



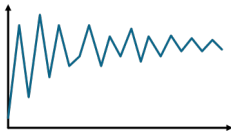
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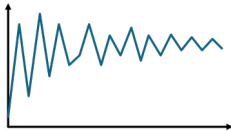
Coupled Markov chains with applications to Approximate Bayesian Computation for model based clustering

E. Bertoni, M. Caldarini, F. Di Filippo, G. Gabrielli, E. Musiari

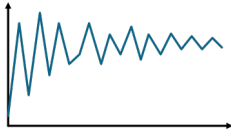
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A complex problem

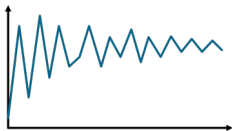




likelihood

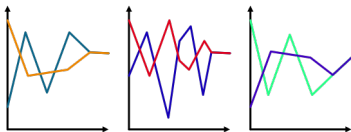


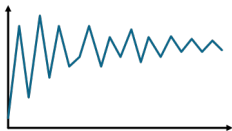
like a good
intractable



likely intractable

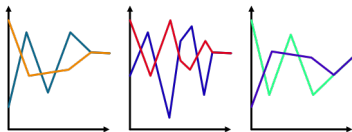
Unbiased Markov chain Monte Carlo methods with couplings





likelihood

Unbiased Markov chain Monte Carlo methods with couplings



Approximate Bayesian Computation



Unbiased Markov chain Monte Carlo methods with couplings

The road to parallelization: coupling of Markov chains

2/17

Faster MCMC \implies Parallelization

The road to parallelization: coupling of Markov chains

2/17

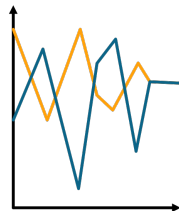
Faster MCMC \implies Parallelization \iff Unbiased estimator

The road to parallelization: coupling of Markov chains

2/17

Faster MCMC \implies Parallelization \iff Unbiased estimator

P. Glynn and C. Rhee proposed in 2018 the class of exact estimations algorithms using **coupling of Markov chain**.



Rhee–Glynn estimator I

The goal is to estimate

$$\mathbb{E}_{\pi}[h(X)] = \int h(x)\pi(\mathrm{d}x).$$

The estimator we are going to construct is based on a coupled pair of Markov chains, $(X_t)_{t \geq 0}$ and $(Y_t)_{t \geq 0}$, which marginally start from π_0 and evolve accordingly to P .

We consider some assumptions:

1 as $t \rightarrow \infty$,

$$\mathbb{E}[h(X_t)] \rightarrow \mathbb{E}_\pi[h(X)];$$

and there exists $\eta > 0$ and $D < \infty$ such that $\mathbb{E}[|h(X_t)|^{2+\eta}] \leq D$ for all $t \geq 0$;

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- ② the chains are such that the meeting time

$$\tau = \inf\{t \geq 1 : X_t = Y_{t-1}\}$$

satisfies $\mathbb{P}(\tau > t) \leq C\delta^t$ for all $t \geq 0$, for some constants $C < \infty$ and $\delta \in (0, 1)$;

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satisfies $\mathbb{P}(\tau > t) \leq C\delta^t$ for all $t \geq 0$, for some constants $C < \infty$ and $\delta \in (0, 1)$;

- ③ the chains stay together after meeting:

$$X_t = Y_{t-1} \text{ for all } t \geq \tau.$$

Rhee–Glynn estimator II

Thanks to the previous assumptions we can prove that:

$$\mathbb{E}_{\pi}[h(X)] = \mathbb{E}[h(X_k) + \sum_{t=k+1}^{\tau-1} \{h(X_t) - h(Y_{t-1})\}];$$

Rhee–Glynn estimator II

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and we define the Rhee–Glynn estimator as:

$$H_k(X, Y) = h(X_k) + \sum_{t=k+1}^{\tau-1} \{h(X_t) - h(Y_{t-1})\}$$

which is **unbiased** by construction.

Time-averaged estimator

$$H_{k:m}(X, Y) = \frac{1}{m - k + 1} \sum_{l=k}^m h(X_l) + \sum_{l=k+1}^{\tau-1} \min(1, \frac{l - k}{m - k + 1}) \{h(X_l) - h(Y_{l-1})\}$$

Time-averaged estimator

$$H_{k:m}(X, Y) = \underbrace{\frac{1}{m-k+1} \sum_{l=k}^m h(X_l)}_{MCMC_{k:m}} + \sum_{l=k+1}^{\tau-1} \min(1, \frac{l-k}{m-k+1}) \{h(X_l) - h(Y_{l-1})\}$$

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Time-averaged estimator

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- $MCMC_{k:m}$ is the standard MCMC average;
- $BC_{k:m}$ is the bias correction;

The MH **algorithm** adapted with couplings:

- ① draw X_0 and Y_0 from an initial distribution π_0 and draw $X_1 \sim P(X_0, \cdot)$;
- ② set $t = 1$: while $t < \max\{m, \tau\}$ and:
 - a draw $(X_{t+1}, Y_t) \sim \bar{P}\{(X_t, Y_{t-1}), \cdot\}$;
 - b set $t \leftarrow t + 1$;
- ③ compute

$$H_{k:m}(X, Y)$$

with the time-averaged estimator.

Application to Metropolis-Hasting algorithm II

The following is the **algorithm** to calculate the coupled kernel

$\bar{P}\{(X_t, Y_{t-1}), \cdot\}$ via MH:

- 1 sample $(X^*, Y^*) | (X_t, Y_{t-1})$ from a maximal coupling of $q(X_t, \cdot)$ and $q(Y_{t-1}, \cdot)$;
- 2 sample $U \sim \mathcal{U}([0, 1])$;

- 3 if

$$U \leq \min \left\{ 1, \frac{\pi(X^*)q(X^*, X_t)}{\pi(X_t)q(X_t, X^*)} \right\}$$

then $X_{t+1} = X^*$; otherwise $X_t = X_{t-1}$;

- 4 if

$$U \leq \min \left\{ 1, \frac{\pi(Y^*)q(Y^*, Y_t)}{\pi(Y_t)q(Y_t, Y^*)} \right\}$$

then $Y_{t+1} = Y^*$; otherwise $Y_t = Y_{t-1}$.



Approximate Bayesian Computation

Likelihood-free rejection sampling algorithm I

Inputs:

- a target posterior density $\pi(\theta|y_{obs}) \propto p(y_{obs}|\theta)\pi(\theta)$, consisting of a prior distribution $\pi(\theta)$ and a procedure of generating data under the model $p(y_{obs}|\theta)$;
- a proposal density $g(\theta)$, with $g(\theta) > 0$ if $\pi(\theta|y_{obs}) > 0$;
- an integer $N > 0$.

Likelihood-free rejection sampling algorithm I

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- an integer $N > 0$.

Sampling for $i = 1, \dots, N$:

- ① generate $\theta^{(i)} \sim g(\theta)$ from sampling density g ;
- ② generate $y \sim p(y|\theta^{(i)})$ from the likelihood;
- ③ if $y = y_{obs}$, then accept $\theta^{(i)}$ with probability $\frac{\pi(\theta^{(i)})}{Kg(\theta^{(i)})}$, where $K \geq \max_{\theta} \frac{\pi(\theta)}{g(\theta)}$; else go to ①.

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 $K \geq \max_{\theta} \frac{\pi(\theta)}{g(\theta)}$; else go to ①.

Output:

- a set of parameter vectors $\theta^{(1)}, \dots, \theta^{(N)}$ which are samples from $\pi(\theta|y_{obs})$.

Is this an efficient method for complex analysis?

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③ If $\|y - y_{obs}\| \leq h$, then accept $\theta^{(i)}$ with probability $\frac{\pi(\theta^{(i)})}{Kg(\theta^{(i)})}$, where $K \geq \max_{\theta} \frac{\pi(\theta)}{g(\theta)}$; else go to ①.

$$\pi(\theta, y|y_{obs}) \propto \mathbb{I}(\|y - y_{obs}\| \leq h) p(y|\theta) \pi(\theta)$$

$$\Downarrow$$

$$\pi_{ABC}(\theta, y|y_{obs}) \propto K_h(u) p(y|\theta) \pi(\theta)$$

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$$\Downarrow$$

$$\pi_{ABC}(\theta, y|y_{obs}) \propto K_h(u) p(y|\theta) \pi(\theta)$$

Where we used a **standard smoothing kernel function**:

$$K_h(u) = \frac{1}{h} K\left(\frac{u}{h}\right), \quad \text{with } u = \|y - y_{obs}\|$$

Is this feasible in practice?

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No

Is this feasible in practice?

No

\implies use summary statistics $s = S(y)$

Critical decision: choice of summary statistics

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⇒ choose sufficient statistics, such that:

$$\pi(\theta|\mathbf{s}_{obs}) \equiv \pi(\theta|y_{obs})$$

Distance measure: substantial impact on ABC algorithm efficiency

$$\| \mathbf{s} - \mathbf{s}_{obs} \| = (\mathbf{s} - \mathbf{s}_{obs})^\top \Sigma^{-1} (\mathbf{s} - \mathbf{s}_{obs})$$

Distance measure: substantial impact on ABC algorithm efficiency

$$\| \mathbf{s} - \mathbf{s}_{obs} \| = (\mathbf{s} - \mathbf{s}_{obs})^\top \Sigma^{-1} (\mathbf{s} - \mathbf{s}_{obs})$$

- $\Sigma = \text{identity matrix} \rightarrow \text{Euclidean distance}$
- $\Sigma = \text{diagonal matrix of non-zero weights} \rightarrow \text{Weighted Euclidean distance}$
- $\Sigma = \text{full covariance matrix of } \mathbf{s} \rightarrow \text{Mahalanobis distance}$

ABC rejection sampling algorithm

Inputs:

- a target posterior density $\pi(\theta|y_{obs}) \propto p(y_{obs}|\theta)\pi(\theta)$, consisting of a prior distribution $\pi(\theta)$ and a procedure of generating data under the model $p(y_{obs}|\theta)$;
- a proposal density $g(\theta)$, with $g(\theta) > 0$ if $\pi(\theta|y_{obs}) > 0$;
- an integer $N > 0$;
- a kernel function $K_h(u)$ and a scale parameter $h > 0$;
- a low dimensional vector of summary statistics $s = S(y)$.

ABC rejection sampling algorithm

Sampling for $i = 1, \dots, N$:

- ① generate $\theta^{(i)} \sim g(\theta)$ from sampling density g ;
- ② generate $y \sim p(y|\theta^{(i)})$ from the likelihood;
- ③ compute summary statistic $s = S(y)$;
- ④ accept $\theta^{(i)}$ with probability $\frac{K_h(\|s - s_{obs}\|)\pi(\theta^{(i)})}{Kg(\theta^{(i)})}$, where
 $K \geq K_h(0) \max_{\theta} \frac{\pi(\theta)}{g(\theta)}$; else go to 1.

Output:

- a set of parameter vectors $\theta^{(1)}, \dots, \theta^{(N)} \sim \pi_{ABC}(\theta|S_{obs})$.



Conclusions

Our focus till now was to understand the fundamental concepts and collect the missing information.

The next step will be a **simple and separate implementation** of both solution to be tested on simulated data.

Further steps will consider the **integration** of both solution into a single implementation and the testing on more complex data.

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