

# Powered Dirichlet Process

## Controlling the “Rich-Get-Richer” Assumption in Bayesian Clustering

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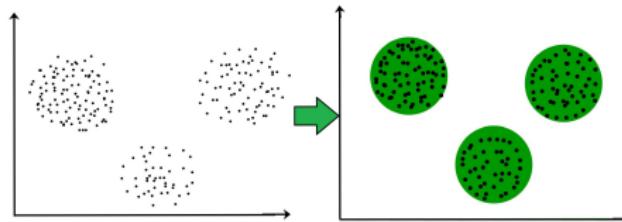


# Bayesian clustering

- Bayesian clustering approaches received a broad attention over the last decades
  - Medicine, natural language processing, genetics, recommender systems, sociology, etc.
- General idea (Bayes theorem):

$$\underbrace{P(\text{cluster}|\text{data})}_{\text{Posterior probability}} \propto \underbrace{P(\text{data}|\text{cluster})}_{\text{Likelihood}} \times \underbrace{P(\text{cluster})}_{\text{Prior probability}}$$

- In most cases, the prior is a Dirichlet distribution
  - Natural: yield an array whose entries sum to 1
  - Convenient: Can be expressed as a process



# Dirichlet process

- Dirichlet process prior probability for the  $i^{th}$  observation:

$$DP(C_i = c | \mathcal{H}, \alpha) = \begin{cases} \frac{N_c}{\alpha + N} & \text{if } c = 1, \dots, K \\ \frac{\alpha}{\alpha + N} & \text{if } c = K+1 \end{cases}$$

- Useful to model sequential data
- The number of clusters does not have to be specified in advance

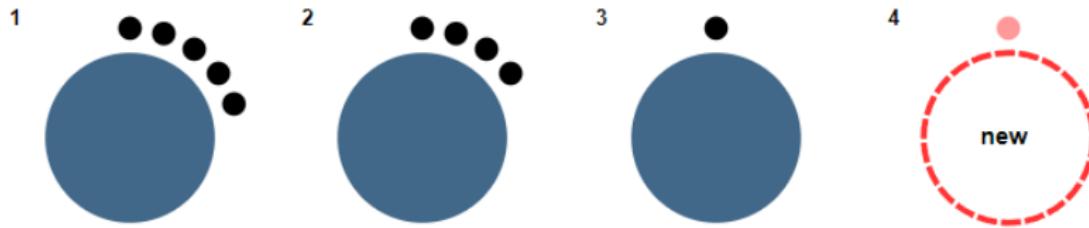
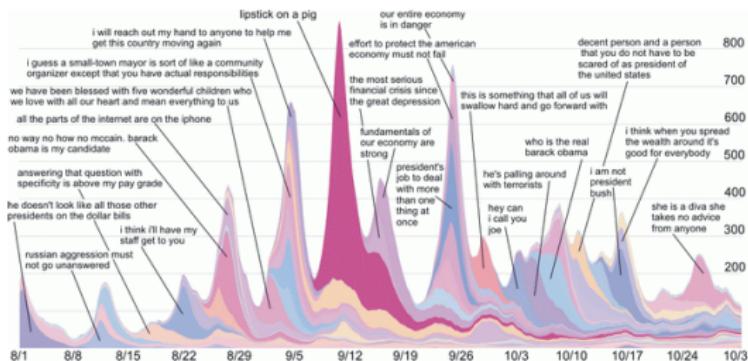


Figure 1: Example of a Dirichlet Process (10 steps)

# Dirichlet Process - Why

- The DP exhibit a linear “rich-get-richer” property ( $P(c) \propto N_c$ )
  - Why  $P(c)$  should linearly depend on  $N_c$ ? (Lee and Sang, 2022)
  - Why  $P(c)$  should depend on population at all? (Wallach et al., 2010)
- The “rich-get-richer” implies that the expected number of clusters K grows as  $\alpha \log(N) \rightarrow$  No *a priori* reason for it to be true
  - Ex. news stream: new clusters may appear at a constant rate
  - Problem usually bypassed by fine-tuning  $\alpha \rightarrow$  We lose all the benefit of a sequential model.



## To summarize

- Dirichlet Processes are an arbitrary choice.
    - Other priors are possible (Welling, 2006; Lee and Sang, 2022)
    - The choice of the prior matters (Wallach et al., 2009)
  - Most variations still consider a linear dependence on  $N_c$ :
    - Pitman-Yor Process:  $P(c) \propto N_c - \beta$
    - Generalized Gamma Process:  $P(c) \propto N_c - \sigma$
    - Indian Buffet Process:  $P(c) \propto N_c - \frac{\alpha}{K}$
  - The Uniform Process gets rid of the dependence on  $N_c$ :
    - Uniform Process:  $P(c) \propto 1$
    - Intermediate alternatives?
- Powered Dirichlet Process as an answer

# Powered Dirichlet Process

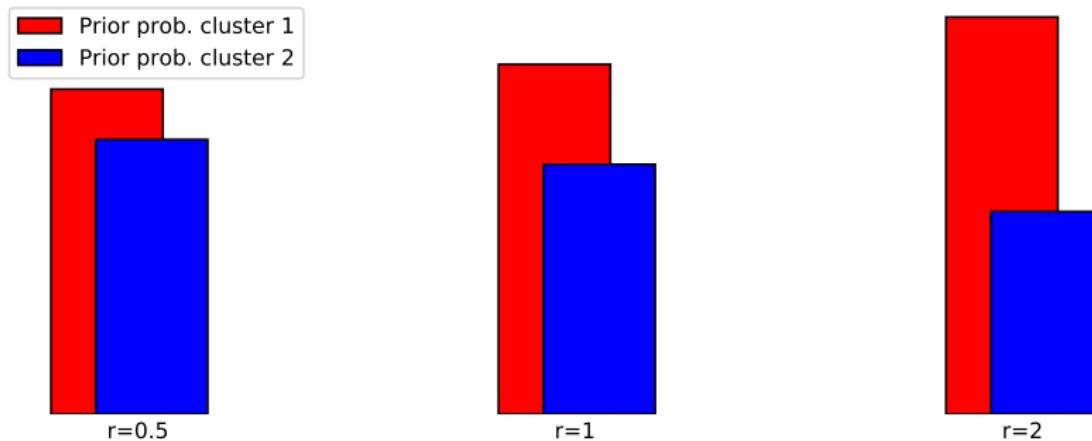
- Powered Dirichlet Process (PDP):

$$PDP(C_i = c | \mathcal{H}, \alpha, r) = \begin{cases} \frac{N_c^r}{\alpha + \sum_k N_k^r} & \text{if } c = 1, \dots, K \\ \frac{\alpha}{\alpha + \sum_k N_k^r} & \text{if } c = K+1 \end{cases}$$

- Generalization of existing models:

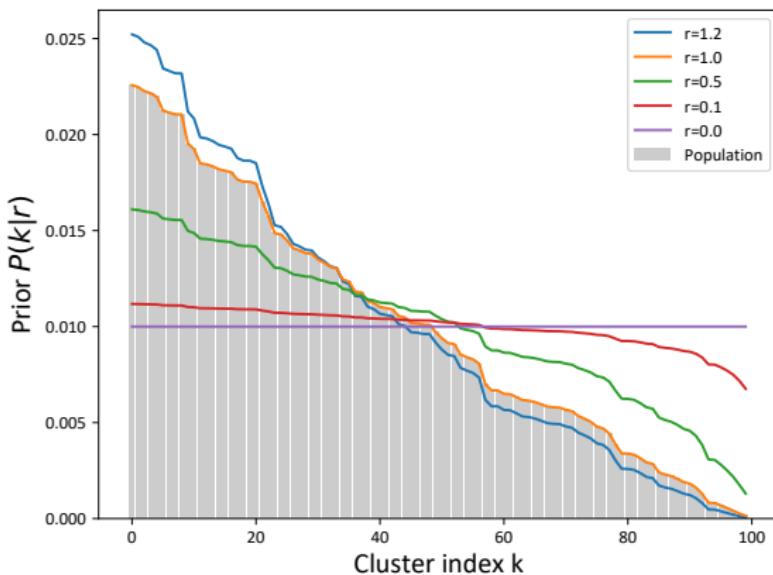
- $r < 0$  : “rich-get-poorer”
- $r = 0$  : “rich-get-no-richer” (Uniform Process)
- $0 < r < 1$  : “rich-get-less-richer”
- $r = 1$  : “rich-get-richer” (Dirichlet Process)
- $r > 1$  : “rich-get-more-richer”

# Implications of PDP



**Figure 2:** If  $r < 1$ , populated clusters have a smaller *a priori* probability to get chosen over smaller ones. If  $r > 1$ , populated clusters have an even greater *a priori* probability to get chosen over smaller ones.

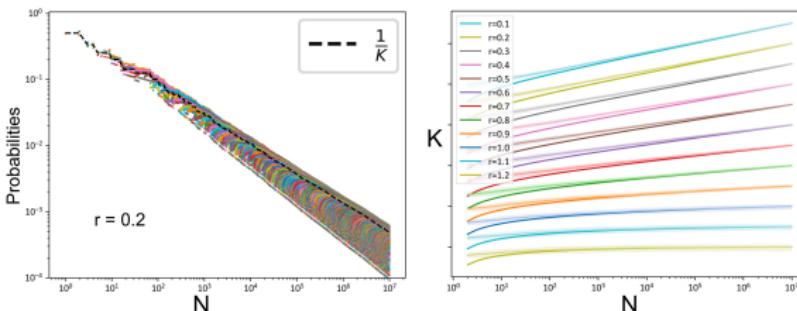
# Implications of PDP



**Figure 3:** Same figure as before, but with 100 clusters. Spot the:  
“rich-get-no-richer”, “rich-get-less-richer”, “rich-get-richer”, “rich-get-more-richer”

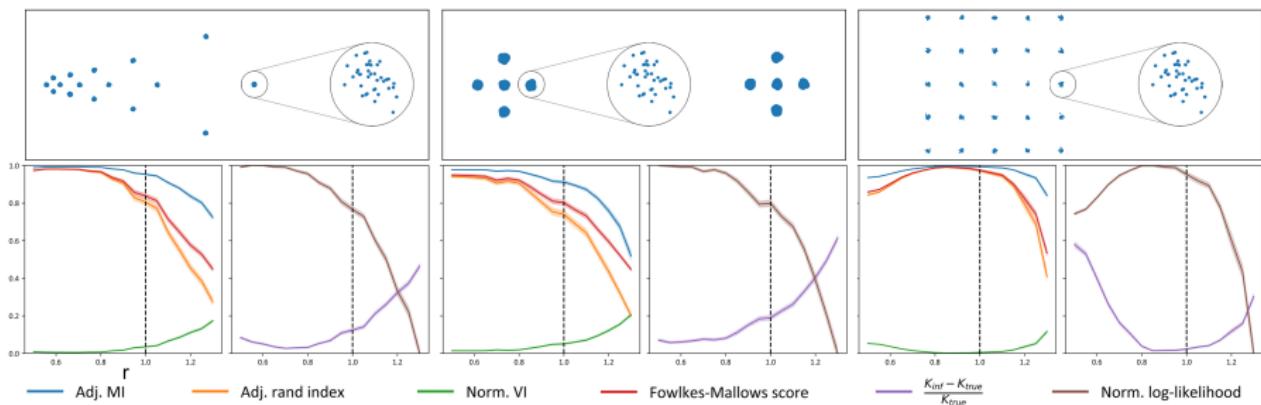
# Elementary results

- Convergence of  $PDP(c|\mathcal{H}, r)$  when  $N \rightarrow \infty$ :
    - $r < 1$ : Uniform distribution
    - $r = 1$ : Dirichlet distribution
    - $r > 1$ : Dirac distribution
  - Expected number of clusters  $\mathbb{E}(K|N)$  when  $N \gg 1$ :
    - $r < 1$ :  $\mathbb{E}(K|N) \propto H_{\frac{r^2+1}{2}}(N) \propto N^{\frac{1-r^2}{2}}$
    - $r = 1$ :  $\mathbb{E}(K|N) \propto H_1(N) \propto \log(N)$
    - $r > 1$ :  $\mathbb{E}(K|N) \propto H_r(N) \propto \zeta(\frac{r^2+1}{2})$
- with  $H_m(n) := \sum_{k=1}^n k^{-m}$  the generalized harmonic number.



# Synthetic data

- We couple PDP with an Infinite Gaussian Mixture Model
 
$$\rightarrow P(c|data) \propto IGMM(data|c) \times \begin{cases} N_c^r & \text{if } c = 1, \dots, K \\ \alpha & \text{if } c = K+1 \end{cases}$$
- We generate 3 types of datasets and run 100 experiments for each
- Results show that tuning  $r$  allows for better results

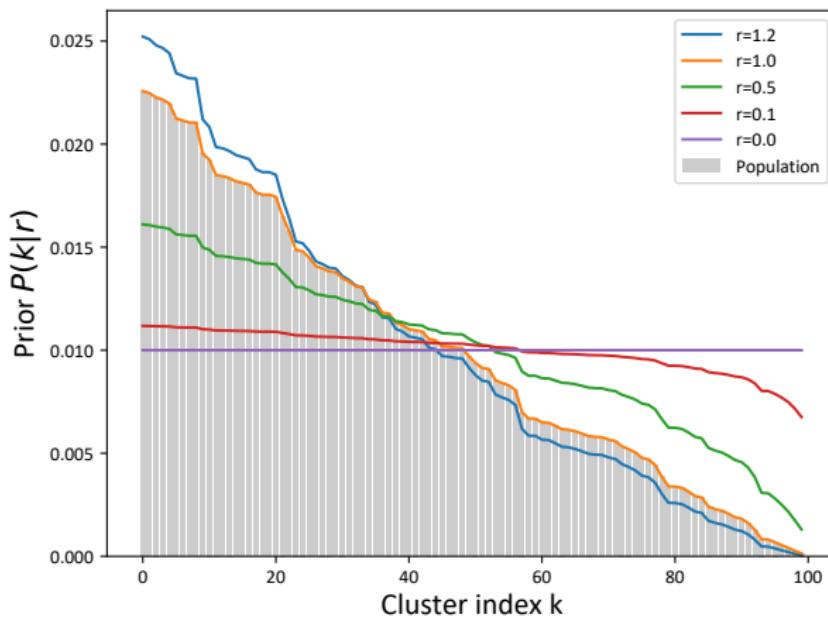


# Real-world data

		Adj.MI (↑)	Adj.RI (↑)	Norm.VI (↓)	$\frac{K_{inf} - K_{true}}{K_{true}}$ (↓)
Iris	PDP (r=0.90)	<b>0.868(4)</b>	<b>0.866(7)</b>	<b>0.057(2)</b>	<b>0.000(0)</b>
	DP (r=1.00)	0.843(6)	0.820(12)	0.065(2)	0.030(10)
	UP (r=0.00)	0.544(2)	0.295(3)	0.303(2)	2.777(32)
Wines	PDP (r=0.10)	<b>0.712(15)</b>	<b>0.637(20)</b>	<b>0.102(5)</b>	<b>0.157(17)</b>
	DP (r=1.00)	0.589(19)	0.461(16)	0.128(4)	0.327(13)
	UP (r=0.00)	<b>0.713(17)</b>	<b>0.657(21)</b>	<b>0.103(5)</b>	<b>0.147(17)</b>
Cancer	PDP (r=0.10)	<b>0.254(17)</b>	<b>0.278(21)</b>	<b>0.118(1)</b>	<b>0.000(0)</b>
	DP (r=1.00)	0.085(16)	0.094(19)	0.108(2)	<b>0.000(0)</b>
	UP (r=0.00)	<b>0.271(17)</b>	<b>0.300(21)</b>	<b>0.118(1)</b>	<b>0.000(0)</b>
20-NG	PDP (r=0.80)	<b>0.421(4)</b>	<b>0.119(3)</b>	<b>0.477(3)</b>	-
	DP (r=1.00)	0.404(4)	0.105(4)	0.491(3)	-
	UP (r=0.00)	0.000(4)	0.000(0)	0.830(3)	-

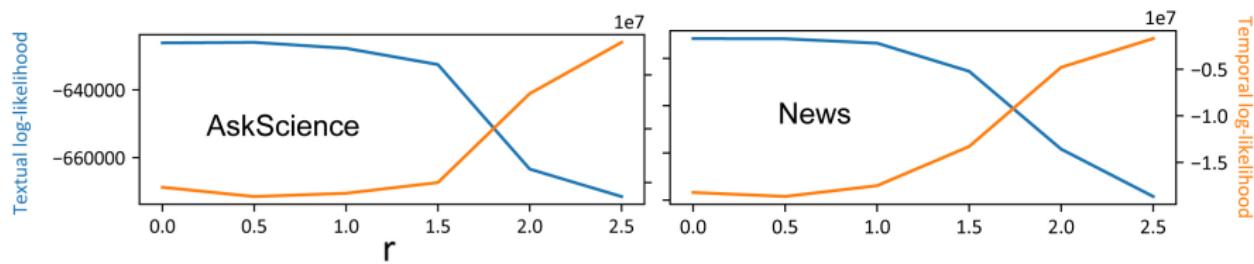
## Control prior's informativeness

- Another way to look at PDP is as a way to control the prior's informativeness regarding the data it uses



# Perspectives

- In (Du et al., 2015): DP combined to Hawkes processes
  - The prior probability relies on the intensity of a temporal process  
→ How much should we rely on this temporal information?
- In (Poux-Médard et al., 2021), we explored this question using PDP
  - Depending on the situation, temporal information can be more or less relevant
  - PDP allows to control its importance in the model



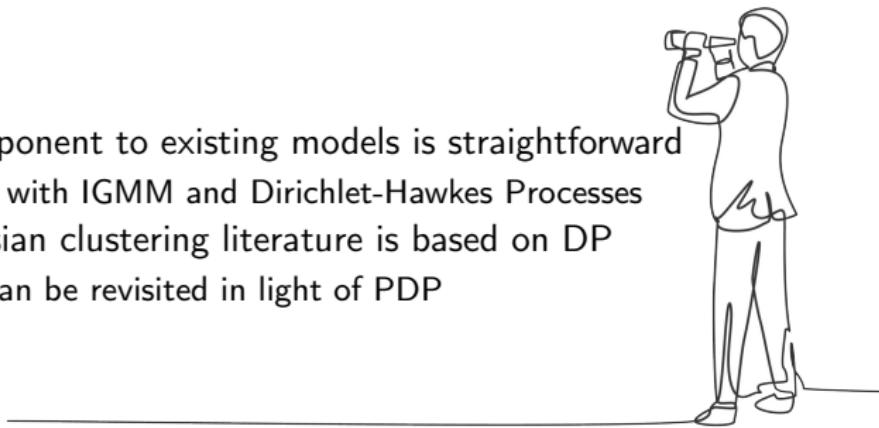
# Conclusion and perspectives

- Conclusions:

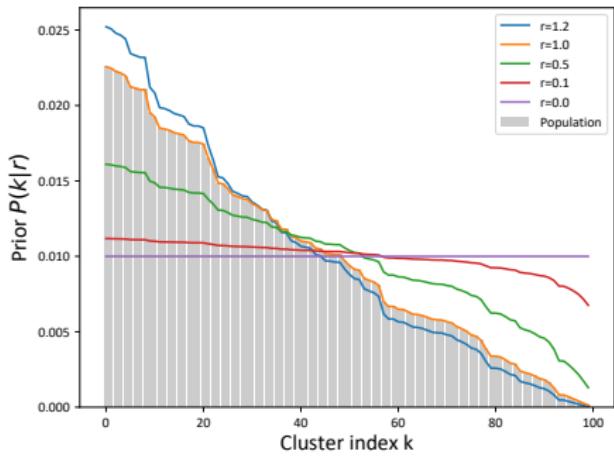
- Dirichlet Processes clustering priors come with a questionable “rich-get-richer” hypothesis
- Powered Dirichlet Process allows for its direct control.
- Powered Dirichlet Process yields better experimental results

- Perspectives:

- Adding the exponent to existing models is straightforward
  - Examples with IGMM and Dirichlet-Hawkes Processes
- Most of Bayesian clustering literature is based on DP
  - All of it can be revisited in light of PDP



# Thanks for your attention!



- Webpage: <https://gaelpouxmedard.github.io/>
- Code and data: <https://github.com/GaelPouxMedard/PDP/>

## Bibliographie I

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