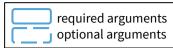
# nimble models:: cheat sheet





**Configure an MCMC** 



**Advanced** 

```
nimbleCode()
                                            NIMBLE lang
   Write model code
                         readBUGSmodel() read BUGS
                         nimbleModel()
  Create model object
                          myModel <- nimbleModel(</pre>
from nimbleCode()
                           code = modelCode,
constants of the model
                           constants = list(N = 8,
e.g. for-loop ranges,
                          numGroups = 4, ...),
known index vectors
                           data = list(y = myData,
values 

                             X = myCovs),
to label as data nodes
                           -inits] = list(beta0 = 0,
starting values —
                              beta1 = 0, ...))
for the parameters
```

constants can't be changed after creating a model data & inits can be changed

```
configureMCMC()
       algorithm
                                             customization
     Build an MCMC
                         buildMCMC()
         object
                          myMCMC <- buildMCMC(</pre>
model object or
                           conf = [myModel|myConf],
MCMC configuration
                           monitors = c("beta0",...),
variables names 🧴
                           thin_{l} = 10,
for MCMC output
                           monitors2, thin2)
thinning interval
```

runMCMC() using MCMC object **Run MCMC** nimbleMCMC() one-line invocation

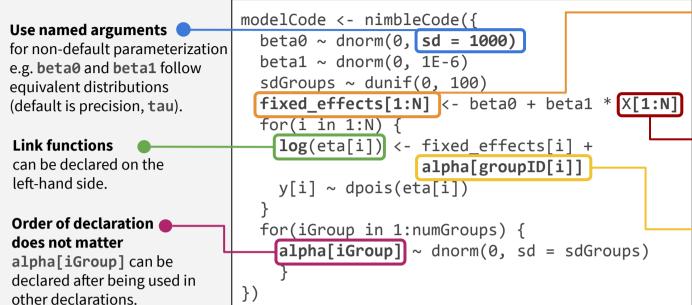
a second set of variables with its own thinning —

```
Compile in C++
                           compMCMC <- compileNimble()</pre>
for faster execution
                           myMCMC,project = myModel)
MCMC from buildMCMC()
                           samples <- runMCMC(</pre>
compiled or uncompiled
                           mcmc = compMCMC,
                           iter=1000, nburnin=100)
number of MCMC
iterations & burnin
```

```
from nimbleCode()
                          samples <- nimbleMCMC(</pre>
                            code = modelCode,
as in nimbleModel()
                            data, constants, inits]
number of MCMC
                            niter, nburnin)
iterations & burnin
```

# Writing model code

**Split code over multiple lines** to help people read it.



Vectorized declarations

create vector nodes. This means fixed effects[1:N] will be a single node. One vector node vs. multiple scalar nodes give different model graphs, so use with care.

Provide explicit index ranges or use empty brackets ([1]) and provide the **dimensions** argument to nimbleModel().

**Nested indexing** is a good way to implement experimental groups or factor levels. If groups are known from the design, include them in constants.

# Using models

Models can be compiled. cModel <- compileNimble(myModel)</pre> In methods below, "mode1" can be cModel or myModel.

Models can access and change variables.

model\$beta0 <- 5 model[["beta0"]] <- 5

Models can simulate or calculate log-probabilities.

model\$calculate(nodes) returns sum of log probability densities.

model\$calculateDiff(nodes)

returns difference in sum of log probability densities between current and previous node values.

model\$getLogProb(nodes)

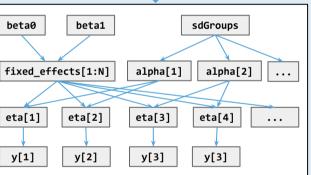
returns sum of most recently calculated log probability densities.

model\$simulate(nodes,

includeData = FALSE)

simulates into stochastic nodes. includeData = FALSE protects data. Models are graphs

myModel\$plot()



• Uncompiled models can be debugged, updated, and copied.

Flag nodes as data and set inits

myModel\$setData("y") myModel\$setInits(inits)

**Debug model errors** 

myModel\$check()

check for missing/invalid values.

mvModel\$initializeInfo()

which nodes are not fully initialized?

myModel\$checkBasics()

check for size/dimension mismatches and NA.

Make a copy

myModel\$newModel(replicate = TRUE)

Models know properties of nodes.

model\$getDimension(node) model\$getDistribution(nodes) model\$isDeterm(nodes)

model\$isStoch(nodes)

model\$isData(nodes)

model\$isDiscrete(nodes) model\$isMultivariate(nodes)

model\$isBinary(nodes)

model\$isEndNode(nodes)

model\$isTruncated(nodes)

Models know about

nodes, variables and relationships.

model\$getNodesNames() returns node names

e.g."eta[1]", "eta[2]",...

model\$getVarNames()

returns variable names e.g. "eta"

model\$expandNodeNames(nodes) e.g. "y" is expanded to "y[1]", "y[2]",...

model\$getDependencies(nodes, ...) returns nodes that depend on input nodes.

# nimble distributions and functions:: cheat sheet



# **Declarations**

### **STOCHASTIC**

x ~ ddist(args)

### **DETERMINISTIC**

z <- fn(args)

### TRUNCATED STOCHASTIC

x ~ T(ddist(args), min, max)

### CENSORED STOCHASTIC

seg ~ dinterval(t, c[1:nSegments]) t ~ ddist(args)

### CONSTRAINT

one ~ dconstraint(condition)

# **Deterministic Functions**

### **SCALAR or COMPONENT-WISE**

**Logical**: |, &, !, >, >=, <, <=, !=,==, equals, step

Arithmetic: +, -, \*, /,  $^{\circ}$ , pow(x, y) %%, exp, log, sqrt, abs, cube

Trigonometric: sin, cos, tan, asin, acos, atan, asinh, acosh, atanh

Links: logit, probit, cloglog (links can also be used on left-hand side of

a declaration)

Inverse links: ilogit/expit, iprobit/phi, icloglog

Rounding: ceiling, floor, round,

trunc

**Specials:** lgamma/loggam, besselK, log1p, lfactorial, logfact

**Distributions**: d, p, q, r forms of available distributions can be used as deterministic functions.

### **VECTOR and/or MATRIX**

Returning scalar: inprod, logdet, sum, mean, sd, prod, min, max Returning vector: pmin, pmax,

eigen(x)\$values, svd(x)\$dReturning matrix: inverse, chol, %\*%, t, solve, forwardsolve,

backsolve, eigen(x)\$vectors,

svd(x)\$u, svd(x)\$v

# Write you own!

See Ch 12 of **User Manual** 

NIMBLE allows you to write **new distributions** and functions using nimbleFunction().

# **Univariate Distributions**

# Continuous



y ~ dbeta([shape1,shape2 |

mean, sd])
shape1=mean^2\*(1-mean)/sd^2-mean shape2=mean\*(1-mean)^2/sd^2+mean-1

# **CHI-SOUARE**

v ~ dchisq(df)

# **DOUBLE EXPONENTIAL (LAPLACE)**

y ~ ddexp(location, [scale|**rate**|var]) scale = 1/rate scale = sqrt(var/2)



## **EXPONENTIAL**

y ~ dexp([rate|scale]) rate = 1/scale



# FLAT (improper)

y ~ dflat()



**GAMMA** 

**DIRICHLET** 

**MULTINOMIAL** 

prec\_param)

 $y[] \sim dmvt(mu[],$ 

**df**, prec param)

v ~ dgamma([shape,[rate|scale]] [[mean,sd]) scale = 1/rate shape =  $mean^2/sd^2$ 



**HALF FLAT (improper)** y ~ dhalfflat()

Multivariate distributions

y[] ~ ddirch(alpha[])

**MULTIVARIATE NORMAL** 

y[] ~ dmnorm(mean[],

**MULTIVARIATE STUDENT T** 

cholesky = chol(prec) : prec\_param=1
cholesky = chol(cov) : prec\_param=0 for dmnorm

cholesky = chol(scale): prec\_param=0 for dmvt

choleský is chol(prec) when prec\_param=1, chol(cov)|chol(scale) when prec param=0

y[] ~ dmulti(prob[], size)

[prec[,] | cov[,] | cholesky[,]],

[prec[,] | scale[,] | cholesky[,]],

scale = sd^2/mean

# **INVERSE GAMMA**

y ~ dinvgamma(shape, [rate[scale]) rate = 1/scale



y ~ dlogis(location, [rate|scale]) scale = 1/rate

### **LOG-NORMAL**

y ~ dlnorm(meanlog, [taulog|sdlog|varlog]) sdlog = 1/sqrt(taulog) sdlog = sqrt(varlog)



y ~ dnorm(mean, [tau|sd|var]) sd = 1/sqrt(tau)sd = sqrt(var)



## STUDENT T

y ~ dt(mu, [tau|sigma|sigma2], df) sigma = 1/sart(tau) sigma = sqrt(sigma2)



# **UNIFORM**

y ~ dunif(min, max)



# **WEIBULL**

y ~ dweib(shape [lambda|scale|rate])  $scale = lambda^{-1/shape}$ scale = 1/rate

### **WISHART**

 $y[,] \sim dwish($ [**R**[,] | S[,] | cholesky[,]], df, scale param)

# **INVERSE WISHART**

y[,] ~ dinvwish([S[,] | R[,] | cholesky[,]], df,scale param)

cholesky = chol(R): scale\_param=0 cholesky = chol(S): scale\_param=1
cholesky is chol(S) when scale\_param=1, chol(R) when scale\_param=0

# **DISTRIBUTION NAME**

y ~ ddist([default|alternative]) canonical = fn(provided)

Lifted nodes are inserted when non-canonical parameters are used. Default parameters are not necessarily canonical.

# Discrete



## **BERNOULLI**

y ~ **dbern**(prob)



# **BINOMIAL**

v ~ dbinom(prob, size)



# **CATEGORICAL**

y ~ **dcat**(prob)



# **NEGATIVE BINOMIAL**

y ~ dnegbin(prob, size)



### **POISSON**

y ~ **dpois**(lambda)

# Distributions for spatial models



## **CONDITIONAL AUTOREGRESSIVE** intrinsic (improper)

y[] ~ dcar normal(adj[], weights[], num[], tau, c, zero mean)

**User Manual** 

See Ch 9 of y[] ~ dcar\_proper(mu[], C[], adj[], num[], M[], tau, gamma)

# Bayesian nonparametric distributions

See Ch 10 of **User Manual** 



### **CHINESE RESTAURANT PROCESS** y[] ~ dCRP(conc, size)

conc= concentration parameter



### STICK BREAKING PROCESS y[] ~ stick\_breaking(z[])

z = vector of breaking points

