

Foundations of Computing

Lecture 20

Arkady Yerukhimovich

April 3, 2025

- 1 Lecture 19 Review
- 2 Verifying vs. Deciding
- 3 Nondeterministic Polynomial Time

- Polynomial Time Computation
- The Complexity Class \mathcal{P}

$$\mathcal{P} = \bigcup_k TIME(n^k)$$

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- But, some problems have resisted our efforts to find efficient algorithms
- Today we will study one important class of such problems

Hamiltonian Path

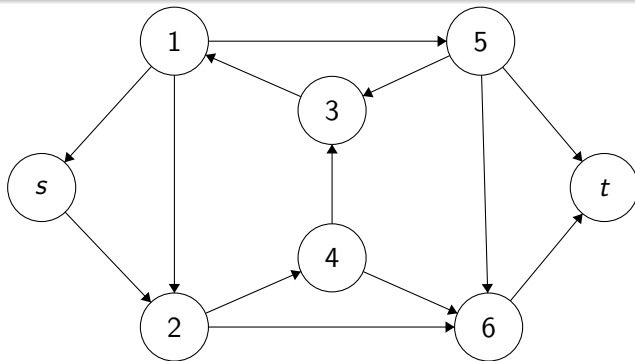
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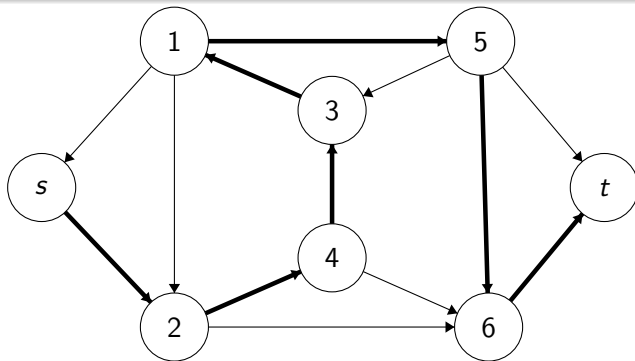
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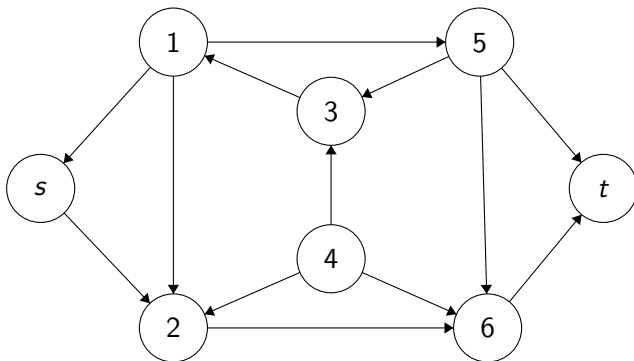


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But, not every graph has a Hamiltonian Path.



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Polynomial Verifiability

However, given a path from s to t , can easily verify whether it is Hamiltonian in polynomial time.

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A Boolean formula is an expression involving Boolean variables and logic operations AND (\wedge), OR (\vee), and NOT (\neg or \bar{x}).

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- Not all formulas are satisfiable

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However, given an assignment (i.e., values for all the variables), can easily verify whether ϕ is satisfied by this assignment in polynomial time.

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- String w is called a witness that $x \in L$

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- \mathcal{NP} is the class of problems where you can verify a solution in poly-time
- Question: $\mathcal{P} \stackrel{?}{=} \mathcal{NP}$

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- (\Leftarrow) A verifier simulates the NTM by using the accepting branch as the witness

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- Let N be an NTM deciding L
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 - ① Simulate N on input x , treating each symbol of w as a description of the nondeterministic choice to make at each step

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 - ① Simulate N on input x , treating each symbol of w as a description of the nondeterministic choice to make at each step
 - ② If this branch of N 's computation accepts, accept, otherwise reject

We can define the class of languages decided by poly-time NTMs

Definition

$$NTIME(t(n)) = \{L \mid L \text{ is a language decided by a } O(t(n)) \text{ time NTM}\}$$

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$$\mathcal{NP} = \bigcup_k NTIME(n^k)$$

Problems in \mathcal{NP} – Example 1

Clique

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$$CLIQUE = \{ \langle G, k \rangle \mid G \text{ is an undirected graph with a } k\text{-clique} \}$$

Problems in \mathcal{NP} – Example 2

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$$SUBSET - SUM = \{ \langle S, t \rangle \mid S = \{x_1, \dots, x_k\} \text{ and for some } \{y_1, \dots, y_l\} \subseteq \{x_1, \dots, x_k\}, \sum y_i = t \}$$

The Million Dollar Question

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- Is it easier to verify a solution than to find that solution?
- This is the biggest open question in complexity theory

Let's Try to Answer It

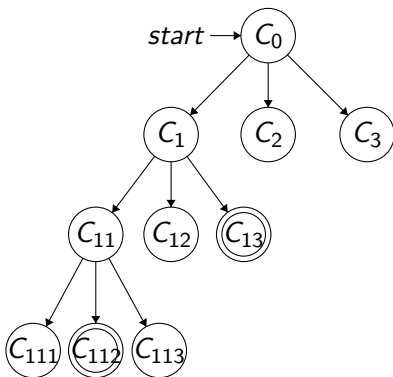
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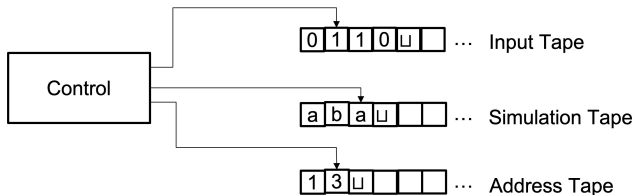
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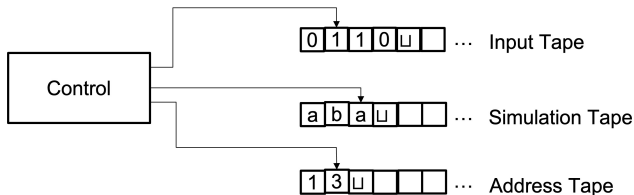
- Recall that an execution of a DTM is a sequence of configurations
- Execution of an NTM is a tree of configurations (branches correspond to non-deterministic choices)
- If any node in the tree is an accept node, the NTM accepts
- To simulate an NTM by a DTM, need to try all configurations in the tree to see if we find an accepting one

Simulating NTM on a 3-tape DTM



To simulate an NTM N by a DTM D , we use three tapes:

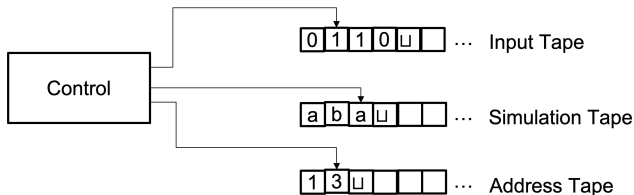
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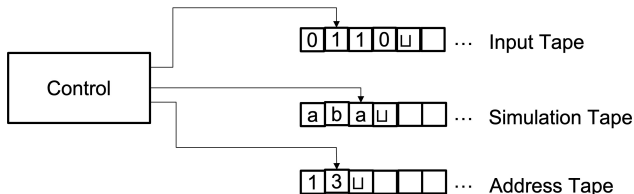
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- 3 Address tape – use to store which nondeterministic branch you are on

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- Resulting DTM runs in exponential time

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- We will show this using reductions – Yay!