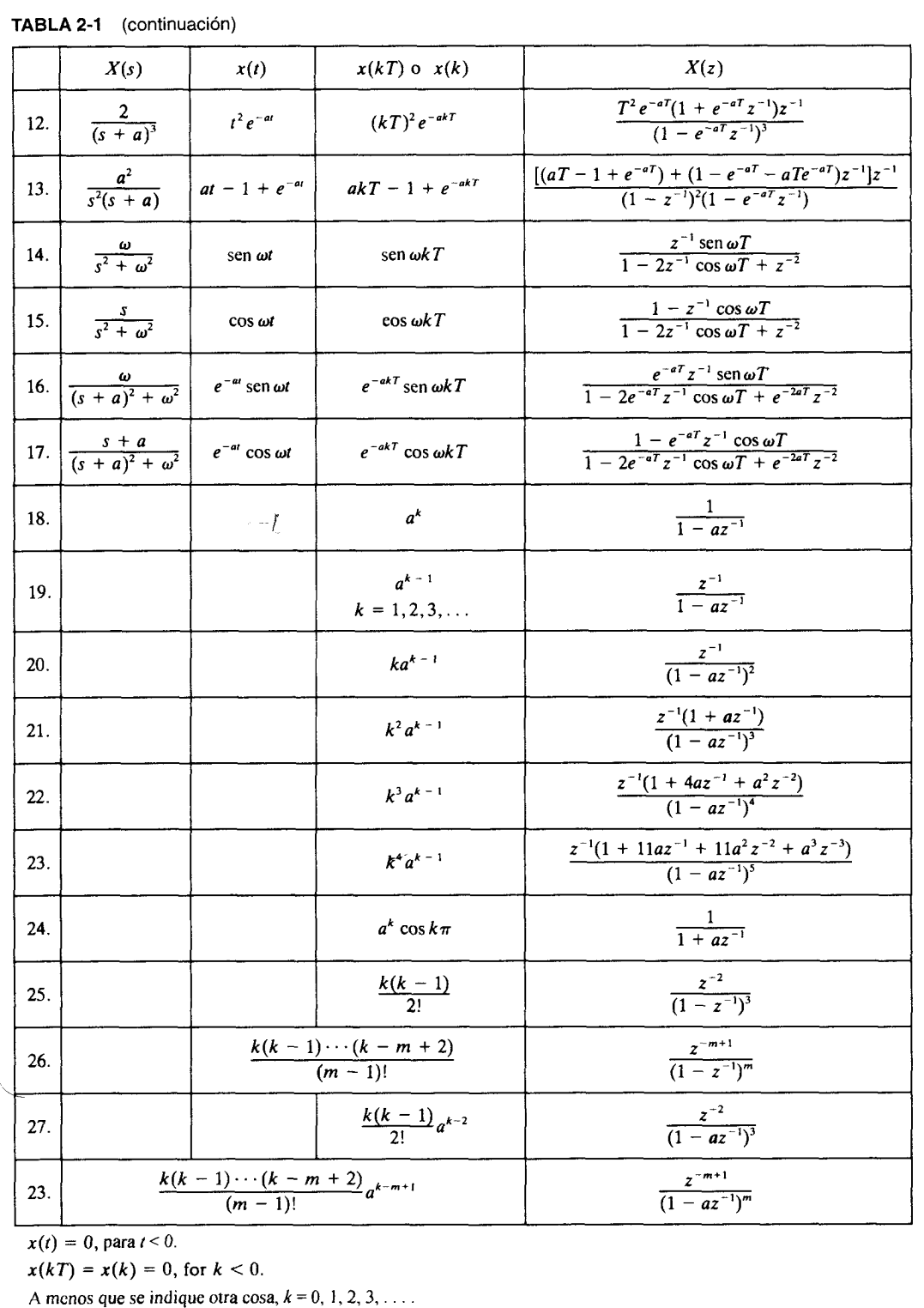


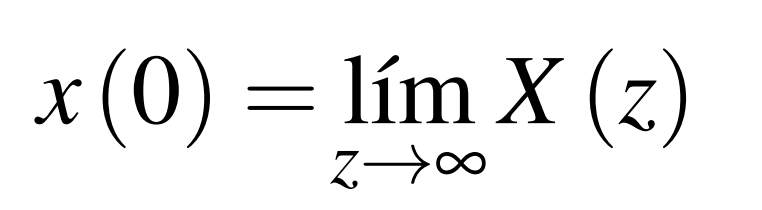
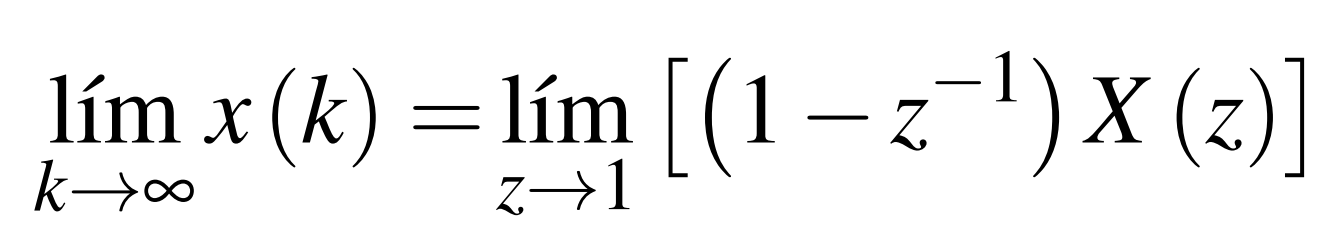






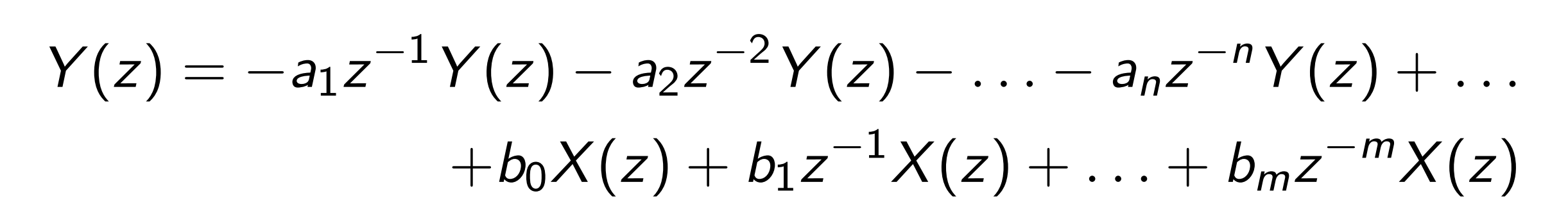


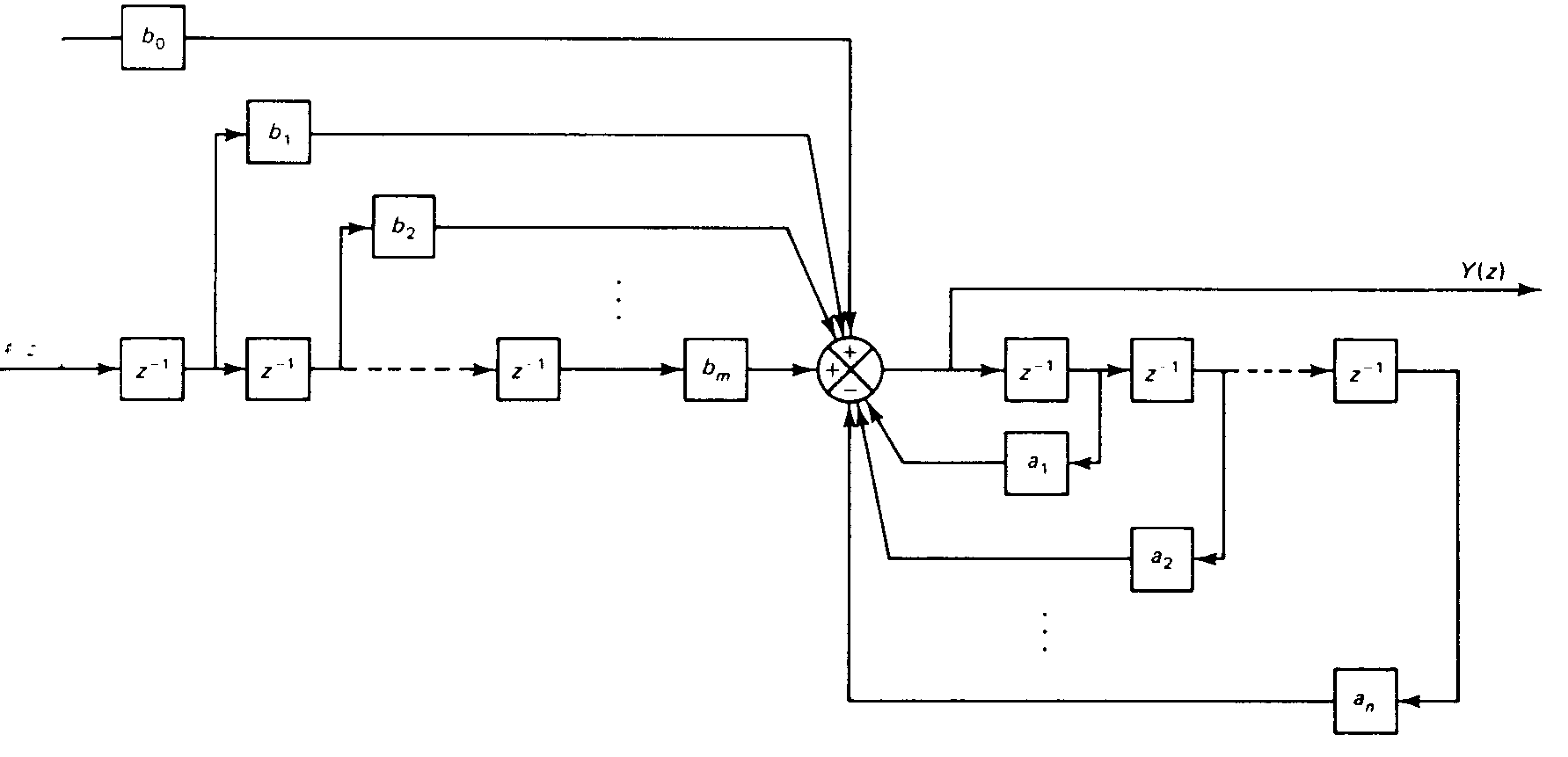
Valor Inicial: , Final: 

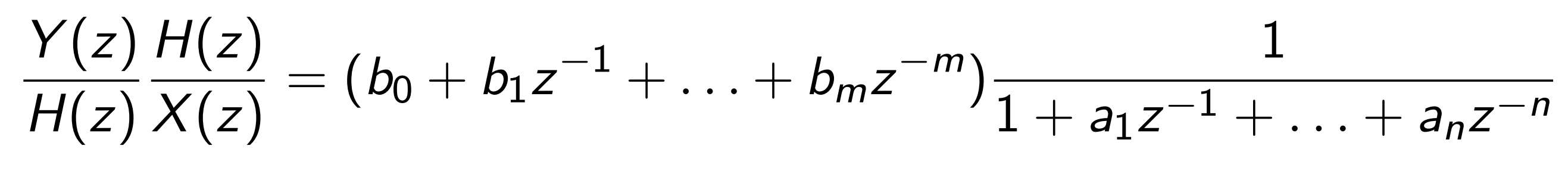
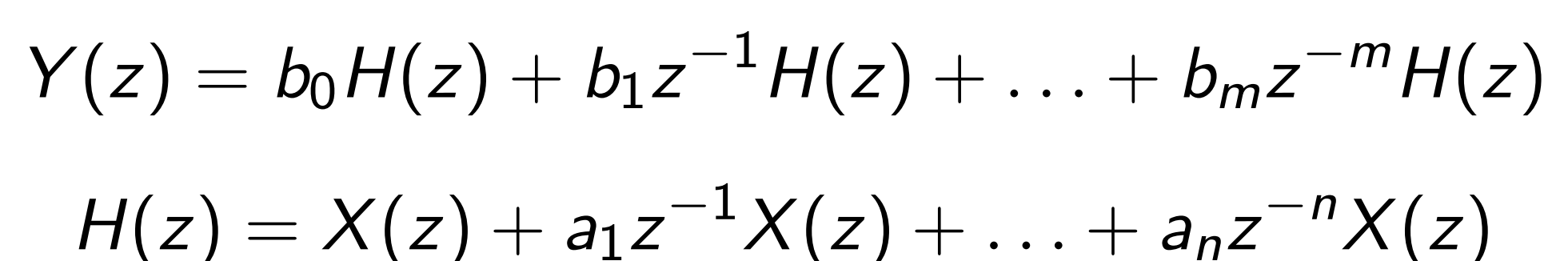


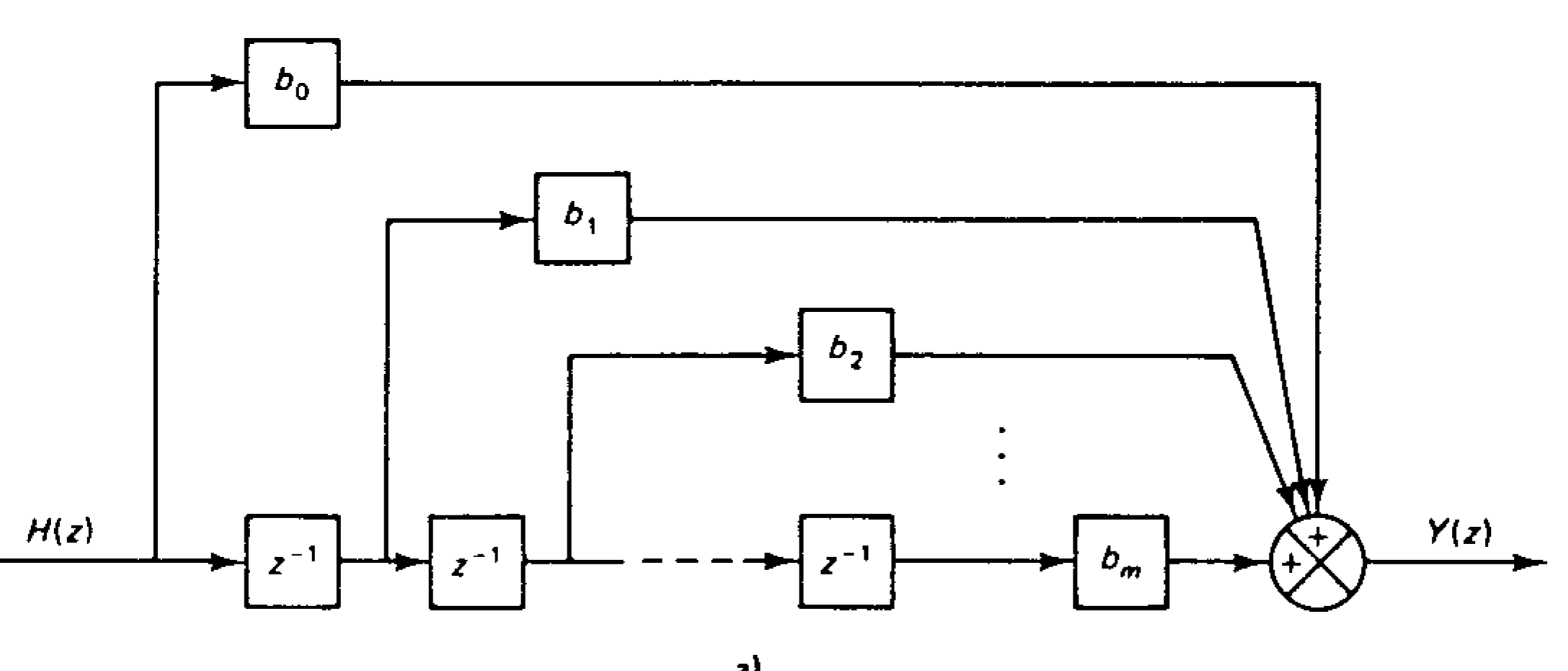


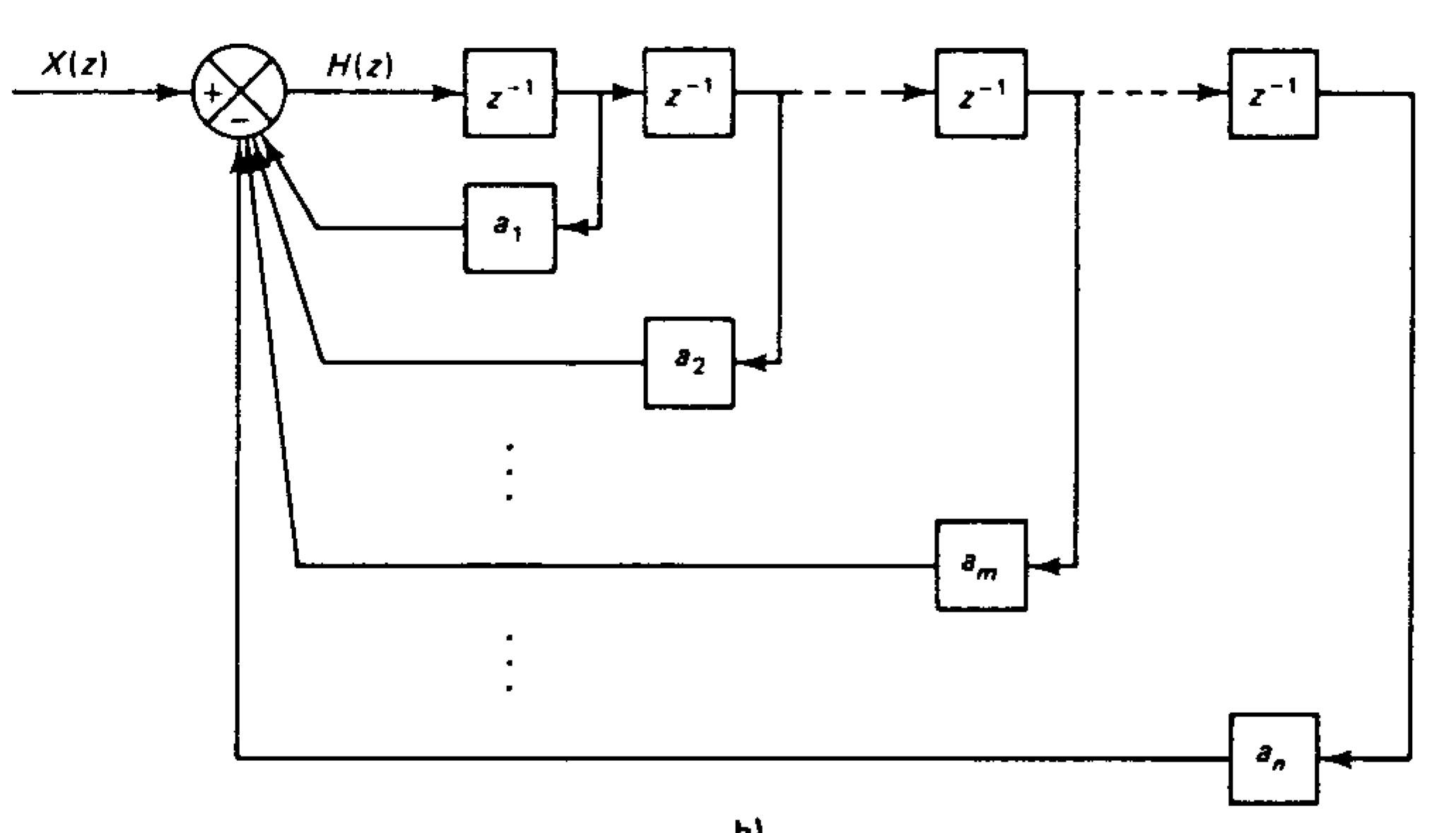


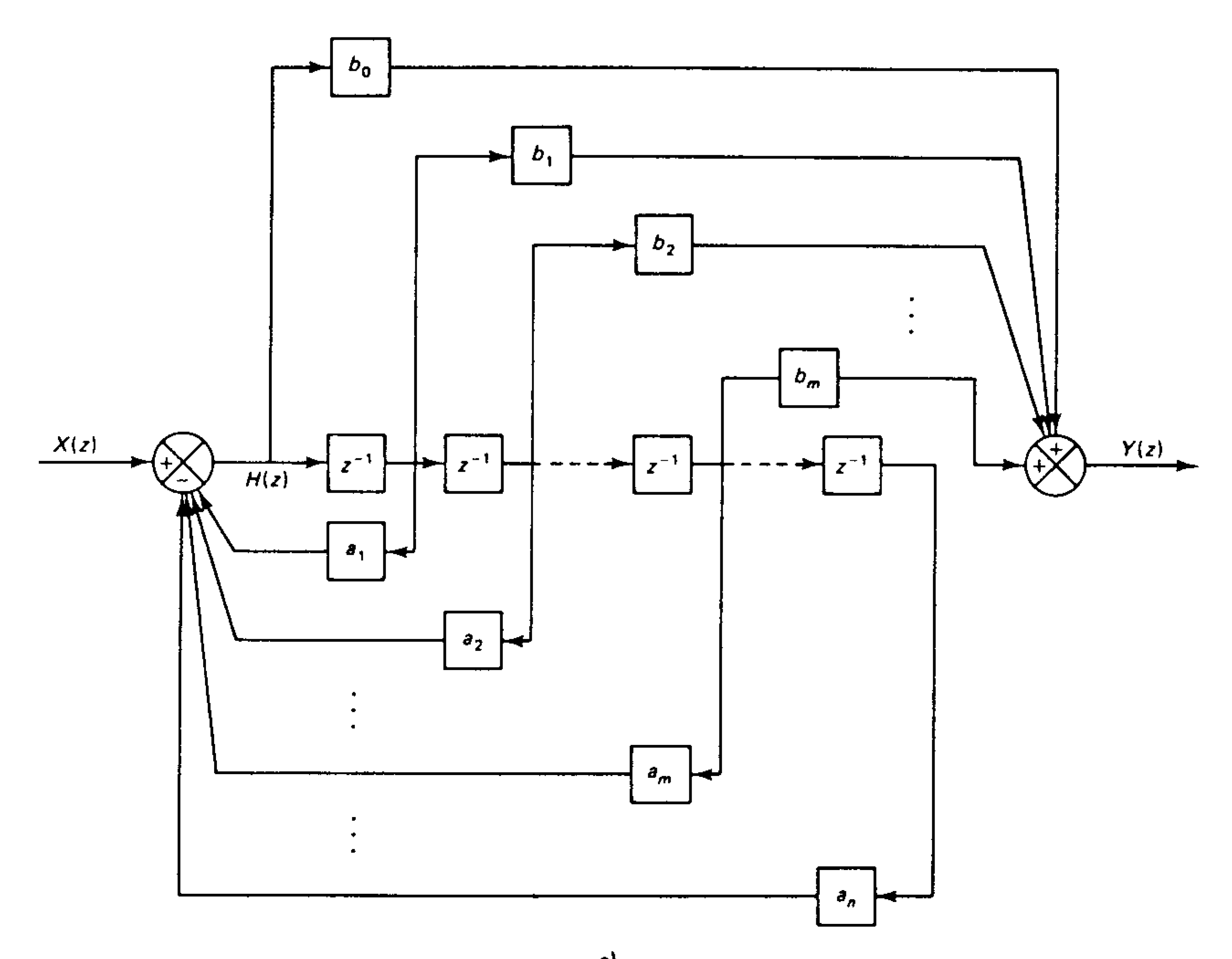




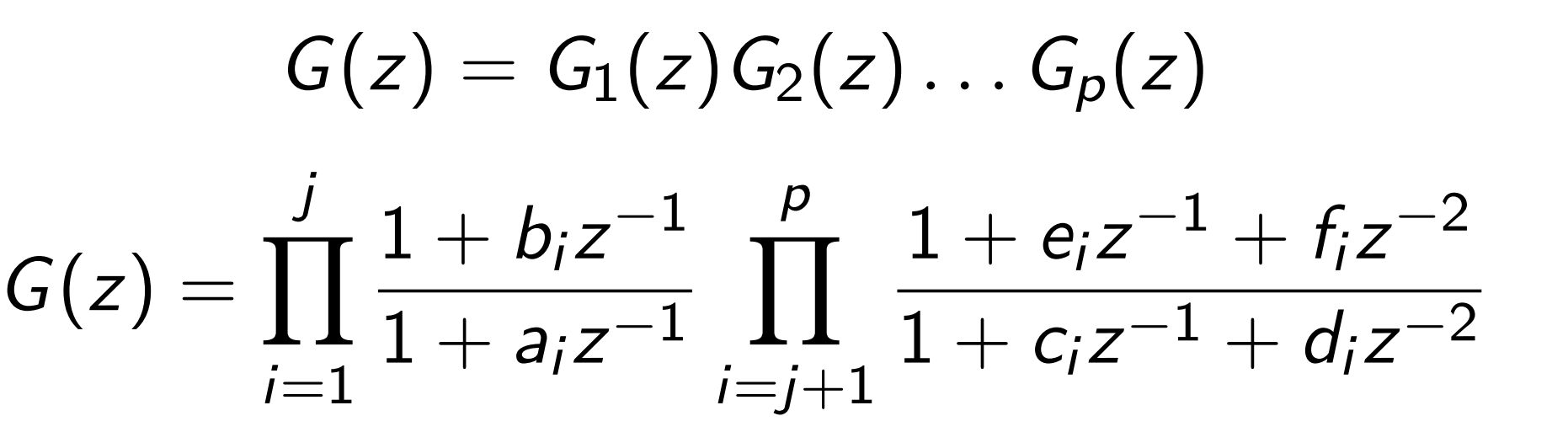
 

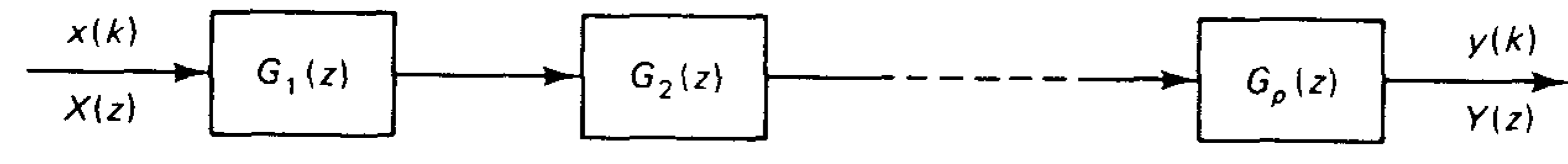


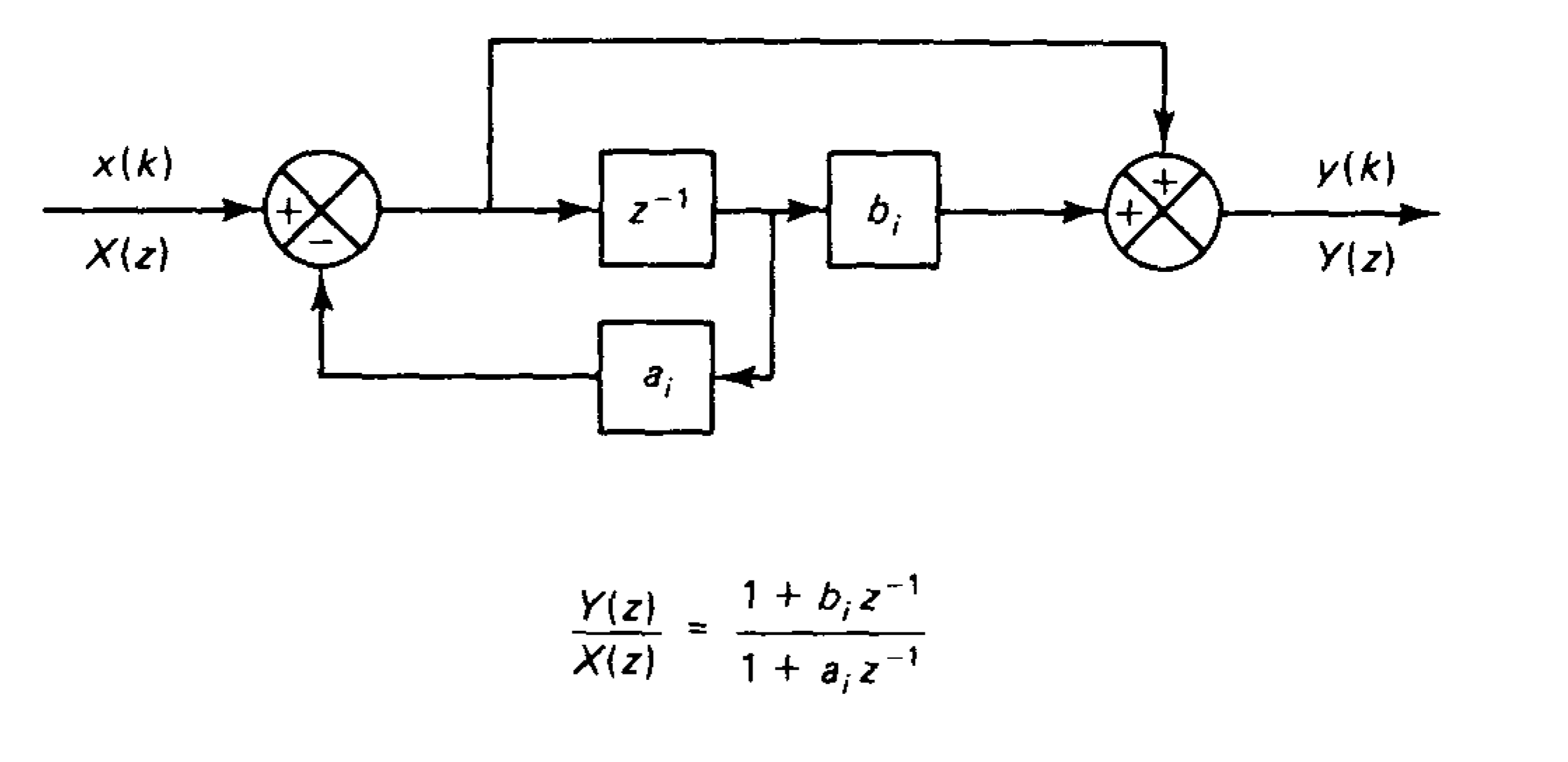
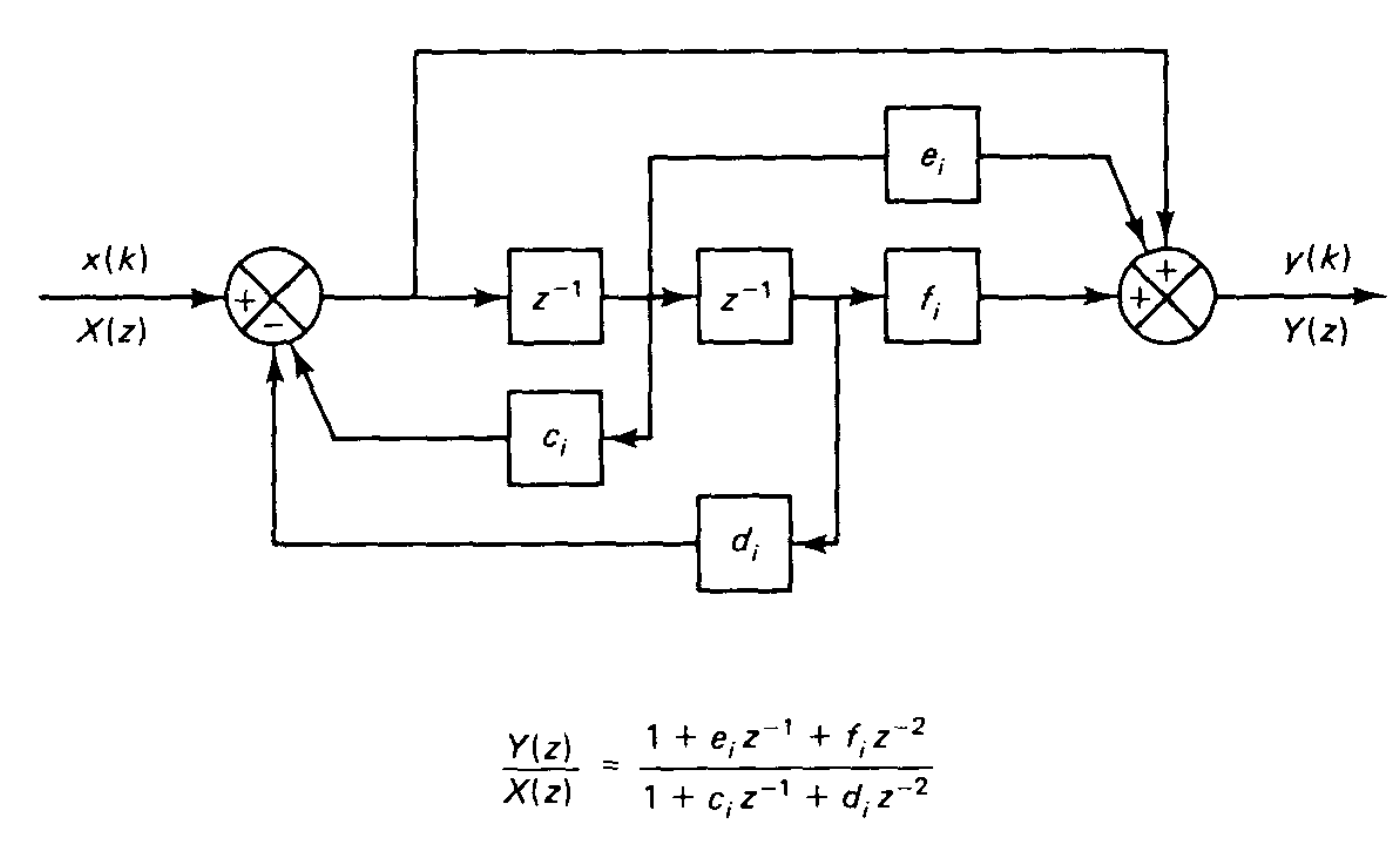
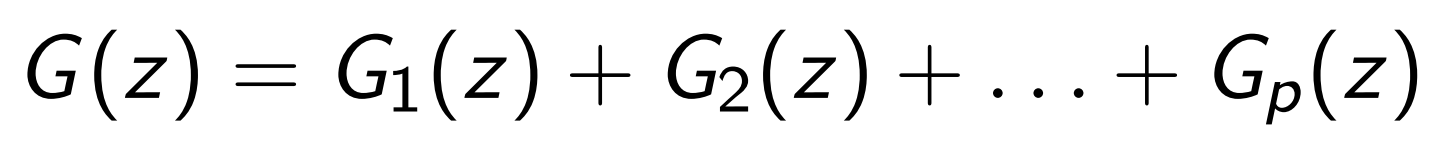
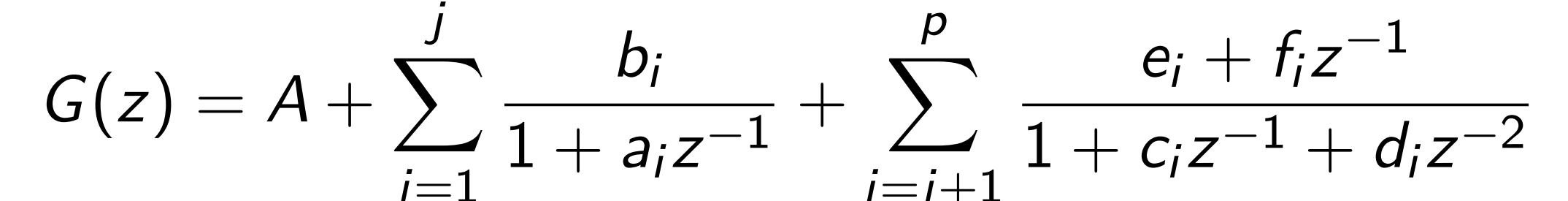


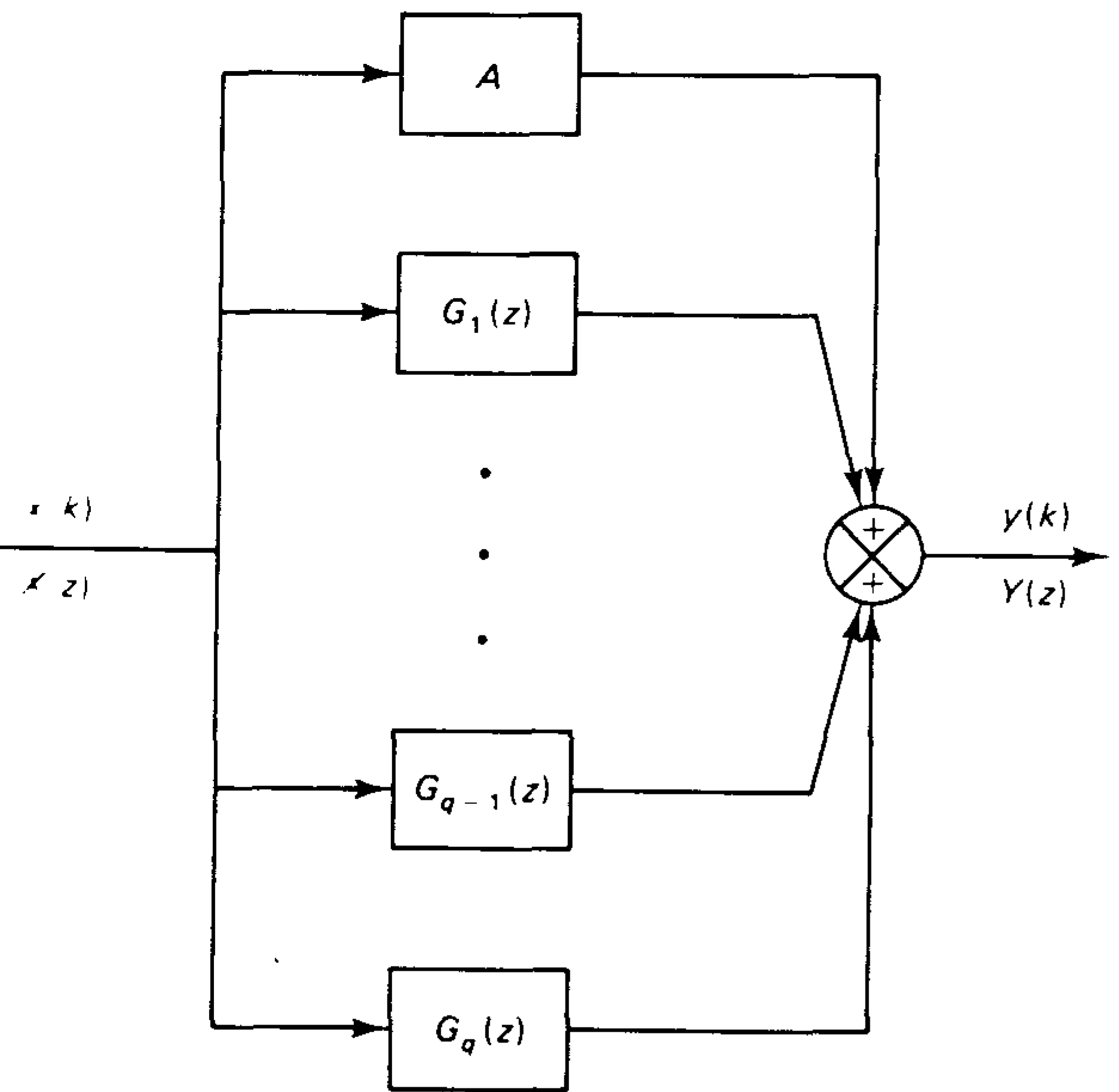


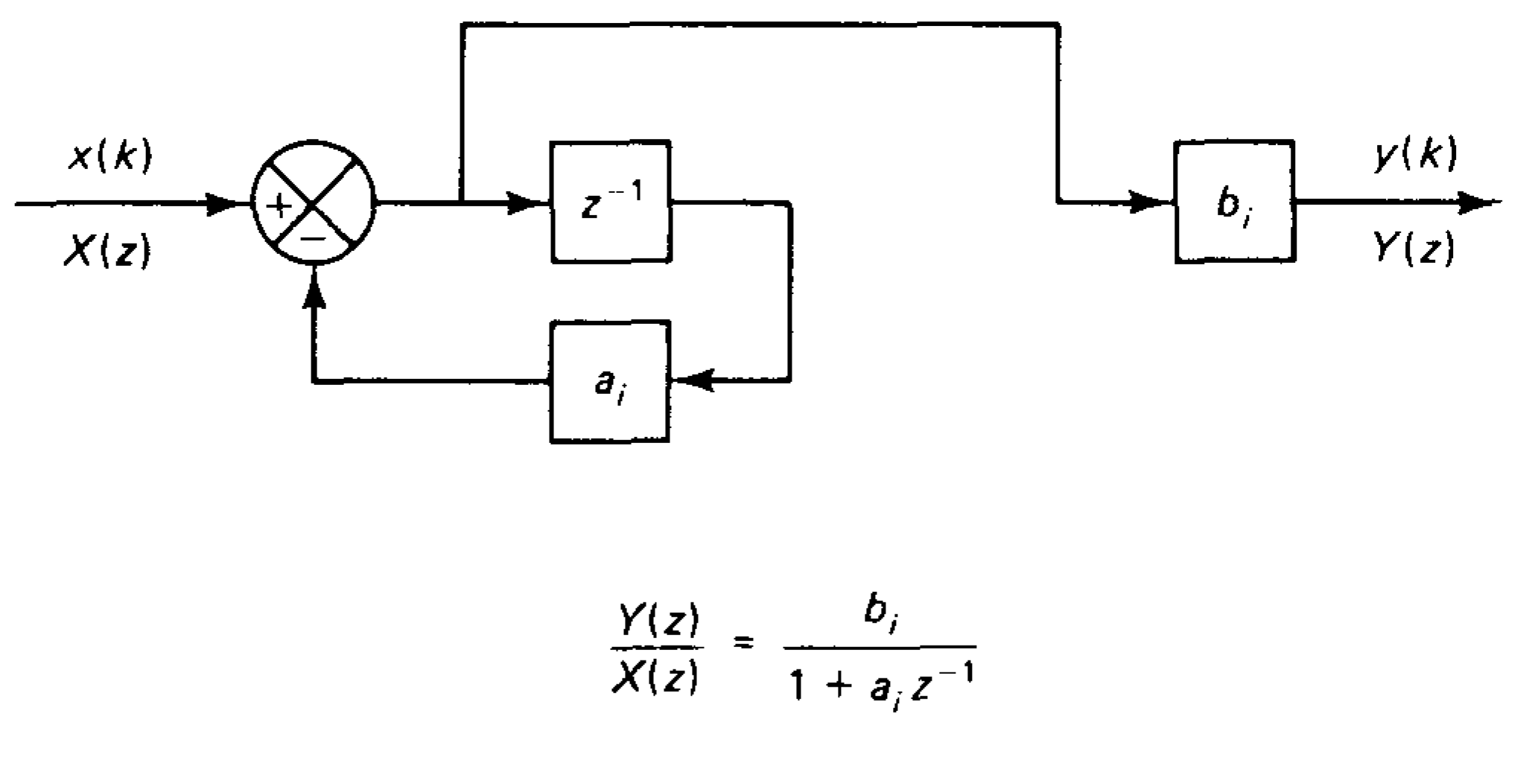
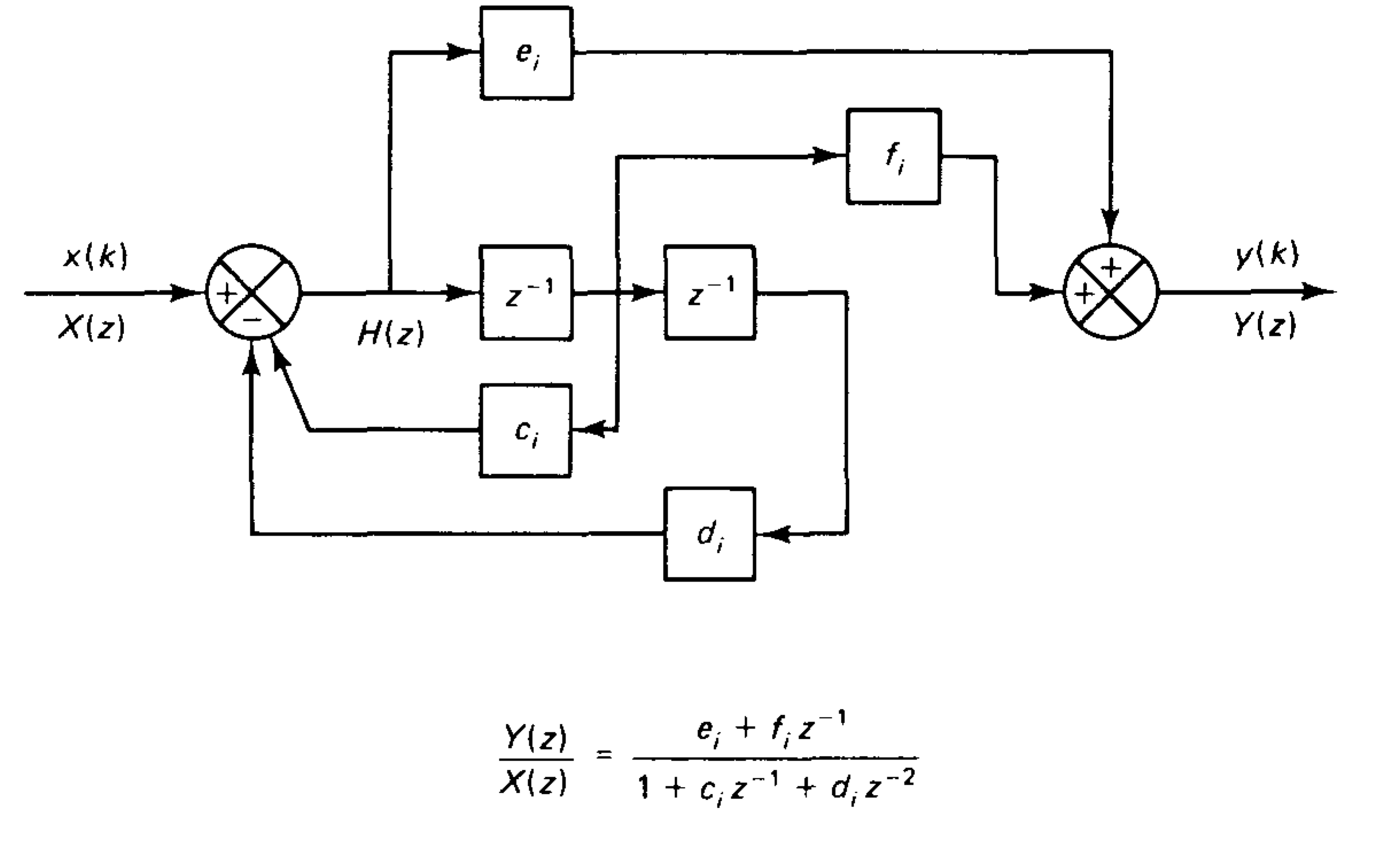
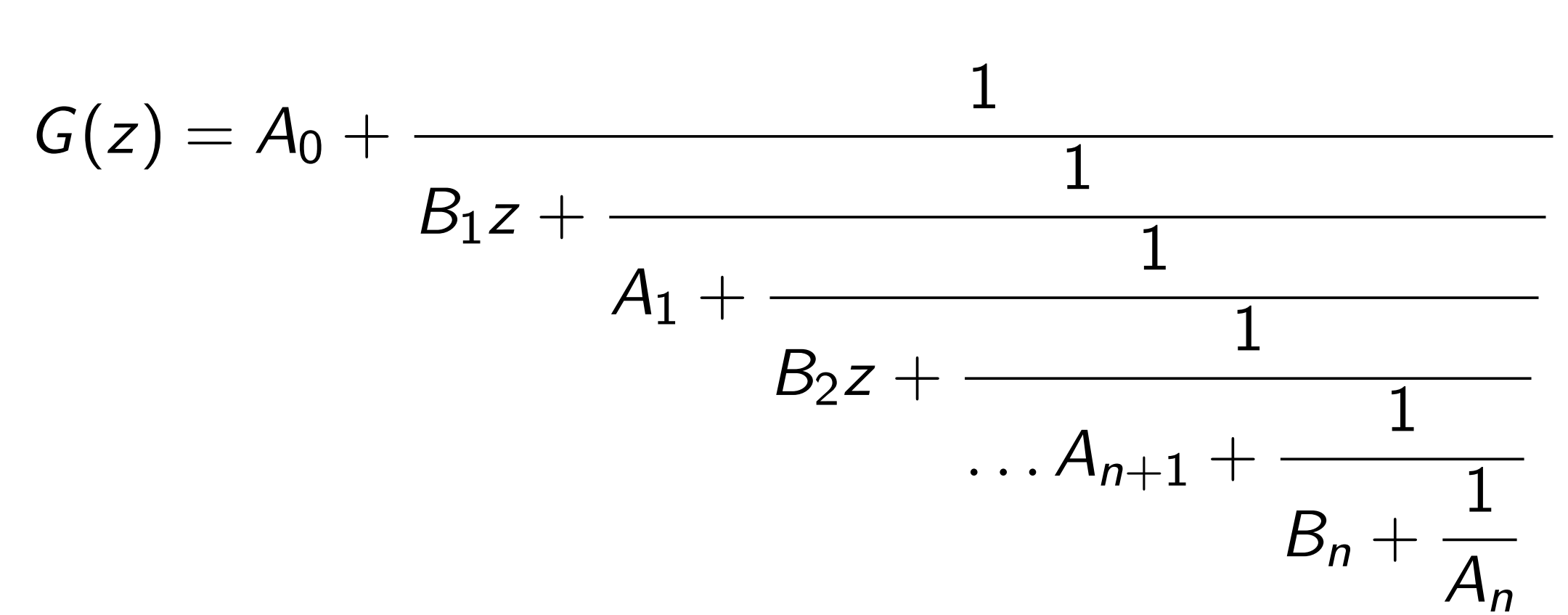
Baja sensibilidad de los coeficientes>

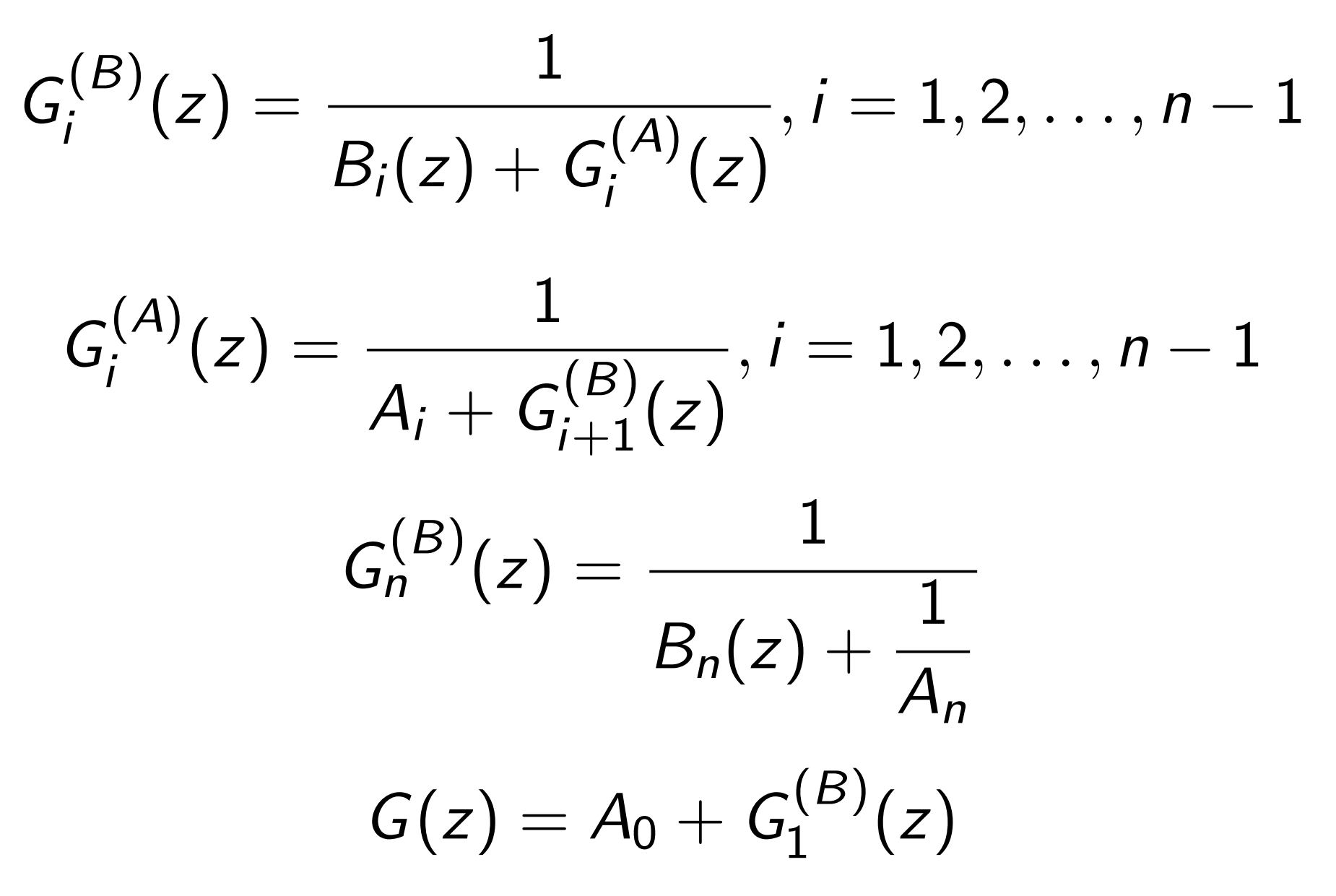
 

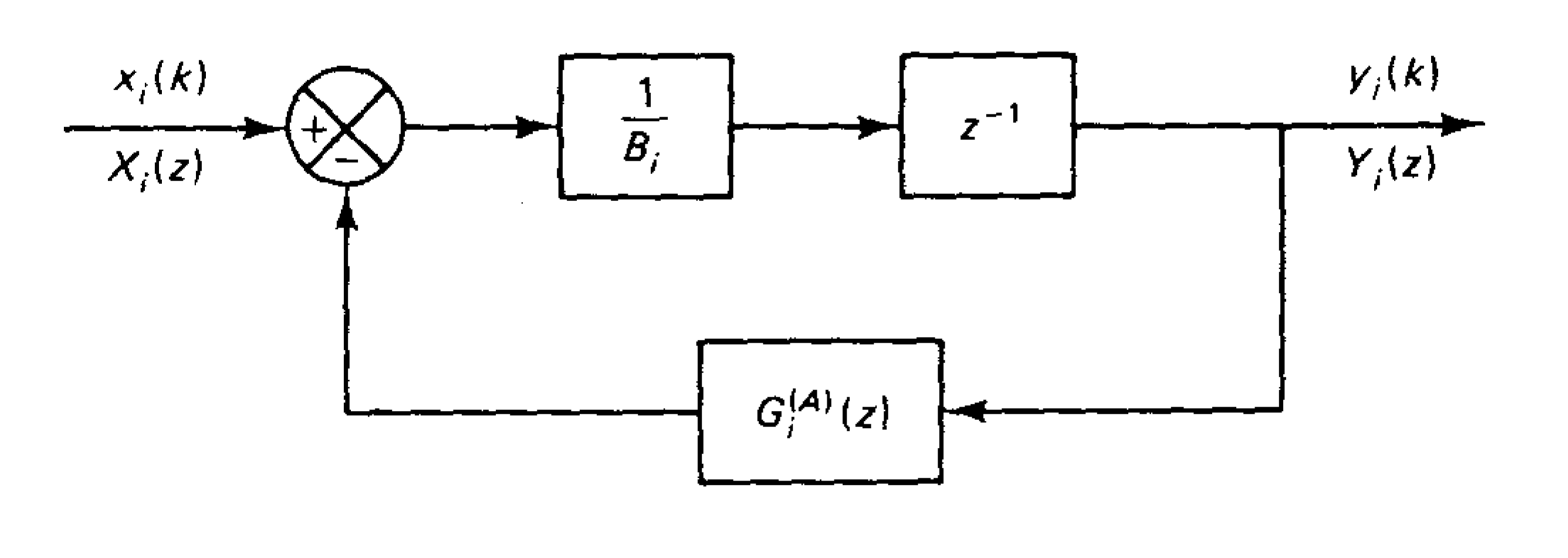


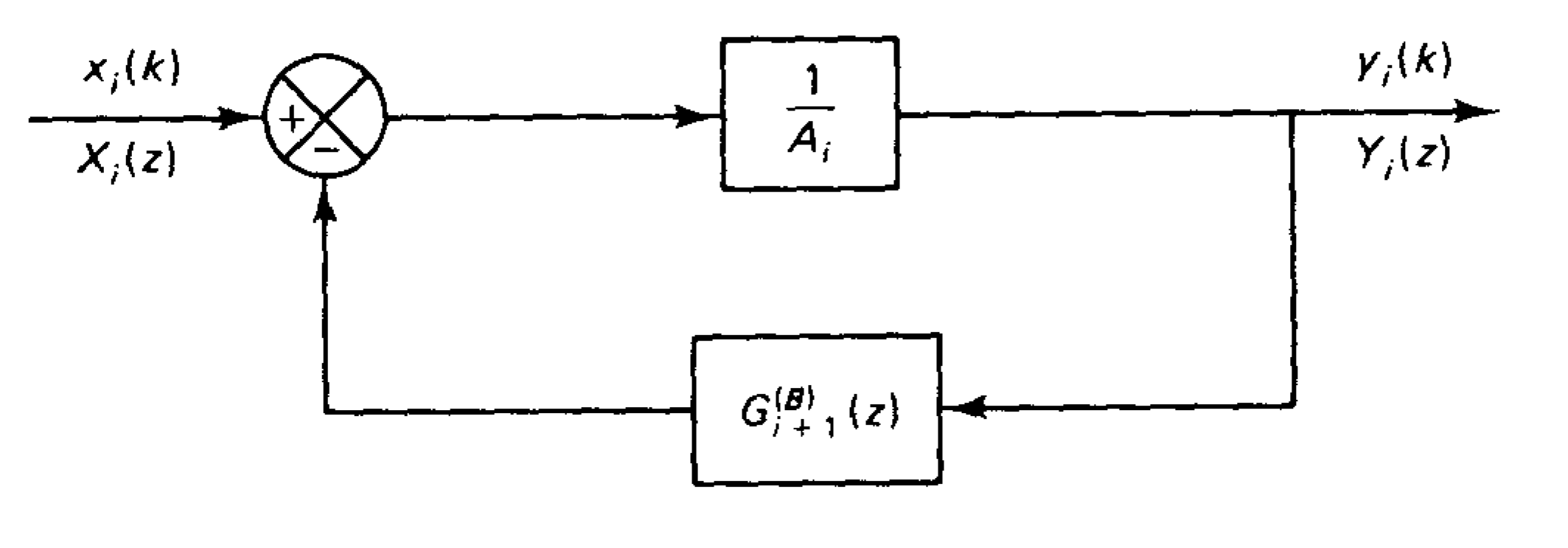
  









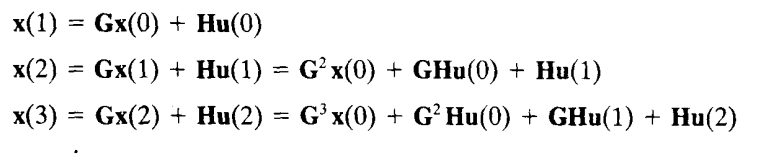
Matriz de Observabilidad



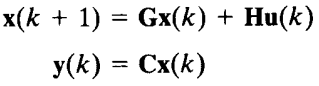
Matriz de Controlabilidad

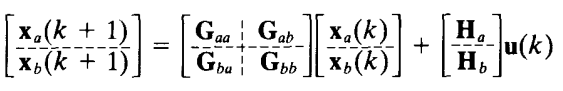
Rango=n, inversa existe

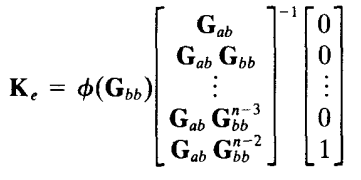
Formulita rara



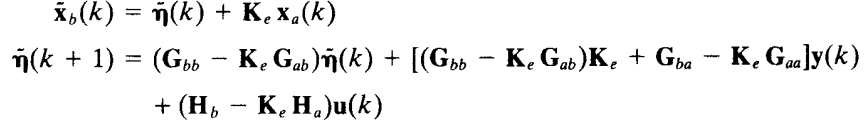
Observabilidad mínima



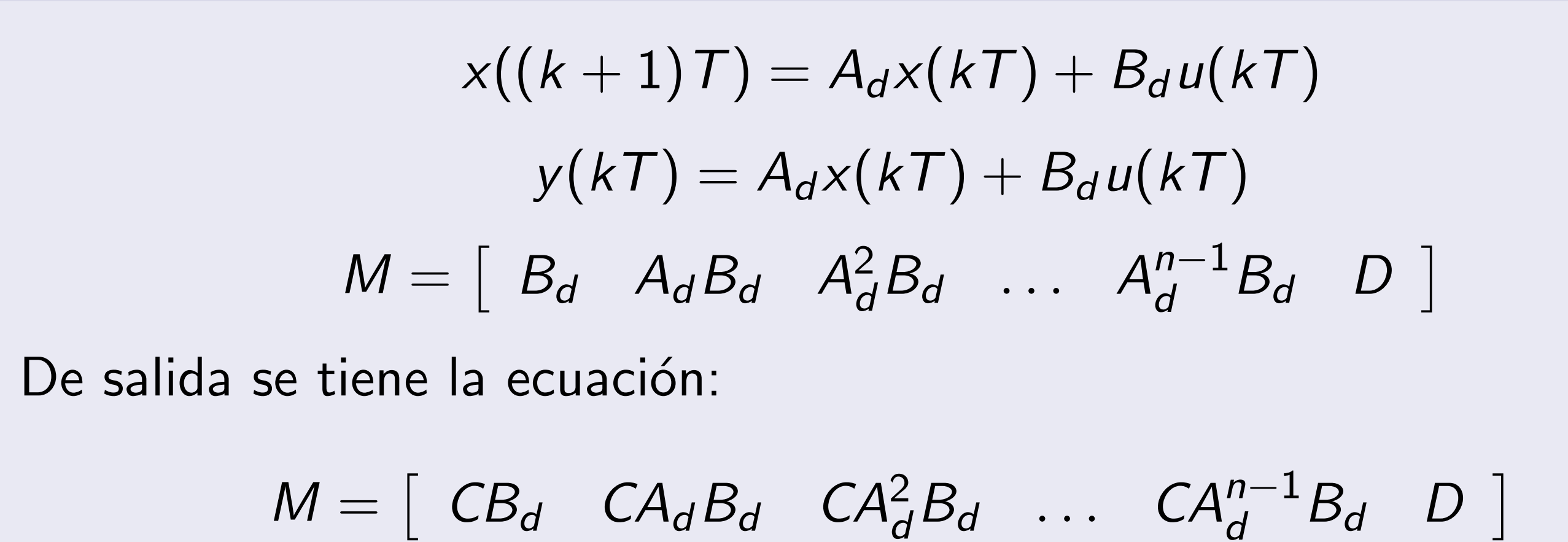




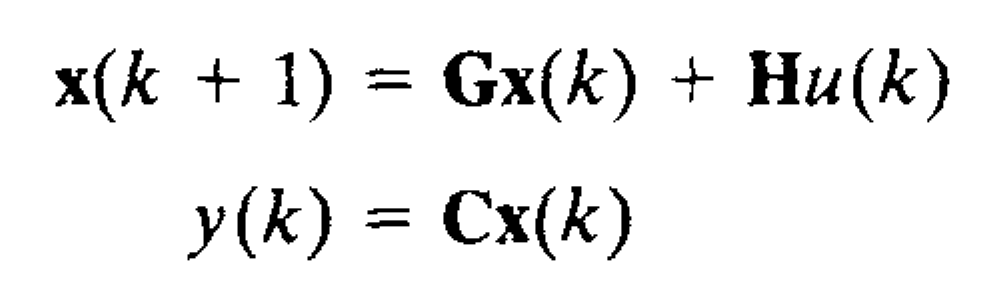


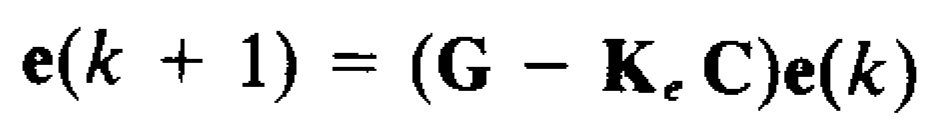
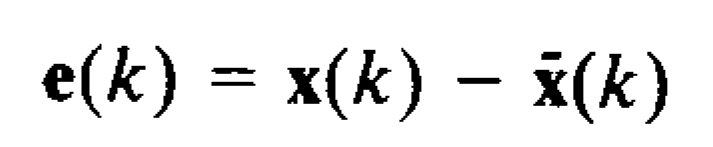


Controlabiilidad a la salida

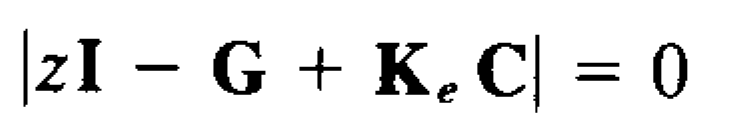


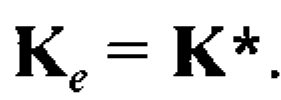
Observabilidad Completa



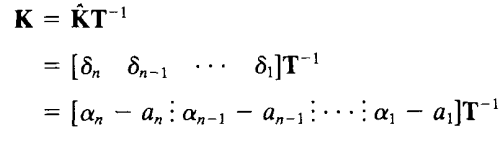




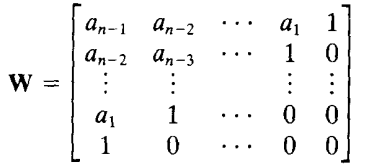


K: Matriz de ganancia de realimentación del estado

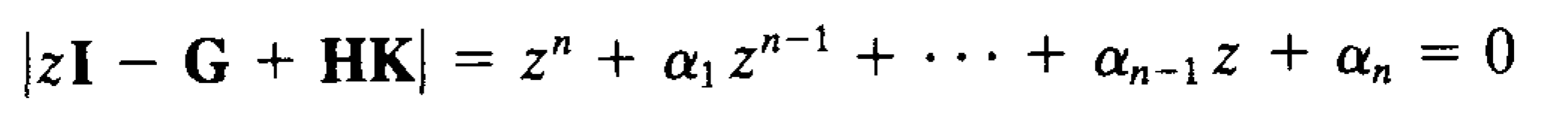


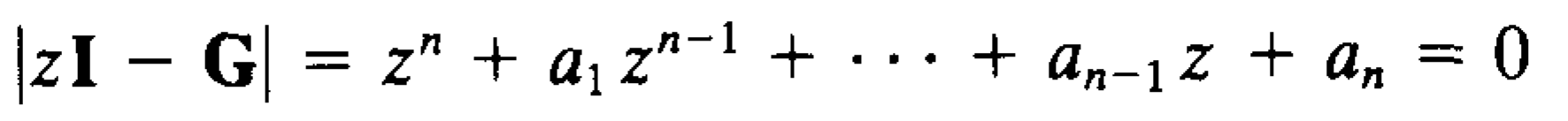




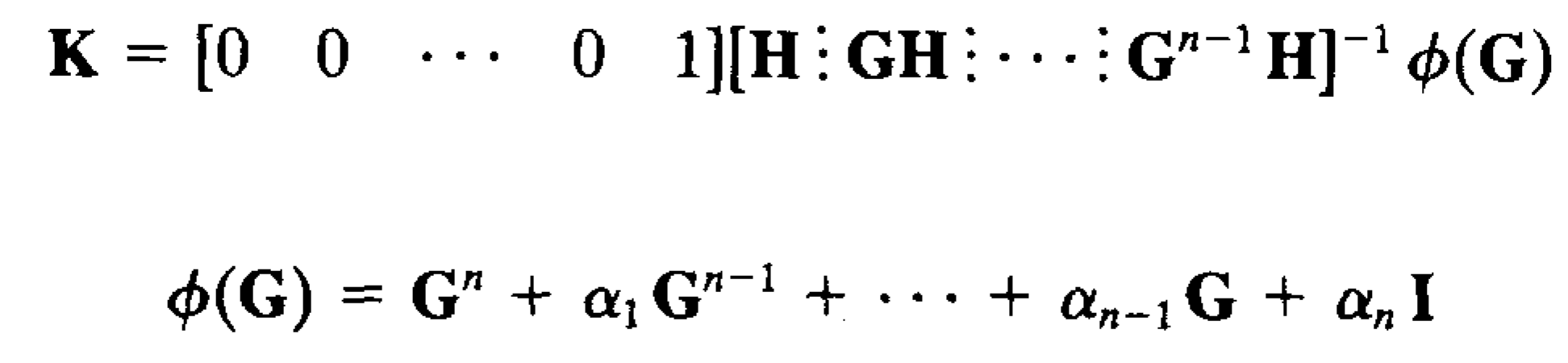




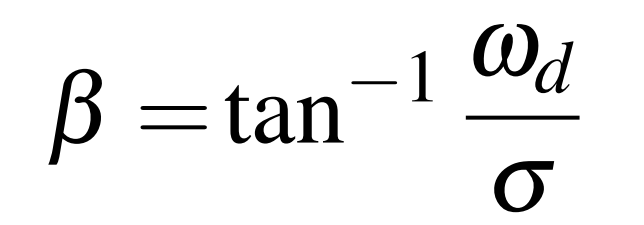


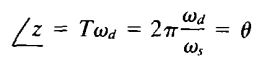
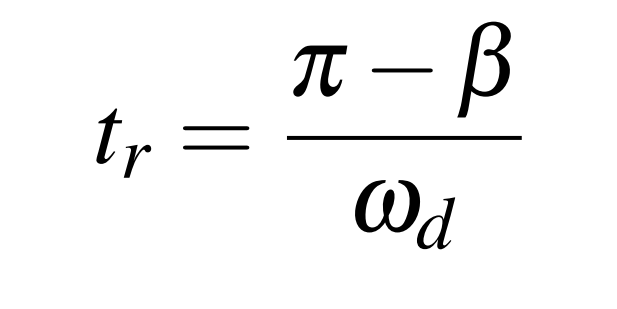


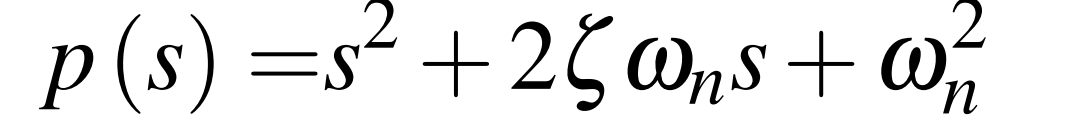
Ackerman

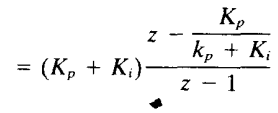
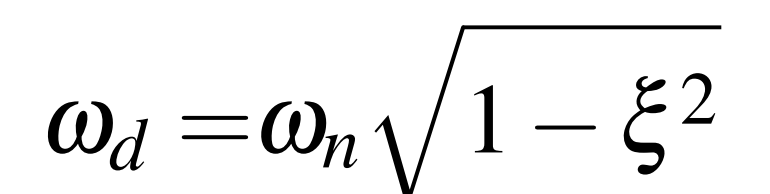


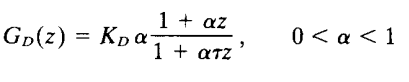
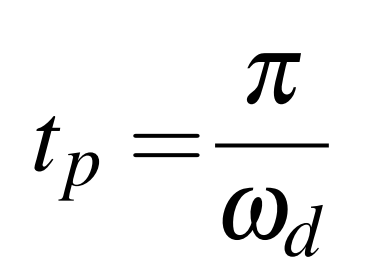
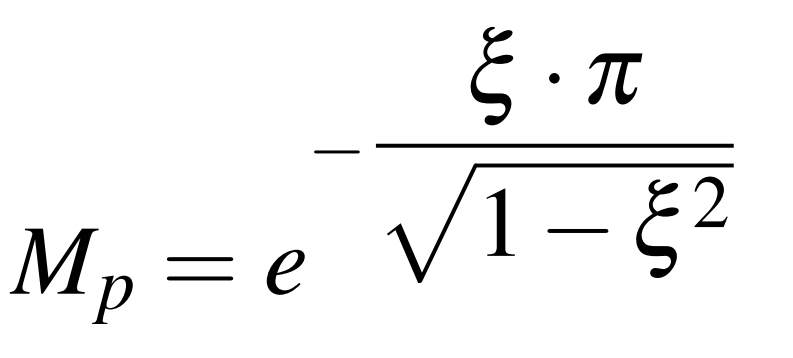
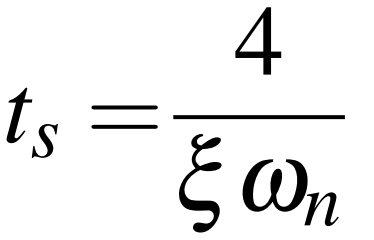
Controladores

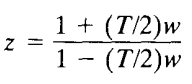
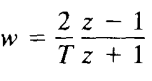
 

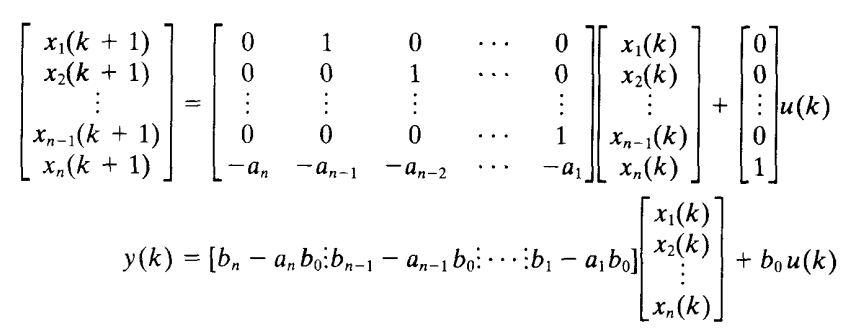
   

Transformación bilineal

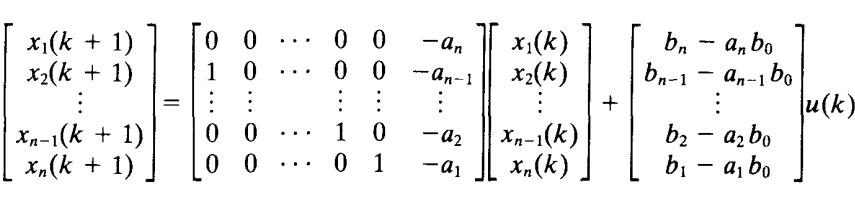
 

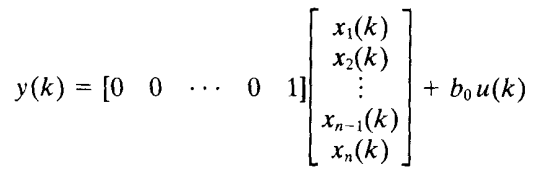


Canonica controlable

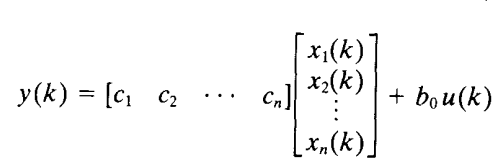
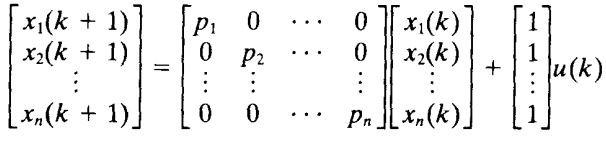


Canonica observable

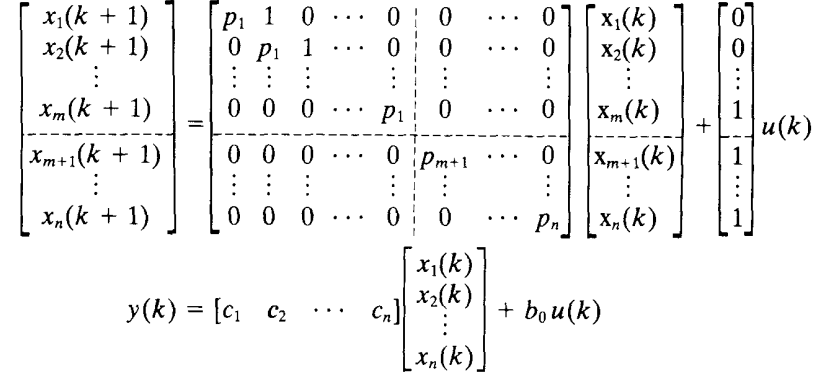




Canonica Diagonal

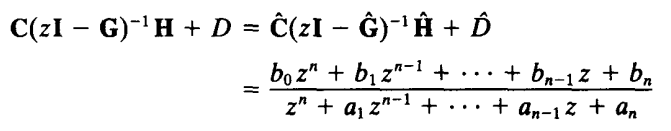
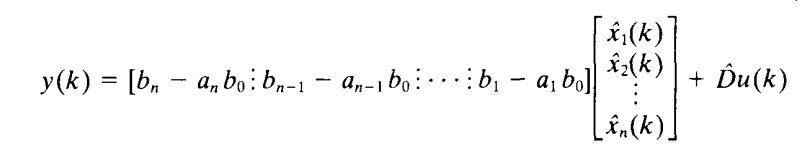
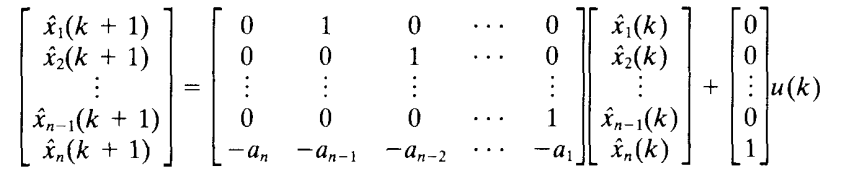
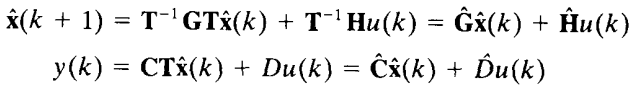
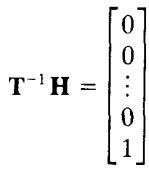
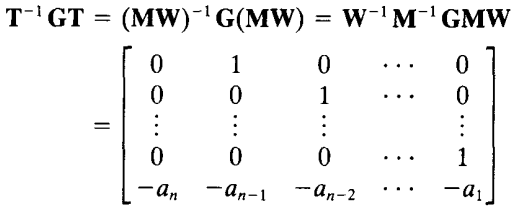
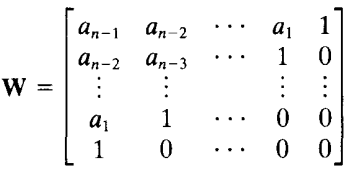






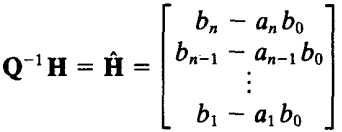
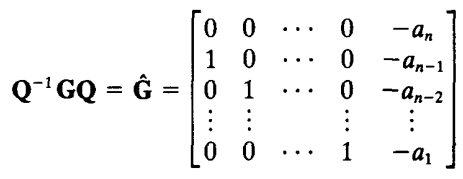
Transformaciones

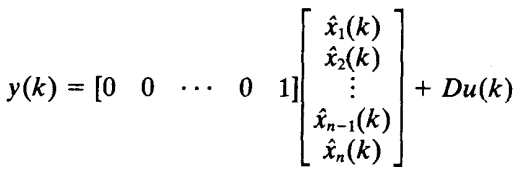
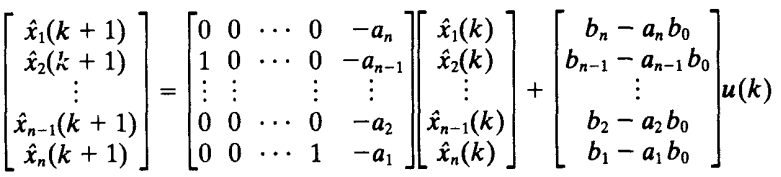
Controlable



Observable

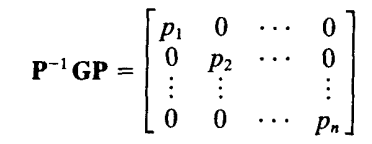




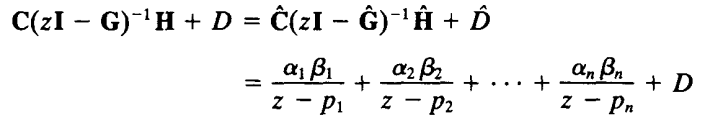
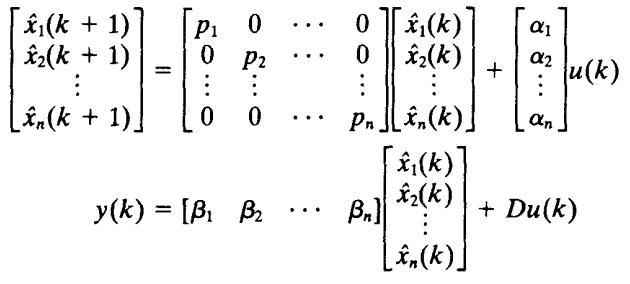
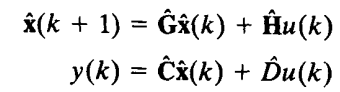




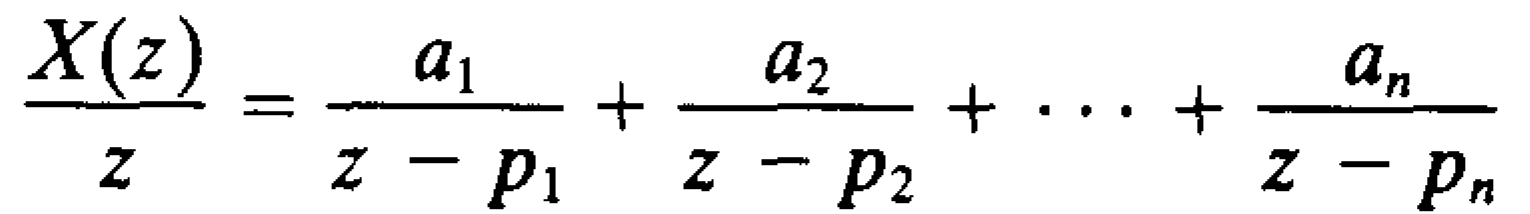


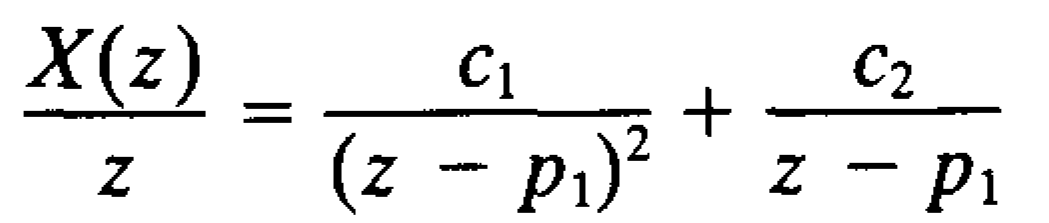
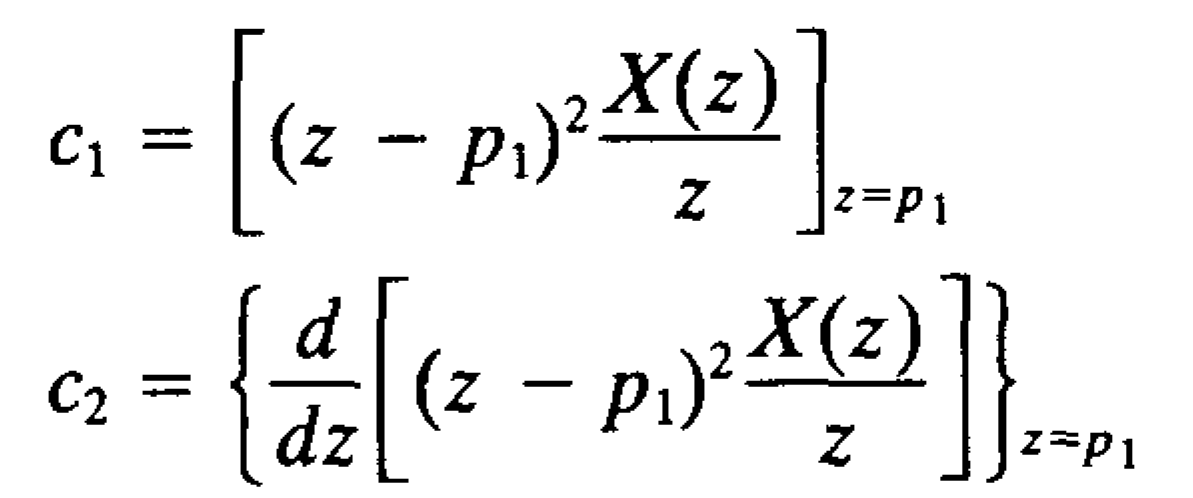






Fracciones Parciales:

Escalera;

