

# Code Generation for MDHs

Our OpenCL implementation is generated as **parametrized in performance-critical parameters** (a.k.a. tuning parameters):

No.	Name	Description
1	NUM_WG <sup>&lt;i&gt;</sup>	number of Work-Groups
2	NUM_WI <sup>&lt;i&gt;</sup>	number of Work-Items
3	LT_SIZE <sup>&lt;i&gt;</sup>	local tile size
4	PT_SIZE <sup>&lt;i&gt;</sup>	private tile size
5	MEM_INP <sup>&lt;LYR,b,i&gt;</sup>	memory regions for caching input
6	MEM_RES <sup>&lt;LYR,b,i&gt;</sup>	memory regions for comp. results
7	$\sigma_{\text{arr} \rightarrow \text{ocl}}^{\langle \text{LYR} \rangle}$	mapping array to OpenCL dimensions
8	$\sigma_{\text{buff-do}}^{\langle \text{LYR},b \rangle}$	buffer dimension order
9	$\sigma_{\text{mdh-do}}^{\langle \text{LYR} \rangle}$	MDH dimension order
10	CMB_RES	layer to combine results on

**All parameters are chosen as optimized for:**

→ *abstract device model;*  
→ *arbitrary MDH;*  
→ *arbitrary input/output characteristics.*

<i> → dimension ; <LYR> → layer ; <b> → buffer