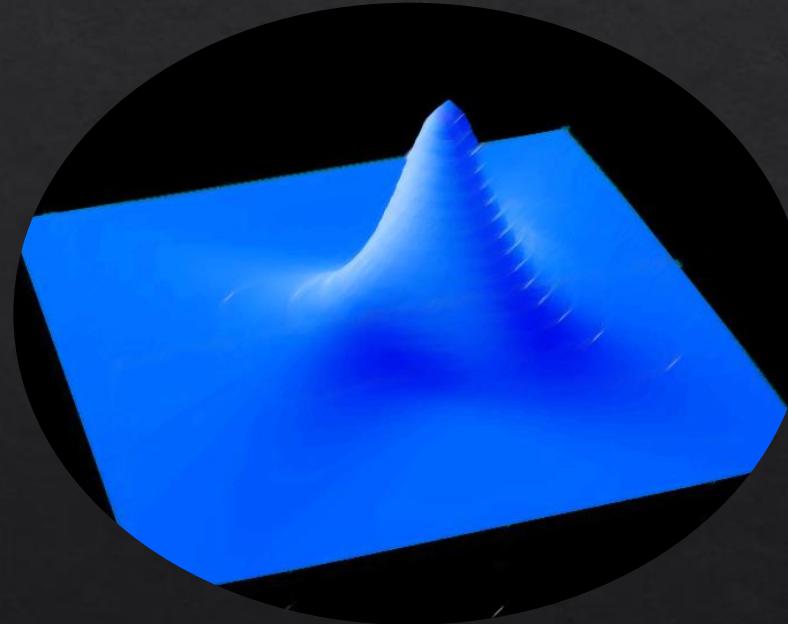
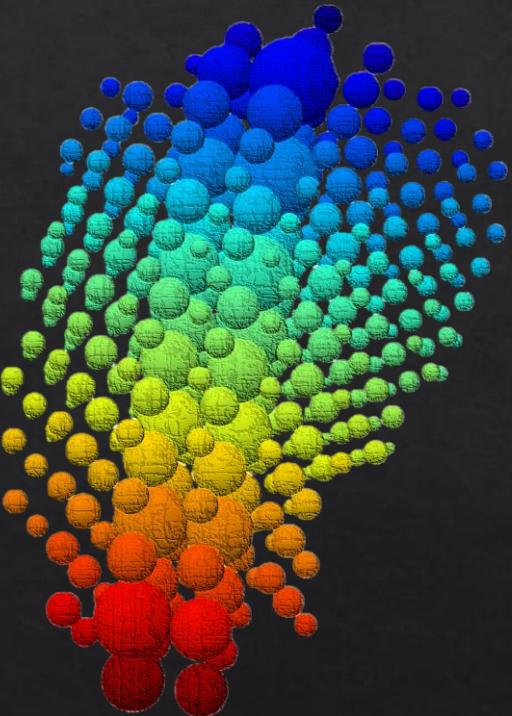


Windchime, Heavy DM Candidates, and QFT in Curved STs

Bahaa Elshimy



Overview

- ❖ Experimental Work: *Gravitational Direct Detection of Dark Matter*
- ❖ Phenomenology Work: *Heavy Dark Matter Candidates for Direct Detection Techniques*
- ❖ Theory Work: *Evolution of Free Scalar Field in Curved Spacetimes*

Overview

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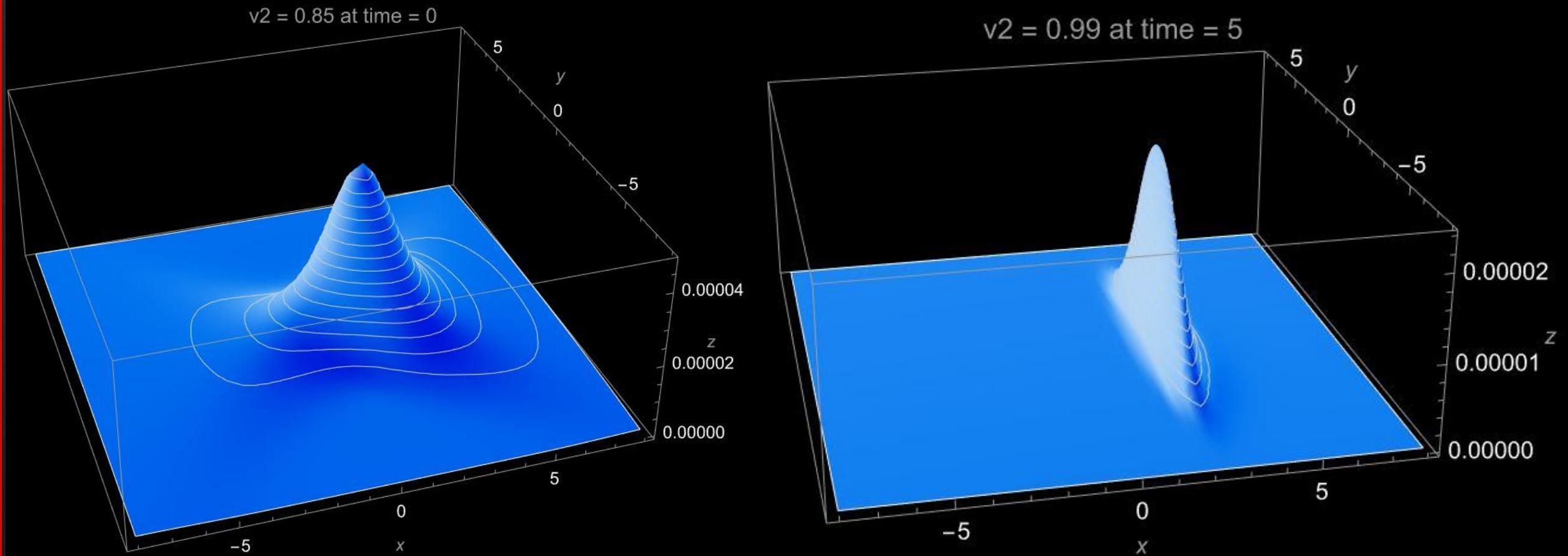
Background

- Standard Approach: Attempt to construct a relativistic quantum theory → QFT with a Flat Background
 - Particles arise naturally as an interpretation of the nonzero components of the Fock space states in the n-fold tensor product space $\otimes_s^n \mathcal{H}$
 - In other words, they are irreducible representations of the associated symmetry group (Poincare)
- Drawback: Relies on the unitary equivalence of the field theory regardless of choice of Hilbert Space
- In curved STs, the machinery can still work, but choice of basis is no longer clear and no longer unique
- Remedy: Reformulate the theory using a symplectic structure and an associated vector space – basically a phase space representation with a symplectic product and a Poisson Bracket

Goal of the Analysis

- Get the energy spectrum of the free particles with different spacetime geometries
 - Analyze what this energy depends on in different regions
- Derive the asymptotic behavior of the scalar fields
 - Determine whether a detector can use information gathered about the evolved state to infer elements of the background geometry via certain behavior observed
- Started with Curvilinear Coordinates, Boosted Frames, & Rindler Coordinates
- Concluded with Static Patch of deSitter Space

WF in Boosted Frame



$g_{\mu\nu}$



$\mathcal{L}(x, \phi)$

$\mathcal{H}(x, \phi)$

Sturm-Liouville
Operator

EOMs for the Field $\phi(x, t)$

$p \equiv \text{Momentum}$

$\phi_{p,l,s}(x)$

$|\psi\rangle = \int d^3p \psi(p, t) a_p^\dagger |0\rangle$

$\Psi(x, t) = \int \langle x|p\rangle \langle p|\psi\rangle dp \equiv \text{Wavefunctional}$

Case 0: Flat Space Spherical Coordinates

$$\mathcal{L}(x, \phi) = -\frac{1}{2}r^2 \sin \theta (-(\partial_t \phi)^2 + (\partial_r \phi)^2 + m^2 \phi^2) - \frac{1}{2} \left(\sin \theta (\partial_\theta \phi)^2 + \frac{1}{\sin \theta} (\partial_\phi \phi)^2 \right)$$

$$\mathcal{H}(x, \phi) = \frac{1}{2} \left[\frac{\pi^2}{r^2 \sin \theta} + r^2 \sin \theta ((\partial_r \phi)^2 + m^2 \phi^2) + \sin \theta (\partial_\theta \phi)^2 + \frac{1}{\sin \theta} (\partial_\phi \phi)^2 \right]$$

$$-\partial_t^2 \phi + \frac{1}{r^2} \partial_r (r^2 \partial_r \phi) + \frac{1}{r^2 \sin \theta} \partial_\theta (\sin \theta \partial_\theta \phi) + \frac{1}{r^2 \sin^2 \theta} \partial_\phi^2 \phi - m^2 \phi = 0$$

$$\phi_{p,l,s}(x) = R(r)Y_l^s(\theta, \varphi) = A e^{is\varphi} j_{\tilde{k}_l}(pr) P_{\tilde{k}_l}^s(\cos \theta)$$

$$\hat{D} = \partial_r (r^2 \partial_r) - \hat{L}^2 - r^2 m^2$$

$$p^2 = \omega_p^2 - m^2$$

$$|\psi\rangle = \psi_0 \int d^3 p e^{-i\omega_p t} a_p^\dagger |0\rangle$$

$$\Psi(r, \theta, \varphi, t) = \int dp \sum_{l,s} A e^{is\varphi} j_{\tilde{k}_l}(pr) P_{\tilde{k}_l}^s(\cos \theta) \psi_0 e^{-i\omega_p t}$$

Free Scalar Field in deSitter Spacetime

$$\mathcal{L}(x, \phi) = -\frac{1}{2} \cos(H\rho) \sin^2(H\rho) \sin \theta \left[-\cos^2(H\rho) (\partial_t \phi)^2 + (\partial_\rho \phi)^2 + H^2 \sin^{-2}(H\rho) \left((\partial_\theta \phi)^2 + \sin^{-2} \theta (\partial_\varphi \phi)^2 \right) - m^2 \phi^2 \right]$$

$$\mathcal{H}(x, \phi) \equiv \dot{\phi}\pi - \mathcal{L} \quad \pi \equiv \frac{\partial \mathcal{L}}{\partial(\partial_t \phi)} = H^{-2} \cos^{-1}(H\rho) \sin^2(H\rho) \sin \theta \dot{\phi}$$

$$D = \partial_r(r^2 \partial_r) - \hat{L}^2 - r^2 m^2$$

EOMs

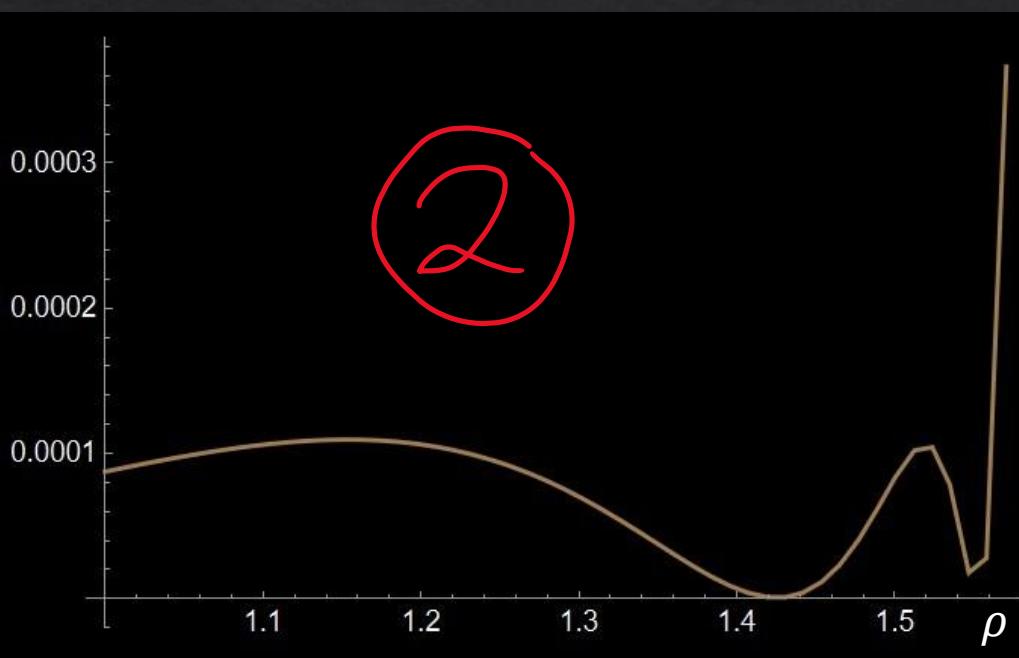
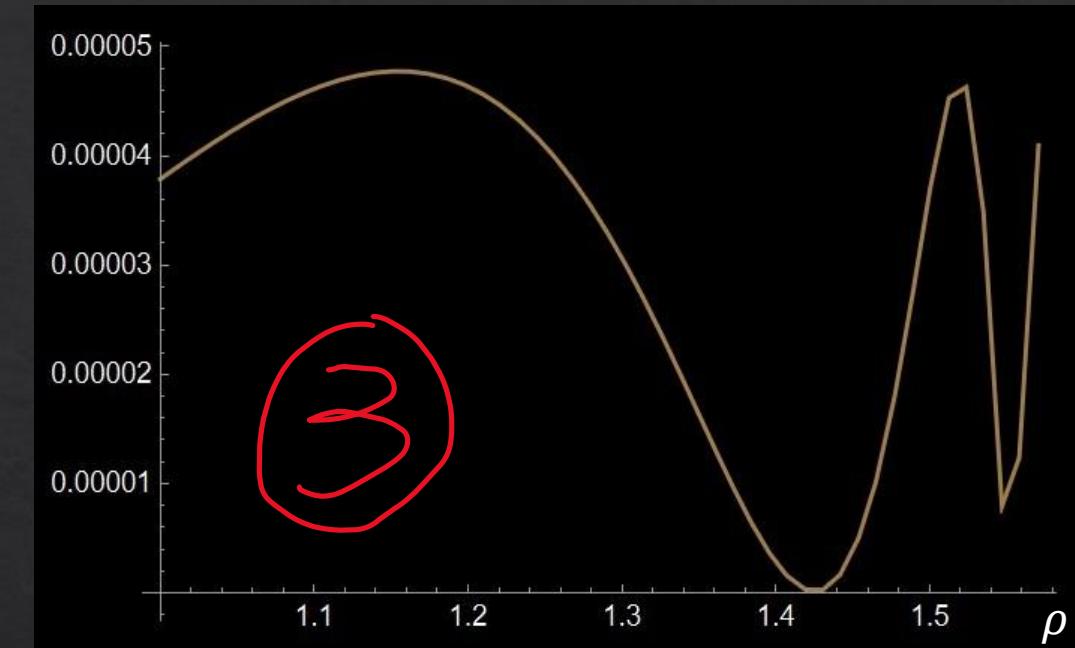
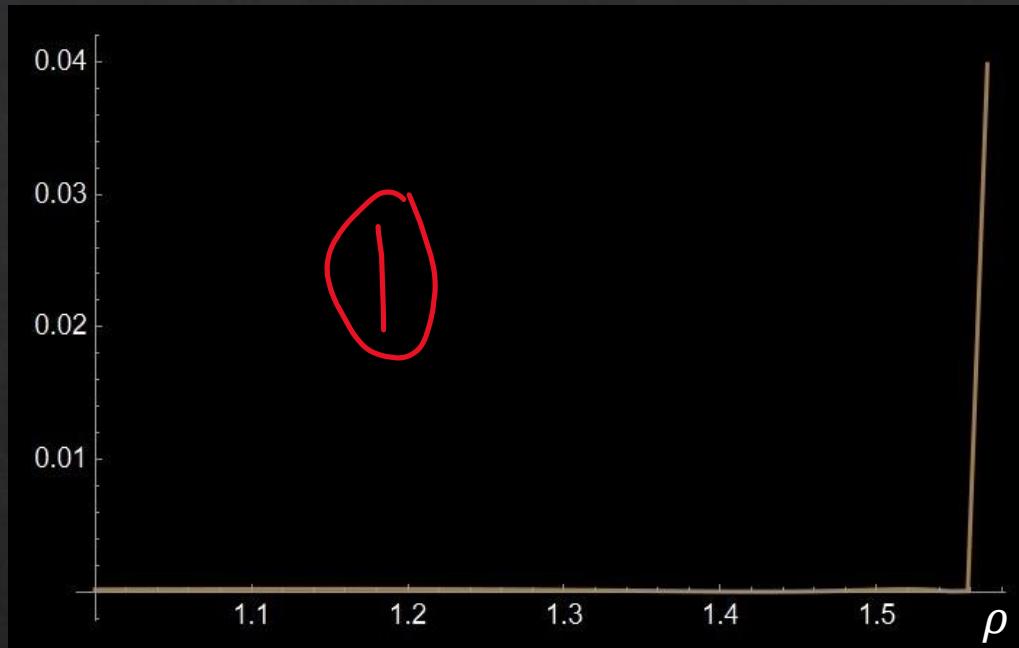
$$\phi_{p,l,s}(r, \theta, \varphi) = A_{l,s} Y_l^s(\theta, \varphi) N_{pl} \tan^l(H\rho) \cos^n(H\rho) {}_2F_1[\text{Args } \{\rho\}]$$

Rescaled Radial Solution
with $\frac{m^2}{H^2} \gg 1$

$$|\psi\rangle$$

$p^2 = \omega_p^2$
at the $\rho \rightarrow \frac{\pi}{2H}$ limit

$$\Psi(x, t) = \int \langle x | p \rangle \langle p | \psi \rangle d\mathbf{p} = \int \phi_{\mathbf{k}}(r, \theta, \varphi, t) \psi_0 e^{-i\omega_{\mathbf{k}} t} d\mathbf{k}$$

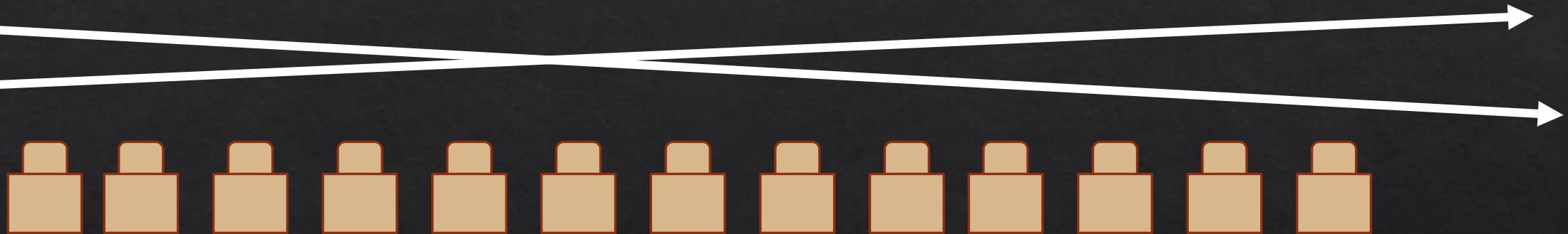


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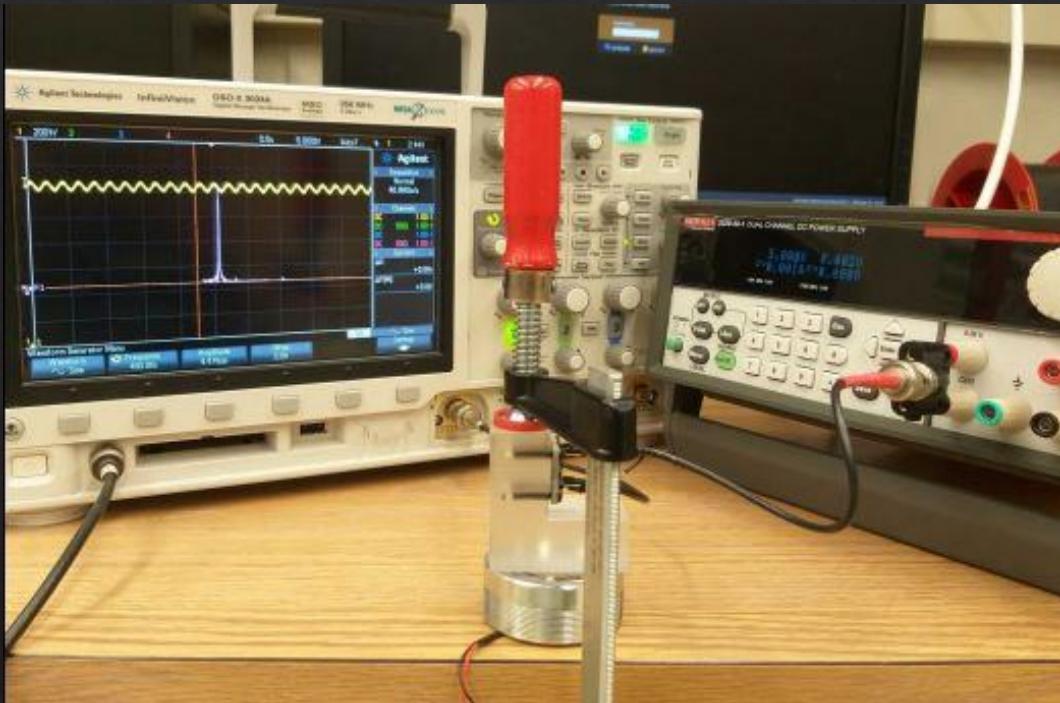
Overview of Gravitational Detection Method

- ❖ Long-term Goal: Detect Dark Matter directly using gravitational Interactions
- ❖ Uses accelerometers jerked by their interaction with the Dark Matter

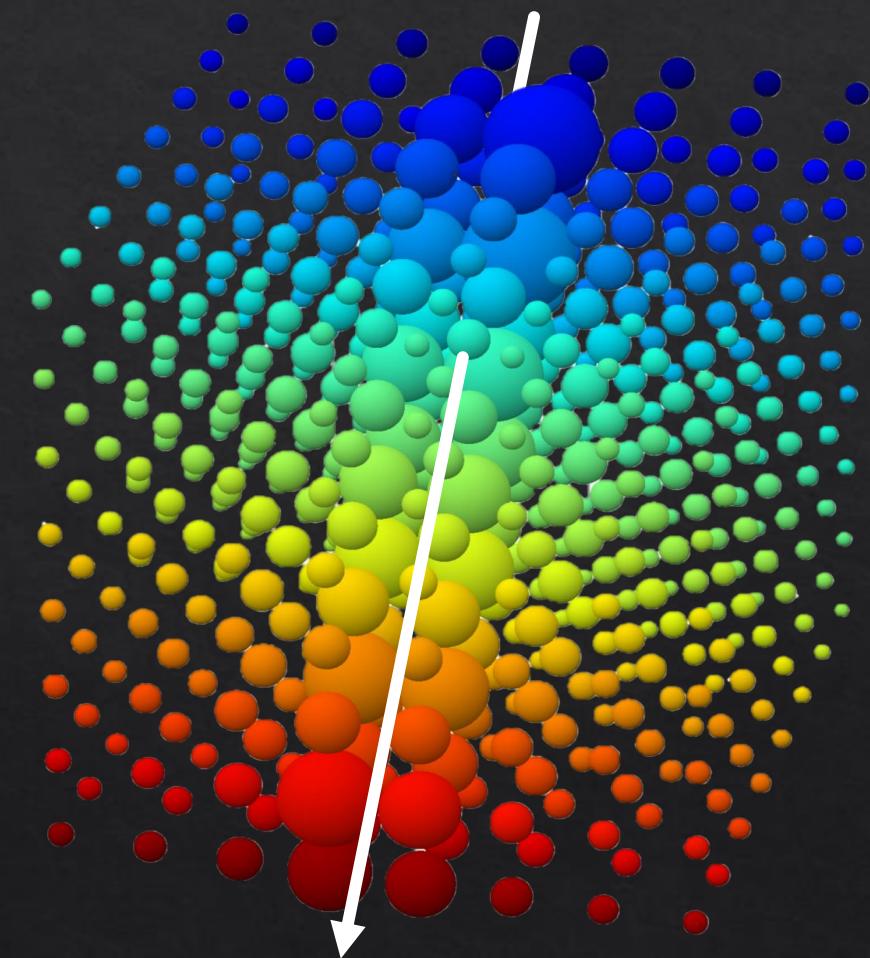


- ❖ Current Challenge: Noise
- ❖ For a Dark Matter particle detection, it is estimated that some 10^9 sensors *in the path* of the particle are required to have a significant Detection
- ❖ Test Statistic: Signal-to-Noise Ratio

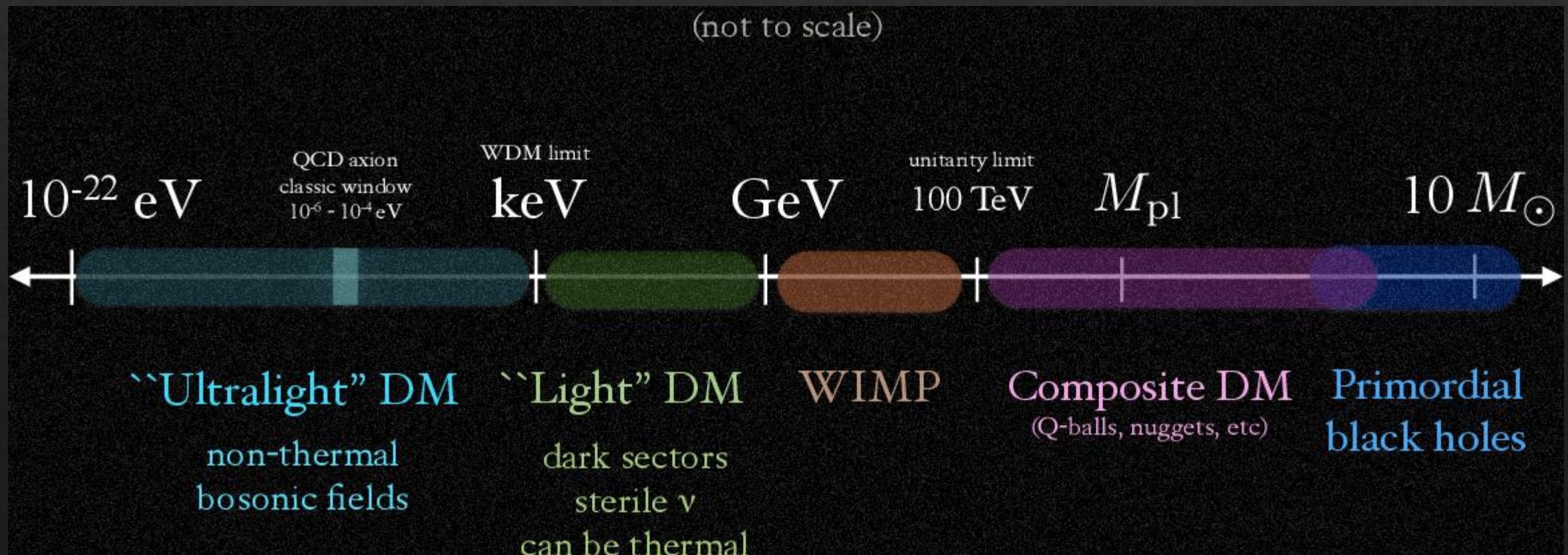
Physical Experiment: Protochime



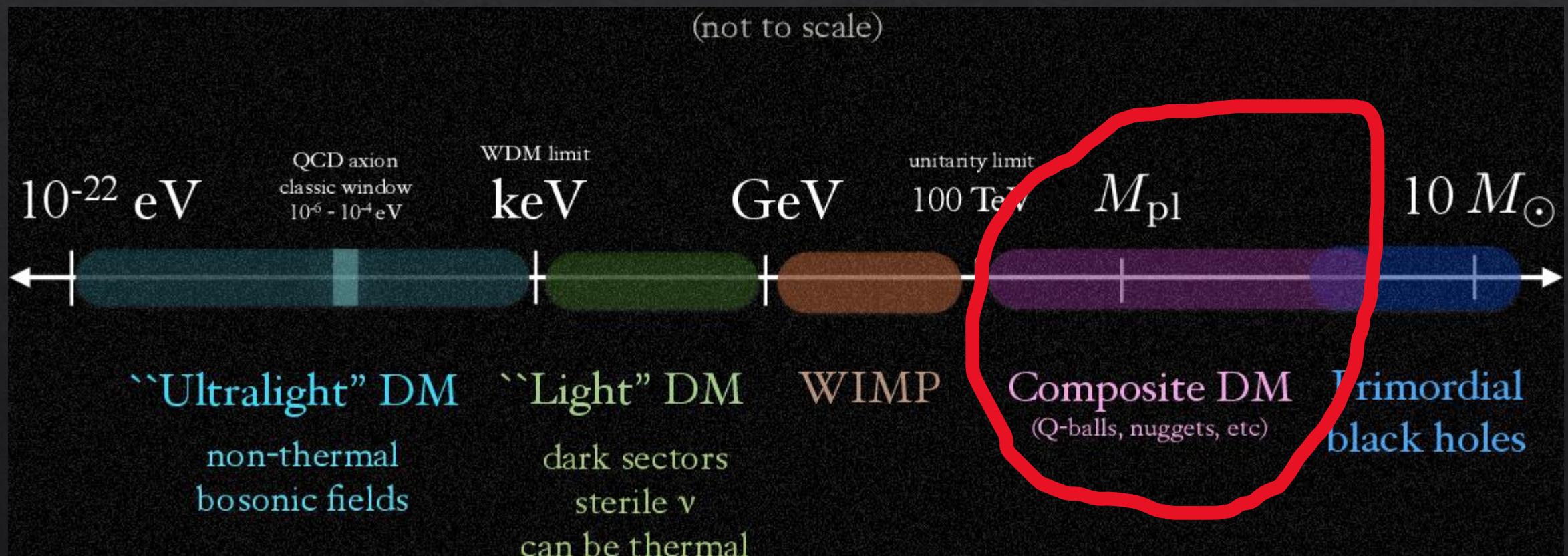
Virtual Experiment



What Kinds of Particles Do We Expect?



My Focus

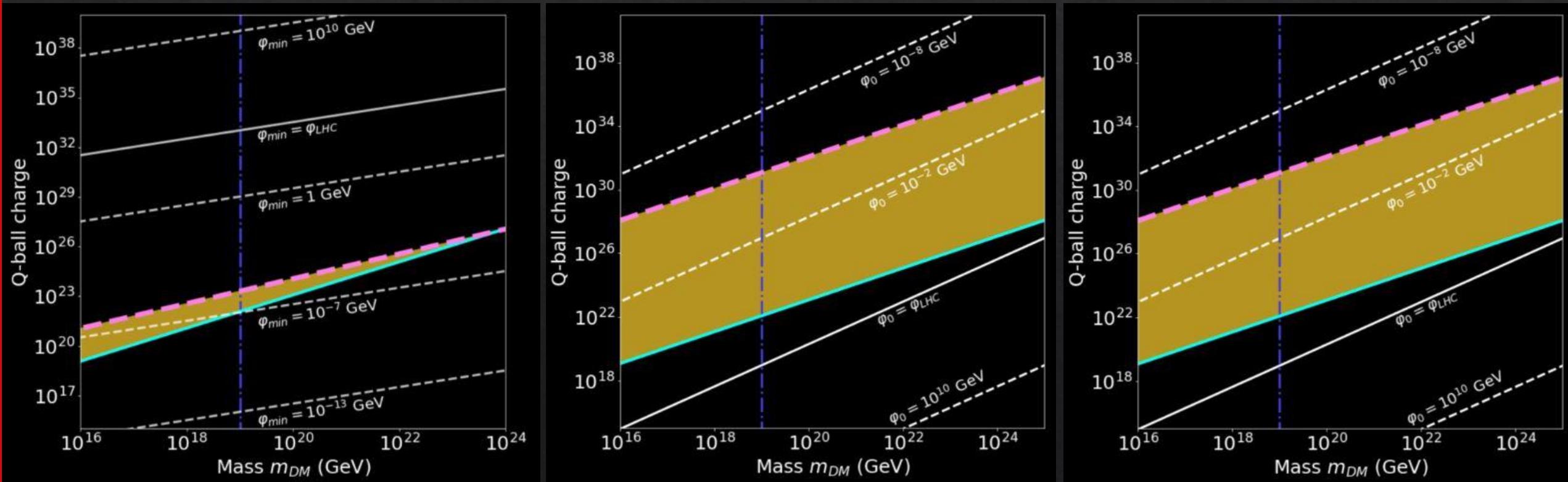


My Focus

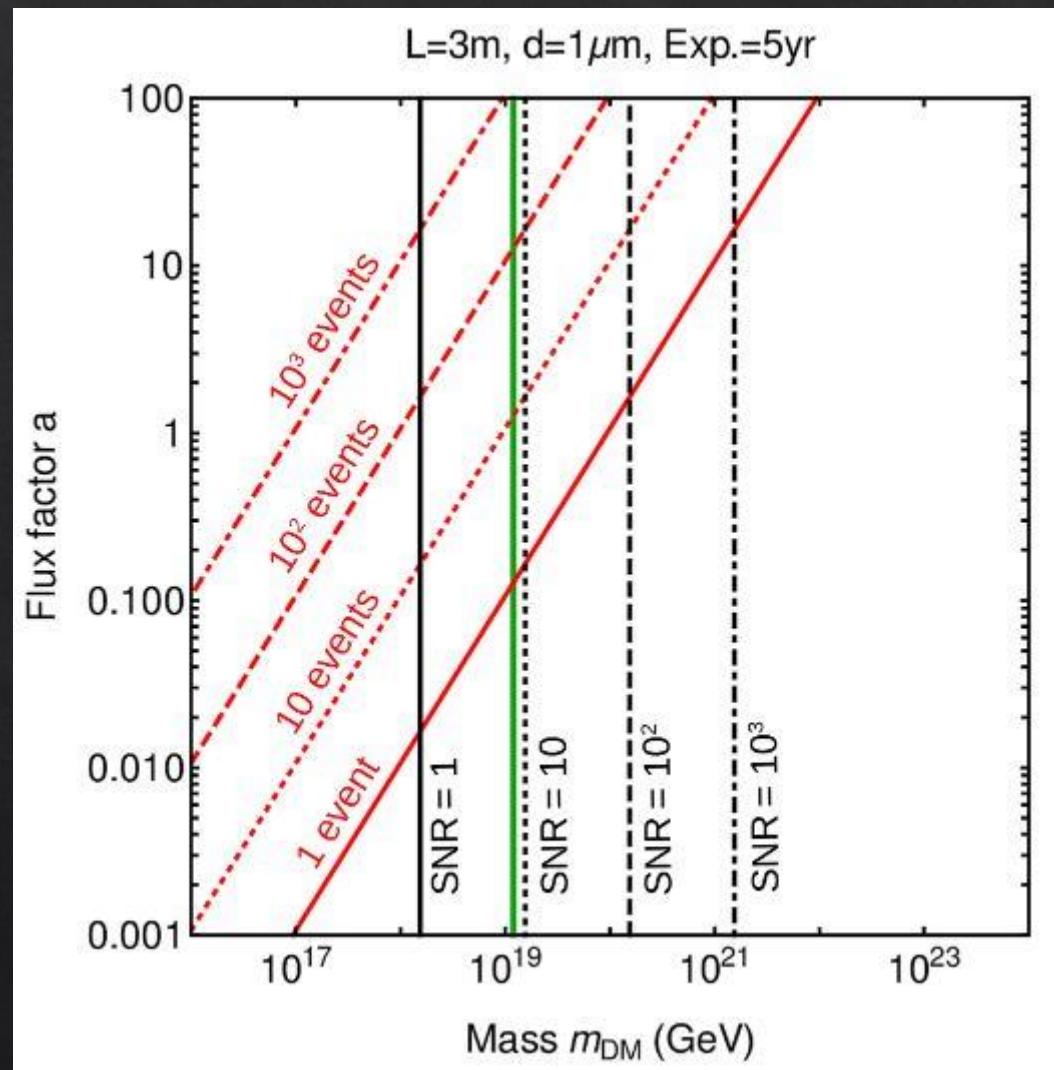
- ❖ Composite Dark Matter
 - ❖ DM Candidates composed of constituent particles
- ❖ Q-Balls – Non-Topological Solitons
 - ❖ Soliton solutions that admit a charge and allow for an energetically favorable massive state
- ❖ Superheavy Dark Matter Candidates
 - ❖ e.g. Extremal and “standard” PBH Relics and Gravitationally Produced particles (such as WIMPZILLAs)
- ❖ Flux Factor for a given candidate (mass) observed at a specific exposure and SNR

Q-Balls

- ❖ Type I - Thin-walled: The VeV is set close to the φ_0 of the scalar field
- ❖ Type II – Thick-walled: Gauge mediated field configuration with a flat potential
- ❖ Type III – Thick-walled: Same as Type II but with a logarithmic potential



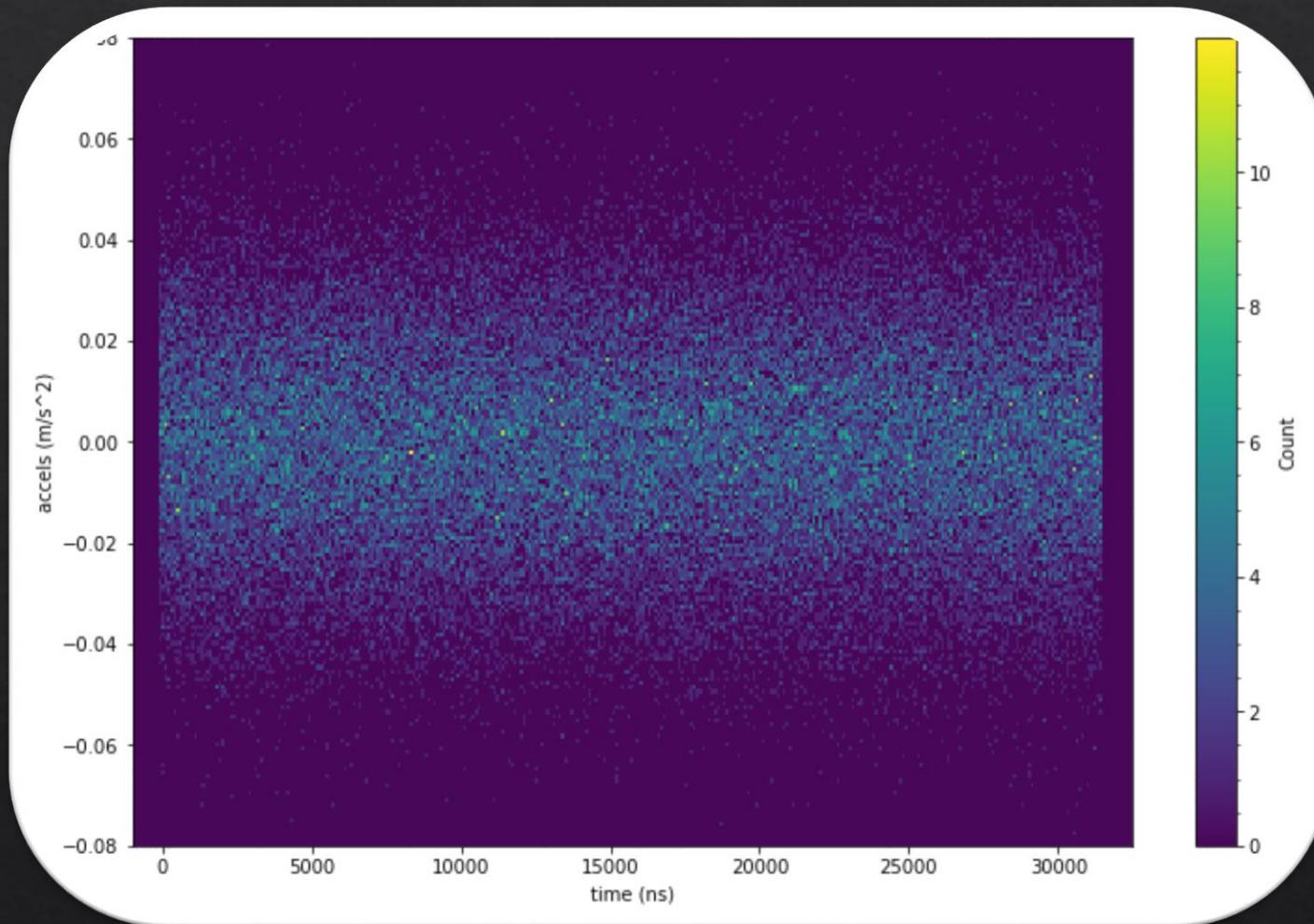
Multicandidate Flux Factor



Overview

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Acceleration Data



Detector

DM Particle
Track



Acceleration
Data

Analysis Framework

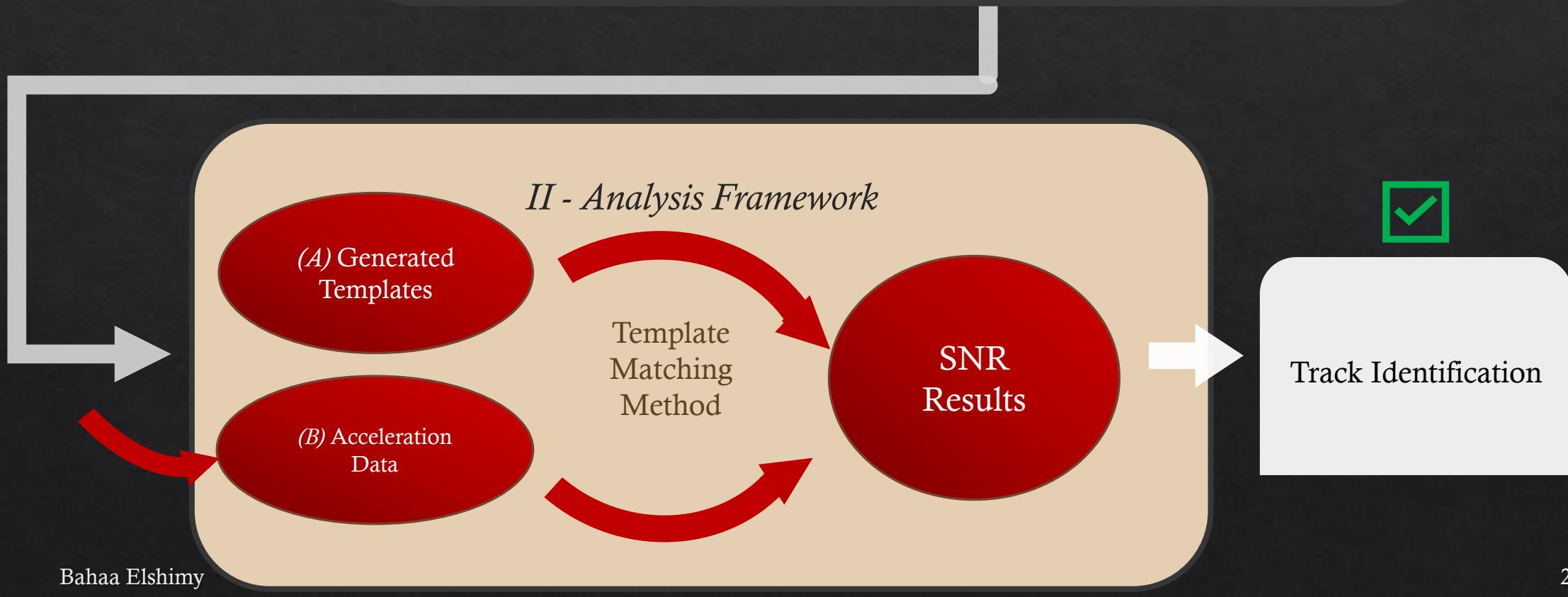
Track
Identification



I - Simulation Framework

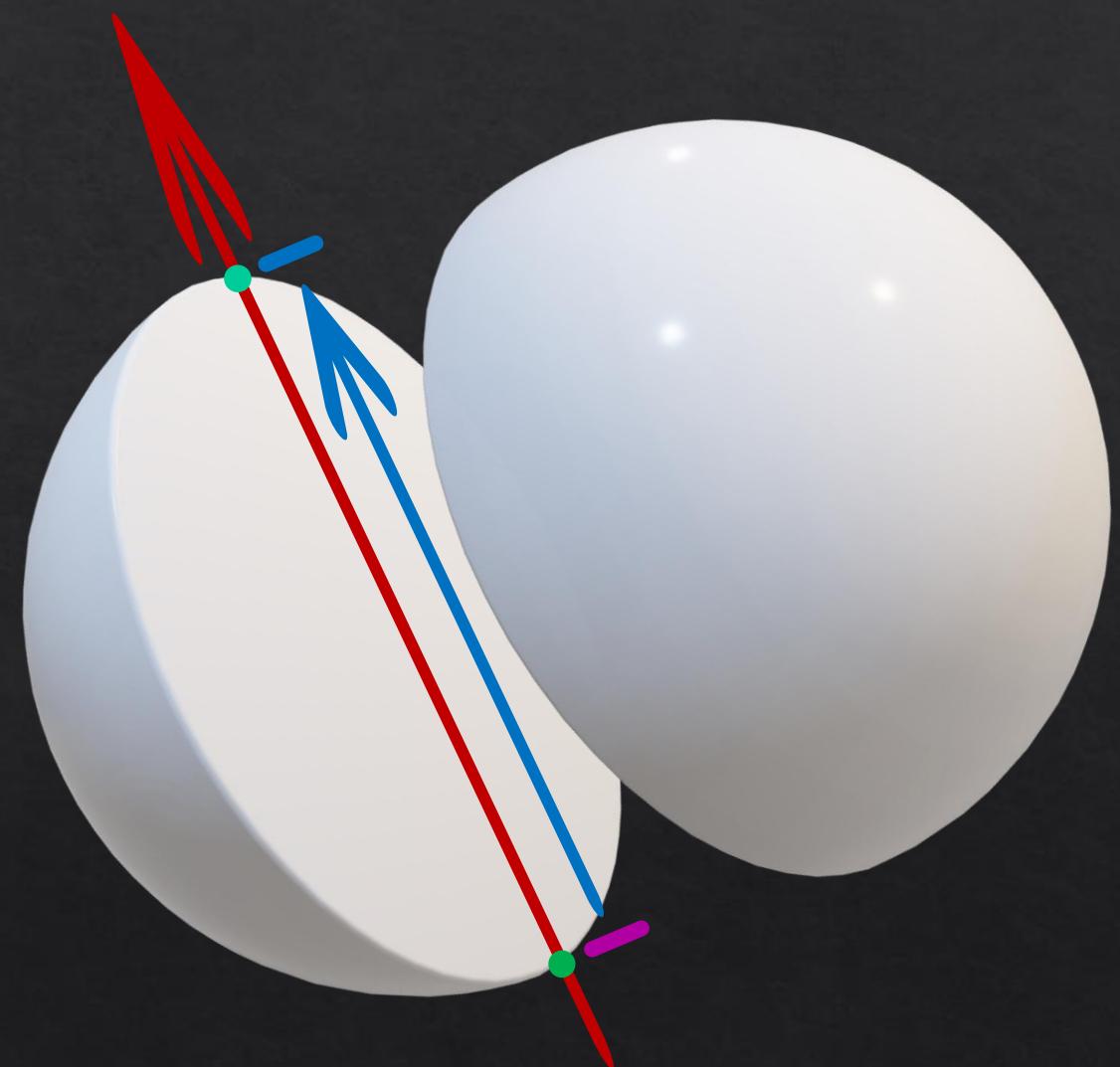


II - Analysis Framework

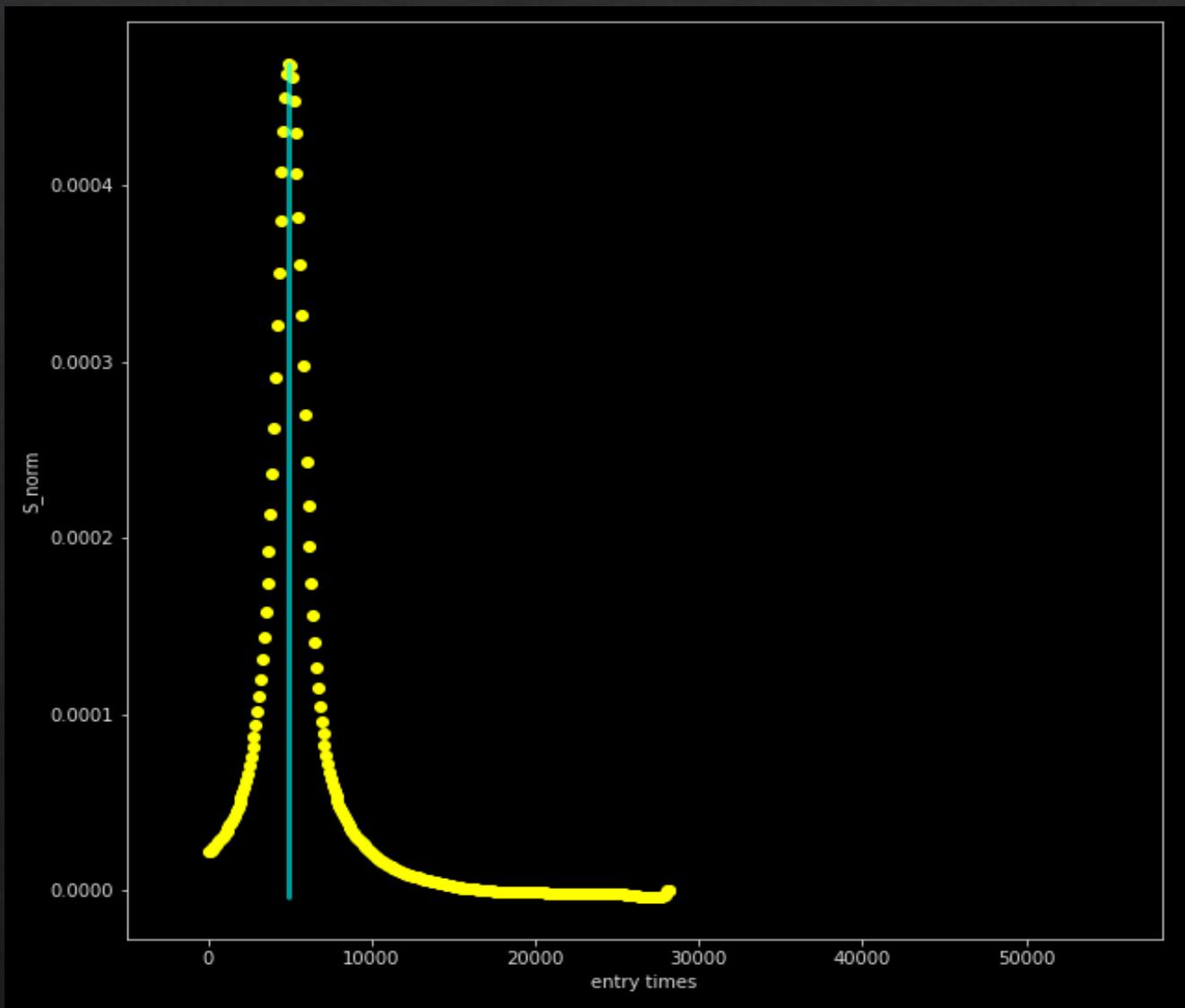


Template Analysis Parameters

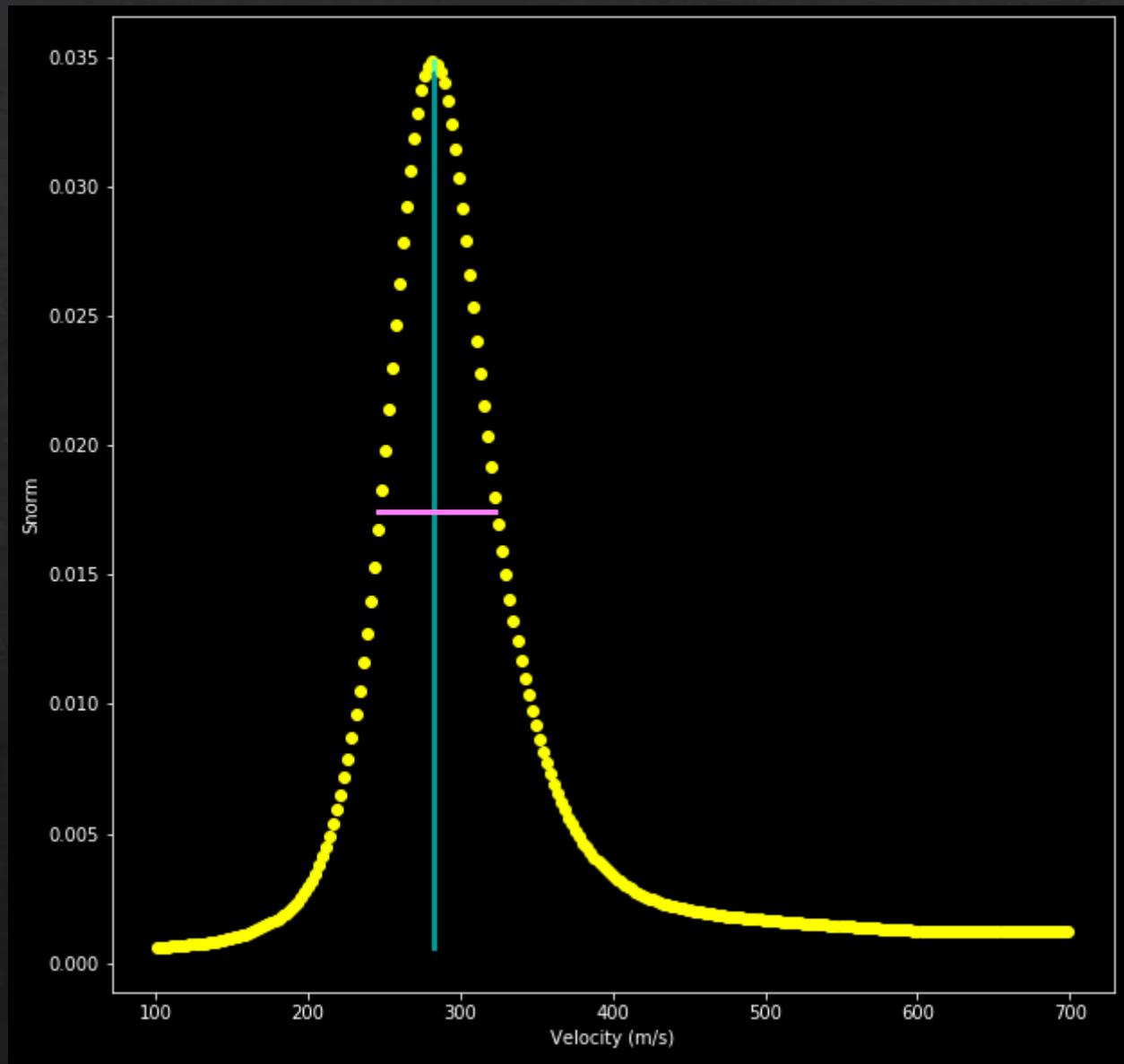
t_{entry} $v_{\text{el}}^{\text{exit}}$ θ_0 φ_0 θ_1 φ_1



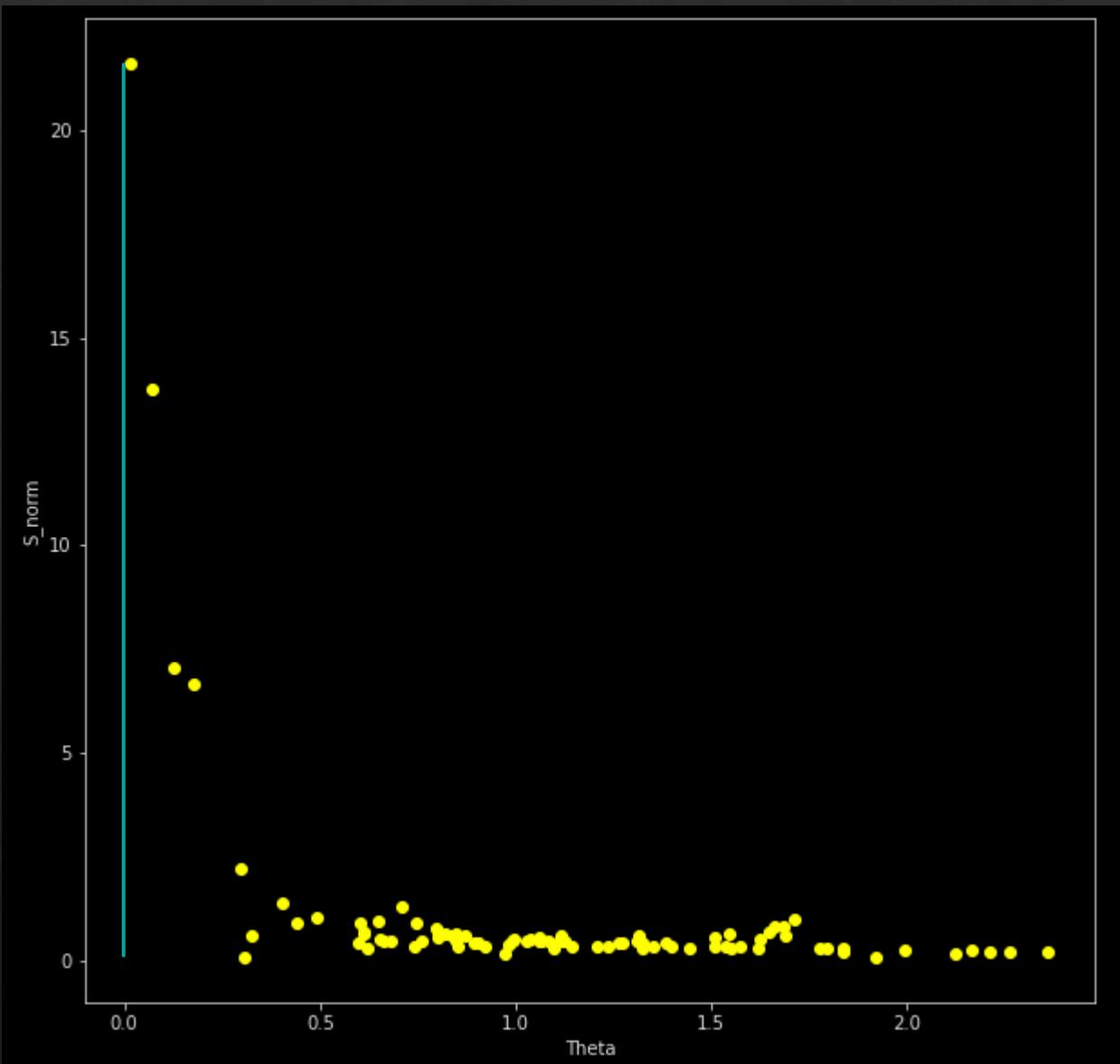
Time Analysis



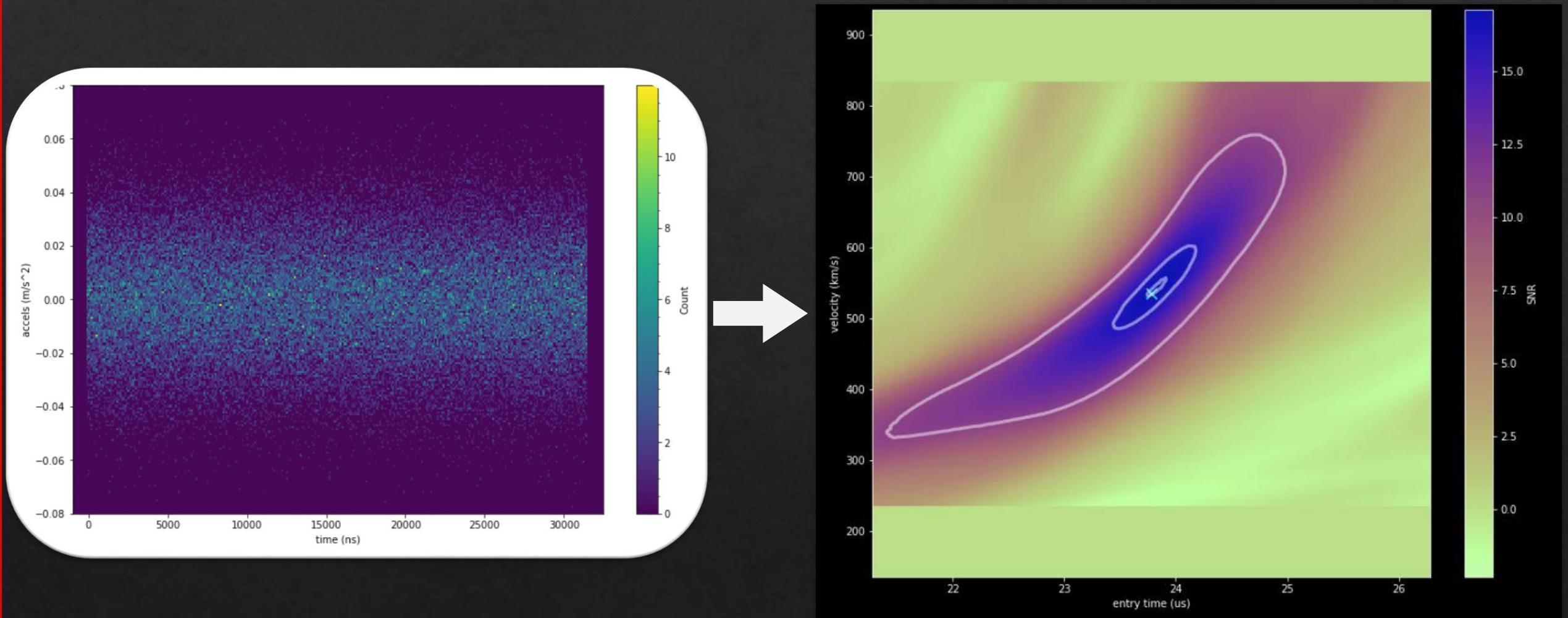
Velocity Analysis



Angular Analysis

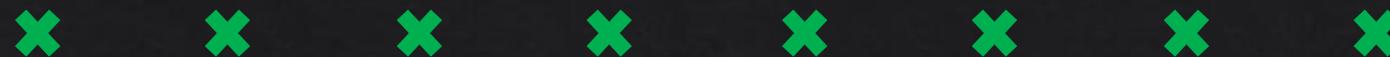


Time & Velocity Analysis



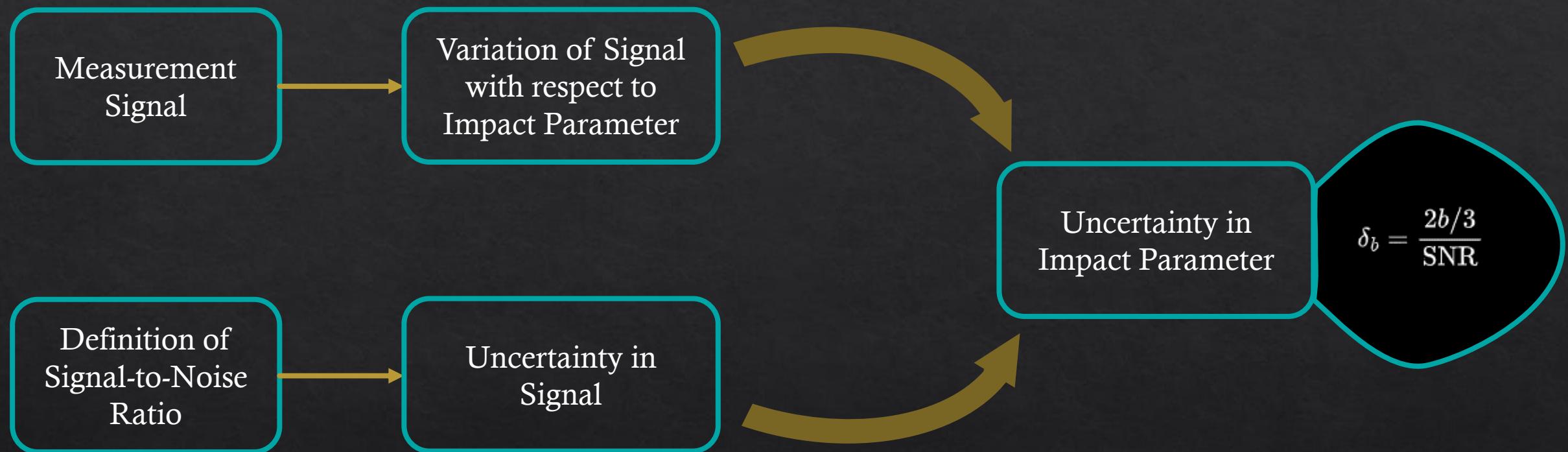
Resolution of the Windchime Detector

- ❖ Capacity to distinguish between different tracks in the detector
 - ❖ Smaller Resolution = Better Detector
- ❖ Defined through the uncertainty of the track parameters caused by sensor measurement errors
 - ❖ Temporal Resolution – Depends on the Exposure Time
 - ❖ Spatial Resolution – Depends on the Detector Geometry

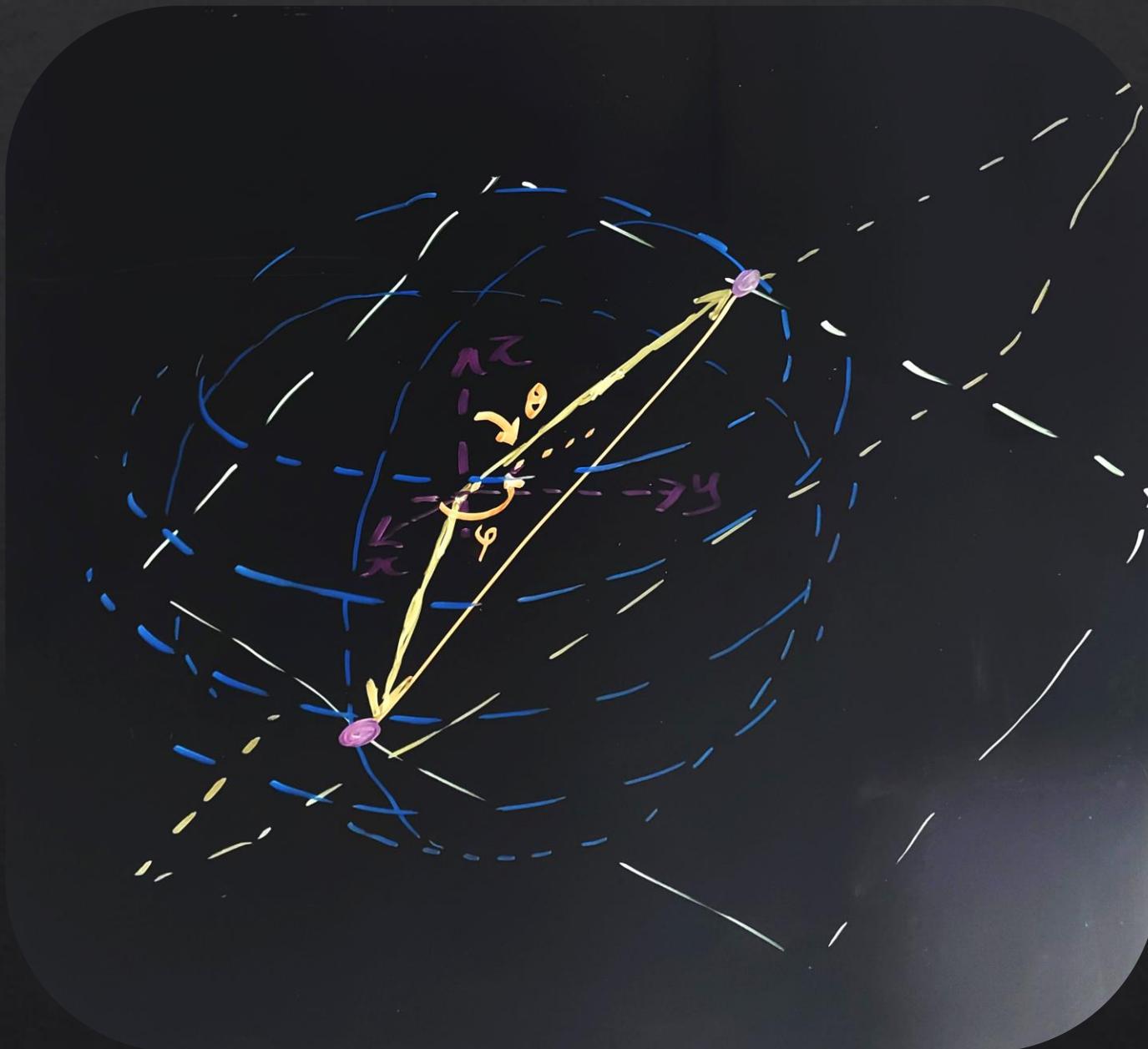


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Sensor Uncertainty



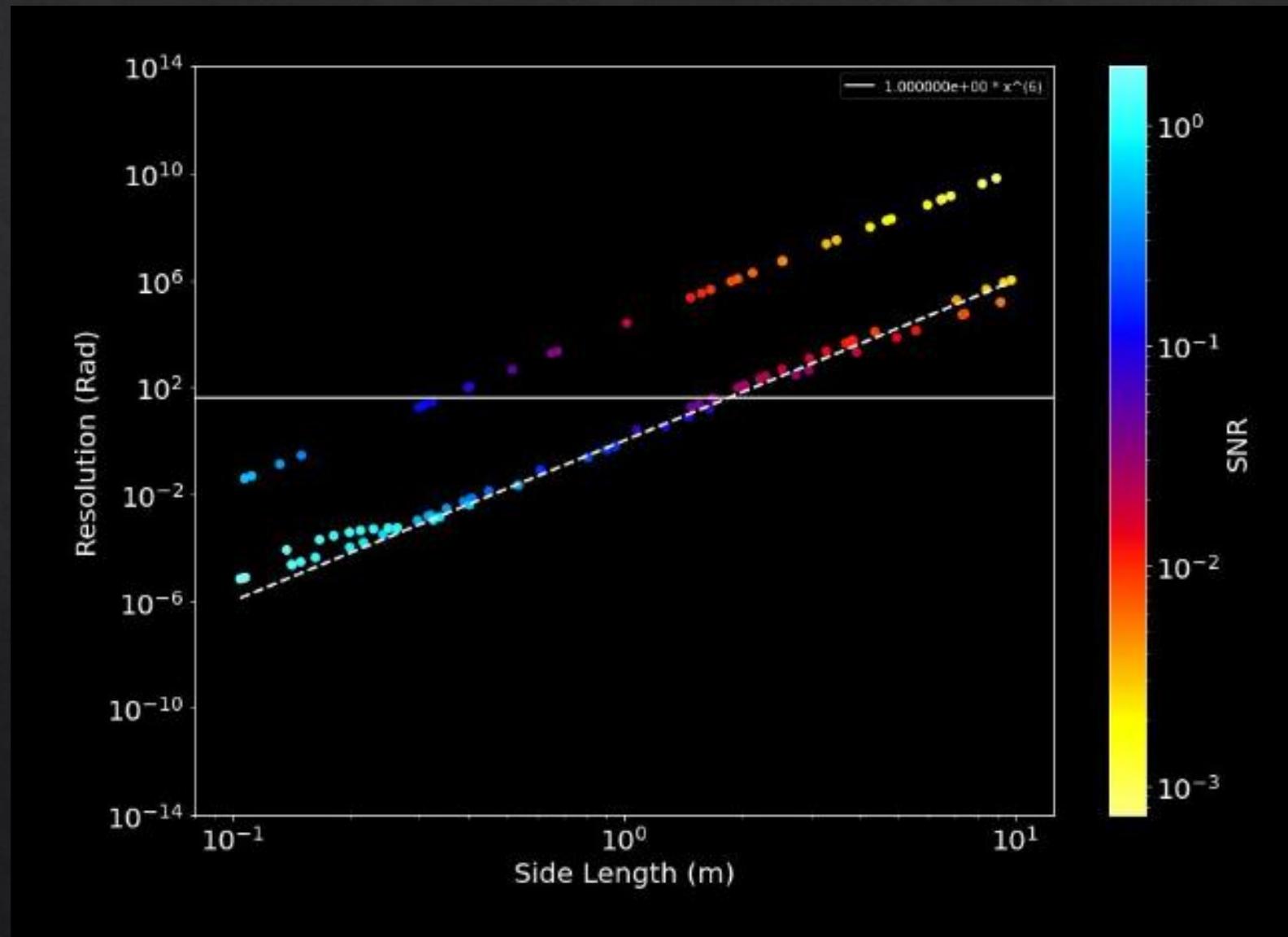
Spatial Resolution Model in 3D



Some of the Results

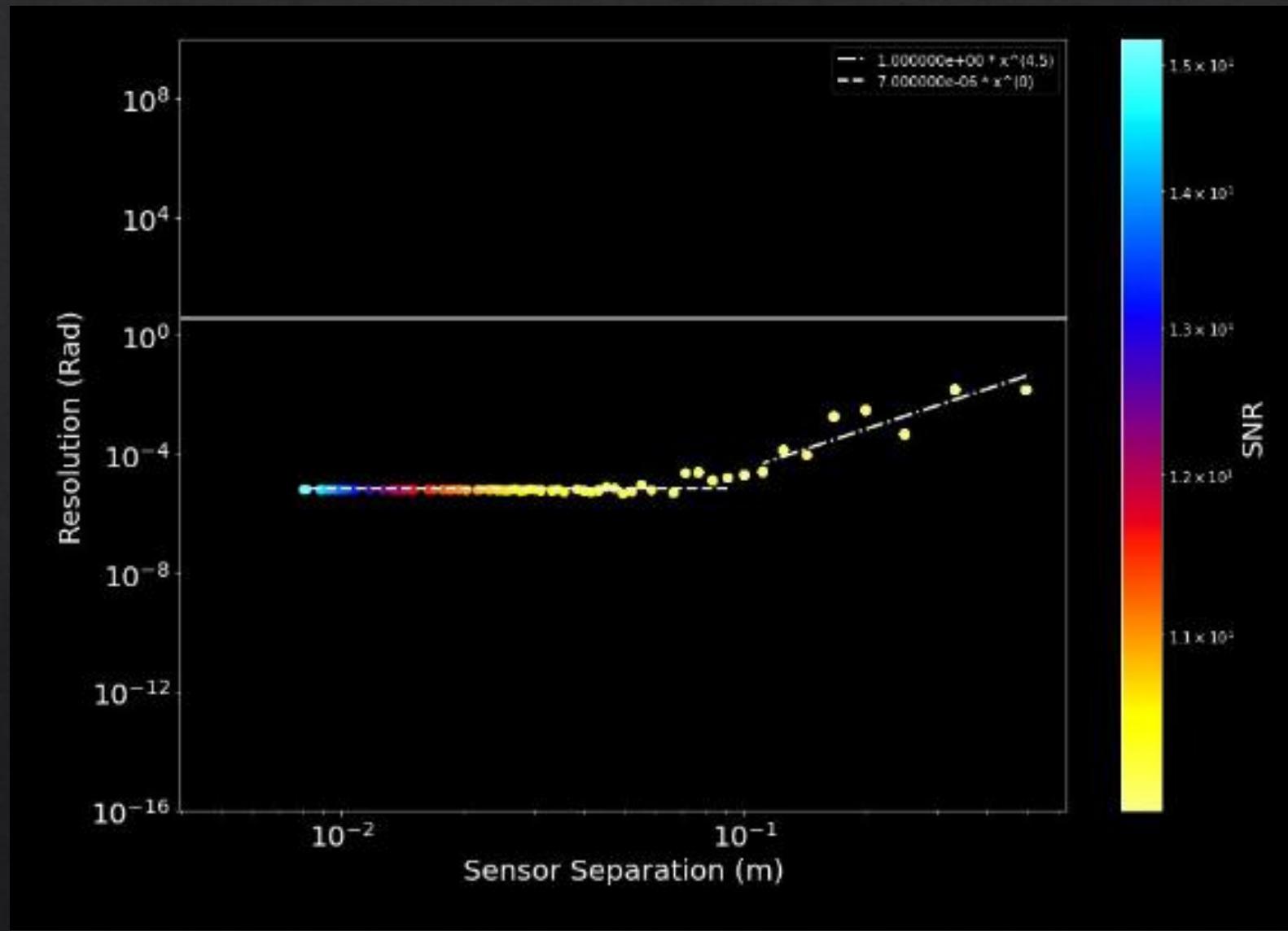
Constant Number
of Sensors
3D Analysis

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Some of the Results

Constant SNR and
Constant Side Length
2D Analysis



Trial Factor

- ◊ A measure of how likely it is to have a *False Positive* detection purely given the size of the parameter space

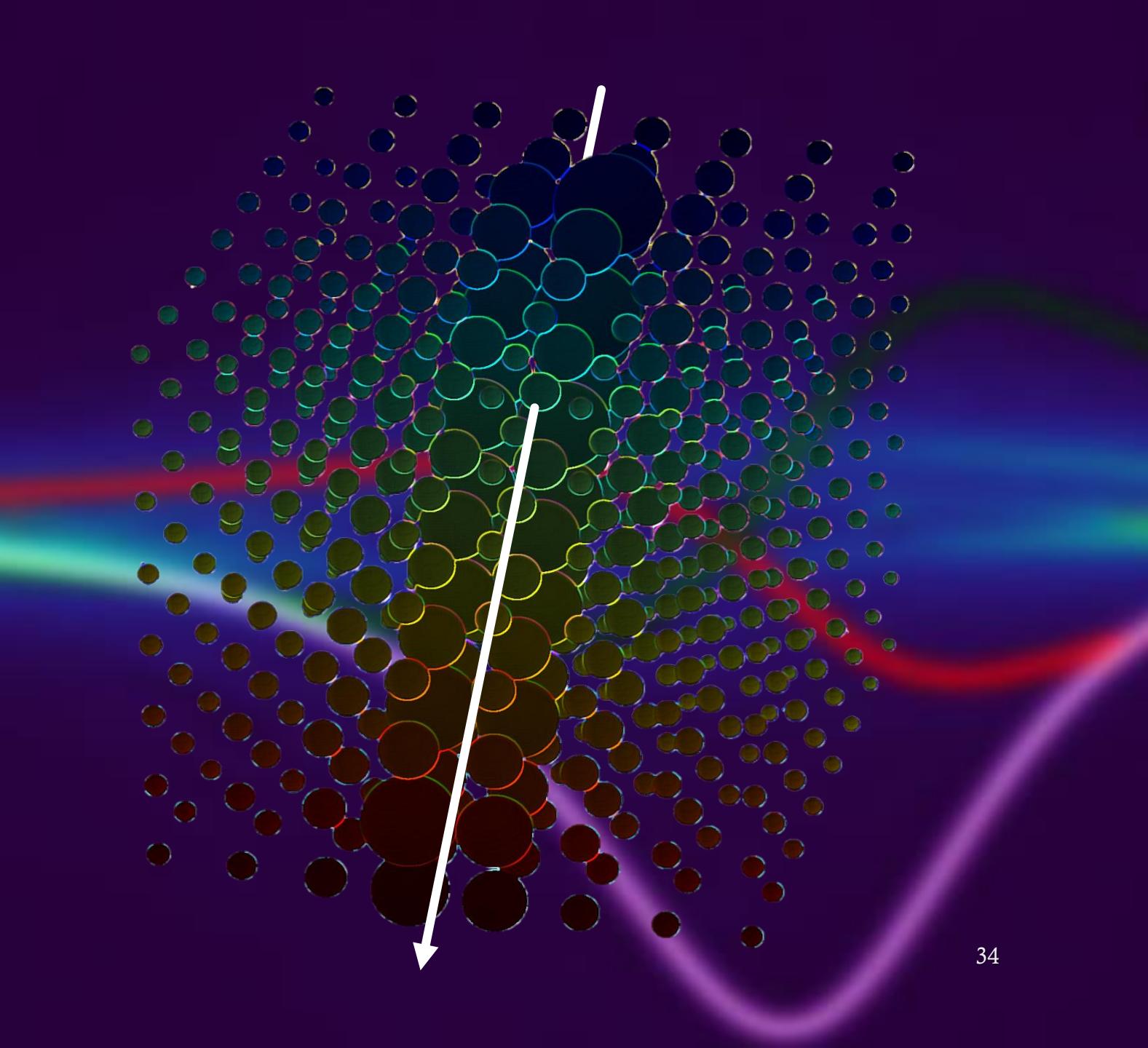
Smaller (better) Resolution = Larger Template (parameter) Space = Larger Trial Factor

$$\text{Trial Factor} = \frac{\text{Range Vol}}{\text{Resolution Vol}} \times Z^{\# \text{Dim}-1} = \frac{4\pi^4}{\delta_{\theta,\text{entry}} \delta_{\theta,\text{exit}} \delta_{\varphi,\text{entry}} \delta_{\varphi,\text{exit}}} \times \text{SNR}^3$$

For a specific given detector setup, this takes the detection significance threshold from an *SNR of 3* to an *SNR of 10*

The State of
Dark Matter
Detection is
Going
Gravitational!

Bahaa Elshimy



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Thank You!

References

- ❖ Gravitational Direct Detection of Dark Matter - <https://arxiv.org/pdf/1903.00492.pdf>
- ❖ Snowmass 2021 White Paper: The Windchime Project -
<https://arxiv.org/pdf/2203.07242.pdf>
- ❖ Models of ultra-heavy dark matter visible to macroscopic mechanical sensing arrays -
<https://arxiv.org/pdf/2112.14784.pdf>