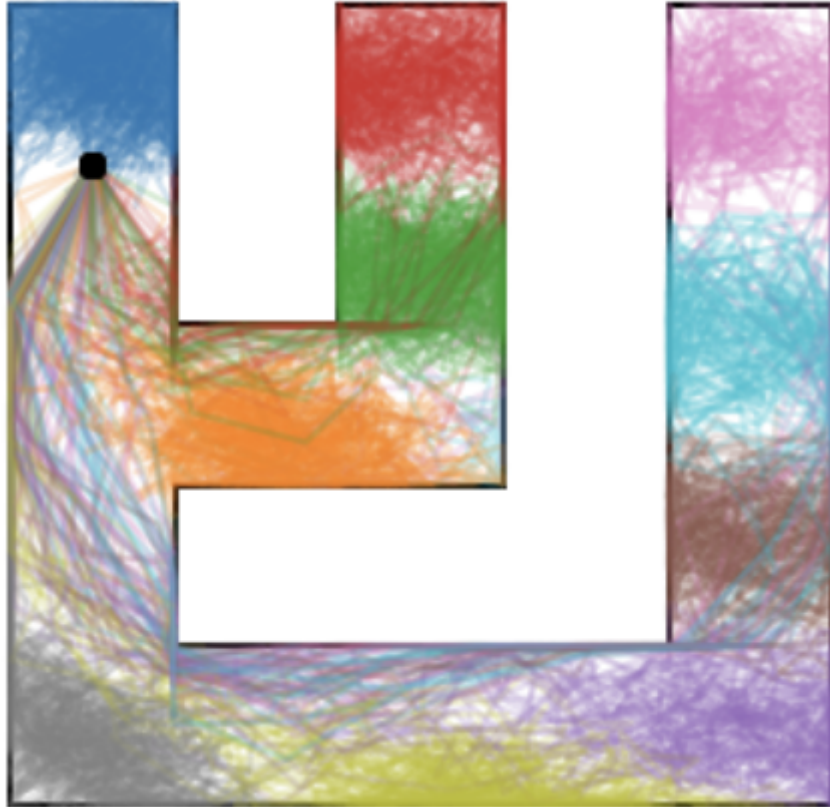


The results of experiments

Maze Environment



URLB Tasks

Task	combination-based method
quadruped_jump	
quadruped_run	
quadruped_stand	
quadruped_walk	