### Latent Variable Models

CS771: Introduction to Machine Learning

### Dimensionality Reduction: Out-of-sample Embedding

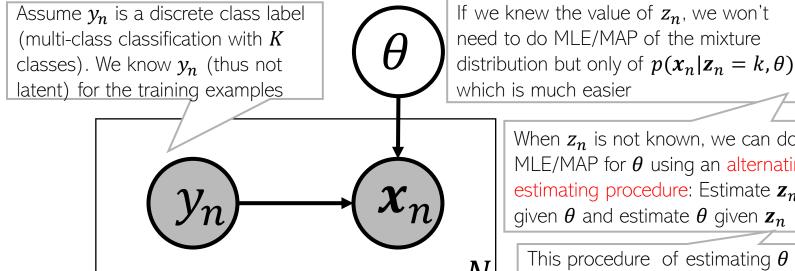
- Some dim-red methods can only compute the embedding of the training data
- $\blacksquare$  Given N training samples  $\{x_1, x_2, ..., x_N\}$  they will give their embedding  $\{z_1, z_2, ..., z_N\}$
- lacktriangleright However, given a new point  $m{x}_*$  (not in the training samples), they can't produce its embedding  $m{z}_*$  easily
  - Thus no easy way of getting "out-of-sample" embedding
- Some of the nonlinear dim-red methods like LLE, SNE, KPCA, etc have this limitation
  - Reason: They don't learn an explicit encoder and directly optimize for  $\{z_n\}_{n=1}^N$  given  $\{x_n\}_{n=1}^N$
  - To get "out-of-sample" embeddings, these methods require some modifications\*
- But many other methods do explicitly learn a mapping z = f(x) in form of an "encoder" f that can give  $z_*$  for any new  $x_*$  as well (such methods are more useful)
  - lacktriangle For PCA, the D imes K projection matrix  $W_K$  is this encoder function and  $z_*=W_K^{\mathsf{T}}x_*$
  - Neural network based autoencoders can also do this (will see them later)

# Latent Variable Models



### Example: Generative Models with Latent Variables

 $\blacksquare$  Two generative models of inputs  $x_n$  without (left) and with (right) latent variables



distribution but only of  $p(x_n|z_n = k, \theta)$ 

When  $z_n$  is not known, we can do MLE/MAP for  $\theta$  using an alternating estimating procedure: Estimate  $\mathbf{z}_n$ 

also gives  $\mathbf{z}_n$  as a by-product

Assume  $\mathbf{z}_n$  is the cluster id of  $oldsymbol{x}_n$  (total K clusters). We don't know the true value of  $\boldsymbol{z_n}$  (thus latent)

- Suppose we wish to estimate (e.g., using MLE/MAP) params  $\theta$  of distribution of  $x_n$
- For case 1, the distribution is  $p(x_n|y_n,\theta)$  and MLE/MAP of  $\theta$  easy since  $y_n$  is known
- Reason: The functional form ■ For case 2, distribution is more complex because true  $z_n$  is not known of mixture can be messy

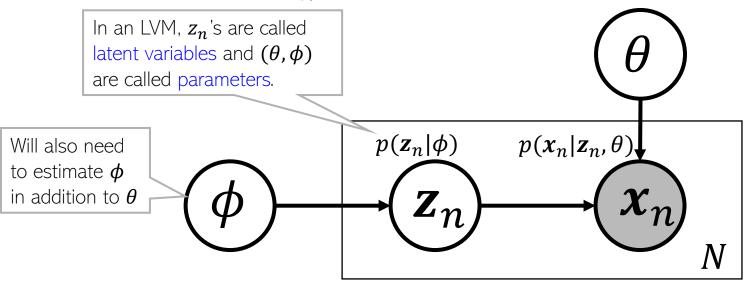
$$p(\boldsymbol{x}_n|\theta) = \sum_{k=1}^K p(\boldsymbol{x}_n, \boldsymbol{z}_n = k|\theta) = \sum_{k=1}^K p(\boldsymbol{z}_n = k)p(\boldsymbol{x}_n|\boldsymbol{z}_n = k,\theta)$$

MLE/MAP a bit difficult for this more complex this more complex than the property of the p

"mixture" of distributions tro to ML

### Components of an LVM

- lacktriangle Recall that the goal is to estimate heta (and  $oldsymbol{z}_n$  is also unknown)
- ullet In LVM, we treat  $oldsymbol{z}_n$  as a random variable and assume a prior distribution  $p(oldsymbol{z}_n|\phi)$



This prior tells us what the value of  $\mathbf{z}_n$  is before we have seen the input  $\mathbf{x}_n$ 

Ultimately, we will compute the distribution of  $\mathbf{z}_n$  conditioned on the input  $\mathbf{x}_n$ 

For example, a D-dimensional Gaussian if  $\boldsymbol{x}_n \in \mathbb{R}^D$ 

- lacktriangle We will also assume a suitable conditional distribution  $p(x_n|z_n,\theta)$  for  $x_n$
- The form of  $p(\mathbf{z}_n|\phi)$  will depend on the nature of  $\mathbf{z}_n$ , e.g.,
  - If  $z_n$  is discrete with K possible values,  $p(z_n|\phi) = \text{multinoulli}(z_n|\pi)$
  - If  $\mathbf{z}_n \in \mathbb{R}^K$ ,  $p(\mathbf{z}_n | \phi) = \mathcal{N}(\mathbf{z}_n | \mu, \Sigma)$ , a K-dim Gaussian



### Why Direct MLE/MAP is Hard for LVMs?

- ullet Direct MLE/MAP of parameters  $( heta,\phi)=\Theta$  without estimating  $oldsymbol{z}_n$  is hard
- Reason: Given N observations  $x_n$ , n = 1, 2, ..., N, the MLE problem for  $\Theta$  will be

$$\underset{\Theta}{\operatorname{argmax}} \sum_{n=1}^{N} \log p(\boldsymbol{x}_{n}|\Theta) = \underset{\Theta}{\operatorname{argmax}} \sum_{n=1}^{N} \log \sum_{\boldsymbol{z}_{n}}^{N} p(\boldsymbol{x}_{n}, \boldsymbol{z}_{n}|\Theta)$$

Summing over all possible values  $\mathbf{z}_n$  can take (would be an integral instead of sum if  $\mathbf{z}_n$  is continuous

Gaussian Mixture Model (GMM).

■ For a mixture of K Gaussians,  $p(x_n|\Theta)$  will be

$$p(\boldsymbol{x}_n|\Theta) = \sum_{k=1}^K p(\boldsymbol{x}_n, \boldsymbol{z}_n = k|\Theta) = \sum_{k=1}^K p(\boldsymbol{z}_n = k|\phi)p(\boldsymbol{x}_n|\boldsymbol{z}_n = k, \theta) = \sum_{k=1}^K \pi_k \mathcal{N}(\boldsymbol{x}_n|\mu_k, \Sigma_k)$$

■ The MLE problem for GMM would be

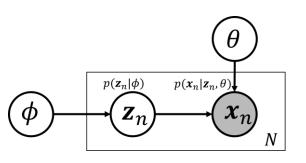
ALT-OPT or EM makes it simpler by using hard/soft guesses of  $z_n$ 's

$$\underset{\Theta}{\operatorname{argmax}} \sum_{n=1}^{N} \log \sum_{k=1}^{K} \pi_{k} \mathcal{N}(\mathbf{x}_{n} | \mu_{k}, \Sigma_{k}) \angle$$

The log of sum doesn't give us a simple expression; MLE can still be done using gradient based methods but updates will be complicated.

### How to Guess $z_n$ in an LVM?

- lacktriangle Note that  $oldsymbol{z}_n$  is a random variable with prior distribution  $p(oldsymbol{z}_n|\phi)$
- Can compute its conditional posterior (CP) distribution as



Called conditional posterior because it is conditioned on data as well as  $\Theta$  (assuming we have already estimated  $\Theta$ )

$$p(\mathbf{z}_n|\mathbf{x}_n,\Theta) = \frac{p(\mathbf{z}_n|\Theta)p(\mathbf{x}_n|\mathbf{z}_n,\Theta)}{p(\mathbf{x}_n|\Theta)} = \frac{p(\mathbf{z}_n|\phi)p(\mathbf{x}_n|\mathbf{z}_n,\theta)}{p(\mathbf{x}_n|\Theta)}$$

 $\blacksquare$  If we just want the single best (hard) guess of  $\mathbf{z}_n$  then that can be computed as

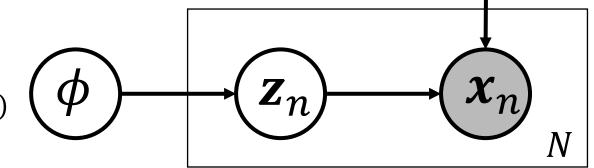
Used in ALT-OPT  $\hat{z}_n = \operatorname{argmax}_{z_n} p(z_n | x_n, \Theta) = \operatorname{argmax}_{z_n} p(z_n | \phi) p(x_n | z_n, \theta)$ 

Used in Expectation-Maximization (EM) algo for LVMs

- Otherwise, we can compute and use CP  $p(z_n|x_n,\Theta)$  to get a soft/probabilistic guess
  - lacktriangle Using the CP  $p(\mathbf{z}_n|\mathbf{x}_n,\Theta)$  we can compute quantities such as expectation of  $\mathbf{z}_n$
  - If  $p(z_n|\phi)$  and  $p(x_n|z_n,\theta)$  are conjugate to each other then CP  $p(z_n|x_n,\theta)$  is easy to compute
- lacktriangle Computing hard guess is usually easier but ignores the uncertainty in  $oldsymbol{z}_n$

## LVMs: Incomplete vs Complete Data Log Likelihood

- We can define two types of likelihoods for LVMs
  - Incomplete data log likelihood (ILL)  $\log p(X|\Theta)$
  - Complete data log likelihood (CLL)  $\log p(X, Z|\Theta)$



- lacktriangle Named so because we can think of latent  $oldsymbol{Z}$  "completing" the observed data  $oldsymbol{X}$
- Since Z is never observed (is latent), to estimate  $\Theta$  we must maximize the ILL

$$\underset{\Theta}{\operatorname{argmax}} \log p(\boldsymbol{X}|\Theta) = \underset{\Theta}{\operatorname{argmax}} \log \sum_{\boldsymbol{Z}} p(\boldsymbol{X},\boldsymbol{Z}|\Theta)$$

■ But since ILL maximization is hard (log of sum/integral over the unknown Z), we instead maximize the CLL  $p(X,Z|\Theta)$  using hard/soft guesses of Z

#### MLE for LVM

Also, we can use this idea to find MAP solution of  $\Theta$  if we want. Assume a prior  $p(\Theta)$  and simply add a  $\log p(\Theta)$  term to these objectives

Note that we aren't solving the original MLE problem  $\underset{\Omega}{\operatorname{argmax}} \log p(X|\Theta)$  anymore.

However, what we are solving now is still justifiable theoretically (will see later)



If using a hard guess

$$\Theta_{MLE} = \underset{\Theta}{\operatorname{argmax}} \log p(X, \widehat{Z} | \Theta)$$

If using a soft (probabilistic) guess

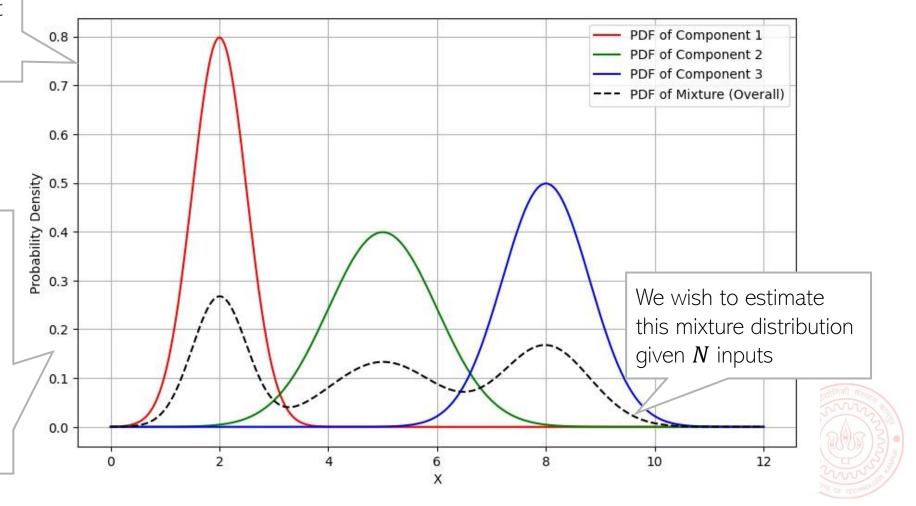
$$\Theta_{MLE} = \operatorname{argmax}_{\Theta} \mathbb{E}[\log p(X, Z|\Theta)]$$

- lacktriangle In LVMs, hard and soft guesses of  $oldsymbol{Z}$  would depend on  $oldsymbol{\Theta}$  (since  $oldsymbol{Z}$  and  $oldsymbol{\Theta}$  are coupled)
- lacktriangledown Thus we need a procedure which alternates between estimating  $oldsymbol{Z}$  and estimating  $oldsymbol{\Theta}$

#### An LVM: Gaussian Mixture Model

Inputs are assumed generated from a mixture of Gaussians. But we don't know which input was generated by which Gaussian

If we knew which input came from which Gaussian (akin to knowing their true labels), the problem is easy — simply estimate each Gaussian using the inputs that came from that Gaussian (just like generative classification)



### Detour: MLE for Generative Classification

- $\blacksquare$  Assume a K class generative classification model with Gaussian class-conditionals
- Assume class k=1,2,...,K is modeled by a Gaussian with mean  $\mu_k$  and cov matrix  $\Sigma_k$
- lacksquare Can assume label  $z_n$  to be one-hot and then  $z_{nk}=1$  if  $z_n=k$ , and  $z_{nk}=0$ , o/w
  - lacktriangle Note: For each label, using notation  $z_n$  instead of  $y_n$
- Assuming class marginal  $p(z_n = k) = \pi_k$ , the model's params  $\Theta = \{\pi_k, \mu_k, \Sigma_k\}_{k=1}^K$
- The MLE objective  $\log p(X, Z|\Theta)$  is (will provide a note for the proof)

$$\Theta_{MLE} = \operatorname{argmax}_{\{\pi_k, \mu_k, \Sigma_k\}} \sum_{k=1}^{K} \sum_{n=1}^{K} z_{nk} [\log \pi_k + \log \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)]$$

$$\hat{\pi}_{k} = \frac{1}{N} \sum_{n=1}^{N} z_{nk} \qquad \hat{\mu}_{k} = \frac{1}{N_{k}} \sum_{n=1}^{N} z_{nk} x_{n} \quad \hat{\Sigma}_{k} = \frac{1}{N_{k}} \sum_{n=1}^{N} z_{nk} (x_{n} - \hat{\mu}_{k}) (x_{n} - \hat{\mu}_{k})^{\mathsf{T}}$$

Same as  $\frac{N_k}{N_k}$  | Same as  $\frac{1}{N_k} \sum_{n:z_n=k}^N x_n$  | Same as  $\frac{1}{N_k} \sum_{n:z_n=k}^N (x_n - \hat{\mu}_k) (x_n - \hat{\mu}_k)^{\mathsf{T}}$ 

### MLE for GMM: Using Guesses of $z_n$

Will have the exact same form for the expression of MLE objective as generative classification with Gaussian classconditionals (except  $z_n$  is unknown)

• Using a hard guess  $\hat{z}_n = \operatorname{argmax}_{z_n} p(z_n | x_n, \Theta)$ , the MLE problem for GMM

Log likelihood of  $\Theta$  w.r.t. data  $\boldsymbol{X}$  and hard guesses  $\hat{Z}$  of cluster ids

Assuming  $x_n$  given  $\underline{z_n}$  and  $\underline{\Theta}$  are i.i.d.

$$\Theta_{MLE} = \underset{\Theta}{\operatorname{argmax}} \log p(\boldsymbol{X}, \widehat{\boldsymbol{Z}} | \Theta) = \operatorname{argmax}_{\Theta} \sum_{n=1}^{N} \sum_{k=1}^{K} \hat{\boldsymbol{z}}_{nk} [\log \pi_k + \log \mathcal{N}(\boldsymbol{x}_n | \mu_k, \Sigma_k)]$$

• Using a soft guess  $\mathbb{E}[z_n]$ , the MLE problem for GMM

Expected log likelihood of  $\boldsymbol{\Theta}$  w.r.t. data  $\boldsymbol{X}$  and  $\boldsymbol{Z}$ 

$$\Theta_{MLE} = \underset{\Theta}{\operatorname{argmax}} \mathbb{E}[\log p(\boldsymbol{X}, \boldsymbol{Z}|\Theta)] = \underset{\Theta}{\operatorname{argmax}} \sum_{n=1}^{N} \sum_{k=1}^{K} \mathbb{E}[\boldsymbol{z}_{nk}][\log \pi_k + \log \mathcal{N}(\boldsymbol{x}_n|\mu_k, \Sigma_k)]$$

 $z_{nk}$  appears at only one place in the log likelihood expression so easily replaced by expectation of  $z_{nk}$  w.r.t the CP  $p(\mathbf{z}_n|\mathbf{x}_n,\Theta)$ 

$$\mathbb{E}[z_{nk}][\log \pi_k + \log \mathcal{N}(x_n|\mu_k, \Sigma_k)]$$

- In both cases, the MLE solution for  $\Theta = \{\pi_k, \mu_k, \Sigma_k\}_{k=1}^K$  will be identical to that of generative classification with Gaussian class cond with  $z_{nk}$  replaced by  $\hat{z}_{nk}$  or  $\mathbb{E}[z_{nk}]$ 
  - Case 1 solved using ALT-OPT alternating b/w estimating  $\Theta_{MLE}$  and  $\widehat{Z}$
  - Case 2 solved using Expectation Maximization (EM) alternating b/w estimating  $\Theta_{MLE}$  and  $\mathbb{E}[Z]$

#### ALT-OPT for GMM

- lacktriangle We will assume we have a "hard" (most probable) guess of  $z_n$ , say  $\hat{z}_n$
- ALT-OPT which maximizes  $\log p(X, \widehat{Z} \mid \Theta)$  would look like this
  - lacktriangle Initialize  $\Theta = \{\pi_k, \mu_k, \Sigma_k\}_{k=1}^K$  as  $\widehat{\Theta}$

Proportional to prior prob times likelihood, i.e.,  $p(z_n = k | \widehat{\Theta}) p(x_n | z_n = k, \widehat{\Theta}) = \widehat{\pi}_k \mathcal{N}(x_n | \widehat{\mu}_k, \widehat{\Sigma}_k)$ 

- Repeat the following until convergence
  - lacktriangle For each n, compute most probable value (our best guess) of  $z_n$  as

Posterior probability of point  $x_n$  belonging to cluster k, given current  $\Theta$ 

$$\hat{z}_n = \operatorname{argmax}_{k=1,2,\dots,K} p(z_n = k | \widehat{\Theta}, \mathbf{x}_n)$$

• Solve MLE problem for  $\Theta$  using most probable  $z_n$ 's

$$\widehat{\Theta} = \operatorname{argmax}_{\Theta} \sum_{n=1}^{N} \sum_{k=1}^{K} \widehat{z}_{nk} [\log \pi_k + \log \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)]$$

$$\hat{\pi}_k = \frac{1}{N} \sum_{n=1}^{N} \hat{z}_{nk}$$

$$\hat{\mu}_k = \frac{1}{N_k} \sum_{n=1}^{N} \hat{z}_{nk} x_n$$

$$\hat{\Sigma}_k = \frac{1}{N_k} \sum_{n=1}^{N} \hat{z}_{nk} (x_n - \hat{\mu}_k) (x_n - \hat{\mu}_k)^{\mathsf{T}}$$



### Expectation-Maximization (EM) for GMM

■ EM finds  $\Theta_{MLE}$  by maximizing  $\mathbb{E}[\log p(X, Z|\Theta)]$ 

Why w.r.t. this distribution? Will see justification in a bit

each input  $x_n$ 

- Note: Expectation will be w.r.t. the CP of Z, i.e.,  $p(Z|X,\Theta)$
- The EM algorithm for GMM operates as follows
  - Initialize  $\Theta = \{\pi_k, \mu_k, \Sigma_k\}_{k=1}^K$  as  $\widehat{\Theta}$
  - Repeat until convergence
    - Compute CP  $p(Z|X,\widehat{\Theta})$  using current estimate of  $\Theta$ . Since obs are i.i.d, compute for each n (and for k=1,2,...K)

Same as  $p(z_{nk} = 1 | x_n, \widehat{\Theta})$ , just a different notation

$$p(\mathbf{z}_n = k | \mathbf{x}_n, \widehat{\Theta}) \propto p(\mathbf{z}_n = k | \widehat{\Theta}) p(\mathbf{x}_n | \mathbf{z}_n = k, \widehat{\Theta}) = \widehat{\pi}_k \mathcal{N}(\mathbf{x}_n | \widehat{\mu}_k, \widehat{\Sigma}_k)$$

■ Update  $\Theta$  by maximizing  $\mathbb{E}[\log p(X, Z|\Theta)]$ 

$$\frac{\sum_{\ell=1}^{K} \widehat{\pi}_{\ell} \mathcal{N}(x_{n} | \widehat{\mu}_{\ell}, \widehat{\Sigma}_{\ell})}{\sum_{\ell=1}^{K} \widehat{\pi}_{\ell} \mathcal{N}(x_{n} | \widehat{\mu}_{\ell}, \widehat{\Sigma}_{\ell})}$$

Note that EM for GMM also gives a soft clustering  $z_n = [\gamma_{n1}, \gamma_{n2}, \dots, \gamma_{nK}]$  for

$$\widehat{\Theta} = \operatorname{argmax}_{\Theta} \mathbb{E}_{p(\boldsymbol{Z}|\boldsymbol{X},\widehat{\Theta})}[\log p(\boldsymbol{X},\boldsymbol{Z}|\Theta)] = \operatorname{argmax}_{\Theta} \sum_{n=1}^{N} \sum_{k=1}^{K} \mathbb{E}[\boldsymbol{z}_{nk}][\log \pi_k + \log \mathcal{N}(\boldsymbol{x}_n|\mu_k,\Sigma_k)]$$

$$\sum_{n=1}^{N} \sum_{k=1}^{K} \mathbb{E}[z_{nk}] [\log \pi_k + \log \mathcal{N}($$

Solution has a similar form as ALT-OPT (or gen. class.), except we now have the expectation of  $z_{nk}$  being used

$$\hat{\pi}_k = \frac{1}{N} \sum_{n=1}^N \mathbb{E}[z_{nk}] \hat{\mu}_k = \frac{1}{N_k} \sum_{n=1}^N \mathbb{E}[z_{nk}] x_n$$

$$\hat{\Sigma}_k = \frac{1}{N_k} \sum_{n=1}^N \mathbb{E}[z_{nk}] (x_n - \hat{\mu}_k) (x_n - \hat{\mu}_k)^{\mathsf{T}}$$

$$\mathbb{E}[z_{nk}] = \gamma_{nk} = 0 \times p(z_{nk} = 0 | x_n, \widehat{\Theta}) + 1 \times p(z_{nk} = 1 | x_n, \widehat{\Theta})$$

$$= p(z_{nk} = 1 | x_n, \widehat{\Theta})$$
Posterior probability of  $x_n$  belonging to  $k^{th}$  cluster

### EM for GMM (Contd)

#### EM for Gaussian Mixture Model

• Initialize  $\Theta = \{\pi_k, \mu_k, \Sigma_k\}_{k=1}^K$  as  $\Theta^{(0)}$ , set t = 1

2 E step: compute the expectation of each  $z_n$  (we need it in M step)

Soft K-means, which are more of a heuristic to get soft-clustering, also gave us probabilities but didn't account for cluster shapes or fraction of points in each cluster

Accounts for fraction of points in each cluster 
$$\mathbb{E}[z_{nk}^{(t)}] = \gamma_{nk}^{(t)} = \frac{\pi_k^{(t-1)} \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_\ell^{(t-1)}, \boldsymbol{\Sigma}_\ell^{(t-1)})}{\sum_{\ell=1}^K \pi_\ell^{(t-1)} \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_\ell^{(t-1)}, \boldsymbol{\Sigma}_\ell^{(t-1)})} \quad \forall n, k$$
 Accounts for cluster shapes (since each cluster is a Gaussian

3 Given "responsibilities"  $\gamma_{nk} = \mathbb{E}[z_{nk}]$ , and  $N_k = \sum_{n=1}^N \gamma_{nk}$ , re-estimate  $\Theta$  via MLE

$$\mu_k^{(t)} = \frac{1}{N_k} \sum_{n=1}^N \gamma_{nk}^{(t)} x_n$$
 Effective number of points in the  $k^{th}$  cluster

M-step: 
$$\boldsymbol{\Sigma}_{k}^{(t)} = \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma_{nk}^{(t)} (\boldsymbol{x}_{n} - \boldsymbol{\mu}_{k}^{(t)}) (\boldsymbol{x}_{n} - \boldsymbol{\mu}_{k}^{(t)})^{\top}$$

$$\boldsymbol{\pi}_{k}^{(t)} = \frac{N_{k}}{N_{k}}$$

• Set t = t + 1 and go to step 2 if not yet converged

