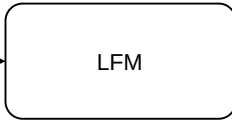




ground
sensors

LF layer

Line Following layer. Robô segue a linha.



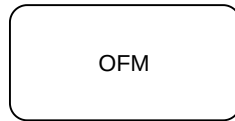
lfm_speed

OM layer

Obstacle Management layer.
Gerenciamento e monitoramento de obstáculos.



LLM



OFM

ofm_speed



LEM

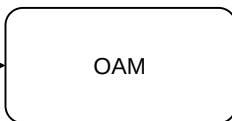
lem_speed



IR
sensors

OA layer

Obstacle Avoidance layer. Ação para desvio dos obstáculos.



OAM

oam_side

oam_speed