

ADSP

Advanced digital signal processing

Main content ADSP course

- ➤ Part A: Stochastic Signal Processing
- **→ Part B: Adaptive Signal Processing**
- ➤ Part C: Array Signal Processing (ASP) (including DOA)
- ➤ Part D: Adaptive Array Signal Processing (AASP)



Focus on single channel adaptive algorithms using FIR structure

- Applications Adaptive Algorithms
- Minimum Mean Square Error (MMSE)
- Constrained MMSE
- Least Square (LS)
- Steepest Gradient Descent (SGD)
- Three LMS variants: NLMS, Complex LMS, Constrained LMS
- Newton
- Recursive Least Squares (RLS) 自の回義上二年
- Frequency Domain Adaptive Filter (FDAF)
- Summary





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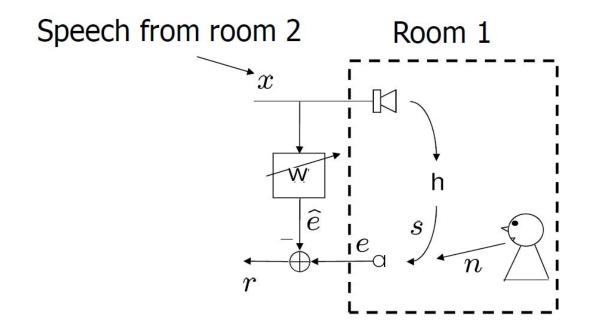


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Three different application classes

1. Signal estimation/ System identification

Example: Acoustic echo cancelling



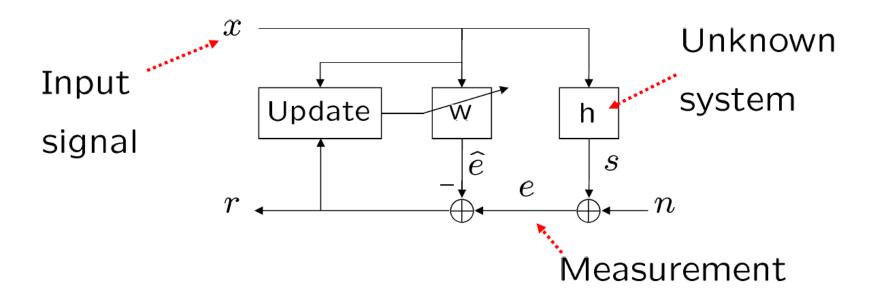


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Three different application classes

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Example: Acoustic echo cancelling



 \hat{e} estimate signal $s \Rightarrow \text{output: } r (\approx n)$

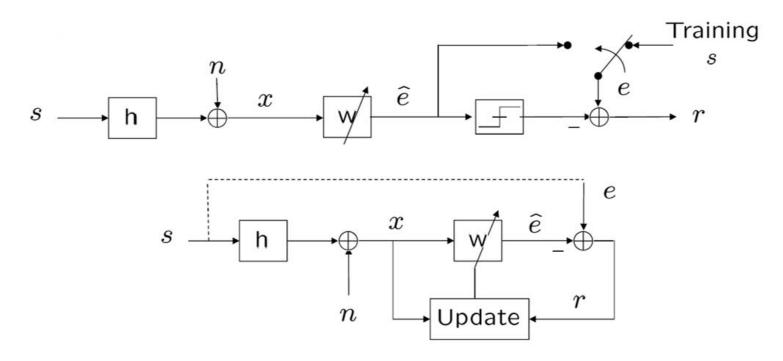


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Three different application classes

2. Signal correction

Example: equalization



Correct noisy input $x \Rightarrow$ output: $\hat{e} (\approx s)$



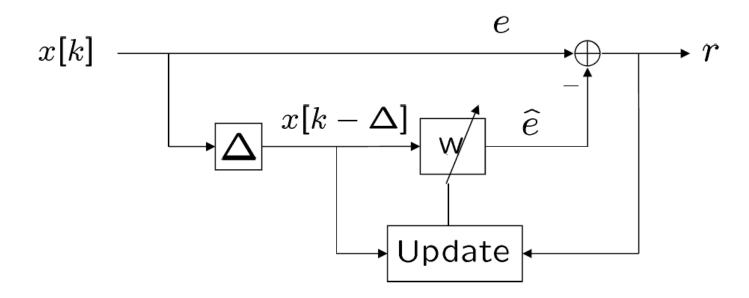
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Three different application classes

3. Signal prediction

Predict x[k] from $x[k-\Delta]$

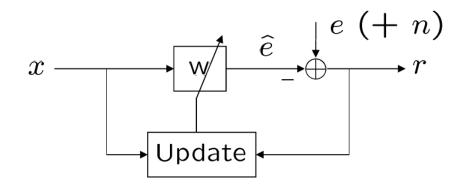
 \Rightarrow output: \hat{e} ($\approx x[k]$)





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General model



Notes:

Signals x, e correlated

Noise n not correlated with other signals

Pragmatic choices: • All signal average zero

这份的选择

• Filter w: FIR

How calculate filter weights w?

- Use quadratic cost function: $J = f(r^2)$
- First fixed weights (MMSE, LS), then adaptive



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MMSE

First calculate <u>fixed</u> filter $\underline{\mathbf{w}} = (w_0, w_1, \dots, w_{N-1})^t$ that Minimizes Mean Square Error (MMSE)

$$\begin{array}{c|c}
x[k] & e[k] \\
\hline
 & r[k]
\end{array}$$

Optimization problem:

Given FIR samples
$$x[k-i]$$
 for $i=0,1,\cdots,N-1$
$$\underline{\mathbf{w}}_o = \arg\min_{\underline{\mathbf{w}}} \{E\{r^2[k]\}\}$$



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MMSE

with
$$\underline{\mathbf{x}}[k]=(x[k],x[k-1],\cdots,x[k-N+1])^t$$
 and $\underline{\mathbf{w}}=(w_0,w_1,\cdots,w_{N-1})^t$

MSE:

$$J = E\{r^2[k]\} = E\{(e[k] - \hat{e}[k])^2\}$$
$$= E\{(e[k] - \underline{\mathbf{w}}^t \cdot \underline{\mathbf{x}}[k])(e[k] - \underline{\mathbf{x}}^t[k] \cdot \underline{\mathbf{w}})\}$$

Neglecting time indices: \(\psi \) fixed

$$J = E\{e^2\} - \underline{\mathbf{w}}^t E\{\underline{\mathbf{x}}e\} - E\{e\underline{\mathbf{x}}^t\}\underline{\mathbf{w}} + \underline{\mathbf{w}}^t E\{\underline{\mathbf{x}}\underline{\mathbf{x}}^t\}\underline{\mathbf{w}}$$
$$= E\{e^2\} - \underline{\mathbf{w}}^t\underline{\mathbf{r}}_{ex} - \underline{\mathbf{r}}_{ex}^t\underline{\mathbf{w}} + \underline{\mathbf{w}}^t\mathbf{R}_x\underline{\mathbf{w}}$$



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MMSE

Autocorrelation $r_x[l] = E\{x[k]x[k-|l|]\}$

Auto correlation matrix:

$$\mathbf{R}_{\chi} = \mathbf{E}\{\underline{\mathbf{x}} \cdot \underline{\mathbf{x}}^t\} = \begin{bmatrix} r_{\chi}[0] & r_{\chi}[1] & \dots & r_{\chi}[N-1] \\ r_{\chi}[1] & r_{\chi}[0] & \dots & r_{\chi}[N-2] \\ \vdots & & \vdots & \vdots & \vdots \\ r_{\chi}[N-1] & r_{\chi}[N-2] & \dots & r_{\chi}[0] \end{bmatrix}$$

X[K-N+1]

Cross correlation $r_{ex}[l] = E\{e[k]x[k-l]\}$

Cross correlation vector:

$$\underline{\mathbf{r}}_{ex} = \mathbf{E}\{e \cdot \underline{\mathbf{x}}\} = (r_{ex}[0], r_{ex}[1], \dots, r_{ex}[N-1])^{t}$$

$$\mathbf{E}\{e[k] \cdot [x[k-1]]\} = [r_{ex}[n]]^{t}$$

$$\mathbf{r}_{ex}[n-1]$$

$$\mathbf{r}_{ex}[n-1]$$

$$\mathbf{r}_{ex}[n-1]$$

$$\mathbf{r}_{ex}[n-1]$$
13

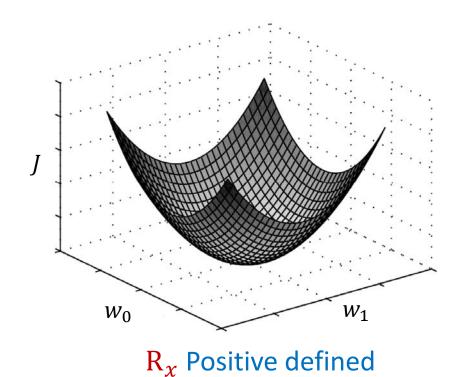


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MMSE

Cost function
$$J = E\{e^2\} - \underline{\mathbf{w}}^t \underline{\mathbf{r}}_{ex} - \underline{\mathbf{r}}_{ex}^t \underline{\mathbf{w}} + \underline{\mathbf{w}}^t \mathbf{R}_x \underline{\mathbf{w}}$$

In theory if R_x Positive defined, J has unique minimum.



 R_x negative defined

 w_0

 W_1



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Cost function $J = E\{e^2\} - \underline{\mathbf{w}}^t \underline{\mathbf{r}}_{ex} - \underline{\mathbf{r}}_{ex}^t \underline{\mathbf{w}} + \underline{\mathbf{w}}^t \mathbf{R}_x \underline{\mathbf{w}}$

- R_x always non-negative $W_x^t Y_{ex} = E[\hat{e}^2]$
- In physical practice, R_x always almost positive

$$R_{x}^{T} = R_{x}$$
 $\alpha R_{x}^{-1} \alpha > 0$

After some manipulations we can write:



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MMSE

Optimum:
$$\frac{dJ}{d\underline{\mathbf{w}}} = \underline{\nabla} = -2\left(\underline{\mathbf{r}}_{ex} - \mathbf{R}_x\underline{\mathbf{w}}\right) = 0$$

$$\Rightarrow \mathbf{R}_x \cdot \underline{\mathbf{w}} = \underline{\mathbf{r}}_{ex} \quad \text{Normal equations}$$

$$\Rightarrow \ \underline{\mathbf{w}}_o = \mathbf{R}_x^{-1} \cdot \underline{\mathbf{r}}_{ex}$$
 Wiener filter

五线数次有 TLE

Cost function:

$$E[r^2] = E[r.(e-\hat{e})] = E[r.e] - E[r.\hat{e}]$$

In optimum:
$$J_{min} = J|_{\underline{\mathbf{w}}=\underline{\mathbf{w}}_o} = E\{r^2\} = E\{r \cdot e\}$$

$$= E\{e^2\} - \underline{\mathbf{r}}_{ex}^t \underline{\mathbf{w}}_o$$

$$= E\{\hat{e}^2\} - E\{\hat$$



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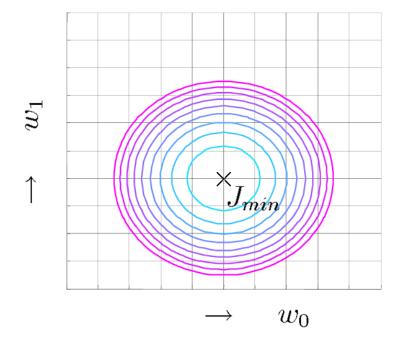
MMSE

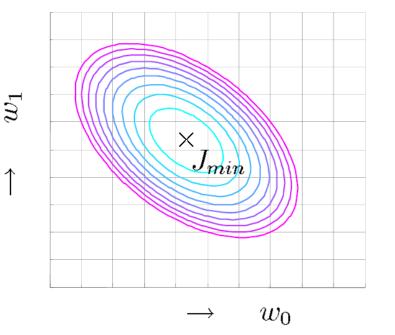
Luex 最大特征值,其所对应的特化的是方向公路重量大

Contour plot:
$$J = J_{min} + (\underline{\mathbf{w}} - \underline{\mathbf{w}}_o)^t \cdot (\underline{\mathbf{R}}_x) \cdot (\underline{\mathbf{w}} - \underline{\mathbf{w}}_o)$$

$$\Gamma_x = \frac{\lambda_{max}}{\lambda_{min}} = 1 \text{ (=white noise)} \qquad \Gamma_x = \frac{\lambda_{max}}{\lambda_{min}} > 1$$

$$\Gamma_x = \frac{\lambda_{max}}{\lambda_{min}} > 1$$





iGM技巧: 0 色= wotx = xtwo ② r= e-色 = e- wotx = e- xtwo

Part B: Adaptive signal processing



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MMSE we have
$$R_{x}w_{0} = r_{0}x$$

$$E[r_{x}] = E[(e-\hat{e})x] = E[(e-x^{\dagger}w_{0})x]$$

In optimum:
$$R_x \underline{w} = \underline{r}_{ex}$$

$$R_x \underline{w} = \underline{r}_{ex}$$

$$= E \left[e \times \right] - E \left[\times \times^{+} w_{0} \times \right]$$

$$= E \left[e \times \right] - E \left[\times \times^{+} w_{0} \right] \times \times \times$$

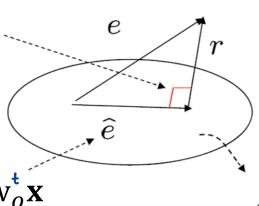
Ortogonality principle:
$$E\{rx\} = 0$$
 = $rex - R_x = 0$

$$\Rightarrow \underline{\nabla}|\underline{\mathbf{w}} = \underline{\mathbf{w}}_o = E\{r^2\}|\underline{\mathbf{w}} = \underline{\mathbf{w}}_o = E\{r \cdot (e - \hat{e})\}|\underline{\mathbf{w}} = \underline{\mathbf{w}}_o = E\{r \cdot e\} \quad \text{E}[r\hat{e}] = 0$$

$$\text{from } E[r \times] = 0 \quad \text{to proof} \quad E[r\hat{e}] = 0 \quad \text{E}[r\hat{e}] = E[r \times] = 0$$

Geometric interpretation

wiener W >> Orthogonal r的自相关对 rse 直相差 色加的粉色对色的电互烟囱 3 E[r2]= E[re] $\hat{e} = \underline{w}_{o}^{t} \underline{x}$



Jmin = Vr = Ver $(J_{min} = E\{r^2\}|_{\mathbf{w}=\mathbf{w}_o}$

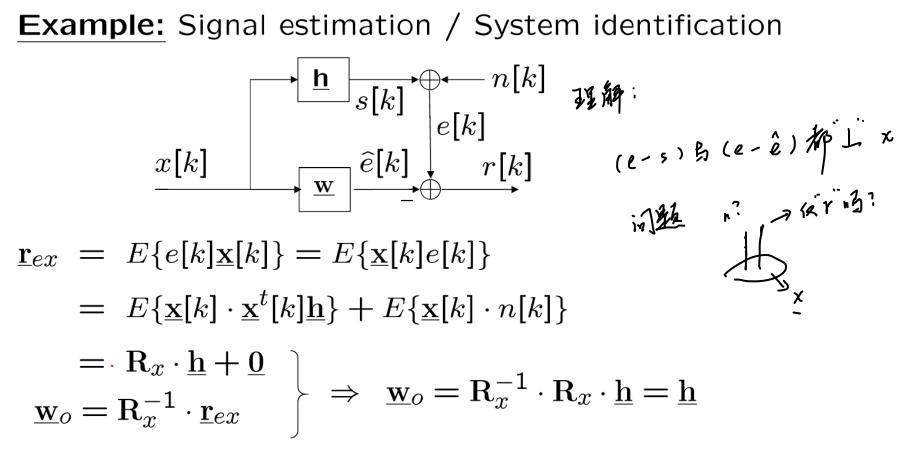
己知M入血压足储号 三与参考信号电、我出展的wiener对力于 2.8 的差别。



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MMSE

Example: Signal estimation / System identification





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Two MMSE variants

Complex-MMSE:

Setup with complex signals and weights

Result similar to previous case:

$$\Rightarrow$$
 Optimum: $\mathbf{\underline{w}}_o = \mathbf{R}_x^{-1} \cdot \mathbf{\underline{r}}_{xe^*}$

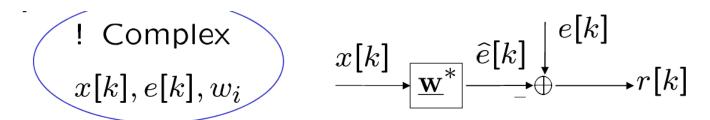
Constrained MMSE:

Setup with set of constraints on weights



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Complex MMSE



Input signal vector: $\underline{\mathbf{x}}[k] = (x[k], \dots, x[k-N+1])^t$

Weight vector: $\underline{\mathbf{w}} = (w_0, \dots, w_{N-1})^t$

Optimization problem: $\underline{\mathbf{w}}_o = arg \min_{\mathbf{w}} \left[E\{|r[k]|^2\} \right]$

MSE: $J = E\{|r[k]|^2\} = E\{r[k] \cdot r^*[k]\}$

$$J = E\{(e[k] - \underline{\mathbf{w}}^h \cdot \underline{\mathbf{x}}[k])(e^*[k] - \underline{\mathbf{x}}^h[k] \cdot \underline{\mathbf{w}})\}$$
$$= \sigma_e^2 - \underline{\mathbf{w}}^h \cdot \underline{\mathbf{r}}_{xe^*} - \underline{\mathbf{r}}_{xe^*}^h \cdot \underline{\mathbf{w}} + \underline{\mathbf{w}}^h \cdot \mathbf{R}_x \cdot \underline{\mathbf{w}}$$

with $\underline{\mathbf{r}}_{xe^*} = E\{\underline{\mathbf{x}}[k]e^*[k]\}$ and $\mathbf{R}_x = \{\underline{\mathbf{x}}[k]\cdot\underline{\mathbf{x}}^h[k]\}$



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Complex MMSE

After some manipulations we can write:

$$J = \sigma_e^2 - \underline{\mathbf{r}}_{xe^*}^h \mathbf{R}_x^{-1} \underline{\mathbf{r}}_{xe^*} +$$

$$+ (\mathbf{R}_x \cdot \underline{\mathbf{w}} - \underline{\mathbf{r}}_{xe^*})^h \cdot \mathbf{R}_x^{-1} (\mathbf{R}_x \cdot \underline{\mathbf{w}} - \underline{\mathbf{r}}_{xe^*})$$

 \Rightarrow Only second part depending on $\underline{\mathbf{w}}$

$$\Rightarrow$$
 Optimum: $\underline{\mathbf{w}}_o = \mathbf{R}_x^{-1} \cdot \underline{\mathbf{r}}_{xe^*}$

Other approch: Via (complex) gradient

Assume we can write compex weight as: $\underline{\mathbf{w}} = \underline{\mathbf{a}} + \mathbf{j}\underline{\mathbf{b}}$

$$\underline{\nabla}w(J) = \frac{dJ}{d\underline{\mathbf{a}}} + \mathbf{j}\frac{dJ}{d\underline{\mathbf{b}}} \iff \underline{\nabla}w(J) = 2\frac{dJ}{d\underline{\mathbf{w}}^*} = 2\left(\mathbf{R}_x \cdot \underline{\mathbf{w}} - \underline{\mathbf{r}}_{xe^*}\right)$$



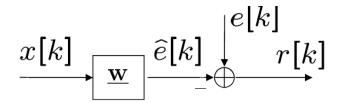
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Constrained MMSE



Minimize $E\{r^2[k]\}$ subject to M constraints:

Example:
$$\sum_{i=0}^{N-1} w_i = 1 \ \Rightarrow \ (1,\cdots,1) \cdot \left(\begin{array}{c} w_0 \\ \vdots \\ w_{N-1} \end{array}\right) = 1$$

General:

$$\underline{\mathbf{c}}_{1}^{t} \cdot \underline{\mathbf{w}} = f_{1} \\
\vdots \\
\underline{\mathbf{c}}_{M}^{t} \cdot \underline{\mathbf{w}} = f_{M}$$

$$\Leftrightarrow \begin{pmatrix} \underline{\mathbf{c}}_{1}^{t} \\ \vdots \\ \underline{\mathbf{c}}_{M}^{t} \end{pmatrix} \cdot \underline{\mathbf{w}} = \underline{\mathbf{f}} \Leftrightarrow \mathbf{C}^{t} \cdot \underline{\mathbf{w}} = \underline{\mathbf{f}}$$



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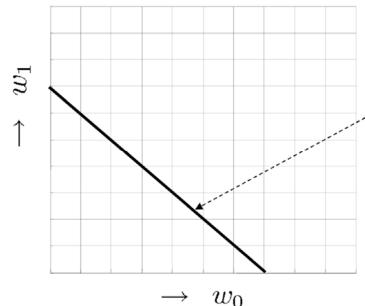
Constrained MMSE

Some notes on solving: $\mathbf{C}^t \cdot \mathbf{w} = \mathbf{f}$

 $M \times 1$ constraint vector: $\underline{\mathbf{f}} = (f_1, \dots, f_M)^t$

 $N \times M$ constraint matrix: $\mathbf{C} = (\underline{\mathbf{c}}_1, \dots, \underline{\mathbf{c}}_M)$

Note: M independent constraints \Rightarrow \mathbf{C} full rank $M \leq N$



$$\{ \underline{\mathbf{w}} : \mathbf{C}^t \cdot \underline{\mathbf{w}} = \underline{\mathbf{f}} \}$$

Example of constraint:

$$w_0 + w_1 = c$$



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Constrained MMSE

Solution $\mathbf{C}^t \cdot \mathbf{w} = \mathbf{f}$:

Case N = M:

$$\Rightarrow \ \underline{\mathbf{w}}^c = \left(\mathbf{C}^t\right)^{-1} \cdot \underline{\mathbf{f}}$$

 \Rightarrow No degrees of freedom left for MMSE

Case N > M:

$$\Rightarrow$$
 Possible solution: $\underline{\mathbf{w}}^c = \left(\mathbf{C}^t\right)^{\dagger} \cdot \underline{\mathbf{f}}$

Appendix: Generalized inverse
$$\left(\mathbf{C}^{t}\right)^{\dagger} = \mathbf{C} \cdot \left(\mathbf{C}^{t} \cdot \mathbf{C}\right)^{-1}$$

$$\Rightarrow N-M$$
 degrees of freedom left over for MMSE

$$N < M \Rightarrow \text{Conflicting solution}$$
 (choose e.g. minimum norm solution)