





There are two obstacles in the track .The robot has to navigate around the RED obstacle and reach the other end of track.If the robot goes into the lane of the green obstacle ,the robot must come in front of the obstacle and go back in the same path it came.If the robot fails to enter the path of the GREEN obstacle,points will be deducted.Touching any of the obstacles will result in point deduction.No color detection needed for the obstacles.

