

Inputs	B_1	B_0	T_1	T_0
0	0	0	1	1
1	0	0	1	1
2	0	0	0	1
3	0	1	0	1
4	1	0	0	1
5	1	0	1	0
6	1	0	1	0
7	1	1	0	1
8	1	1	0	1
9	1	1	0	1

$T_1 = 1$
 $T_0 = \overline{x} \overline{B_1} + x B_1 = x \oplus B_1$

x	B_1	B_0
0	0	1
1	0	1
2	0	0
3	0	1
4	1	0
5	1	0
6	1	0
7	1	1
8	1	1
9	1	1

$B_1 = 1 \rightarrow 0$
 $B_0 = 1 \rightarrow 1$
 $T_1 = 1$
 $T_0 = 0 \oplus 1 = 0$

punto 4 Motor & Parar

x	B_3	B_2	B_1	B_0	N_3	N_2	N_1	N_0	D_3	D_2	D_1	D_0
0	1	0	1	0	1	0	0	1	1	0	0	1
1	1	0	0	1	0	1	1	0	0	1	1	0
2	1	0	1	1	0	1	0	1	0	1	0	1
3	1	0	1	0	1	0	1	0	1	0	1	0
4	1	0	1	1	1	0	1	0	1	1	0	1
5	1	0	1	0	1	0	1	0	1	1	0	1
6	1	0	1	1	1	1	0	0	1	1	0	1
7	1	0	1	0	1	0	1	0	1	1	0	1
8	1	0	1	1	1	1	1	0	1	1	0	1
9	1	0	1	0	1	0	1	0	1	1	0	1

$D_1 = 1010$ $D_2 = 0110$
 $D_3 = 1001$ $D_0 = 0101$

D_1	0	1	0	1
D_2	0	1	1	0
D_3	1	0	0	1
D_0	0	1	0	1

Memoria
 Memoria
 Memoria
 Memoria

0	0	0	0
1	0	0	1
2	0	0	1
3	0	0	1
4	0	1	0
5	0	1	0
6	0	1	0
7	0	1	0
8	1	1	1
9	1	1	1

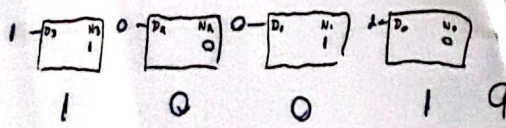
$f(x=1)$
 Estado D_1 $Q_{A0} = 1010$
 $Q_{A1} = 1001$
 $Q_{A2} = 1001$
 Estado D_2 $Q_{A0} = 1001$
 $Q_{A1} = 0110$
 $Q_{A2} = 0110$
 Estado D_3 $Q_{A0} = 0110$
 $Q_{A1} = 0101$
 $Q_{A2} = 0101$
 Estado D_4 $Q_{A0} = 0101$
 $Q_{A1} = 1010$
 $Q_{A2} = 0101$

P.A.H	vector	valor en D1
2	3	1
3	2	0
10	1	0

otro caso

valores del vector con los estados transitorios de la memoria se ocupan los primeros de la tabla de estado al 10

Secuencia N° 11 a 9



D_3

$B_1 B_0$	00	01	10	11
$B_3 B_2$	00	X	X	X
	01	X	X	X
	11	X	X	X
	10	X	X	X

$D_3 = B_2 \overline{B_1} + B_3 B_1$

D_1

$B_1 B_0$	00	01	10	11
$B_3 B_2$	00	X	X	X
	01	X	X	X
	11	X	X	X
	10	X	X	X

$D_1 = B_1$

D_2

$B_1 B_0$	00	01	10	11
$B_3 B_2$	00	X	X	X
	01	X	X	X
	11	X	X	X
	10	X	X	X

$D_2 = B_3 \overline{B_1} + B_3 B_1$

D_0

$B_1 B_0$	00	01	10	11
$B_3 B_2$	00	X	X	X
	01	X	X	X
	11	X	X	X
	10	X	X	X

$D_0 = B_1$

para $x=1$