

# Alt F Trio

## UFPB

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16 de agosto de 2024

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# 1 Sorting

## 1.1 Bubble Sort

```
// compara es:  $C(n) = O(n^2)$ 
// trocas:  $T(n) = O(n^2)$ 
// adaptativo:  $O(n)$  quando vetor est parcialmente ordenado
```

```
// Vantagens:
// algoritmo est vel
// simples
```

```
// Desvantagens:
// n o adapt vel
// muitas trocas
```

```
a33 void bubbleSort(int *ar, int n){
8f9     int i, aux;
011     bool troca;

016     do {
6fc         troca = false;
f50         for(int i = 0; i < n - 1; i++){
d7e             if(ar[i + 1] < ar[i]){
194                 aux = ar[i + 1];
89d                 ar[i + 1] = ar[i];
78a                 ar[i] = aux;
9c0                 troca = true;
9db             }
5df         }

51a     } while(troca);

505     return;
13c }
```

## 1.2 Inserction Sort

```
// compara es  $C(n) = O(n^2)$ 
// trocas  $T(n) = O(n^2)$ 
// adaptativo  $O(n)$  quando vetor est parcialmente ordenado
```

```
// Vantagens:
// bom quando o vetor est "quase" ordenado
// um bom m todo quando se deseja adicionar poucos itens a um
// arquivo ordenado, pois o custo linear
```

```
// Desvantagens:
// custo de compara es  $O(n^2)$ 
// custo de movimenta es  $O(n^2)$ 
```

```
492 void insertionSort(int *ar, int n){
141     int i, j , aux;
b4c     for(i = 1; i < n; i++){
28a         aux = ar[i];
37f         j = i - 1;
11c         while(j >= 0 && aux < ar[j]){
aa0             ar[j + 1] = ar[j];
237             j--;
10f         }
a9e         ar[j + 1] = aux;
64f     }
505     return;
71b }
```

## 1.3 Quick Sort

```
7fb void troca(int *ar, int i, int j){
133     int aux;
28a     aux = ar[i];
76b     ar[i] = ar[j];
b32     ar[j] = aux;
505     return;
d34 }
```

```
ded int particao(int *ar, int l, int r){
71d     int i = 0, fim = 0;
e7e     fim = l;
f5a     for(i = l + 1; i <= r; i++){
485         if(ar[i] < ar[l]){
83e             fim = fim + 1;
ebf             troca(ar, fim, i);
1dc         }
c41     }
a6b     troca(ar, l, fim);
645     return fim;
504 }
```

```

35a void quickSort(int *ar, int l, int r){
181     int i = 0;

572     if(l >= r) return;

073     i = particao(ar, l, r);
8cf     quickSort(ar, l, i - 1);
167     quickSort(ar, i + 1, r);

505     return;
d70 }

```

## 1.4 Selection Sort

```

// compara es  $C(n) = O(n^2)$ 
// trocas  $T(n) = O(n)$ 

// Vantagens:
// bom quando a opera o de trocar for muito cara

// Desvantagens:
// n o adapt vel
// n o est vel

475 void selectionSort(int *ar, int n){
ab3     int i, j;
15b     int menor, indexMenor;

3f3     for(i = 0; i < n; i++){
f18         menor = ar[i];
776         indexMenor = i;
8f7         for(j = i + 1; j < n; j++){
c69             if(ar[j] < menor){
4eb                 indexMenor = j;
6b5                 menor = ar[j];
5ee             }
bfb         }
fa5         ar[indexMenor] = ar[i];
b2e         ar[i] = menor;
292     }
505     return;
6cd }

```

## 2 DP

### 2.1 Mochila

```

7df int solve(int n, int C, vector<pair<int, int>> &v) {
11e     int res = 0;
0f7     for(int mask = 1, l = 1 << n; mask < l; mask++) {
0bf         int W = 0, V = 0;
04b         for(int i = 0, p = 1; i < n; i++, p <=<= 1) {
b81             if(mask & p) {
c90                 W += v[i].first;
1ec                 V += v[i].second;
8a9             }
c0e         }
806         if(W <= C) {
ff0             res = max(res, V);
f87         }
12c     }
b50     return res;
5e3 }

e8d int main() {
4ad     int n, C;
6b9     cin >> n >> C;
6f7     vector<pair<int, int>> v(n); // (w, v)
385     for(int i = 0; i < n; i++) cin >> v[i].first >> v[i].second;
044     cout << solve(n, C, v) << endl;
bb3     return 0;
ec5 }

```

## 3 Matematica

### 3.1 Algoritmo de Euclides

```

// Time Complexity:  $O(\log \min(a,b))$ 
// Auxiliary Space:  $O(\log \min(a,b))$ 

eea int recursive_gcd(int a, int b){
650     if(b == 0) return a;
8c3     else return recursive_gcd(b, a % b);
bd9 }

```

```

ba4 int non_recursive_gcd(int a, int b){
1b4     while(b){
cae         a %= b;
257         swap(a, b);
22e     }
3f5     return a;
7c3 }

```

## 3.2 Algoritmo de Euclides Otimizado

```

// is an optimization to the normal Euclidean algorithm
// The slow part of the normal algorithm are the modulo operations.
// Modulo operations  $O(1)$ , but are a lot slower than simpler
    operations like addition, subtraction or bitwise operations.

```

```

bce int binary_gcd(int a, int b) {
206     if(!a || !b) return a | b;
308     unsigned shift = __builtin_ctz(a | b);
2db     a >>= __builtin_ctz(a);
016     do {
cfd         b >>= __builtin_ctz(b);
f78         if (a > b)
257             swap(a, b);
064         b -= a;
788     } while(b);
c09     return a << shift;
232 }

```

## 3.3 Crivo de Erastotenes

```

// Time Complexity:  $O(n \log \log n)$ 
// Auxiliary Space:  $O(n)$ 
// Find primes in range [2, n]

```

```

705 vector<int> sieve(int n){
e6e     vector<int> is_prime(n + 1, true);
19e     is_prime[0] = is_prime[1] = false;

bc4     for(int i = 2; (long long)i * i <= n; i++){
4a3         if(is_prime[i]){
985             for(int j = i * i; j <= n; j += i){
db3                 is_prime[j] = false;
f80             }
b3f         }

```

```

26e     }
054     return is_prime;
0c7 }

```

## 3.4 Euclides Extendido

```

// Teorema de B zout
// Time Complexity:  $O(\log N)$ 
// Auxiliary Space:  $O(\log N)$ 

```

```

// ax + by = gcd(a, b)
// gcd(a, b) = gcd(b % a, a) = (b % a) * x1 + a * y1
// ax + by = (b - (b/a) * a) * x1 + a * y1
// ax + by = a(y1 - (b/a) * x1) + b * x1
// x = y1 - (b/a) * x1
// y = x1

```

```

e4b int gcdExtended(int a, int b, int *x, int *y) {
220     if(a == 0){
b9d         *x = 0;
288         *y = 1;
73f         return b;
420     }

608     int x1, y1; // To store results of recursive call
c2d     int gcd = gcdExtended(b%a, a, &x1, &y1);

        // Update x and y using results of
        // recursive call
98c     *x = y1 - (b/a) * x1;
9bf     *y = x1;

e06     return gcd;
059 }

```

## 3.5 Euler's totient function

```

// Time Complexity:  $O(\sqrt{n})$ 
3fc int phi(int n){
efa     int result = n;
2ed     for(int i = 2; i * i <= n; i++){
c06         if(n % i == 0){
b52             int count = 0;
4cd             while(n % i == 0){

```

```

135         n /= i;
157     }
21c     result -= result / i;
850 }
741 }
726 if(n > 1) result -= result / n;
dc8 return result;
8e9 }

// Euler's totient function 1 to n in O(nlog(log(n)))
// use the same ideas as the Sieve of Eratosthenes
429 vector<int> phi_1_to_n(int n){
675     vector<int> vec(n + 1);
4e3     for(int i = 0; i <= n; i++){
716         vec[i] = i;
508     for(int i = 2; i <= n; i++){
10b         if(vec[i] == i){
c6c             for(int j = i; j <= n; j += i){
816                 vec[j] -= vec[j] / i;
502             }
196         }
352     }
9d8     return vec;
eea }

```

### 3.6 Exponenciacao Rapida

```

// result = a^b % m
// Time Complexity = O(log b)

d95 ll binpow(ll a, ll b, ll m){
df2     ll result = 1;
63a     while(b > 0){
00f         if(b & 1) result *= a % m;
26c         a *= a % m;
1b4         b >>= 1;
4ea     }
dc8     return result;
6e8 }

```

### 3.7 Inversa Modular

// The exact time complexity of the this recursion is not known.

```

// It's is somewhere between 0 (logm / loglogm) and O(m^(1/3 - 2/177
+ e))
// demo:
// m prime and a, r < m -> exist a_inv and r_inv
// m = k*a + r
// 0      k*a + r (mod m)
// -k*a    r (mod m)
// -k      r*a_inv (mod m)
// a_inv   k*r_inv (mod m)

a18 int inv(int a, int m){
033     return a <= 1 ? a : m - (long long)(m / a) * inv(m % a, m) % m;
5fc }

// Binary Exponentiation method
// O(log m)
// if a and m are relatively prime and m is prime
// power(a, m - 2)      a_inv (mod m)
951 long long binpow(long long a, long long b){
3fe     long long result = 1;
63a     while(b > 0){
427         if(b & 1) result *= a;
70c         a *= a;
1b4         b >>= 1;
aa4     }
dc8     return result;
4ad }

// precompute the inverse for every number in the range [1, m- 1] in
O(m)
e8d int main(){
7f4     int m = 1000000007;
641     int invArray[m];
7d1     invArray[1] = 1;
92c     for(int a = 2; a < m; a++){
b75         invArray[a] = m - (long long)(m / a) * invArray[m % a] % m;
463     }
c20 }

```

### 3.8 Kadane

```

// Calcula o subarray com maior soma em O(n)

a5c int kadane(vector<int> &vec) {
0b3     int mx = INT_MIN;
6f5     int curr = 0;

```

```

bdb     for (int x : vec) {
ad4         curr += x;
e95         mx = max(mx, curr);
f67         curr = max(curr, 0);
9d6     }
55e     return curr;
b0d }

```

### 3.9 Mínimo Múltiplo Comum

```

// Time Complexity: O(log min(a,b))
// Auxiliary Space: O(log min(a,b))
// lcm(a, b) * gcd(a, b) = a * b

ebb int lcm(int a, int b){
    // return a * b / __gcd(a, b) could be overflow
c27     return a / __gcd(a, b) * b;
312 }

```

### 3.10 Método de Horner para Avaliação Polinomial

```

// f(x) = (Cn * x^n) + (Cn-1 * x^(n-1)) + (Cn-2 * x^(n-2)) + ... + (C1 *
    x) + C0
/* Ex:
ecd f(x) = 2x3 - 6x2 + 2x - 1
649 poly = {2, -6, 2, -1}
4f0 x = 3 -> f(3) = 5
c4c */

//Time Complexity: O(n)
//Auxiliary Space: O(1)

628 int horner(vector<int> &poly, int x){
855     int result = poly[0];
bc6     int n = poly.size();

6f5     for(int i = 1; i < n; i++){
a32         result = result * x + poly[i];
27a     }

dc8     return result;
f2a }

```

## 4 Grafos

### 4.1 Dijkstra

```

// Encontra o menor caminho do v rtice de index s at os outros
    v rtices
//
// O(n^2)

431 const int INF = 0x3f3f3f3f;
63c vector<vector<pair<int, int>>> adj; // {to, weight}

dca int dijkstra(int s, vector<int> &dist, vector<int> &pred) {
b4c     int n = adj.size();
ef2     dist.assign(n, INF);
b7c     pred.assign(n, -1);
4f4     vector<bool> vis(n, false);

a93     dist[s] = 0;
603     for (int i = 0; i < n; i++) {
78b         int v = -1;
578         for (int j = 0; j < n; j++) {
            // procura o n o visitado de menor caminho
af2             if (!vis[j] && (v == -1 || dist[j] < dist[v])) v = j;
c2c         }

a90         if (dist[v] == INF) break;

c25         vis[v] = true;
e57         for (auto edge : adj[v]) {
f04             int to = edge.first;
360             int len = edge.second;

f00             if (dist[v] + len < d[to]) {
4f0                 d[to] = d[v] + len;
b10                 pred[to] = v;
f12             }
8c3         }
a3a     }
f82 }

```

### 4.2 Floyd-Warshall

```

// encontra o menor caminho entre todo par de vertices
// retorna 1 se ha ciclo negativo

```

```

//
// dist[i][i] = 0
// para i != j
// d[i][j] = peso , se h aresta
// dist[i][j] = INF, c.c.
//
// O(n^3)

77e const long long LINF = 0x3f3f3f3f3f3f3f3fll;
1a8 int n;
2a4 long long dist[n][n];

b87 bool floydWarshal() {
9ba     for (int k = 0; k < n; k++) {
603         for (int i = 0; i < n; i++) {
578             for (int j = 0; j < n; j++) {
4c4                 dist[i][j] = min(dist[i][j], dist[i][k] +
dist[k][j]);
1c1             }
37a         }
4cd     }

320     for (int i = 0; i < n; i++) if (dist[i][i] < 0) return 1;

bb3     return 0;
093 }

```

## 4.3 Kruskal

```

// Gera e retorna uma AGM de um grafo G
// Para a rvore geradora m xima basta que peso = -peso
//
// V = {0, 1, 3, ..., N - 1}
// O (MlogM + N^2) : M = |E|, N = |V|

e9b struct Edge {
58e     int u, v, weight;
0a1     bool operator<(Edge const& other) {
d96         return weight < other.weight;
308     }
973 };

b24 vector<Edge> kruskal(vector<Edge> *edges, int n) {
704     int cost = 0;
0a4     vector<Edge> msp;
a5e     vector<int> tree_id(n);

```

```

9e5     for (int i = 0; i < n; i++) tree_id[i] = i;

ff1     sort(edges.begin(), edges.end());

508     for (Edge e : edges) {
6da         if (tree_id[e.u] != tree_id[e.v]) {
89c             cost += e.weight;
623             msp.push_back(e);

// unite
016             int old_id = tree_id[e.u], new_id = tree_id[e.v];
603             for (int i = 0; i < n; i++) {
7c2                 if (tree_id[i] == old_id) tree_id[i] = new_id;
a2a             }
15a         }
d62     }
756 }

```

## 5 Estruturas

### 5.1 BIT

```

// build - O(n)
// update - O(log(n))
// query - O(log(n))

714 struct BIT {
d3f     vector<ll> elements;
673     int size;

3db     BIT(int _size) {
a1a         elements = vector<ll>(_size);
3cc         size = _size;
2dd     }

a97     void update(int index, ll delta) {
3b1         for(int i = index; i < size; i += i&-i) {
467             elements[i] += delta;
562         }
516     }

959     ll query(int index) {
5ff         ll sum = 0;
57e         for(int i = index; i > 0; i -= i&-i) {

```

```

ce0          sum += elements[i];
d3e      }

e66          return sum;
d81      }
879 };

```

## 5.2 SegTree

```

// build : O(n)
// update : O(logn)
// query : O(logn)

3c9 struct node {
97f     int val;

5e1     node() {
aa1         val = 0;
           // val = elemento neutro
a06     }

a25     node(int val) : val(val) {
a6f     }

40c     node operator + (const node &rhs) const {
6d8         return node(val + rhs.val);
           // return node(val op rhs.val);
ad2     }
772 };

383 struct SegTree {
1a8     int n;
093     vector<node> st;

bd8     SegTree(){}
dd4     SegTree(int n) : n(n) {
502         st.resize(4 * n + 2);
2d1     }
d75     SegTree(vector<int> &a) {
9dc         n = a.size();
502         st.resize(4 * n + 2);
77f         build(1, 0, n - 1, a);
fa6     }

a6c     void build(int pos, int l, int r, vector<int> &a) {
893         if(l == r) {

```

```

76e             st[pos] = node(a[l]);
505             return;
b03         }
f7e         int mi = (l + r) / 2;
b01         build(2 * pos, l, mi, a);
e9b         build(2 * pos + 1, mi + 1, r, a);
4f4         st[pos] = st[2 * pos] + st[2 * pos + 1];
3eb     }

ea5     void update(int x, int y, int pos, int l, int r) { //void
update(int x, node y, int pos, int l, int r)
893         if(l == r) {
90b             st[pos] = node(y); //st[pos] = y;
505             return;
cdd         }
f7e         int mi = (l + r) / 2;
a9a         if(x <= mi) update(x, y, 2 * pos, l, mi);
40b         else update(x, y, 2 * pos + 1, mi + 1, r);
4f4         st[pos] = st[2 * pos] + st[2 * pos + 1];
bc4     }
105     void update(int x, int y) { // void update(int x, node y)
051         update(x, y, 1, 0, n - 1);
2ec     }

052     node query(int x, int y, int pos, int l, int r) {
fe9         if(y < l || r < x) return node();
c0e         if(x <= l && r <= y) return st[pos];
f7e         int mi = (l + r) / 2;
5f9         return query(x, y, 2 * pos, l, mi) + query(x, y, 2 * pos +
1, mi + 1, r);
6e5     }
9a5     node query(int x, int y) {
0c9         return query(x, y, 1, 0, n - 1);
cb8     }
b73 };

```

## 6 Problemas

### 6.1 Intersecao de Retangulos

```

2b7 #include <bits/stdc++.h>

ca4 using namespace std;

```



```

ef2 struct Rect {
619     int x1, y1, x2, y2;
0ac     int area(){
065         return (y2 - y1) * (x2 - x1);
b37     }
985 };

c93 int intersect(Rect p, Rect q){
6a6     int xOverlap = max(0, min(p.x2, q.x2) - max(p.x1, q.x1));
931     int yOverlap = max(0, min(p.y2, q.y2) - max(p.y1, q.y1));
1e5     return xOverlap * yOverlap;
e02 }

```

## 6.2 Permutacoes de String

```

// CSES - Creating Strings
// https://cses.fi/problemset/task/1622/

```

```

2b7 #include <bits/stdc++.h>

ca4 using namespace std;

d25 string str;
f6a vector<string> perms;
e41 int char_count[26];

497 void search(const string &curr = ""){
532     if(curr.size() == str.size()){
5b5         perms.push_back(curr);
505         return;
d12     }
42f     for(int i = 0; i < 26; i++){
962         if(char_count[i] > 0){
19c             char_count[i]--;
efd             search(curr + (char)('a' + i));
411             char_count[i]++;
818         }
08b     }
9ac }

e8d int main(){
912     cin >> str;
e28     for(char c : str){
f9d         char_count[c - 'a']++;
b4a     }

```

```

ff4     search();

161     cout << perms.size() << endl;
63a     for(int i = 0; i < perms.size(); i++){
efc         cout << perms[i] << endl;
657     }

bb3     return 0;
e7e }

```

## 6.3 Problema das 8 Damas

```

2b7 #include <bits/stdc++.h>
f3d #define _ ios_base::sync_with_stdio(0);cin.tie(0);
42a #define endl '\n'
efe #define pb push_back
ca4 using namespace std;

1a8 int n;
ac9 int cnt = 0;

890 void add(vector<bool> &cols, vector<bool> &diag1, vector<bool>
&diag2, int row, int col) {
3ba     cols[col] = true;
fd8     diag1[row - col + n - 1] = true;
5de     diag2[row + col] = true;
294 }

b21 void rem(vector<bool> &cols, vector<bool> &diag1, vector<bool>
&diag2, int row, int col) {
bfe     cols[col] = false;
9fb     diag1[row - col + n - 1] = false;
8b3     diag2[row + col] = false;
d15 }

4a5 void backtracking(int row, vector<bool> &cols, vector<bool>
&diag1, vector<bool> &diag2) {
e99     if(row == n) {
b8d         cnt += 1;
505         return;
a21     }
27b     for(int col = 0; col < n; col++) {
a5b         if(!cols[col] && !diag1[row - col + n - 1] && !diag2[row +
col]) {
b88             add(cols, diag1, diag2, row, col);
8c7             backtracking(row + 1, cols, diag1, diag2);

```

```

2c6         rem(cols, diag1, diag2, row, col);
ef2     }
4d7 }
826 }

f77 int main(){ _
a68     cin >> n; // number of rows = columns
a4f     vector<bool> cols(n, false), diag1(2 * n - 1, false), diag2(2
    * n - 1, false);
72c     backtracking(0, cols, diag1, diag2);
0a9     cout << cnt << endl;

bb3     return 0;
24f }

```

## 6.4 Quadrado Perfeito

```

2b7 #include <bits/stdc++.h>

// Time Complexity: O(log n)
// Auxiliary Space: O(1)
d5a bool isPerfectSquare(long double n){
884     if(n >= 0){
        // se a raiz de n inteira n o haver arredondamento
        // para o menor inteiro
569         long long sr = sqrt(n);

        // verifica se houve o arredondamento e retorna a resposta
9b6         return (sr * sr == n);
9b3     }

    //retorna falso caso x < 0
d1f     return false;
e0b }

// Time Complexity: O(log n)
// Auxiliary Space: O(1)
c38 bool binary_isPerfectSquare(long long n){
    // caso 0 e 1
8e8     if(n <= 1) return true;

    // limites da busca binaria
fb9     long long l = 1, r = n;
e47     long long square, mid;
3d5     while(l <= r){
        // calcular valor do meio

```

```

b7b         mid = (l + r) / 2;

        // calcular quadrado do termo do meio
f94         square = mid * mid;

e55         if(square == n){
8a6             return true;
cbc         }

        // buscar na direita
852         else if(square < n){
0dc             l = mid + 1;
fb0         }

        // buscar na esquerda
4e6         else {
982             r = mid - 1;
2e2         }
665     }

    // caso saia do loop sem achar um quadrado perfeito
d1f     return false;
f49 }

// Time Complexity: O(sqrt(n))
// Auxiliary Space: O(1)
d5a bool isPerfectSquare(long double n){
5c7     if(floor(sqrt(n)) == ceil(sqrt(n))) return true;
00b     else return false;
e67 }

```

## 6.5 Ruina do Jogador

```

2b7 #include <bits/stdc++.h>

ca4 using namespace std;

// p a probabilidade de ganhar um turno
// q = 1 - p, ou seja, a probabilidade de perder um turno
// Ri a quantia inicial de dinheiro
// N quantidade de dinheiro para ser vitorioso

773 double solve(double p, double q, int Ri, int N){
425     if(Ri == 0) return 0;
b21     if(Ri == N) return 1;

```

```

3b2      // jogo justo
        if(p == q) return (double)Ri / N;

4c3      // p != q
        return (1 - (double)pow(q / p, Ri)) / (1 - (double)pow(q / p,
afc }    N));

```

## 7 Extra

### 7.1 template.cpp

```

#include <bits/stdc++.h>
#define _ ios_base::sync_with_stdio(0);cin.tie(0);
#define endl '\n'
#define pb push_back
#define all(x) (x).begin(), (x).end()

using namespace std;

typedef long long ll;
typedef unsigned long long llu;

const int INF = 0x3f3f3f3f;
const ll LINF = 0x3f3f3f3f3f3f3f3fll;

int main() { _
    int tt;
    cin >> tt;
    while(tt--) {

        }

    return 0;
};

```