

Please Refer to the MKS SERVO42D Manual for further instructions.

You will need a Dupont male to female cable, 2 x 16 gauge wires and one USB C to USB A Data cable.

The 2 16 gauge wires must be twisted as shown. One cable will go to CAN L, One will go to CAN H. These are necessary for CAN communication.

Connect the jumper cable to Ground, this will wire to A Ground pin (pin 39) on the raspberry pi.

Connect the USB C cable from the CAN adapter to one of the usb ports on the raspberry pi.

