MYLAPS X2 Decoder - Quick start guide









Installing the MYLAPS X2 Decoder



The detection loop: Connect here the coax cable coming from the detection loop to the MYLAPS X2 decoder.



The auxiliary port: This port can be used to connect a photocell, external start pulse or a sync pulse. For more information on how to connect these devices, see appendix D of the MYLAPS X2 decoder manual.



The GPS antenna: Connect the GPS antenna cable and place the antenna where it has a clear view of the sky overhead to be able to make connections to satellites in order to synchronize to the time of day very accurately.



CAN connector: for future use



The network: Use a UTP cable to connect the MYLAPS X2 Decoder to the MYLAPS X2 Server on the red port of the MYLAPS X2 Decoder. The LEDs on the connector will show if a physical network connection is available.



Power: Connect the supplied VDC adapter to the decoder and mains. It is recommended to connect the VDC adapter to mains through an Uninterruptable Power Supply (UPS) to avoid any interruption of power supply to the decoder.

Appr. 5W

Future use

10 to 14.4VDC, Typical 12VDC

Technical Specifications of the MYLAPS X2 Decoder

220x180x60mm / 8.7x7x2.4inch Dimensions

Weight 1.5kg / 3.3lb 0.5PPM Clock Stabilitu

GPS Receiver quick fix, -160dB, 15nS

GPS antenna connection SMA, active Timing Resolution 0.001s

1x BNC, max. 20m loop Loop connection Operating temperature range -20 to 50 °C / -4 to 122 °F 10% to 90% relative

Humidity range

Operating voltage range

Power consumption Network Interface

 Auxiliary connector Can connection

10-100BT (RJ45) DB15, Female

Specifications are subject to change without notice



CE information:

This device complies with the EMC directive 89/336/EEC. A copy of the declaration of conformity can be obtained at:

MYLAPS Sports Timing Zuiderhoutlaan 4 2012 PJ Haarlem The Netherlands

FCC information:

This equipment complies with part 15 of the FCC rules. Operation is subject to the following two conditions: (1) This equipment may not cause harmful interference, and (2) this equipment must accept any interference received, including interference that may cause undesired operation.

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