# Zhenhao Zhao

Curriculum Vitae

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#### Education

Ph.D. Student George Washington University (GWU), DC, USA

2022 - present, Department of Biomedical Engineer Assistive Robotics & Telemedicine (ART-MED) Lab

Advisor: Prof. Chung-Hyuk Park

Master of Science George Washington University (GWU), DC, USA

2020 - 2022, Department of Computer Science Intelligent Aerospace Systems Lab (IASL)

Advisor: Prof. Peng Wei

Bachelor of Science Beijing Information Sci & Tech University (BISTU), Beijing, China

2016 - 2020, Department of Computer Science

Exchange Program Oakland University (OU), MI, USA

2018 - 2019, Department of Computer Science

#### Research Interests

Computer Vision, Machine Learning, Robotic Intelligent System

#### **Publications**

AIAA SciTech 2023 Camera Vision based Perception for UAS Autonomous Landing

(under review) Zhenhao Zhao, Jonathan Lee, Zongyao Li and Peng Wei AIAA SciTech Forum, 2023

Research and Work Experiences

Research Assistant George Washington University, DC, USA

Aug. 2022 - Present

Lab: Assistive Robotics & Telemedicine (ART-MED) Lab

Research Focus: Artificial intelligence system, computer vision, medical data processing

Research Assistant George Washington University, DC, USA

Dec. 2021 - Present

Lab: Intelligent Aerospace Systems Lab (IASL)

Research Focus: Automatic Landing, Computer Vision

Machine Learning Engineer

Union Strong Technology Co., LTD, Beijing, China Mar. 2021 - Aug. 2021

Project: Optimization of 3D DSA aneurysm segmentation model

- Building and training the No New U-Net (nnUNet) to do the accurate segmentation for the 3D digital subtraction angiography images.
- The dice coefficient was taken as the evaluation standard, and the accuracy had reached above 90 percent.

Research Assistant Infervision Medical Technology Co., LTD, Beijing, China

Aug. 2020 - Mar. 2021

Lab: Institute of Advanced Research (IAR) **Project: Medical Image Processing** 

- Deep learning-assisted screening of asymptomatic Covid-19
- Using deep learning model to diagnose tuberculosis

Undergraduate Thesis **Tsinghua University**, Beijing, China

Oct. 2019 - Jun. 2020

Lab: Knowledge Engineering Group (KEG), Department of Computer Science

Advisor: Prof. Juanzi Li

Research Focus: Relationship Mining, Natural Language Processing

### Honors & Awards

### Aug. 2018 - Aug. 2019 Beijing municipal scholarship for overseas study, Beijing, China

Tuition for 40 credits to study computer science courses in USA and living expenses per month.

#### Professional Activities

Journal Reviewer Journal of Aerospace Information Systems

### Research and Academic Projects

#### Research Project UAS vision and perception, GWU, DC, USA

Dec. 2021 - Present, Intelligent Aerospace Systems Lab (IASL), Advisor: Prof. Peng Wei

- Design and implement UAS vision and perception algorithms to assist landing automatically
- Build and train the object detection models to do the pedestrians and cars detection and compare the performance between two models.
- Inference on the drone level video dataset. (Collected by ourselves)
- Track objects by the DeepSORT
- Deploy the whole perception algorithm on the drone level computer. (Jetson Xavier NX)

Undergraduate Thesis Relationship mining for intelligent manufacturing companies, THU, Beijing, China Oct. 2019 - Jun. 2020, Knowledge Engineering Group (KEG), Advisor: Prof. Juanzi Li

- Using the Cypher statement of neo4j graphic database to process 13 enterprise declarations and construct the enterprise information knowledge map.
- Using Python Word document processing tool to extract and clean data, and using Py2neo class library to constructs the knowledge map
- Visualize data and provides a friendly interface

### Course Project White blood cell classification, GWU, DC, USA

Aug. 2021 - Jan, 2022, Advisor: Prof. Kinga Dobolyi

- Classify the blood smear images by the deep learning methods.
- o Train and tune the Resnet, EfficientNet and Alexnet and compared the performance by the accuracy, confusion matrix, specificity, sensitivity etc.
- Result analysis: saliency map, average images, histogram of pixels distribution, etc.

#### Course Project Robotic perception and vision, GWU, DC, USA

Dec. 2021 - May 2022, Advisor: Prof. Taeyoung Lee

- Visual odometry: Deploy the sparse reconstruction on the self-collected video.
- Face tracking: Record a video and track my face in it by the KLT algorithm.

#### Selected Courses:

Machine Learning: 4/4

Linear Algebra: 4/4

Data structure: 4/4

Robotic perception and vision: 4/4

Theory of Computation: 4/4

## Skills

Programming Python, C/C++, R, Java

Toolbox/Software PyTorch, TensorFlow, Caffe, OpenCV, Neo4j

Operating System Linux, Windows, MacOS