

# LEC10 Depth-First Search

3.27 [https://github.com/GUMI-21/MIT6.006\\_note](https://github.com/GUMI-21/MIT6.006_note)

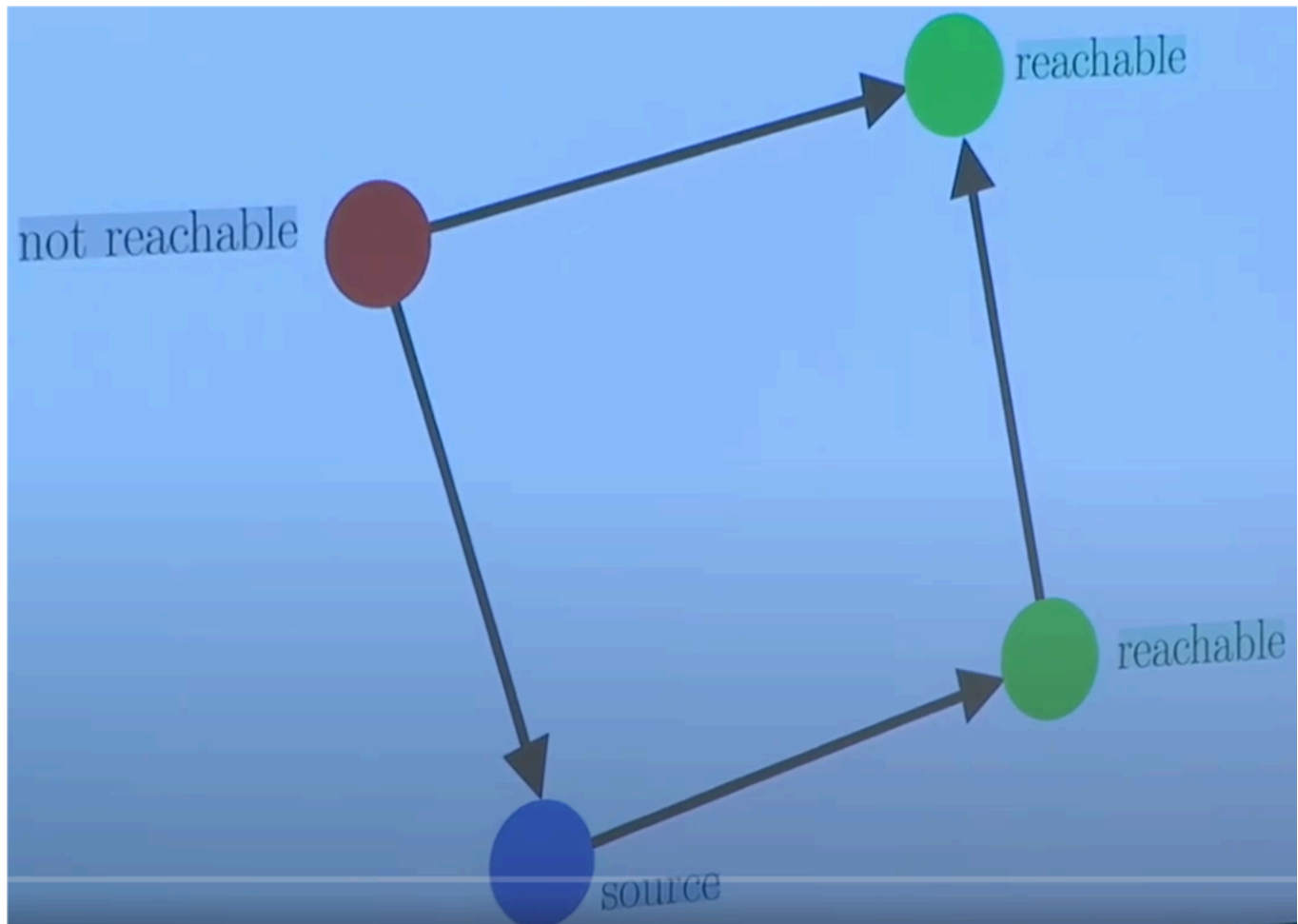
## Previously

- Graph definitions
  - directed/undirected, simple, neighbors, degree
- Graph representations
  - Set mapping vertices to adjacency lists
- Paths
  - simple paths(a path every vertex appear once), path length, distance, shortest path
- Graph Path Problems
  - Single Pair Reachability( $G, s, t$ )
  - Single Source Reachability( $G, s$ )
  - Single Pair Shortest Path( $G, s, t$ )
  - Single Source Shortest Paths( $G, s$ ) (SSSP)
- BFS
  - algorithm that solves Single Source Shortest Paths
  - with appropriate data structures, runs in  $O(|V| + |E|)$  time (linear in input size)

## Depth-First Search (DFS)

### New Problem

## Single Source Reachability.



maintain a tree just like Parent[] in BFS(linear time), but I don't need my tree is the shortest path.

## Alg

diff with BFS P: *Not level sets*

Set P(s) = None and then run visit(s)

```

visit(u):
    for every  $v \in \text{Adj}^+(u)$ :
        if  $P(v) = \text{None}$ :
            Set  $P(v) = u$ 
            Call visit(v)

```

When the recursion is unraveled  $\rightarrow$  the function will back trace, it's different from BFS, from source to deepest node then back call left nodes.

## Proof

Claim: DFS visits all reachable  $v \in V$  & correctly sets  $P(v)$ .

Use Induction on  $k$ : distance to  $S$  (Source)

Base case:  $K=0 \Rightarrow S=0$ , ok

Induction step: Consider a vertex  $v$  with  $\text{distance}(s, v) = k + 1$

Take  $u$  in  $V$  prev. on shortest path  $\Rightarrow \text{distance}(s, u) = k$ .

DFS consider  $v$  in  $\text{Adj}^+(u)$ ,

1.  $P(v) \neq \text{None}$  2.  $P(v) = \text{None}$  .done

## Runtime

$O(|E|) + O(|V|)$  parent array

A example of DFS path is not the shortest path



if  $A \rightarrow B \rightarrow D \rightarrow E$  then recurse  $\rightarrow \text{Parent}[c] = A$   
 DFS will lose edge of CE, But BFS loses edge DE.

## Graph Connectivity

An undirected graph is connected if there is a path connecting every pair of vertices.  
 In a directed graph, vertex  $u$  may be reachable from  $v$ , but  $v$  may not be reachable from  $u$ .

## Full-BFS and Full-DFS

### Full-DFS to solve connectivity

-for  $v \in V$ : if  $v$  is unvisited:  $\{\text{DFS}(v)\}$

- runtime  
 $O(V+E)$ , linear time.

## DAGS and Topological Ordering

### Directed Acyclic Graph (DAG)

Directed graph that contains no directed cycle.  
 example: *A tree*.

### Topological order

A Topological Order of a graph  $G = (V, E)$  is an ordering  $f$  on the vertices such that: every edge  $(u, v) \in E$  satisfies  $f(u) < f(v)$ .

- $f$ : **the time of DFS finished processing the node. After recursion back to the node.**  
 Means  $u$  has to appear before  $v$ .  
*not unique*  
 *$\rightarrow$  If there is a directed edge  $(u \rightarrow v)$ , then vertex  $u$  must appear before vertex  $v$  in the ordering.*

### Finishing order

Order in which a Full-DFS finishes visiting each vertex.  
 *$G$  is DAG  $\Rightarrow$  reverse of finishing order is a Topological order*

- $(u,v) \in E$ , want:  $u$  is ordered before  $v$ .

1.  $u$  visited before  $v$ . means  $visit(v)$  must be called before  $visit(u)$

visit(v) completes without seeing u.

Full-DFS will find a topological order if a graph  $G = (V, E)$  is acyclic.

- if only if*

- if G has a Cycle

Proof: Take cycle  $(V_0, V_1, \dots, V_k, V_0)$

let  $v_0$  is first visited by DFS,  $\Rightarrow$  visit  $V_k \Rightarrow$  see  $(V_k, V_c) \notin E$

## Task Scheduling.

### Circuit Dependency Analysis.

### Expression Evaluation.