

Graph Algorithms - Lecture 13

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Tree decompositions

- Tree width
- Small tree decompositions
- Tree decomposition properties
- Rooted tree decomposition
- Applications

Tree decomposition - Definition

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Definition

A tree decomposition of a graph $G = (V, E)$ is a pair $\mathcal{T} = (T, \{V_t : t \in T\})$, where T is a tree and $\{V_t : t \in V(T)\}$ is a family of subsets of vertices of G , $V_t \subseteq V$ for every node $t \in T$ such that:

- (Node coverage) $V = \bigcup_{t \in V(T)} V_t$;
- (Edge coverage) For every $e \in E$, both endpoints of e are contained in V_t for some $t \in V(T)$.
- (Coherence) Let t_1, t_2, t_3 be three nodes in T such that t_2 lies on the path between t_1 and t_3 in T . Then, if $v \in V$ belongs to both V_{t_1} and V_{t_3} , v must also belong to V_{t_2} .

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Tree-width - Definition

Remarks

The coherence can be rephrased like follows

- (Coherence') Let $t_1, t_2, t_3 \in V(T)$ s. t. t_2 belongs to the path from t_1 to t_3 in T . Then $V_{t_1} \cap V_{t_3} \subseteq V_{t_2}$.
- (Coherence'') For every $x \in V$, the subgraph of T induced by $\{t \in V(T) : x \in V_t\}$ is (a subtree of T) connected.

The sets V_t are called the **bags** of the corresponding tree decomposition.

Definition

Let $\mathcal{T} = (T, \{V_t : t \in T\})$ be a tree decomposition of G , the **width** of \mathcal{T} is

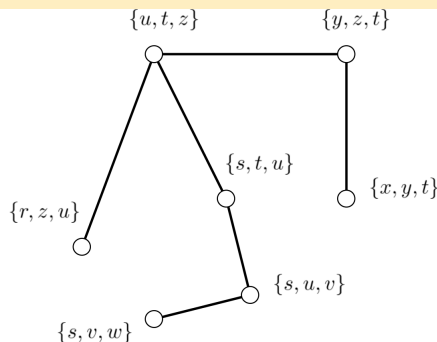
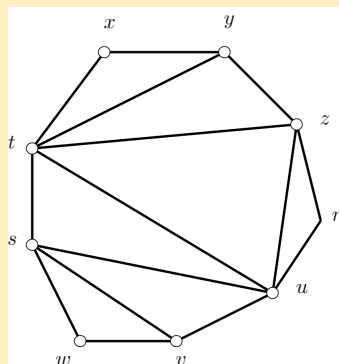
$$\text{width}(\mathcal{T}) = \max_{t \in V(T)} (|V_t| - 1).$$

Tree-width - Definition

Definition

The **tree-width** of a graph G , is the minimum width of a tree decomposition of G :

$$tw(G) = \min \{ width(\mathcal{T}) : \mathcal{T} \text{ tree decomposition of } G \}.$$



Remark

$tw(G) = 0$ if and only if $E(G) = \emptyset$.

Proposition

If G is a forest with $E(G) \neq \emptyset$, then $tw(G) = 1$.

Proof. $tw(G) \geq 1$ by the above remark. If G is a tree, then

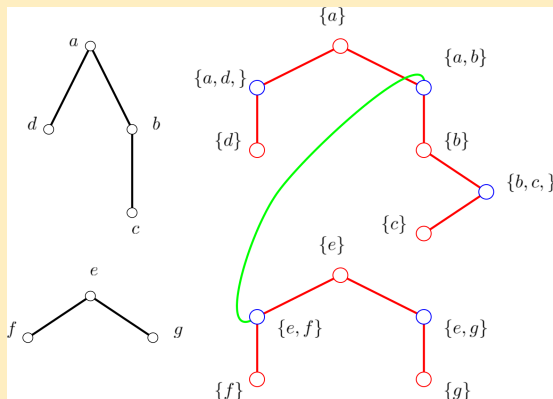
- let T be obtained from G by renaming t_v each vertex $v \in V(G)$,
- insert on each edge $t_u t_v$ ($uv \in E(G)$) a new vertex t_{uv} ,
- set $V_{t_u} = \{u\}$ for all t_u associated to $u \in V(G)$, and $V_{t_{uv}} = \{u, v\}$ for all $t_{uv} \in V(T)$ associated to $uv \in E(G)$.
- $(T, \{V_t : t \in V(T)\})$ is a tree decomposition of G with width 1.

Tree-width

Proof (cont'd). A tree decomposition of a forest with k components can be obtained by adding $k - 1$ arbitrary edges to tree decompositions for the components (without creating cycles).



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Definition

A tree decomposition, $\mathcal{T} = (T, \{V_t : t \in V(T)\})$, is **small** if there are no distinct vertices $t_1, t_2 \in V(T)$ such that $V_{t_1} \subseteq V_{t_2}$.

Proposition

Given a tree decomposition of G , a small tree decomposition of G with the same width can be constructed in polynomial time.

Proof. Let $\mathcal{T} = (T, \{V_t : t \in V(T)\})$ be a tree decomposition of G with $V_{t_1} \subseteq V_{t_2}$ for $t_1, t_2 \in V(T)$, $t_1 \neq t_2$. We can suppose that $t_1 t_2 \in E(T)$ (otherwise, we find adjacent nodes with this property, by considering a path from t_1 to t_2).

Contracting $t_1 t_2$ into a new node t_{12} with $V_{t_{12}} = V_{t_2}$, gives a smaller tree decomposition of G (it contains less pairs of vertices (t'_1, t'_2) with $V_{t'_1} \subseteq V_{t'_2}$).

Small tree decompositions

Proof (cont'd). Repeat this reduction until a small tree decomposition is obtained



Proposition

If $\mathcal{T} = (T, \{V_t : t \in V(T)\})$ is a small tree decomposition of G , then $|T| \leq |G|$.

Proof. By induction on $n = |G|$. If $n = 1$, then $|T| = 1$.

In the inductive step, for $n \geq 2$, consider a leaf t_1 of T with neighbor t_2 . $(T - t_1, \{V_t : t \in V(T - t_1)\})$ is a small tree decomposition of $G' = G \setminus (V_{t_1} \setminus V_{t_2})$. By induction hypothesis $|T - t_1| \leq |G'|$, therefore

$$|T| = |T - t_1| + 1 \leq |G'| + 1 \leq |G|.$$



Remarks

- If the graph H is obtained from G by contracting an edge uv into z , then $tw(H) \leq tw(G)$: in a tree decomposition of G , insert z in every bag containing u or v , and then remove u and v from every bag to obtain a tree decomposition of H .
- If H is a subgraph of G , then $tw(H) \leq tw(G)$.

Definition

H is a **minor** of a graph G if it can be obtained from G by iteratively deleting and contracting edges.

Corollary

If H is a minor of a graph G , then $tw(H) \leq tw(G)$.

Proof. Using the above remarks.



Tree-width

Let $TW_k = \{G : tw(G) \leq k\}$.

TW (Tree-Width - decision version)

Instance: G a graph and $k \in \mathbb{N}$.

Question: $G \in TW_k$?

Theorem

Tree-Width (decision version) problem is NP-complete.

Proof. Omitted.

Tree-width is FPT (fixed-parameter tractable)

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Lemma

For every positive integer k , TW_k is minor closed.

Theorem

(Bodlaender) For every fixed k , the problem of determining whether or not $G \in TW_k$ can be solved in $\mathcal{O}(f(k) \cdot n)$ time.

Proofs. Omitted. ($f(k)$ is exponential in k .)

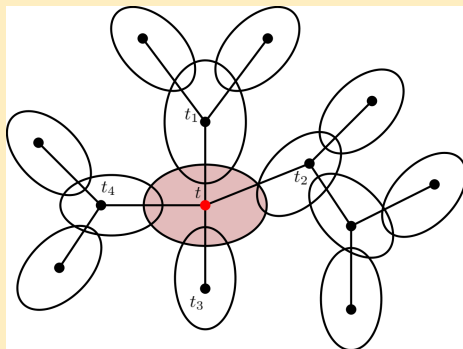
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Notation: Let $\mathcal{T} = (T, \{V_t : t \in V(T)\})$ be a tree decomposition of G . Then, if T' is a subgraph of T , $G_{T'}$ denotes the subgraph of G induced by the set of vertices $\bigcup_{t \in V(T')} V_t$.

Tree decomposition properties

Theorem

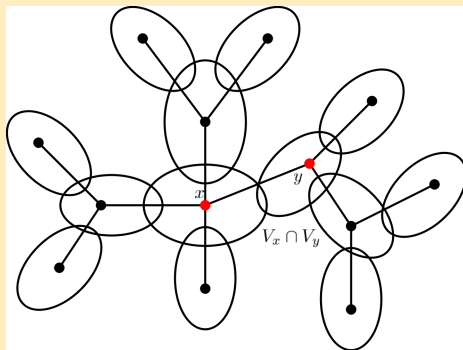
(Node separation property.) Suppose $T - t$ has connected components T_1, T_2, \dots, T_p . Then the subgraphs $G_{T_1} - V_t, G_{T_2} - V_t, \dots, G_{T_p} - V_t$ have no vertices in common and there are no edges between them.



Tree decomposition properties

Theorem

(Edge separation property.) Let X and Y be the two connected components of T after the deletion of edge $xy \in E(T)$. Then, deleting $V_x \cap V_y$ disconnects G into two subgraphs $H_X = G_X - V_x \cap V_y$ and $H_Y = G_Y - V_x \cap V_y$. That is H_X and H_Y share no vertices and there is no edge in G with one endpoint in H_X and the other in H_Y .



Rooted tree decomposition

Definition

A **rooted tree decomposition** of G is a tree decomposition $\mathcal{T} = (T, \{V_t : t \in V(T)\})$ of G , where some vertex r of T is declared to be the root.

Notations: let t be a vertex in a rooted tree decomposition $\mathcal{T} = (T, \{V_t : t \in V(T)\})$.

- T_t is the subtree of T rooted at t .
- $G[t]$ is the subgraph of G induced by the vertices in $\bigcup_{x \in V(T_t)} V_x$ (i.e., $G[t] = G_{T_t}$).

- Recall: a p -vertex coloring of a graph $G = (V, E)$ is a function $c : V \rightarrow \{1, 2, \dots, p\}$ such that for all $uv \in E$, $c(u) \neq c(v)$.
- Let H' and H'' be two subgraphs of G , with p -colorings c' and c'' , respectively. c'' is c' -compatible if for all $v \in V(H') \cap V(H'')$, $c'(v) = c''(v)$.
- Let $\mathcal{T} = (T, \{V_t : t \in V(T)\})$ a rooted tree decompositions of G . For every $t \in T$ and every p -coloring c of G_t , define

$$Prev_t(c) = \begin{cases} 1, & \text{if } G[t] \text{ has an } c\text{-compatible } p\text{-coloring } \bar{c} \\ 0, & \text{otherwise.} \end{cases}$$

Proposition

$Prev_u(c) = 1$ if and only if for all children v of u , there exists a c -compatible coloring \bar{c} of G_v with $Prev_v(\bar{c}) = 1$

Applications - Vertex coloring

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Proof. “ \implies ” If γ is a c -compatible coloring of $G[u]$, since G_v is a subgraph of $G[u]$, then the restriction of γ to G_v gives the required coloring \bar{c} .

“ \impliedby ” Suppose that u has exactly two children v and w , and we have two c -compatible colorings \bar{c}' and \bar{c}'' , respectively (the proof is similar for more children).

Since $(T, \{V_t : t \in V(T)\})$ is a tree decomposition, $V(G[v]) \cap V(G[w]) \subseteq V_u$, so \bar{c}' is \bar{c}'' -compatible.

Combining \bar{c}' and \bar{c}'' gives $\bar{c} : V(G[u]) \rightarrow \{1, 2, \dots, p\}$. Since $(T, \{V_t : t \in V(T)\})$ is a tree decomposition, there are no edges $xy \in E(G)$ with $x \in V(G[v]) - V_u$ and $y \in V(G[w]) - V_u$, so \bar{c} is a p -coloring of $G[u]$.

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Theorem

If G , a graph of order n , has a small tree decomposition $(T, \{V_t : t \in V(T)\})$ of width w , then we can decide if G is p -colorable in $\mathcal{O}(p^{w+1} \cdot n^{\mathcal{O}(1)})$ time complexity.

Proof. Transform $(T, \{V_t : t \in V(T)\})$ in a rooted tree decomposition (r is the root). For every $v \in V(T)$ and every p -coloring c of G_v , we compute $Prev_v(c)$: start at the leaves of T , and use the above proposition for the other nodes, in the right order.

$G = G[r]$ is p -colorable if and only if $Prev_r(c) = 1$ for some c . Testing whether c is a G_v coloring and computing $Prev_v(c)$ can be done in polynomial time $\mathcal{O}(n^{\mathcal{O}(1)})$, so the total time complexity is mainly determined by the number of candidates for c , which is $p^{|V_v|}$.

Complexity: $|V(T)| \cdot p^{w+1} \cdot n^{\mathcal{O}(1)} = \mathcal{O}(p^{w+1} \cdot n^{\mathcal{O}(1)})$.



Other applications - Similar approaches (more advanced dynamic programming)

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Theorem

If G , a graph of order n , has a small tree decomposition $(T, \{V_t : t \in V(T)\})$ of width w , the size of a minimum vertex cover of G can be computed in $\mathcal{O}(2^{w+1} \cdot n^{\mathcal{O}(1)})$ time complexity.

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Theorem

If G , a vertex-weighted graph of order n , has a small tree decomposition $(T, \{V_t : t \in V(T)\})$ of width w , a maximum stable set of G can be computed in $\mathcal{O}(4^{w+1} \cdot w \cdot n)$ time complexity.

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