Laser Scanner
Hokuyo UTM-30LX

545.44

Front

⌀ 165.10
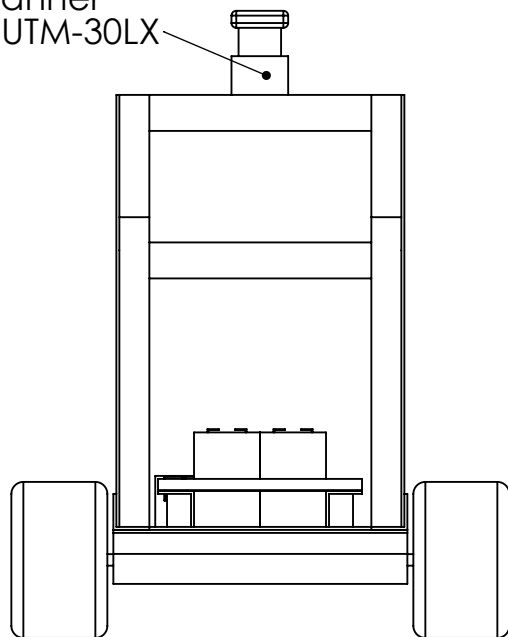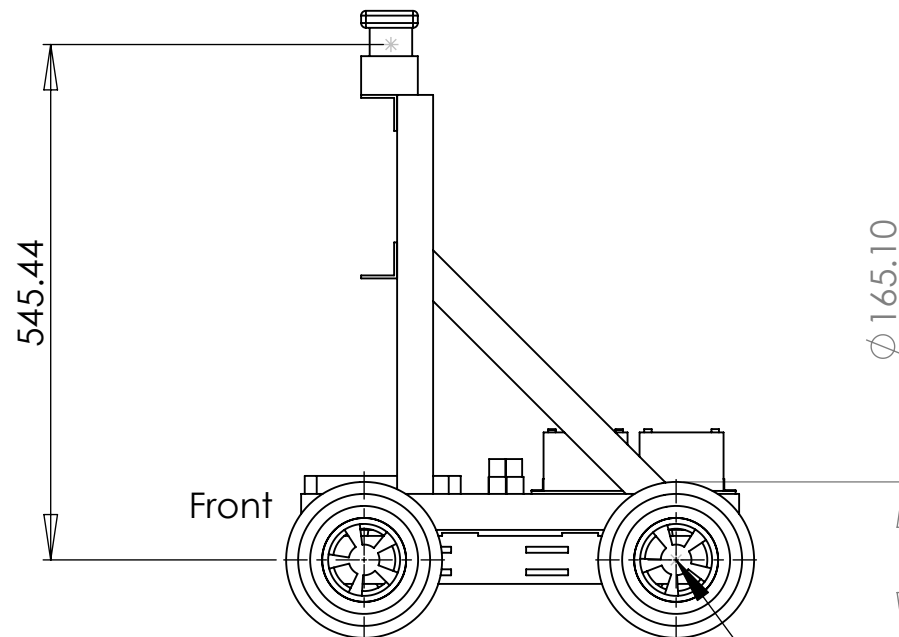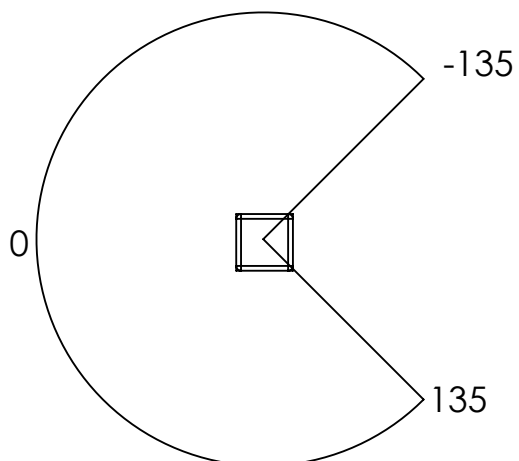
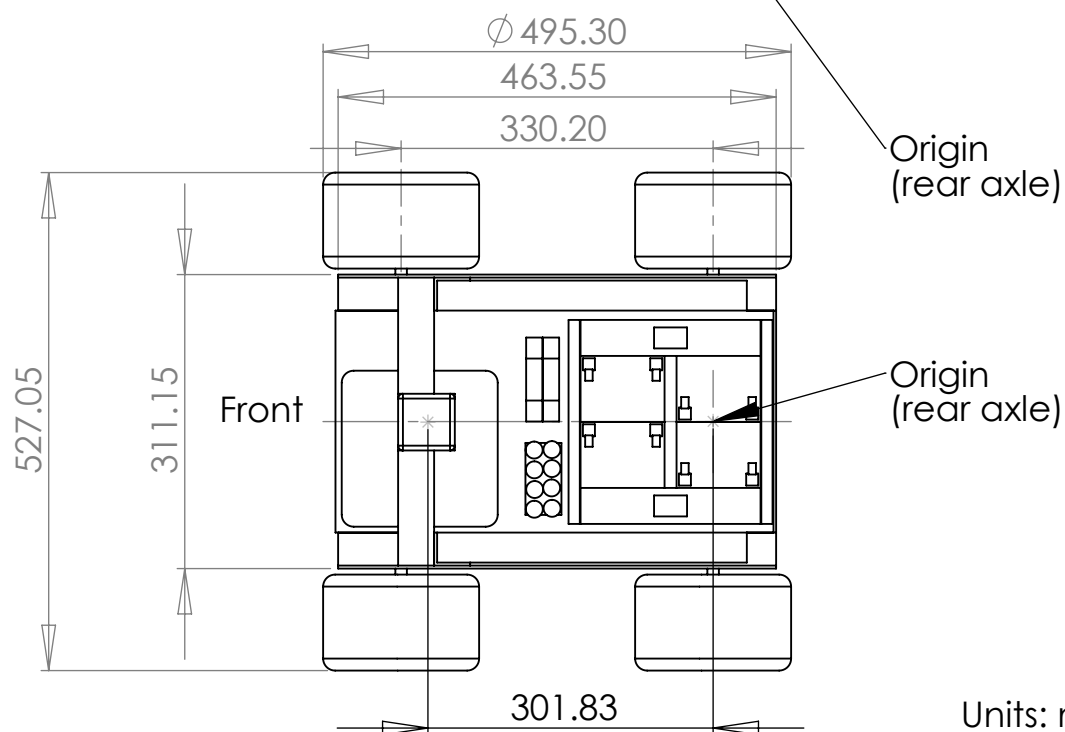Encoders: 180 counts/revolution

Encoder Order: FR FL RR RL

Encoder Direction: Forward motion = positive

Lidar 0-angle is forward, rotation is
counterclockwise from -135 to 135 degrees

-135

0

135

⌀ 495.30
463.55
330.20

Origin
(rear axle)

527.05

311.15

Front

Origin
(rear axle)

301.83

Units: mm

5   4   3   2   1