

DYNAMICAL SYSTEM IN \mathbb{R}^d

It is widely used in numerical weather prediction and various simulation.

$$\frac{d\mathbf{X}(t)}{dt} = \mathbf{V}(\mathbf{X}(t), t) \quad (1)$$

or equivalently finding *characteristic* of advection equation

$$\frac{\partial f(\mathbf{x}, t)}{\partial t} + \mathbf{V}(\mathbf{x}, t) \cdot \nabla_x f = 0 \quad (2)$$

Method

- ▶ Semi-Lagrangian

$$f(\mathbf{x}_m, t_n + \Delta t) = f(\mathbf{x}_m - 2\alpha_m, t_n - \Delta t) \quad (3)$$

- ▶ Second order accuracy and iteration

$$\alpha_m = \Delta t \mathbf{V}(\mathbf{x}_m - \alpha_m, t_n) \quad (4)$$

Pro

- ▶ No need to worry about CFL condition.

Con

- ▶ This scheme is at best second order accurate in approximating the backtracking point, if \mathbf{V} is variable.

SEMI-LAGRANGIAN ENO/WENO

General Steps

- ▶ 1D problem:
 - ▶ Backtracking in time.
 - ▶ Spacial interpolation using ENO/WENO.
- ▶ Multi-D problem:
Strang splitting: decompose into several 1D problems.

SEQUENTIAL METHOD

- ▶ If \mathbf{V} is constant vector, then it is fast to know the solution by simply interpolation and implement high order accuracy scheme by ENO/WENO.
- ▶ To achieve $2k + 1$ order accuracy in \mathbf{R}^d , with number of time steps as N and mesh size M , by using WENO. Time complexity is $O(kNM^d)$. (Qiu & Shu 2011) =====
- ▶ If \mathbf{V} is constant vector, then it is fast to know the solution by simply interpolation, and easy to implement arbitrary accuracy scheme by ENO/WENO.
- ▶ To achieve $2k + 1$ order accuracy in \mathbf{R}^d , with time step as N and mesh size M , by using WENO. Time complexity is $O(kNM^d)$.

SEQUENTIAL METHOD

- ▶ If \mathbf{V} is variable and divergence free. Tracking back is no longer an easy job within high accuracy. We shall use some high order time integrator to implement this.
- ▶ For example, Semi-Lagrangian method with Runge-Kutta high order solver(time integrator) for back tracking. The time complexity is $O(M^d N \times T(SL))$ with second order time splitting and WENO. (Qiu & Shu 2011)

PARALLEL METHOD

Most of running time are consumed in Semi-Lagrangian back tracking and interpolation. And this can be parallelized perfectly, since back tracking with different end points \mathbf{x}_m are independent process. Work-depth model time complexity here is $O(T(SL) \times N)$.

MILESTONES

- ▶ 1D Sequential Semi-Lagrangian ENO/WENO implementation. (April 12)
- ▶ 3D Semi-Lagrangian ENO/WENO implementation. (April 18)
- ▶ 3D shared memory implementation. (April 25)
- ▶ 3D distributed memory implementation. (May 9)