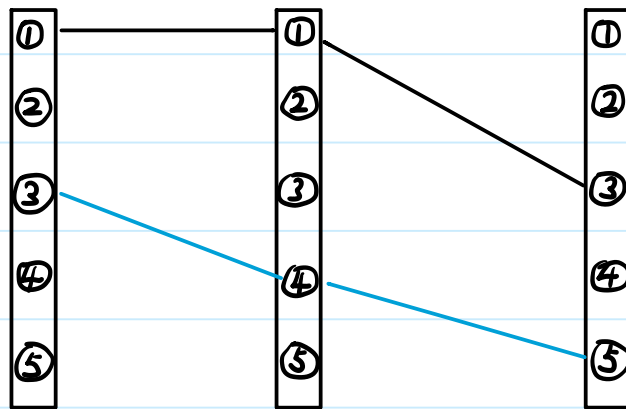


Deep Retrieval

Sunday, March 17, 2024

4:34 PM

Index: item is represented as a path.



depth = 3

width = 5

item = {1, 1, 3}

item = {3, 4, 5}

index 1: item \rightarrow List <path>: an item is represented by a path.

index 2: path \rightarrow List <item>: a path may correspond multiple items.

Estimated like score:

① path = [a, b, c]

② given user feature \vec{x} , estimate like on node a: $P_1(a|\vec{x})$

③ given \vec{x} and a, estimate like score on node b: $P_2(b|a;\vec{x})$

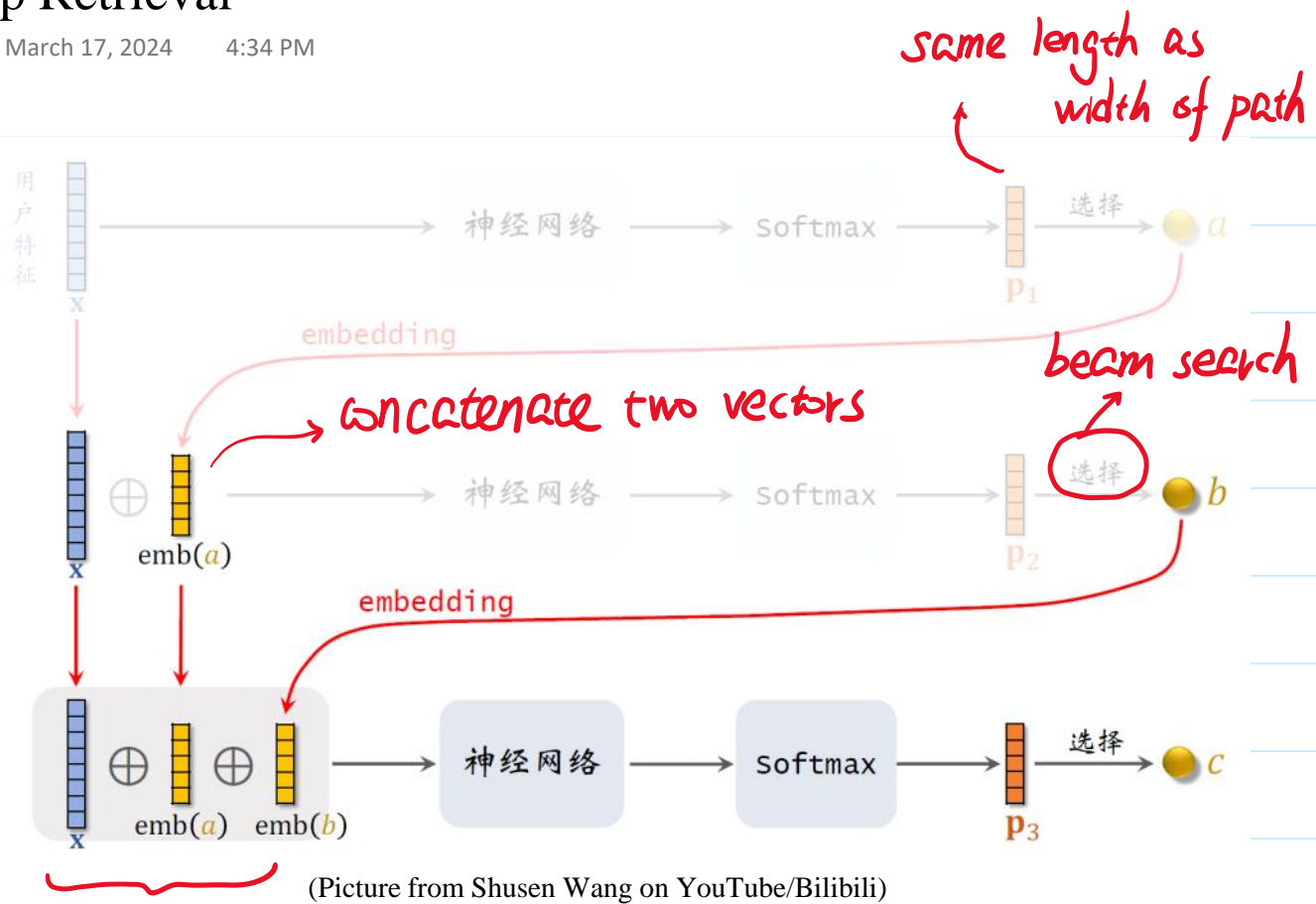
④ given \vec{x} , a, b, estimate like score on node c: $P_3(c|a;b;\vec{x})$

⑤ overall, like score on [a, b, c]:

$$P(a,b,c|\vec{x}) = P_1(a|\vec{x}) \cdot P_2(b|a;\vec{x}) \cdot P_3(c|a;b;\vec{x})$$

Deep Retrieval

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Online Retrieval: user \rightarrow path \rightarrow item

- ① given user feature, we beam search to get a set of paths
- ② we index "path \rightarrow List<item>" to find 1st batch of items
- ③ compute like score and rank: get a subset.

Beam Search:

- ① Path breadth = k ; depth = 3 \rightarrow total k^3 paths
- ② using neural network to score k^3 is too expensive
- ③ use beam search to reduce computation load
hyper-parameter: beam size

How does beam search work?

- ① set beam size = 1 ; path breadth = k .
- ② from i^{th} layer to $(i+1)^{\text{th}}$ layer:
calculate k scores
select 1 node whose score is highest
- ③ repeat step ② for every layer
optimal path:
$$[a^*, b^*, c^*] = \underset{a, b, c}{\operatorname{argmax}} P(a, b, c | \vec{X})$$

beam size = 1 is actually greedy algorithm

it cannot generate global optimal path

More generally, if beam size = B \rightarrow path depth
Then total calculation is $O(B^3)$

Offline Training:

① learn parameters of NN for $P(a, b, c | \vec{x})$

② learn item representation:

item \rightarrow List <path>

path \rightarrow List <item>

③ Only rely on positive samples: user clicked item

④ item representation: an item $\rightarrow J$ paths

$[a_1, b_1, c_1], [a_2, b_2, c_2], \dots, [a_j, b_j, c_j]$

⑤ if user clicks the item:

make $\sum_{j=1}^J P(a_j, b_j, c_j | x)$ as large as possible

⑥ loss function:

$$\text{loss} = -\log \left(\sum_{j=1}^J P(a_j, b_j, c_j | x) \right)$$

⑦ user like score on patch $[a, b, c]$

$$P(\text{path} | \text{user}) = P(a, b, c | x)$$

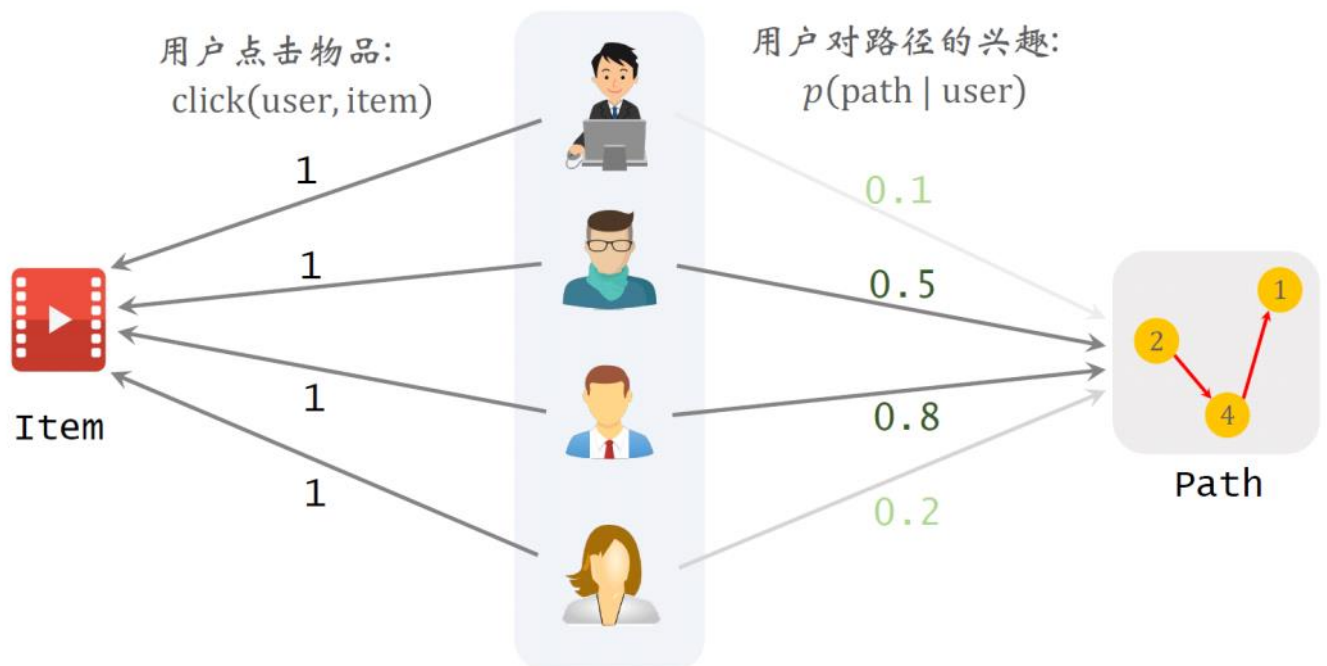
⑧ item and path correlation:

$$\text{score}(\text{item}, \text{path}) = \sum_{\text{user}} P(\text{path} | \text{user}) \cdot \text{click}(\text{user}, \text{item})$$

like score to path whether click (0 or 1)

⑨ select J paths as item representation from score

表征: 物品 \rightarrow 路径



(Picture from Shusen Wang on YouTube/Bilibili)

⑩ J paths : $\pi = \{path_1, \dots, path_J\}$

⑪ loss function:

$$\text{loss}(\text{item}, \pi) = -\log \left[\sum_{j=1}^J \text{score}(\text{item}, path_j) \right]$$

⑫ regularization:

$$\text{reg}(path_j) = (\# \text{ of items on } path_j)^4$$

Summary of item representation:

- ① assume items are represented as J paths π
- ② every time fix $\{\text{path}_i\}_{i \neq l}$; select a new path_l
$$\text{path}_l \leftarrow \underset{\text{path}_l}{\text{argmin}} \text{loss}(\text{item}, \pi) + \alpha \cdot \text{reg}(\text{path}_l)$$
- ③ the path selected has high score
meanwhile the path does not have too many items.

Summary of Training:

update Neural Network

- ① like score: $p(\text{path} | x)$
- ② data: (a) item \rightarrow path
(b) clicked items
- ③ if user clicked item
and item correspond
to path
update NN parameters
to increase $p(\text{path} | x)$

update item representation

- ① correlation between item & path
$$\text{item} \xleftarrow{\text{clicked item}} \text{user} \xrightarrow{\text{like score from NN}} \text{path}$$
- ② let each item correlates J paths
(a) item and path are highly correlated
(b) single path cannot have too many items.