

CS 1010



Deep dive into Raspberry Pi (sense HAT) with Python

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Playing with the [sense HAT]

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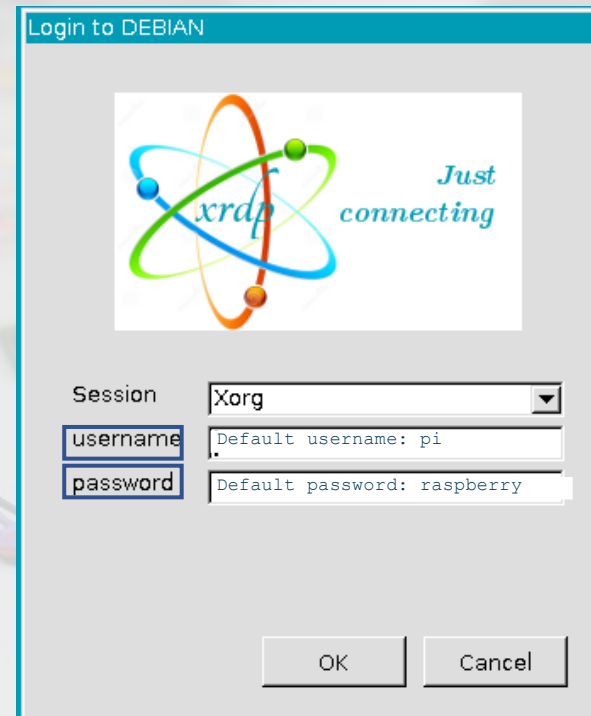
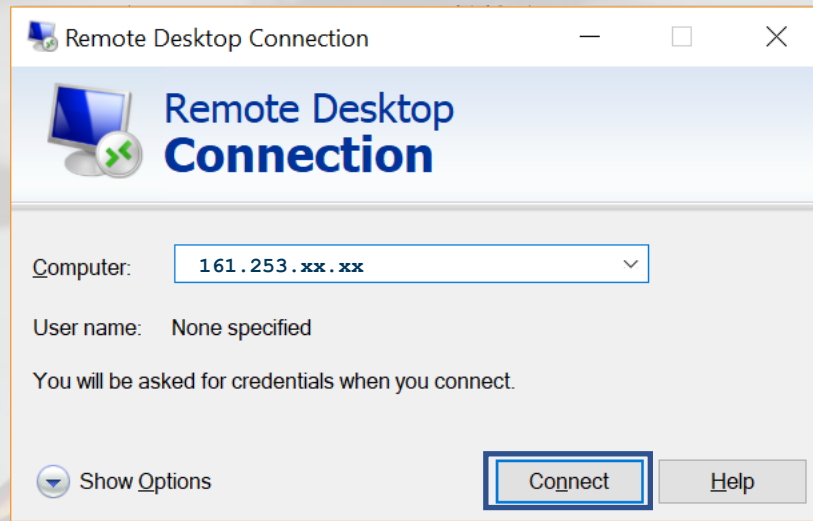
School of Engineering
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THE GEORGE WASHINGTON UNIVERSITY

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Photo: Kartik Bulusu

Access to the RPi in the laboratory



Each RPi is assigned a unique

- IP address
<161.253.30.xxx>
- OR DNS name
<kartik###.seas.gwu.edu>
- *username & password*

Source: https://upload.wikimedia.org/wikipedia/commons/f/f1/XRDP_Screenshot.png

“Put on the Sense HAT” ...

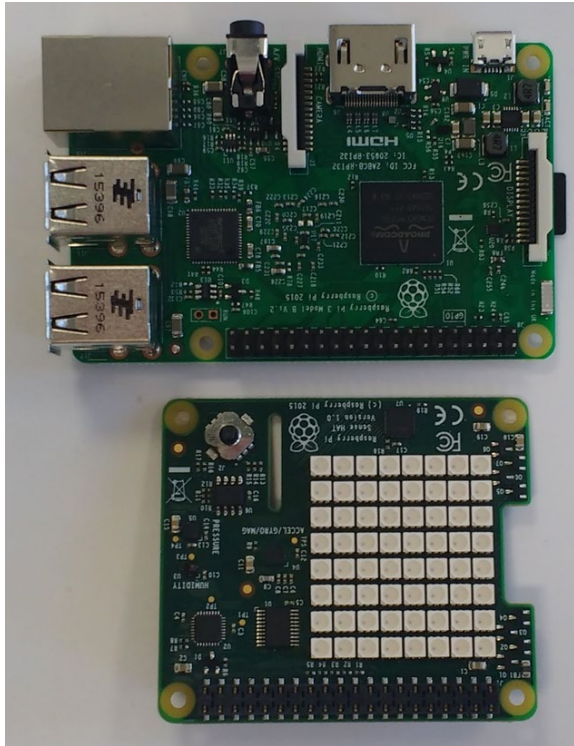


Image and animation source: <https://projects.raspberrypi.org/en/projects/getting-started-with-the-sense-hat/2>

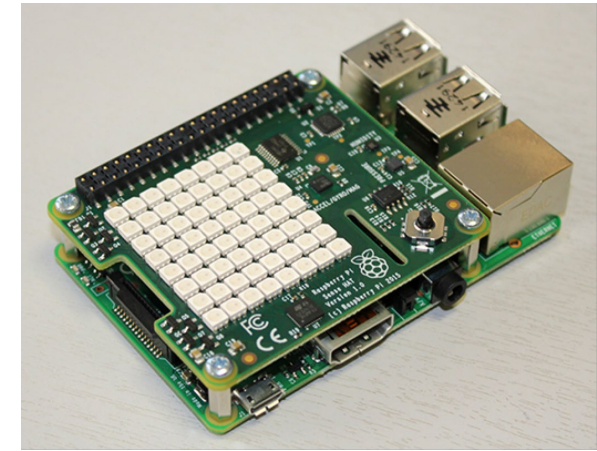
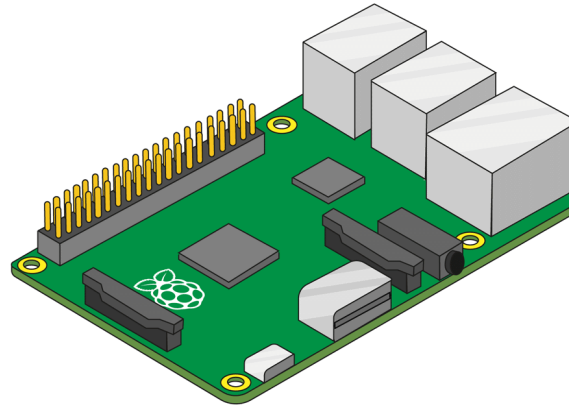
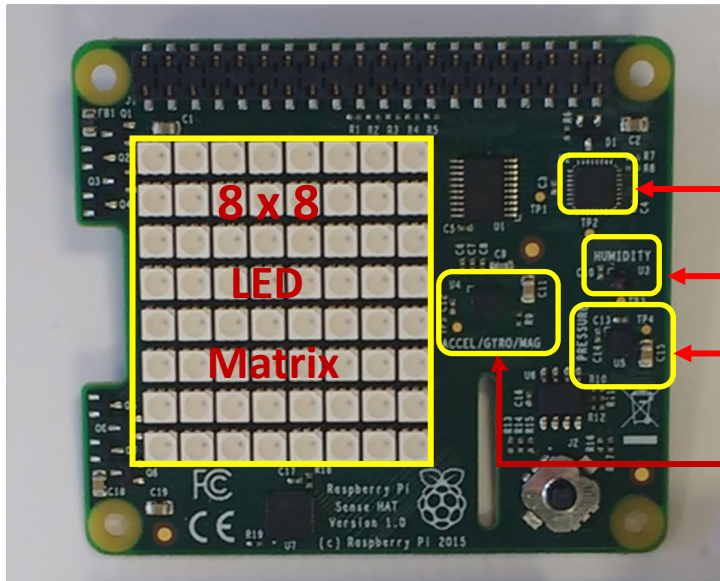


Image source: <https://reference.wolfram.com/language/ref/device/SenseHAT.html>



Source: <https://youtu.be/8NwWNOMqai4>

“and take a closer look” ...

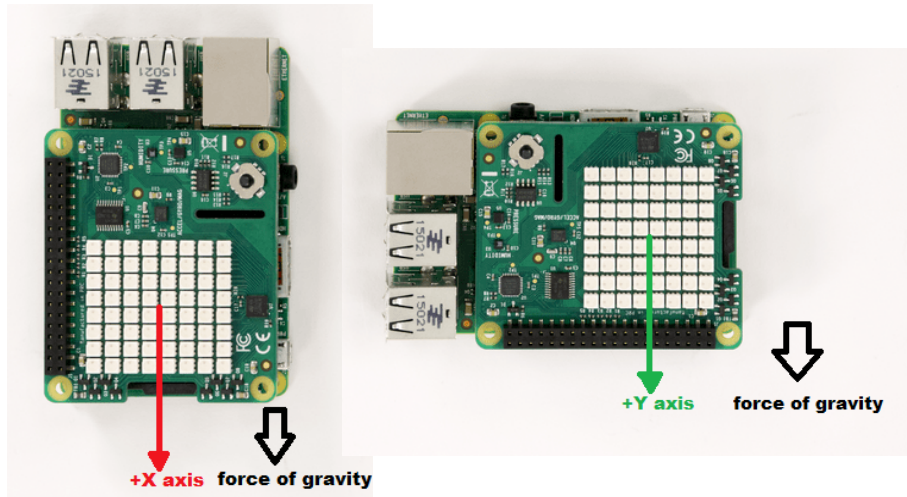


IMU
Inertial
Measurement
Unit

▪ The Sense HAT has a variety of sensors that can be read from:

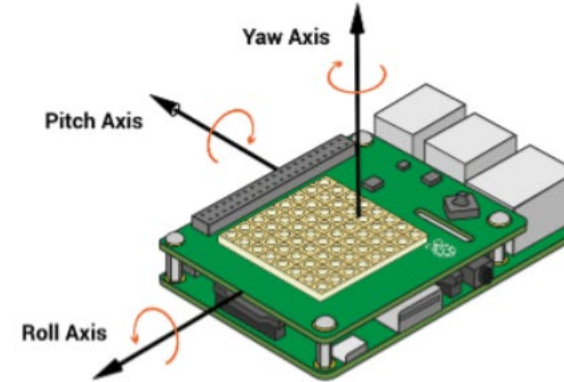
"Temperature"	reads temperature in degrees Celsius
"Humidity"	reads humidity in % RH
"Pressure"	reads atmospheric pressure in millibars
"Rotation"	reads gyroscopic motion in revolutions per second
"Acceleration"	reads acceleration in terms of standard accelerations due to gravity on Earth's surface
"Orientation"	reads orientation relative to magnetic north in degrees
"Magnetic Field"	reads strength and direction of a magnetic field around the sensor in microteslas

Image source: <https://projects.raspberrypi.org/en/projects/getting-started-with-the-sense-hat/2>



Source: <https://www.mathworks.com/help/supportpkg/raspberrypi/examples/auto-rotate-an-image-displayed-on-sense-hat-led-matrix.html>

▪ The gyroscope, accelerometer, and magnetometer sensors return a list of three values that corresponds to $\{roll, pitch, yaw\}$, as oriented according to the following image:



Starting point for further exploration:

[Link for "Getting started with the Sense HAT"](#)

Source: <https://reference.wolfram.com/language/ref/device/SenseHAT.html>



Example of who is using the sense HAT and where
- Astro Pi



Source: https://youtu.be/kk_7KNuRLrk

What we will do today

- Co-work
 - Observe, ask and try in groups
- Write small program using Python
- Think about
 - Challenges, Opportunities, Gaps and Surprises

What we will learn today

- Communicate with the Sense HAT using Python
- Access the outputs of the Sense HAT
- Use the Sense HAT library to display messages and images
- Use loops to repeat certain code blocks