

Definitions and Results afferent to Unitary Recurrent Networks

Jean-Philippe Bernardy

April 1, 2022

1 Orthogonal matrices

Definition 1.1 (Orthogonal matrix). *A matrix Q is orthogonal iff it is square and $Q^T Q = I$.*

Theorem 1.2 (Properties of orthogonal matrices). *A matrix Q is orthogonal iff.*

- $|\det Q| = 1$
- *the rows of Q form an orthogonal basis*
- *the columns of Q form an orthogonal basis*
- *multiplying by Q preserve dot products*
- *multiplying by Q preserve euclidean norms*

Theorem 1.3 (Orthogonal matrices form a group). *If Q is orthogonal, its inverse is Q^T . If P and Q are orthogonal, so is their product PQ .*

Definition 1.4 (Skew-symmetric matrix). *A square matrix S is skew-symmetric iff $S^T = -S$.*

Theorem 1.5. *Assume S , u and λ , such that $S^T = -S$ and $Su = \lambda u$. Then λ is pure imaginary.*

Proof. We have $u^* Su = \lambda u^* u = \lambda \|u\|^2$. Taking the hermitian conjugate of both sides yields $u^* S^* u = \bar{\lambda} \|u\|^2$. Because S is skew-symmetric, we also have $-u^* Su = \bar{\lambda} \|u\|^2$. We then conclude $\lambda = -\bar{\lambda}$, which is satisfied only when λ is pure imaginary. \square

Theorem 1.6. *If S is skew-symmetric then e^S is orthogonal.*

Proof. By the spectral theorem, S admits a unitary diagonalisation $S = Q^* \Theta Q$. Let $\Lambda = e^\Theta$. By properties of matrix exponential, $e^S = Q^* \Lambda Q$. Because Θ is diagonal with elements $i\theta_j$, Λ is diagonal with elements $\lambda_j = e^{i\theta_j}$. By ??, every θ_j is real, and thus every λ_j is unimodular. Consequently, Λ is unitary. Thus e^S is the product of unitary matrices, and consequently itself unitary. \square

2 Average effect and distances

Theorem 2.1. *For every orthogonal matrix Q of dimension n and a random unit vector s , $\mathbb{E}_s[\langle Qs, s \rangle] = \frac{1}{n} \text{trace}(Q)$.*

Proof. By the spectral theorem, Q admits a diagonalisation of the form $Q = U^* \Lambda U$, with U unitary. Let λ_i be the (diagonal) elements of Λ and let $x = Us$. Remark that because U is unitary, $\|x\| = \|s\| = 1$. Thus $\sum_i |x_i|^2 = 1$.¹ Obviously, $\mathbb{E} \left[\sum_i |x_i|^2 = 1 \right]$. By assumption, all dimensions of x have the same distribution (applying Q to s does not change this fact, because multiplying by it conserve densities), and thus $\mathbb{E}[|x_i|^2] = \frac{1}{n}$. We can now compute:

$$\begin{aligned}
\mathbb{E}_s[\langle Qs, s \rangle] &= \mathbb{E}_s[s^T Q s] \\
&= \mathbb{E}_s[s^T U^* \Lambda U s] \\
&= \mathbb{E}_x[x^* \Lambda x] \\
&= \mathbb{E}_x \left[\sum_i |x_i|^2 \lambda_i \right] && \text{by } \Lambda \text{ diagonal} \\
&= \sum_i \lambda_i \mathbb{E}_x[|x_i|^2] && \text{by linearity of expectation} \\
&= \frac{1}{n} \sum_i \lambda_i \\
&= \frac{1}{n} \text{trace}(\Lambda) \\
&= \frac{1}{n} \text{trace}(\Lambda U U^*) \\
&= \frac{1}{n} \text{trace}(U^* \Lambda U)
\end{aligned}$$

\square

Theorem 2.2. *For any two orthogonal matrices P and Q of dimension n , $\|P - Q\|^2 = 2(n - \langle P, Q \rangle)$.*

¹Here, even if Q is real, U , λ_i and thus x_i are complex.

Proof.

$$\begin{aligned}
\|P - Q\|^2 &= \langle P - Q, P - Q \rangle \\
&= \langle P, P \rangle - \langle P, Q \rangle - \langle P, Q \rangle + \langle Q, Q \rangle \\
&= n - 2\langle P, Q \rangle + n
\end{aligned}$$

□

Theorem 2.3. *For any two orthogonal matrices P and Q of dimension n , and a random unit vector s , $\mathbb{E}_s[\langle Ps, Qs \rangle] = \frac{1}{n} \langle P, Q \rangle$.*

Proof. By the spectral theorem, $P^T Q$ admits a diagonalisation of the form $P^T Q = U^* \Lambda U$, with U unitary. The proof proceeds as for ??.

□

Theorem 2.4. *For every orthogonal matrices P and Q of dimension n and a random unit vector s , $\mathbb{E}_s[\|Ps - Qs\|^2] = \frac{1}{n} \|P - Q\|^2$.*

Proof. A direct consequence of ?? and ??.

□

3 Planes

Theorem 3.1. *If S is skew-symmetric, the rank of S gives the maximum number of eigenvalues of e^S different from 1.*

Proof. The proof relies on the construction provided in the proof of ??.

We then note that if $\theta_j = 0$ then $\lambda_j = 1$. Because the rank of S gives the number of non-zero elements of Θ , it is also the maximum number of elements of Λ different from 1. (These numbers can differ when $\theta_j = 2\pi$ for some j .)

□

Definition 3.2 (Plane similarity). *Assume two planes in n -dimensional space, each defined by two orthogonal vectors arranged in a n by 2 matrix. The similarity between A and B is defined by $\text{sim}(A, B) = \max_{\Omega} \langle B, A\Omega \rangle$ for Ω orthogonal.*

The role of taking the minimum for Ω is to account for equal planes, but which are defined by another basis. Indeed, $A\Omega$ covers all possible bases of the plane defined by A when varying Ω .

Theorem 3.3. *$\text{sim}(A, B)$ is the sum of singular values of $B^T A$.*

Proof. Let $U\Sigma V^T = B^T A$ be a singular value decomposition of $B^T A$.

$$\begin{aligned}
 \max_{\Omega} \langle B, A\Omega \rangle &= \max_{\Omega} \text{trace}(B^T A\Omega) \\
 &= \max_{\Omega} \text{trace}(U\Sigma V^T \Omega) \\
 &= \max_{\Omega} \text{trace}(\Sigma V^T \Omega U) \\
 &= \text{trace}(\Sigma)
 \end{aligned}$$

The last step is justified by $V^T \Omega U$ being orthogonal. Because Σ is diagonal, the maximum trace for the product is achieved when $V^T \Omega U = I$. \square