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Conclusion  
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# Dirichlet-Point Processes

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# Introduction

- Every minute:

 400h of video  
 350 000 tweets

 500 000 comments  
 4 200 000 searches

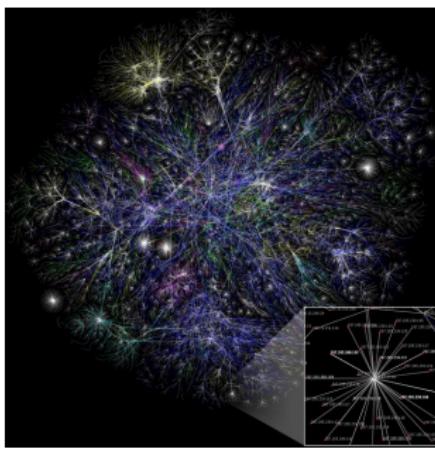


Figure 1: Snapshot of the internet (Wikipedia)

## Motivation

- Every minute:



400h of video



350 000 tweets



500 000 comments



4 200 000 searches

- How to make sense out of *that*?

- 1 News - [Protecting your environment](#) 2 days ago  
More Antarctic penguin accidentally travels 3,000km to New Zealand
- 1 News - [200 million Americans](#) 3 weeks ago
- 1 News - [Protecting shareholders](#) 3 years ago  
**The NYPD is using machine learning to spot crime patterns | StateScoop**
- 1 News - [Protecting shareholders](#) 3 years ago  
73 updates · 27 comments · 4 shares
- 1 News - [Protecting shareholders](#) 3 years ago  
**Climate change: Major US oil companies face grilling by Congress**
- 1 News - [Protecting shareholders](#) 3 years ago  
79 updates · 22 comments · 3 shares
- 1 News - [Protecting shareholders](#) 3 years ago  
**Algorithmic algorithms outperform deep-learning machines at video**

- [Climate](#) - Posted by [Ricardo](#), 2 years ago
- **Potential antibiotic discoverer using machine learning for first time**  
100 species, 100 compounds, 100 assays
- [Climate](#) - Posted by [NickCleary](#), 13 days ago
- **New estimates predict climate change is coming for crops sooner than expected**  
2.1K species, 200 comments, 5 votes up
- [Climate](#) - Posted by [Ricardo](#), 3 days ago
- **U.S. holds historic oil and gas lease sale in Gulf of Mexico days after climate summit!**  
100 species, 100 comments, 100 assays
- [Climate](#) - Posted by [schoenfelder](#), 10 days ago
- **Drag the ugly New Zealand potato could be world's biggest**  
[schoenfelder](#), 10 days ago

- [China - Printed by 100 Factories \(447\) 3 months ago](#)
- [New Zealand's Covid-19 cases touch all-time high, govt pushes for vaccination](#)
- [China - Printed by 1,400 Factories \(207\) 3 months ago](#)
- [China - Printed by 1,400 Factories \(196\) 3 months ago](#)
- [Silicon Valley: Thousands protest in New Zealand against COVID-19 rules.](#)
- [China - Printed by 1,400 Factories \(196\) 3 months ago](#)
- [Only Humans, Not AI Machines, Can Get a U.S. Patent, Judge Rules](#)
- [China - Printed by 1,400 Factories \(208\) 3 months ago](#)
- [4.8 billion - 4.8 billion - 2 years old](#)
- [China - Printed by 1,400 Factories \(209\) 2 days ago](#)
- [Earth gets hotter, deadlier during decades of climate talk](#)
- [1.8 species - 1.8 species - 3 months](#)

15 hours · [Marking](#) · 1 reply · 21 views · 1 min ago  
"Yeah, we're speaking!": All starting to have big real-world impact, says expert

15 hours · [Marking](#) · 1 comment · 1 view · 1 min ago  
Tired of broken promises? climate activists launch hunger strike outside White House

15 hours · [Marking](#) · 20 comments · 5 views  
Protecting children at school & everyday life

15 hours · [Marking](#) · 1 comment · 1 view · 1 min ago  
Reckon? New Zealand's PM Ardern apologises for 1970s immigration raids on Pacific community

15 hours · [Marking](#) · 1 comment · 1 view · 1 min ago  
Protecting playgrounds 3 months ago

15 hours · [Marking](#) · 1 comment · 1 view · 1 min ago  
AI-driven robot Mayflower sails back after fault develops

**Figure 2:** A typical stream from r/news

# Motivation

- Every minute:

400h of video  
 350 000 tweets

500 000 comments  
 4 200 000 searches

- How to make sense out of *that?*  
→ Hidden semantic links



Figure 2: A typical stream from r/news – with topics

# Available information

- Main clues:
  - Textual information



Figure 3: We can use textual information

# Available information

- Main clues:
  - Textual information
  - Temporal information

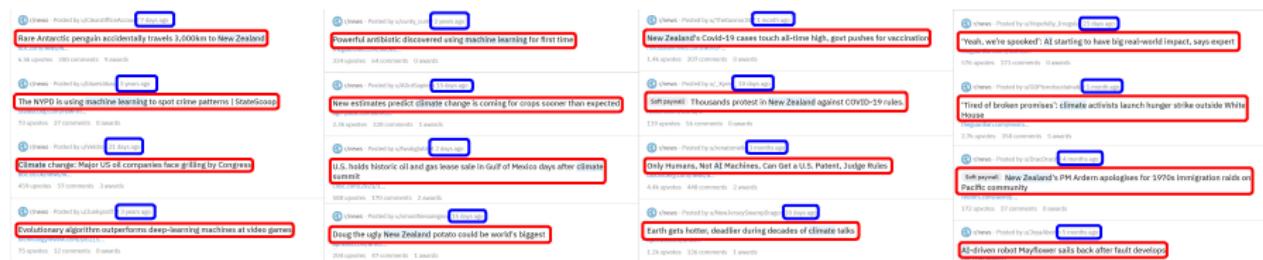


Figure 3: We can use textual information and temporal information

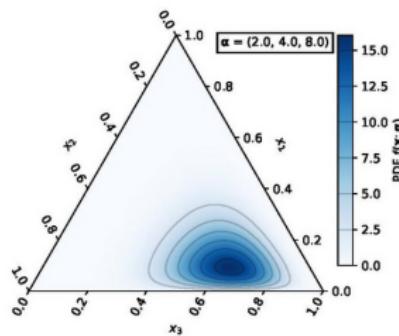
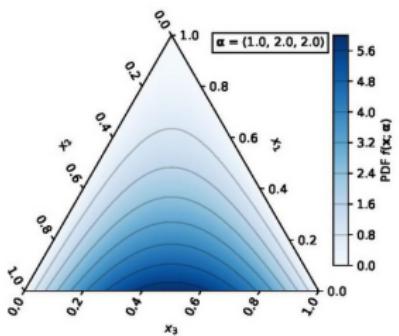
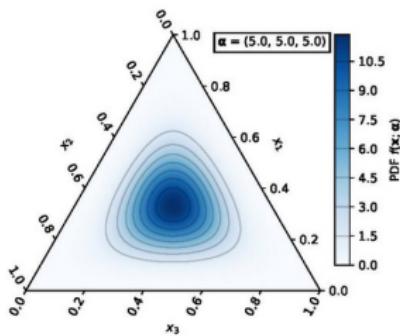
# Documents stream

- The data is therefore a documents stream



# Dirichlet process

- Dirichlet distribution:  $\vec{X} \sim Dir(\alpha)$  s.t.  $\sum_k X_k = 1$
- Often used as a prior distribution in Bayesian clustering
  - ◇ Typically  $X_k$  is the probability to belong to cluster  $k$



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# Chinese restaurant process

- Chinese Restaurant Process:

$$CRP(C_i = c | C_1, C_2, \dots, C_{i-1}, \alpha) = \begin{cases} \frac{N_c}{\alpha + N} & \text{if } c = 1, \dots, K \\ \frac{\alpha}{\alpha + N} & \text{if } c = K+1 \end{cases}$$



## Handling a stream of documents

- Chinese Restaurant Process:

$$CRP(C_i = c | C_1, C_2, \dots, C_{i-1}, \alpha) = \begin{cases} \frac{N_c}{\alpha + N} & \text{if } c = 1, \dots, K \\ \frac{\alpha}{\alpha + N} & \text{if } c = K+1 \end{cases}$$

- Useful for sequential modeling (explicit posterior at each step, allows Gibbs sampling)

$$\underbrace{P(n^{th} obs = c | D, history)}_{Posterior} \propto \underbrace{P(D | n^{th} obs = c)}_{Likelihood} \times \underbrace{P(n^{th} obs = c | history)}_{CRP \ prior}$$

- Hypothesis: “rich-get-richer”

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## Variants

- Variants of DP exist:
  - ◊ Uniform process [Wallach et al., 2010]
  - ◊ Pitman-Yor process [Pitman and Yor, 1997]
  - ◊ Hierarchical Dirichlet process [Teh et al., 2006]
  - ◊ Nested Dirichlet process [Rodríguez et al., 2008]
- Most exhibit “rich-get-richer” property
- All consider counts, none consider temporal dimension

## Modeling time as a continuous variable

- Time often “modeled” by sampling observations (DTM [Blei and Lafferty, 2006], RCRP [Ahmed and Xing, 2008, Diao and Jiang, 2014], DDCRP [Blei and Frazier, 2010] etc.)
  - ◊ Problems: how to slice data, which sampling function use, how to weight observations, etc.
- Modeling time explicitly: point processes

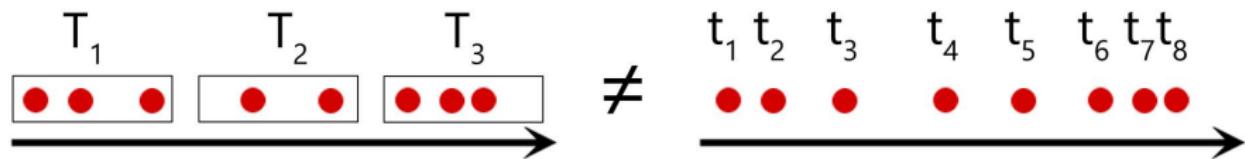


Figure 4: Data sampling/slicing is an approximation

## Poisson process

- Poisson processes are characterized by an **intensity**  $\lambda$ .
  - ◊  $\lambda \Delta t \xrightarrow{\Delta t \rightarrow 0} P(\mathbb{N}(t + \Delta t) - \mathbb{N}(t) = 1)$
  - ◊ Instantaneous probability for *one* event

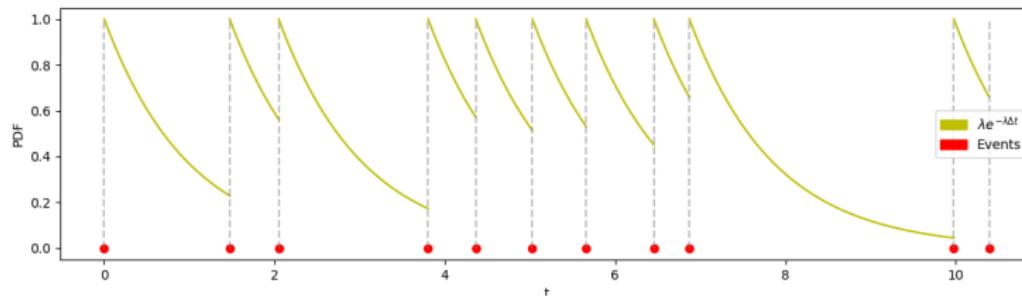


Figure 5: Could model radioactive decay events of atoms whose half-life is 1

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## Non-homogeneous Poisson process

- $\lambda(t)$  is a function
- $\lambda(t)\Delta t \stackrel{\Delta t \rightarrow 0}{=} P(\mathbb{N}(t + \Delta t) - \mathbb{N}(t) = 1)$

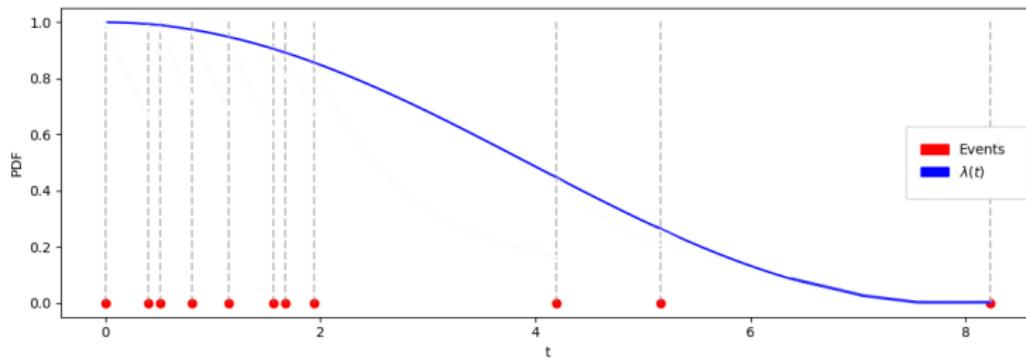


Figure 6: Could model cars arrival at gas station throughout a day

## Hawkes process

- Hawkes processes:  $\lambda(t|\mathcal{H}_t)$  depends on past events  $\mathcal{H}_t = \{t_i | t_i < t\}$ 
  - “Self-exciting process”
- Typically:  $\lambda(t|\mathcal{H}_t) = \lambda_0 + \sum_{t_i \in \mathcal{H}_t} \phi(t - t_i)$

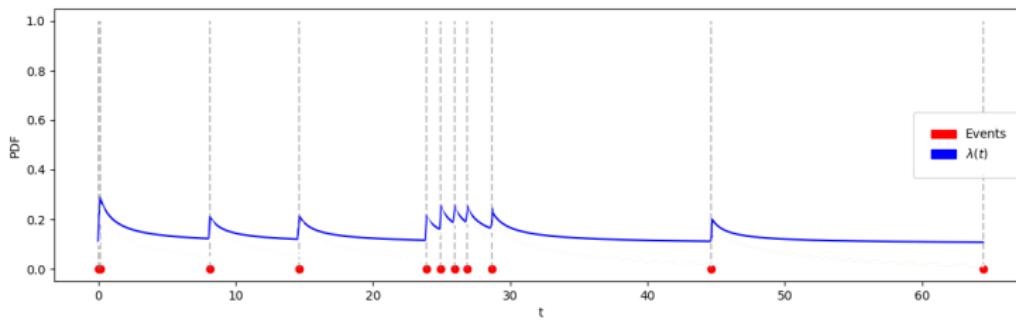


Figure 7: Could model online posting dynamics

## Inference

- Log-likelihood of a data stream  $\mathcal{D} = \{t_0, \dots, t_N\}$ :

$$\begin{aligned}\ell(\lambda, \mathcal{D}) = & - \int_{t_0}^{t_N} \lambda(t) dt + \sum_{t_i < t_N} \log \lambda(t_i) = \log \lambda(t_1) - \int_{t_0}^{t_1} \lambda(t) dt \\ & + \log \lambda(t_2) - \int_{t_1}^{t_2} \lambda(t) dt \\ & + \dots \\ & + \log \lambda(t_N) - \int_{t_{N-1}}^{t_N} \lambda(t) dt\end{aligned}$$

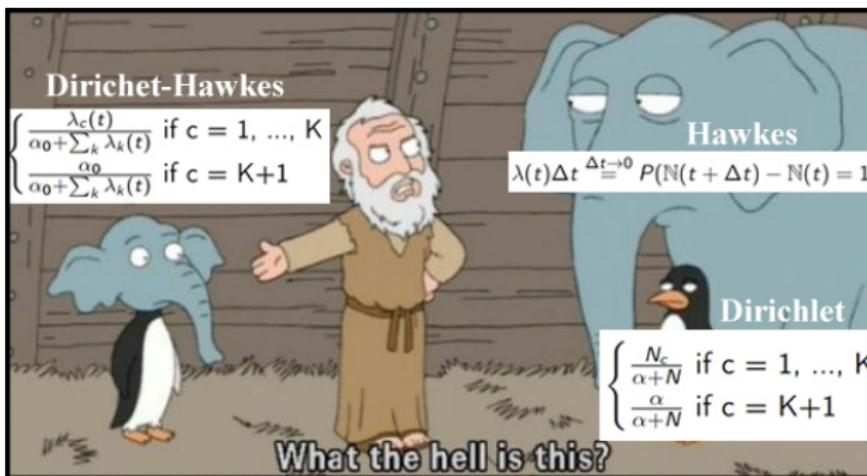
- Convex for certain shapes of  $\lambda(t)$  (exp, ray, PL, Gaussian, ...).

# Dirichlet-Hawkes process

- [Du et al., 2015]: Dirichlet-Hawkes prior (Bayesian inference)

$$P(\text{cluster}|\text{text, time, } \mathcal{H}) \propto \underbrace{P(\text{text}|\text{cluster})}_{\substack{\text{Textual likelihood} \\ (\text{Dirichlet-Multinomial})}} \times \underbrace{P(\text{cluster}|\text{time, } \mathcal{H})}_{\substack{\text{Temporal prior} \\ (\text{Dirichlet-Hawkes})}}$$

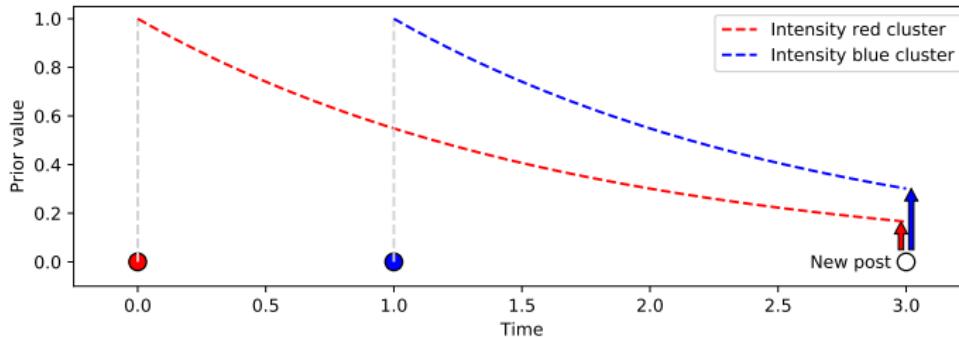
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## Dirichlet-Hawkes process – Explicit

- $P(c|t, \mathcal{H})$ : prior prob. of cluster  $c$  at time  $t$  given history  $\mathcal{H}$
- $\lambda_c(t)$ : Hawkes intensity of cluster  $c$  at time  $t$
- Dirichlet process with counts  $N_c$  replaced by  $\lambda_c(t)$

$$\underbrace{P(c|t, \mathcal{H})}_{\substack{\text{Temporal prior} \\ (\text{Dirichlet-Hawkes})}} = \begin{cases} \frac{\lambda_c(t)}{\alpha_0 + \sum_k \lambda_k(t)} & \text{if } c = 1, \dots, K \\ \frac{\alpha_0}{\alpha_0 + \sum_k \lambda_k(t)} & \text{if } c = K+1 \end{cases}$$



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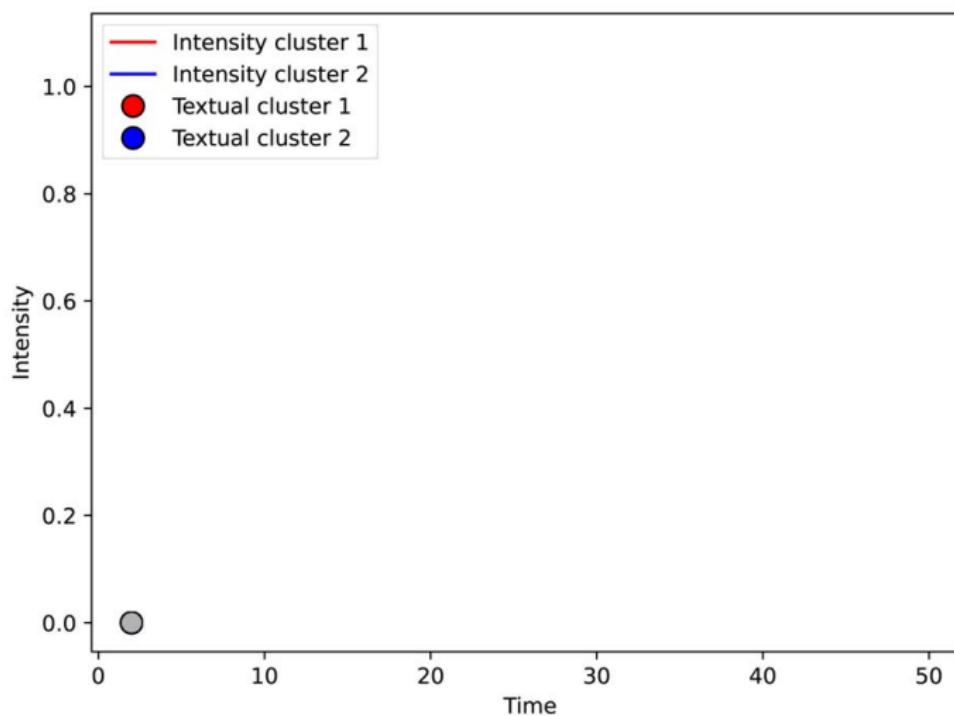
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## Inference (1 particle)



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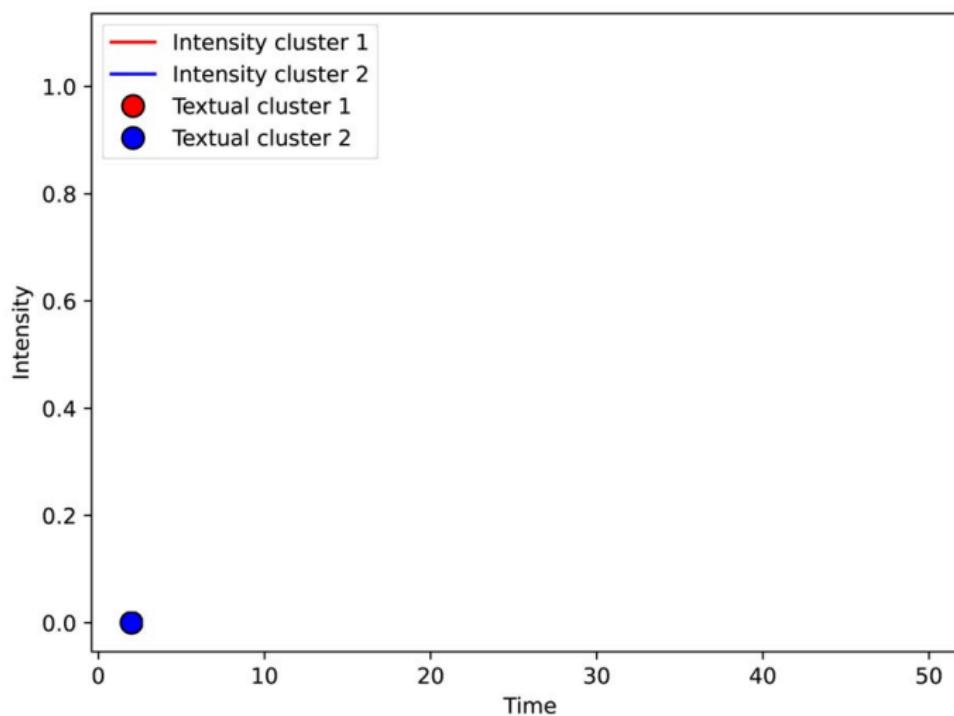
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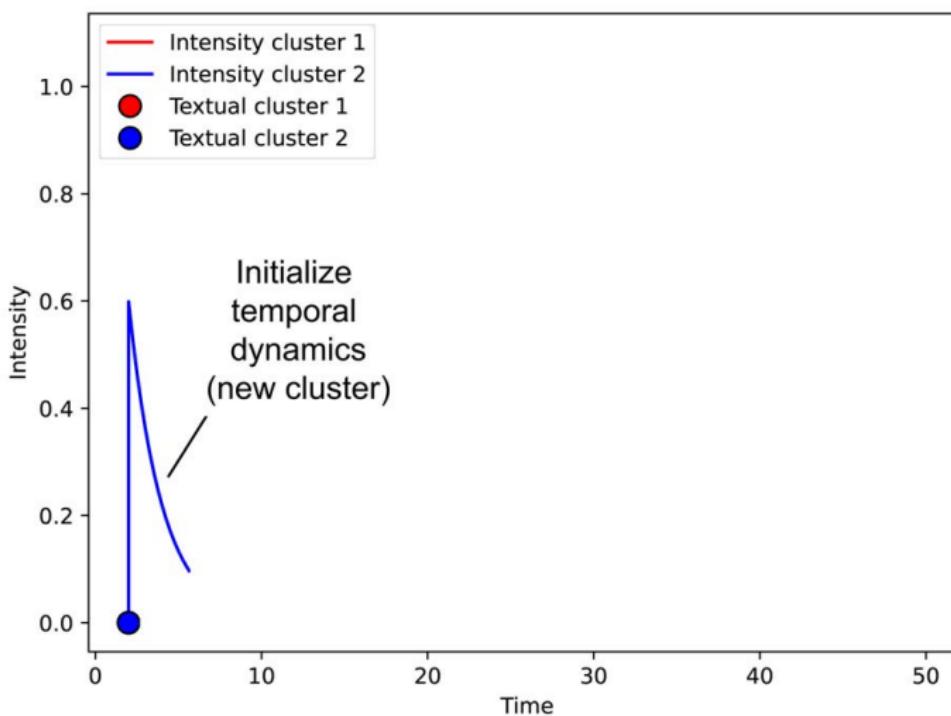
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## Inference (1 particle)



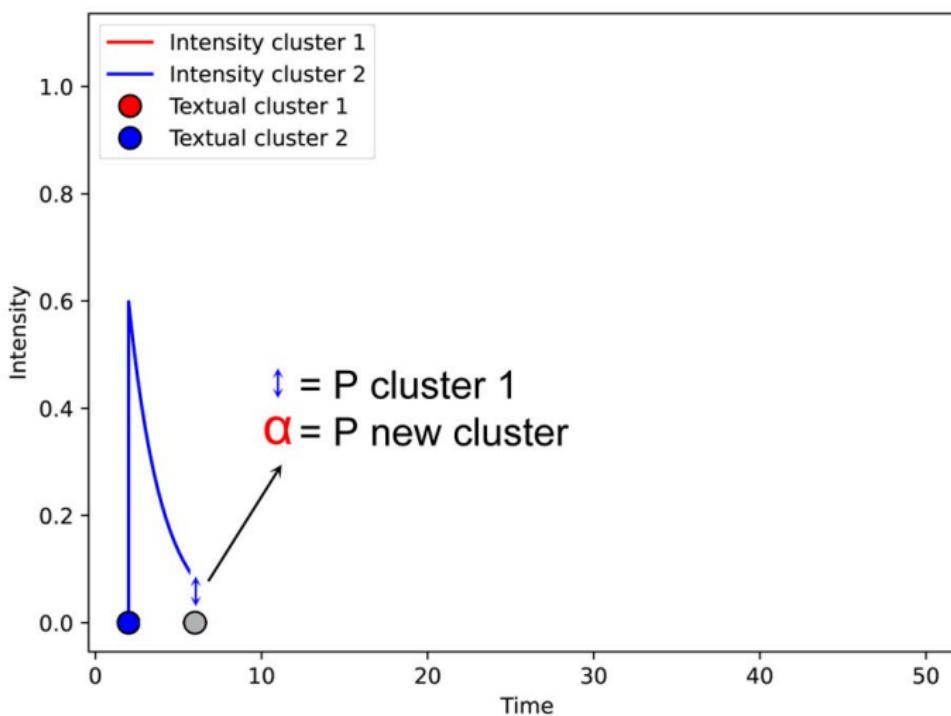
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## Inference (1 particle)



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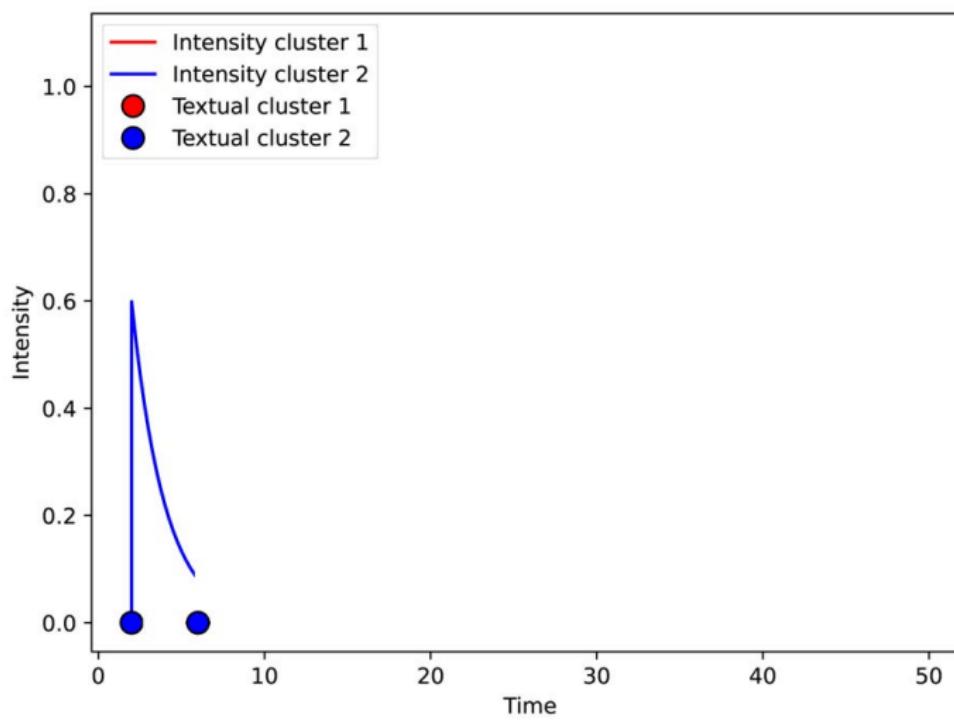
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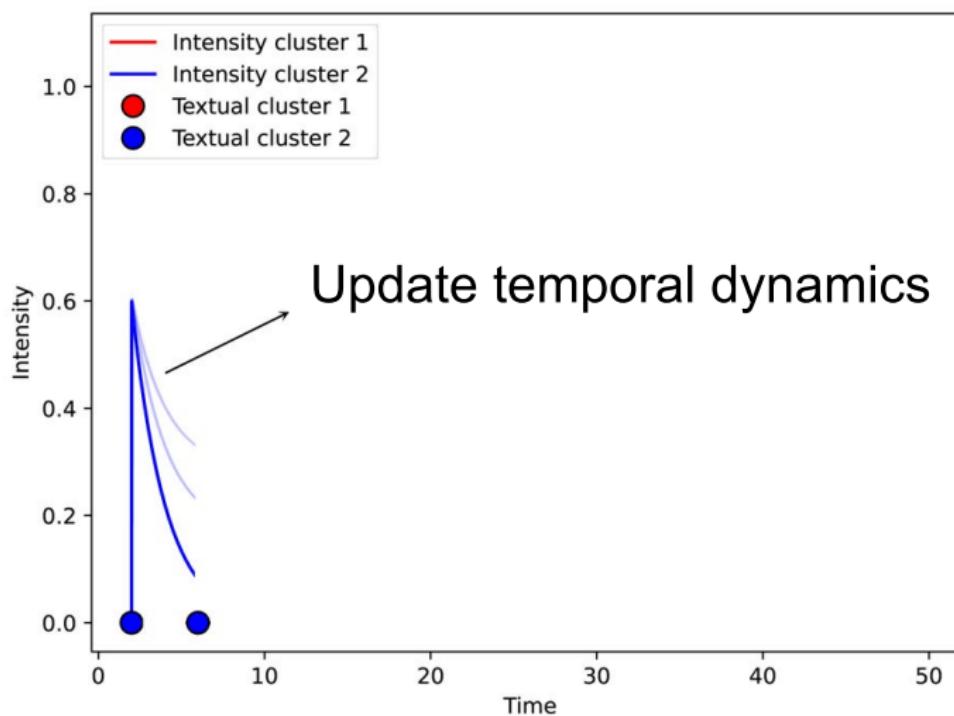
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## Inference (1 particle)



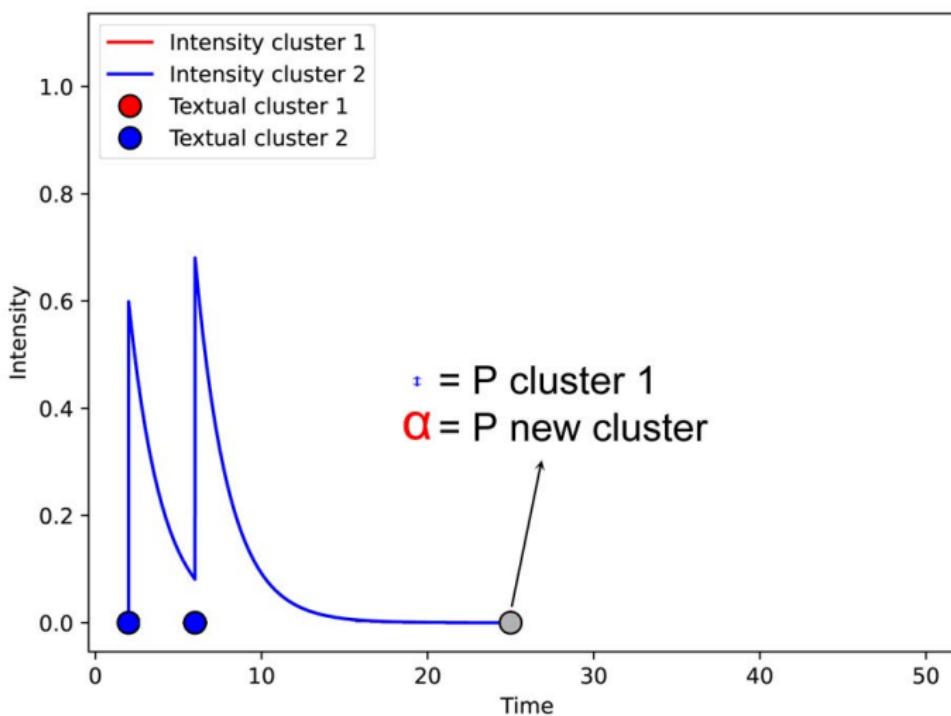
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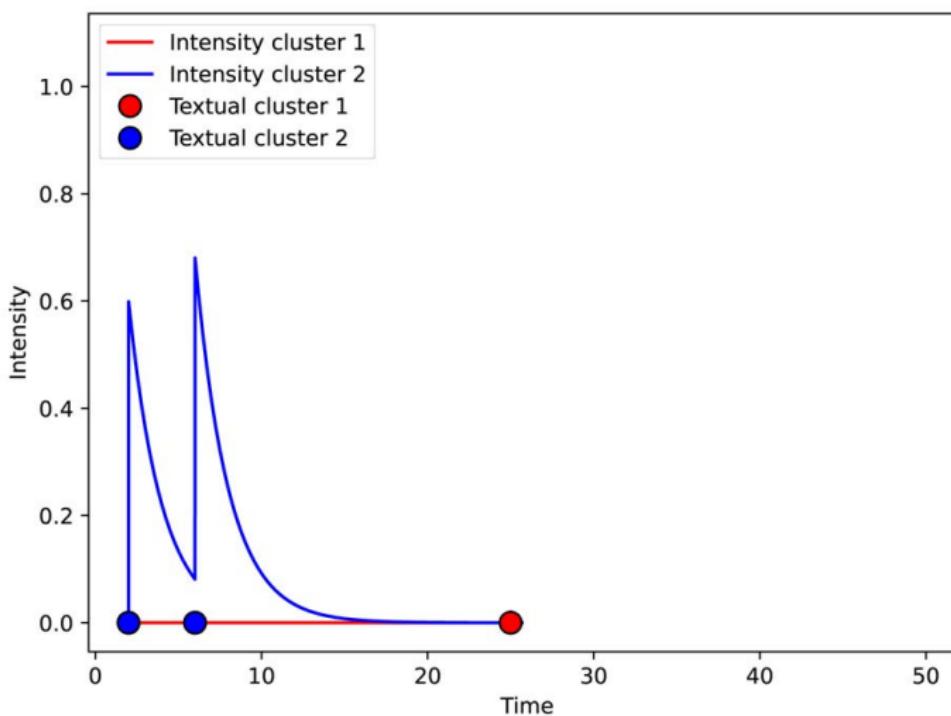
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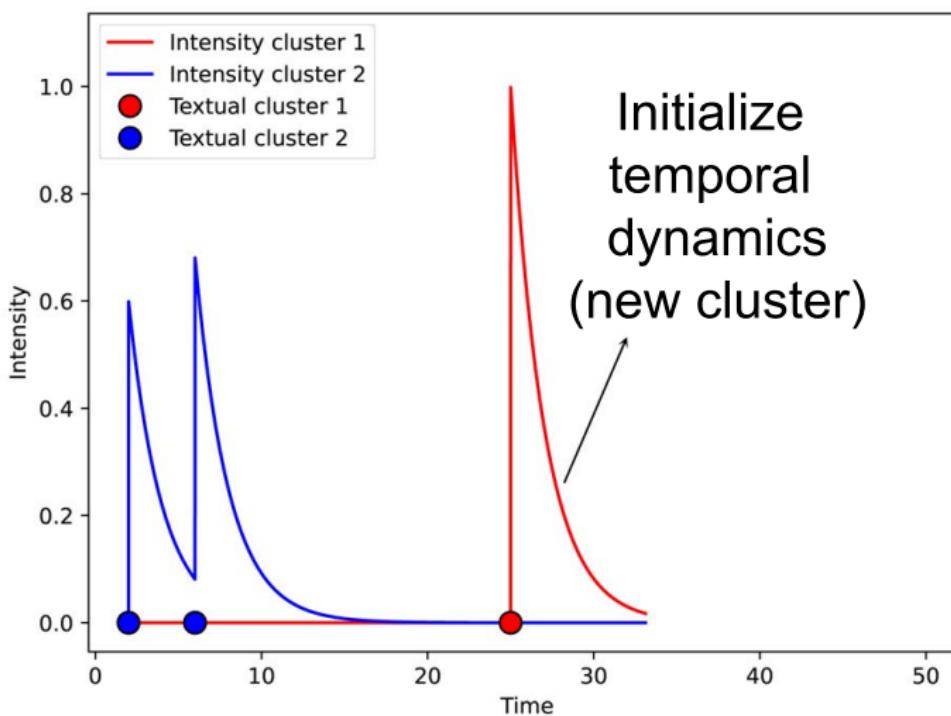
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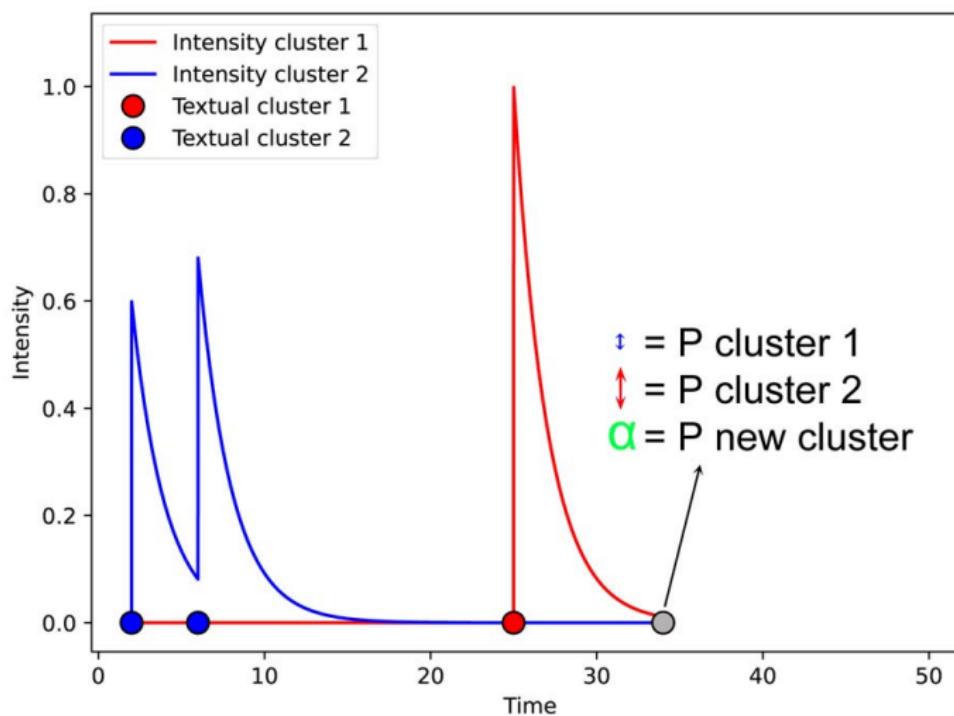
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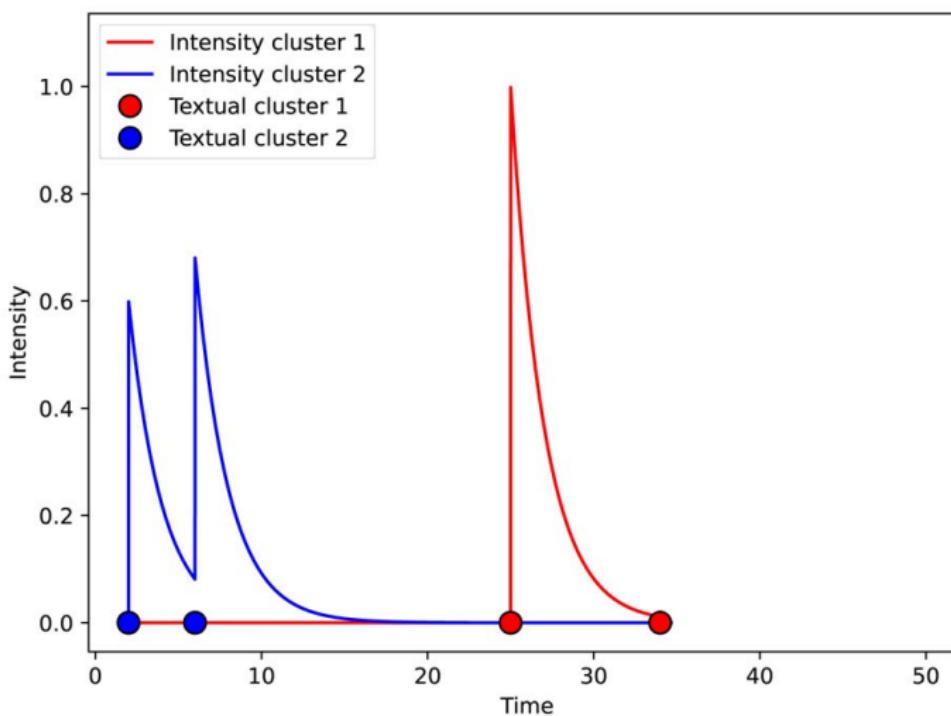
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## Inference (1 particle)



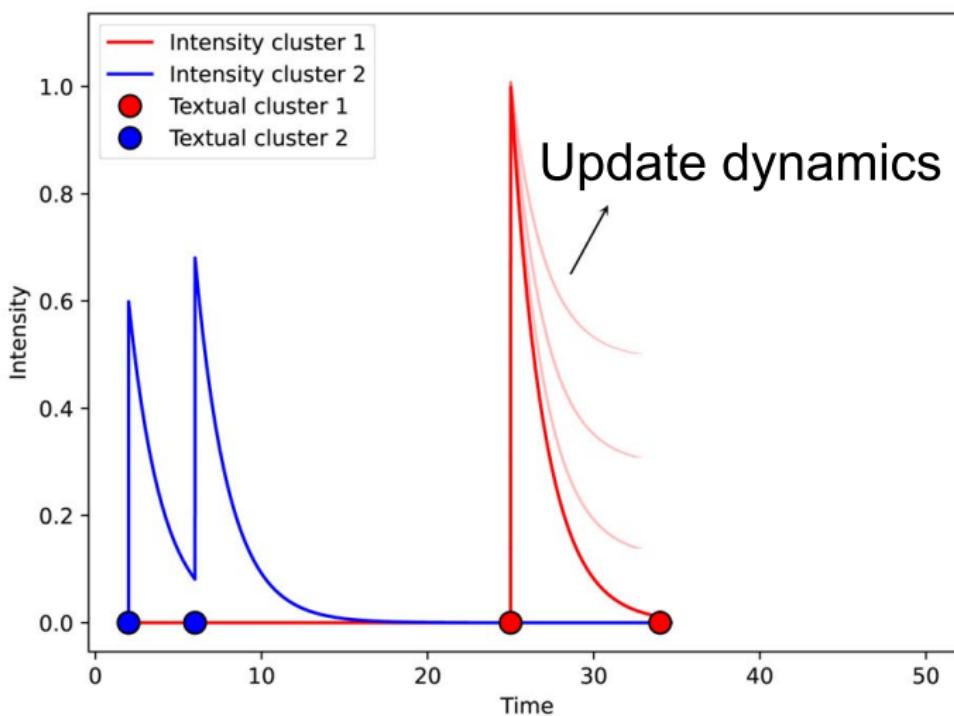
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## Inference (1 particle)



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## Inference (1 particle)



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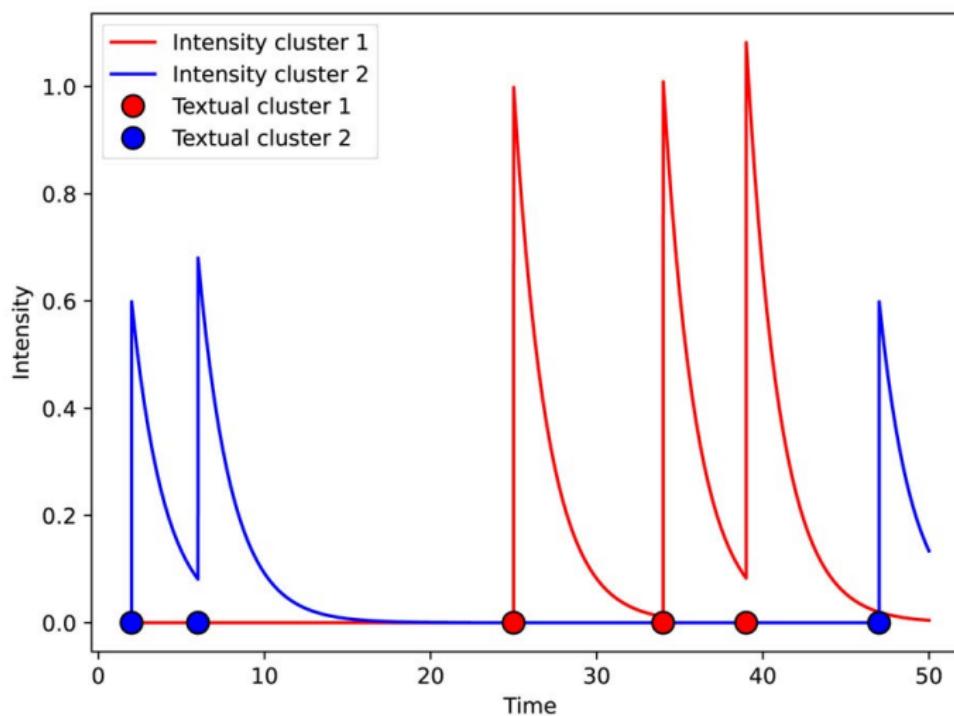
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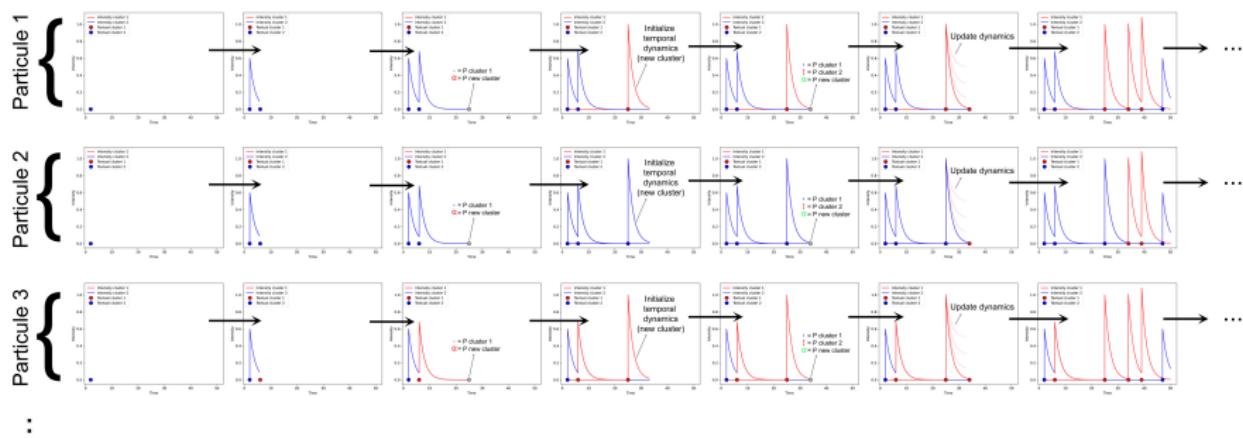
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## Inference (1 particle)



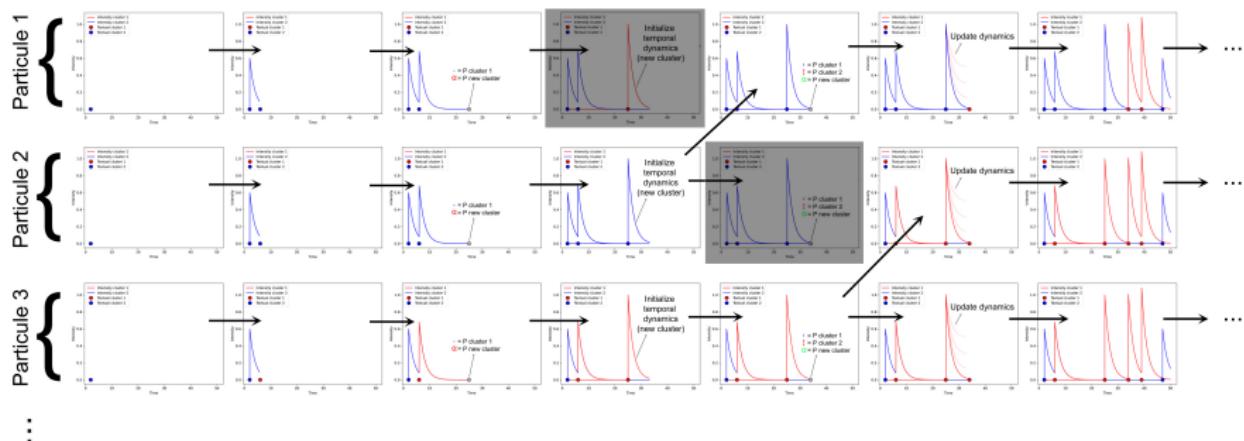
# Inference (all particles)

- Run simultaneously on several *particles*

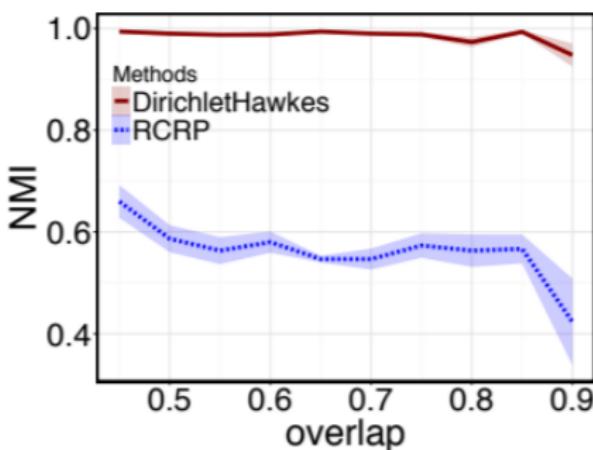
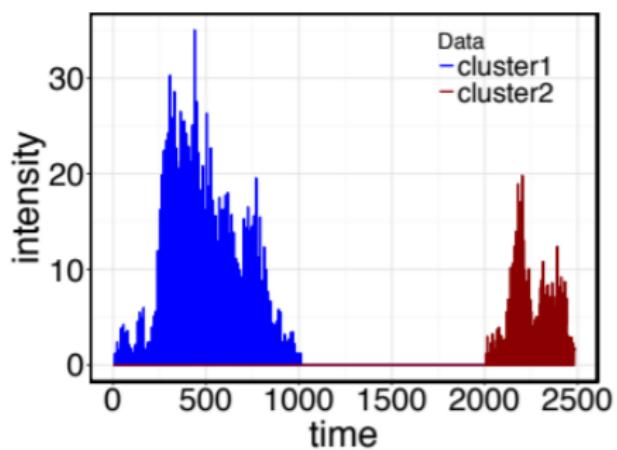


# Inference (all particles)

- Discard unlikely particles and replace them by more likely ones



## Performances (well-separated)

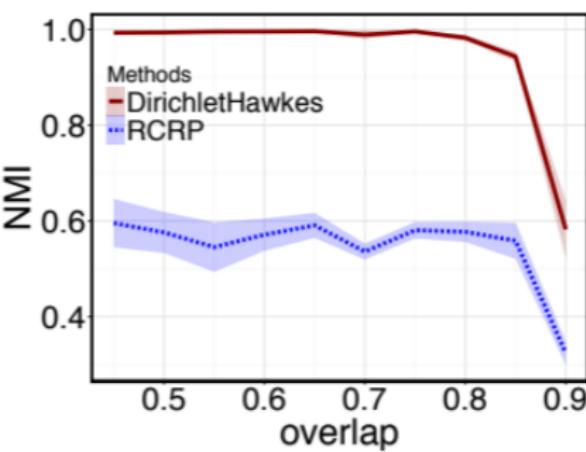
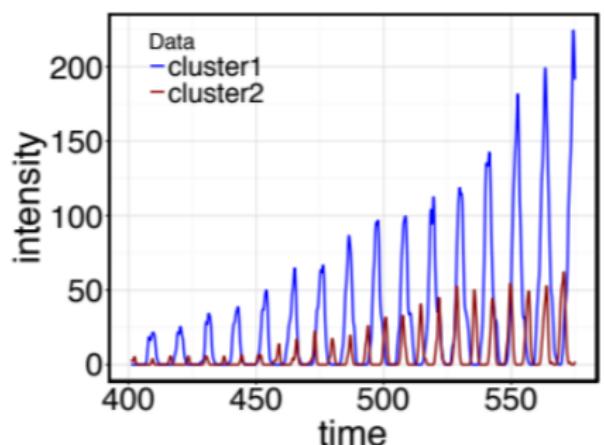


(a) Temporally well-separated clusters.

Figure 10: [Du et al., 2015]

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## Performances (“not” well-separated)



(b) Temporally interleaved clusters.

Figure 11: [Du et al., 2015]

## Output

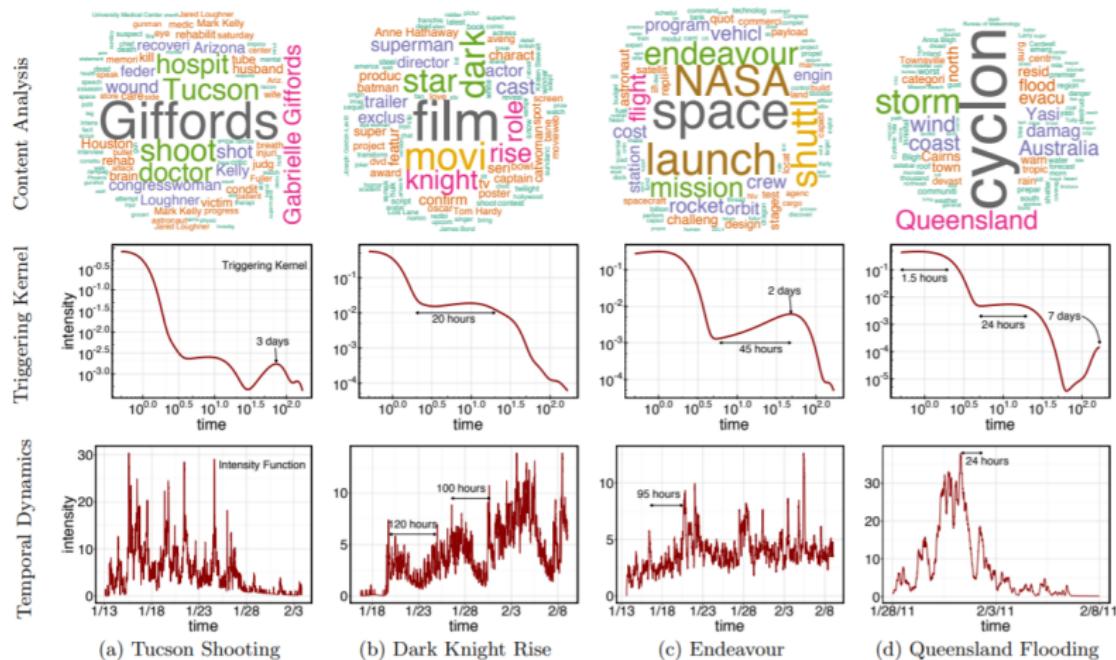


Figure 12: [Du et al., 2015]

## Variants

- Some variants based on Dirichlet-Hawkes process
  - Hierarchical (CRF) and Nested (nCRP) extensions of DHP
  - Not-vanishing DHP prior [Kapoor et al., 2018]

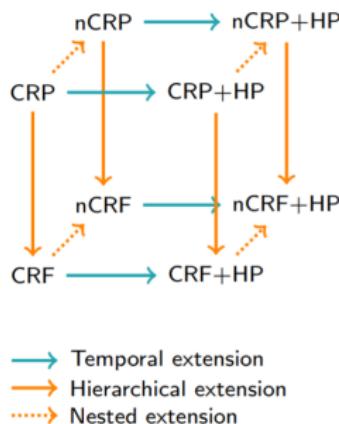


Figure 13: [Kapoor et al., 2018]

BUT!

# Dirichlet prior is a choice

- Dirichlet-based priors are an arbitrary choice
  - ◊ Other priors are as fit [Welling, 2006]
  - ◊ The choice of the prior matters [Wallach et al., 2009]
  - ◊ Few variations proposed [Wallach et al., 2010, Pitman and Yor, 1997]
- DP exhibits “rich-get-richer” property
  - ◊ Why linear dependence?
  - ◊ Why this assumption at all? [Wallach et al., 2010]

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## Powered Dirichlet process

- Powered Chinese Restaurant Process:

$$PCRP(C_i = c | C_1, \dots, C_{i-1}, \alpha, r) = \begin{cases} \frac{N_c^r}{\alpha + \sum_k N_k^r} & \text{if } c = 1, \dots, K \\ \frac{\alpha}{\alpha + \sum_k N_k^r} & \text{if } c = K+1 \end{cases}$$

- ◊  $r < 0$ : “rich-get-poorer”
- ◊  $r = 0$ : “rich-get-no-richer” (Uniform Process)
- ◊  $0 < r < 1$ : “rich-get-less-richer”
- ◊  $r = 1$ : “rich-get-richer” (Dirichlet Process)
- ◊  $r = \frac{\log(N_k - \beta)}{\log(N_k)}$ : “rich-get-richer” (Pitman-Yor Process)
- ◊  $r > 1$ : “rich-get-more-richer”

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## PDP into DHP

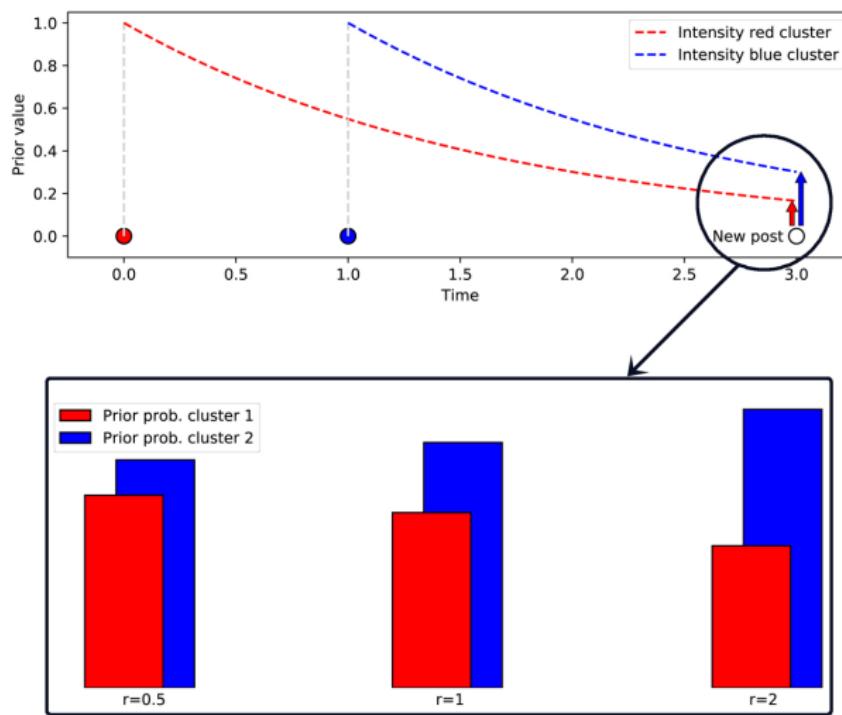
- Powered Dirichlet-Hawkes Process [Poux-Médard et al., 2021]:

$$\underbrace{P(c|t, \mathcal{H}, \mathbf{r})}_{\text{PDHP prior}} = \begin{cases} \frac{\lambda_c(t)^r}{\alpha_0 + \sum_k \lambda_k(t)^r} & \text{if } c = 1, \dots, K \\ \frac{\alpha_0}{\alpha_0 + \sum_k \lambda_k(t)^r} & \text{if } c = K+1 \end{cases}$$

- Generalization:
  - Uniform process:  $r = 0$  (only textual information)
  - Dirichlet-Hawkes process:  $r = 1$  (temporal and textual information)
  - Deterministic Hawkes process:  $r \rightarrow \infty$  (only temporal information)

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## Effect of $r$



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## Changes induced by PDHP

$$P(\text{cluster}|\text{text}, \text{time}) \propto \underbrace{P(\text{text}|\text{cluster})}_{\text{Textual likelihood}} \times \underbrace{P(\text{cluster}|\text{time}, r, \text{history})}_{\text{PDHP temporal prior}}$$

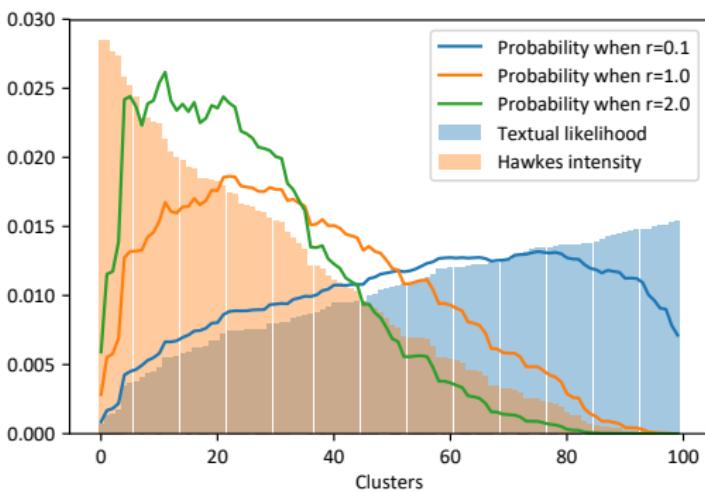
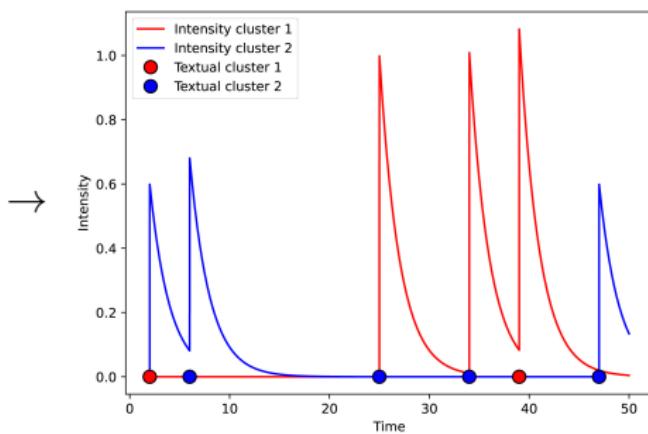
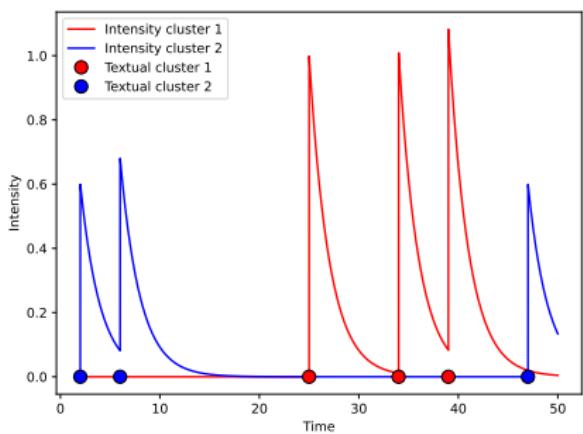


Figure 14: [Poux-Médard et al., 2021]

# Why is it relevant - Decorrelations

- Decorrelations:

- ◊ Ex: influent journal publishing on a topic does not have same dynamics as less influent one on the same topic



# Results for various decorrelations

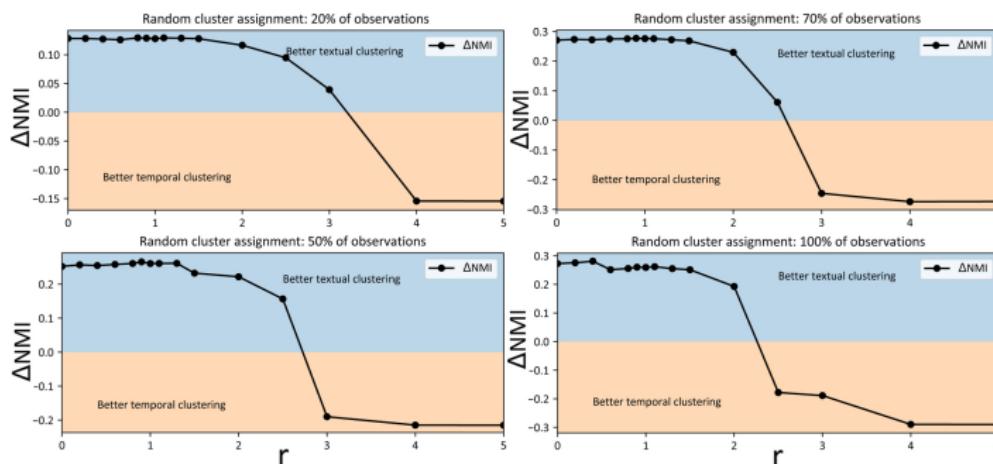


Figure 15: [Poux-Médard et al., 2021]

- PDHP retrieves either temporal or textual clusters
  - ◊ Small  $r$ : good textual clusters
  - ◊ Large  $r$ : good temporal clusters

# PDHP handles challenging situations

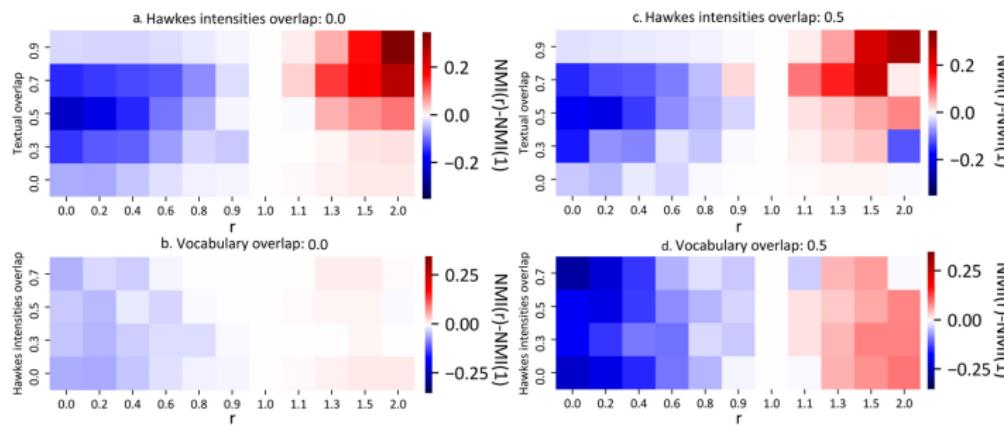
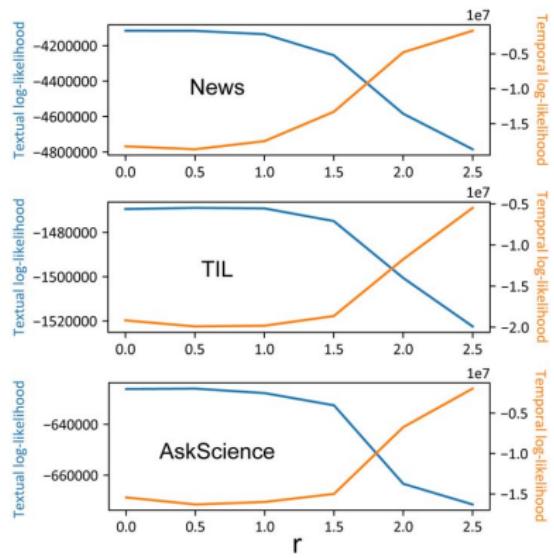


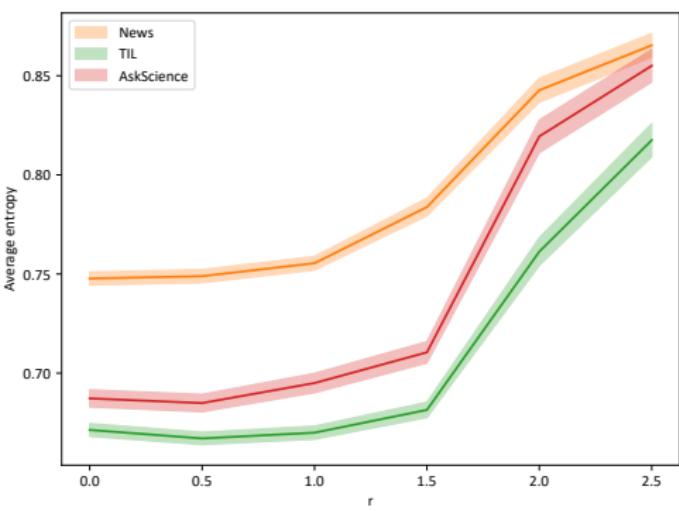
Figure 16: [Poux-Médard et al., 2021]

- PDHP adapts to various situations better than DHP (+0.3 NMI):
  - ◊ Large textual overlap
  - ◊ Large temporal overlap
  - ◊ No overlap

# Reddit r/news, r/TodayILearned, r/AskScience - Some metrics



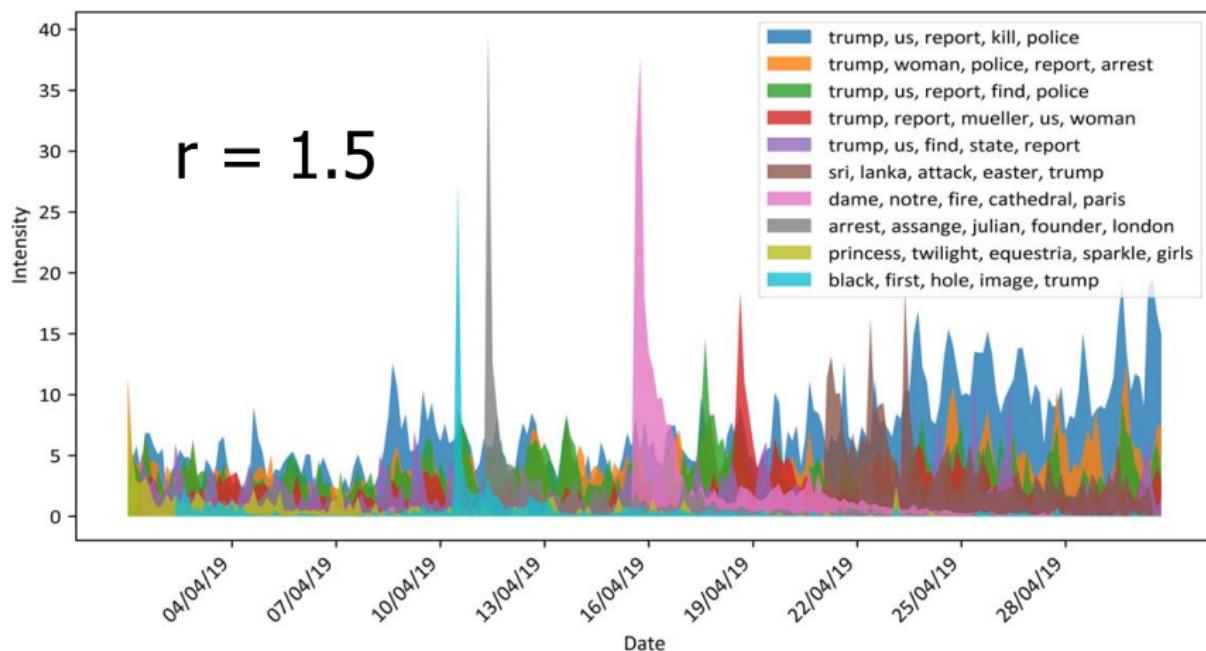
**Figure 17:** Textual and temporal likelihood vs  $r$   
[Poux-Médard et al., 2021]



**Figure 18:** Entropy of textual clusters:  
sharper textual clusters for low  $r$   
[Poux-Médard et al., 2021]

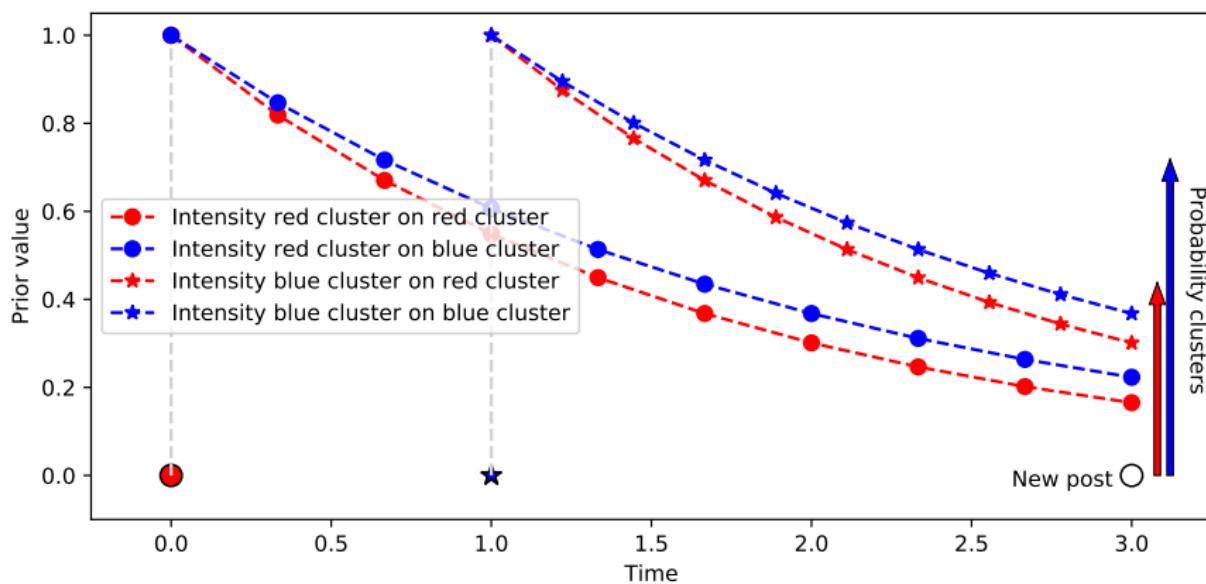
## Summary generation

- Powered Dirichlet-Hawkes prior: summary from data flows using temporal interactions



# Multivariate Powered Dirichlet-Hawkes process

- Extension: Multivariate Powered Dirichlet-Hawkes prior
  - How clusters influence each other



Motivation  
ooooDP  
ooooHP  
oooooDHP  
ooooooooPDP  
ooPDHP  
ooooooooMPDHP  
oooHouston  
ooooooConclusion  
oo

# Inferred clusters

Cluster 16 - 1498 obs



Cluster 80 - 337 obs



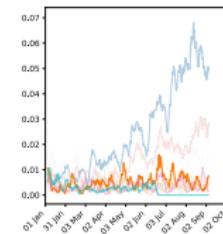
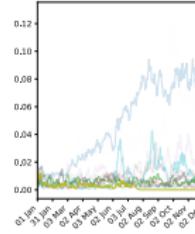
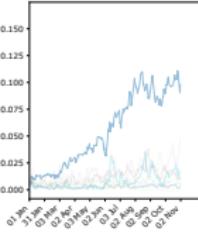
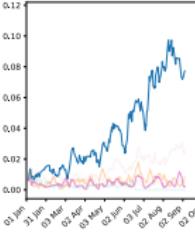
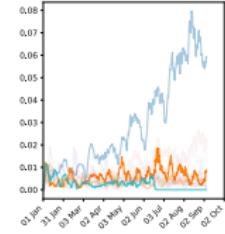
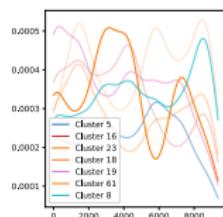
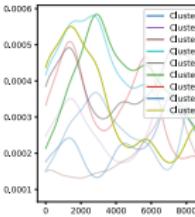
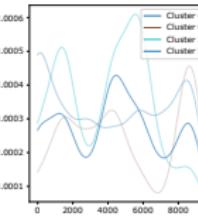
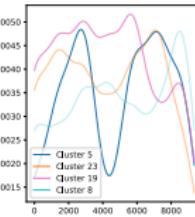
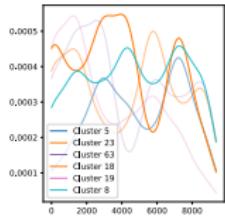
Cluster 56 - 324 obs



Cluster 40 - 1009 obs



Cluster 94 - 1073 obs



# Cluster interaction network

- MPDHP prior: Cluster interaction network

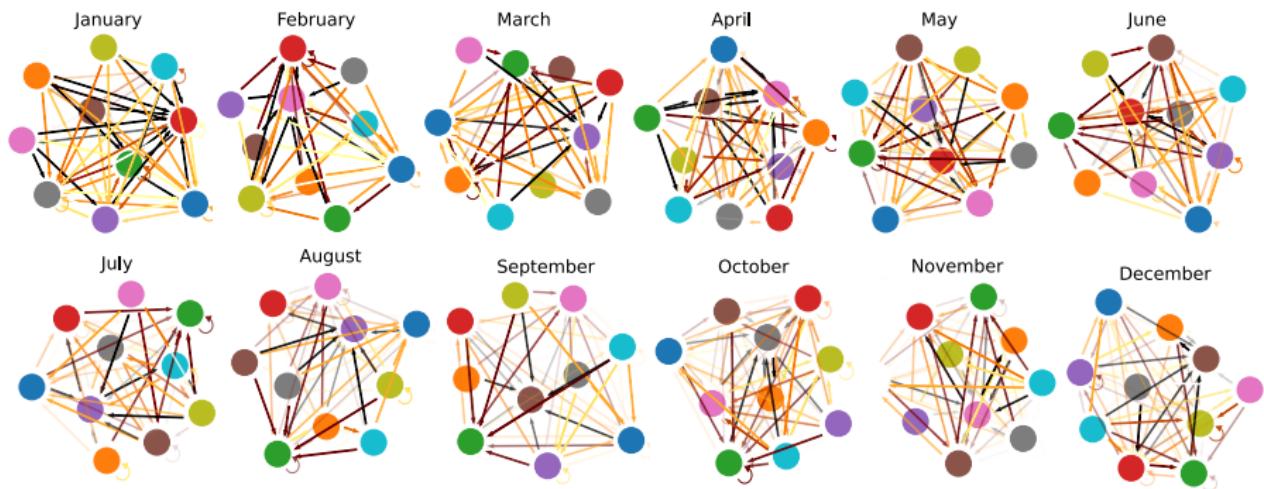


Figure 19: Topical interaction network over a year

## Perspective MPDHP – Summary generation

- Multivariate Powered Dirichlet-Hawkes prior: Cluster interaction network

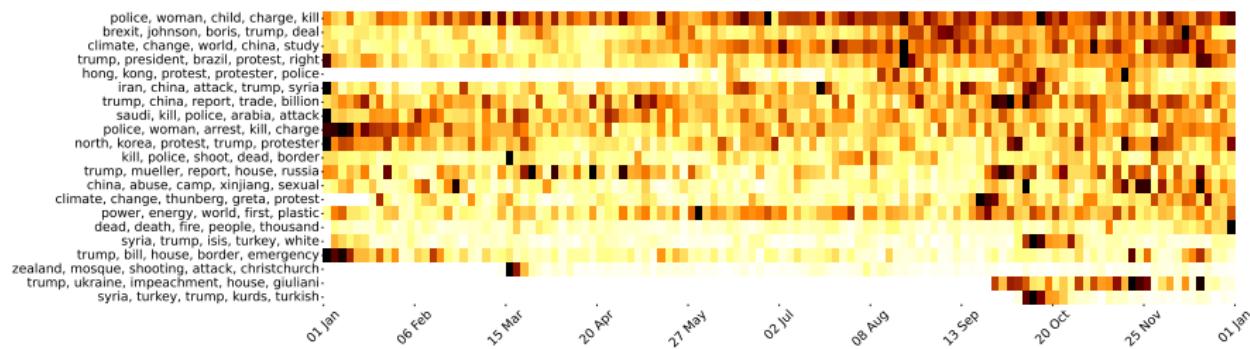


Figure 20: Inferred topics timeline

Motivation  
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DP  
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HP  
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DHP  
oooooooo

PDP  
oo

PDHP  
oooooooo

MPDHP  
oooo

Houston  
●oooo

Conclusion  
oo

## Structure matters!

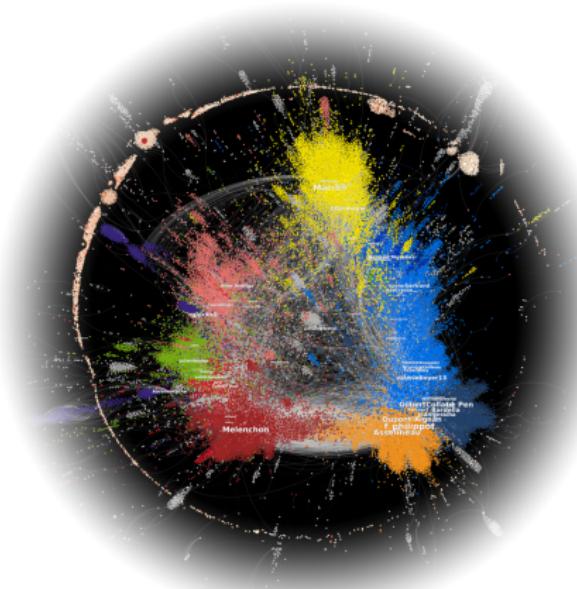


Figure 21: Sample of Twitter structure (Politoscope [Gaumont et al., 2018])

## Why (MP)DHP is incomplete

- (MP)DHP prior accounts for time but not structure
  - ◊ Infers aggregated dynamics
  - ◊ Misses the structural aspect: discussions are not the same among different groups

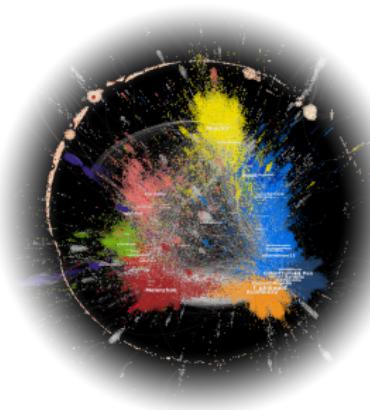


Figure 22: Sample of Twitter structure (Politoscope [Gaumont et al., 2018])

## Network inference – Literature

- Several works on network inference using survival analysis:
  - ◊ NetRate [Gomez-Rodriguez et al., 2011]
  - ◊ KernelCascade [Du et al., 2012]
  - ◊ MoNet [Wang et al., 2012]
  - ◊ InfoPath [Gomez-Rodriguez et al., 2013a]
  - ◊ TopicCascade [Du et al., 2013]
- They are all special cases of [Gomez-Rodriguez et al., 2013b]
  - ◊ Bridges the gap between network inference and point processes
  - ◊ Formulates each of previous models as a **counting point process**



# Temporal and structural prior

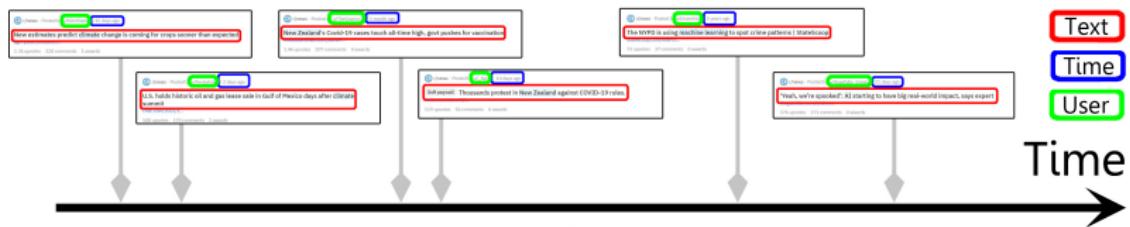
- Houston: **Heterogeneous Online User-Topic Network** inference
- Prior on cluster membership  $C_i$  of observation  $i$  observed on node  $u$  at time  $t$  given history  $\mathcal{H}$  and cluster-dependent networks  $A$ :

$$P(C_i = k | u, t, \mathcal{H}, A)$$

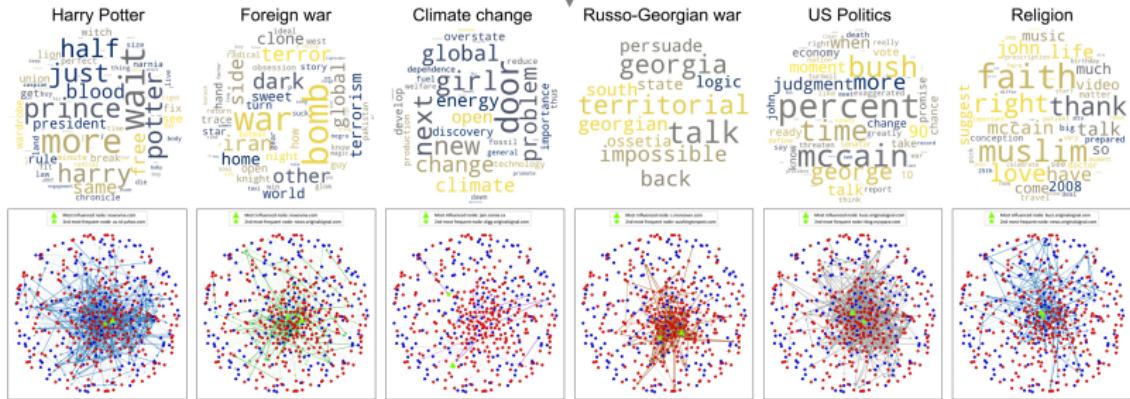
$$= \begin{cases} \frac{\lambda_0^{(k)} + \sum_{\mathcal{H}_{i,c}^{(k)}} H(t_i^c | t_j^c, \alpha_{u_j^c, u_i^c}^{(k)})}{\lambda_0^{(K+1)} + \sum_k^K \lambda_0^{(k)} + \sum_{\mathcal{H}_{i,c}^{(k)}} H(t_i^c | t_j^c, \alpha_{u_j^c, u_i^c}^{(k)})} & \text{if } k = 1, \dots, K \\ \frac{\lambda_0^{(K+1)}}{\lambda_0^{(K+1)} + \sum_k^K \lambda_0^{(k)} + \sum_{\mathcal{H}_{i,c}^{(k)}} H(t_i^c | t_j^c, \alpha_{u_j^c, u_i^c}^{(k)})} & \text{if } k = K+1 \end{cases}$$

$$= \begin{cases} \frac{\text{Strength of incoming edges of cluster/subnetwork } k \text{ at time } t}{\text{Normalizing term}} & \text{if } k = 1, \dots, K \\ \frac{\text{Probability of a new cluster/subnetwork } k+1 \text{ at time } t}{\text{Normalizing term}} & \text{if } k = K+1 \end{cases}$$

## Task

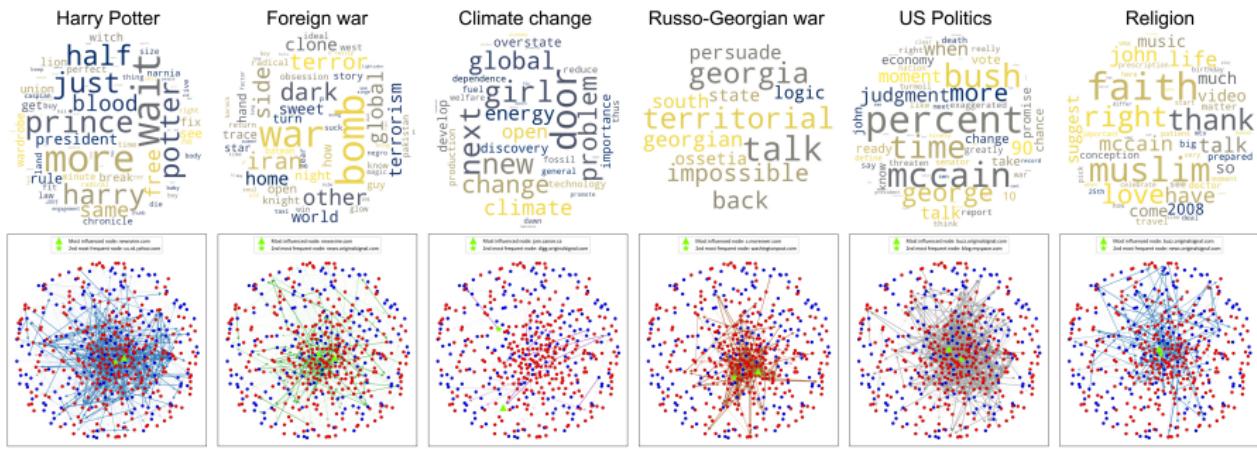


## Dirichlet-Survival Process



# Results – Real world

- Memetracker data (2009)



- Disclaimer: other works performing the same task, maybe better, without Dirichlet-Point processes [Barbieri et al., 2017]

# Conclusion

- Dirichlet and Hawkes process have an old and separate history
  - ◊ Only recently (2015) they have been brought together
  - ◊ Their reunion launched a new branch of inductive machine learning
- As many new perspectives as possible combinations

(DP, HDP, nHDP, **PDP**, IBP, PIBP, PnHDP, PPY, PnPY, PHPY, ...)

×

(Hawkes, Multi Hawkes, Survival, Cox, Poisson, Determinantal, ...)

=

(DHP, HDHP, IBHP, **PDHP**, MPDHP, Houston, ...?)

Motivation  
oooo

DP  
oooo

HP  
ooooo

DHP  
oooooooo

PDP  
oo

PDHP  
oooooooo

MPDHP  
oooo

Houston  
oooooo

Conclusion  
o●

Thanks for your attention!

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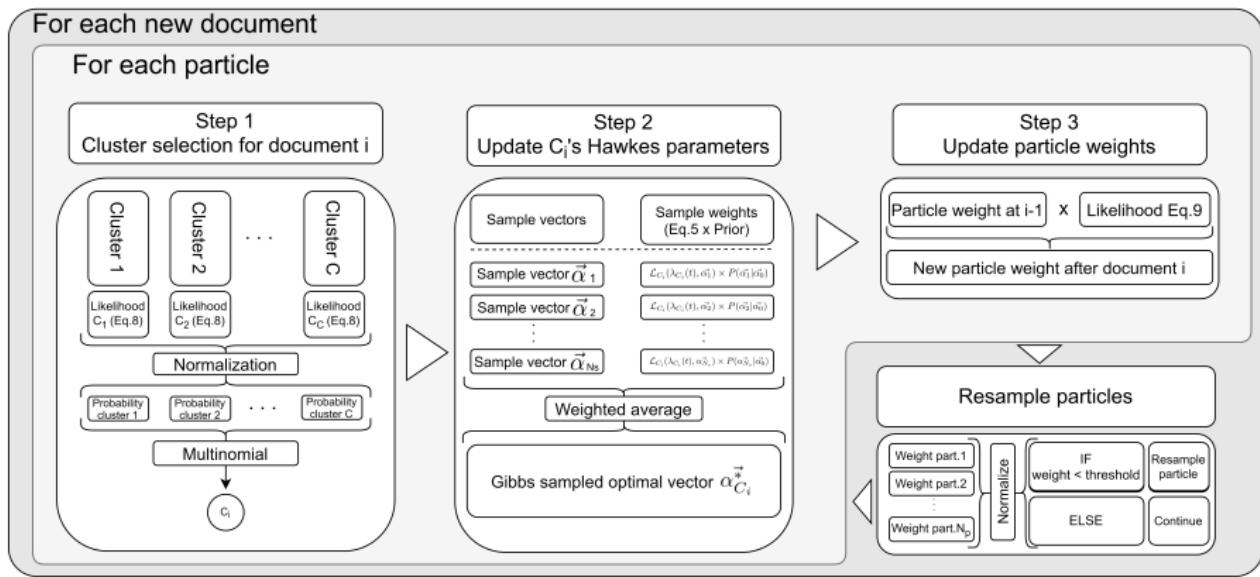
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# Inference (summarized)



## PDP impact

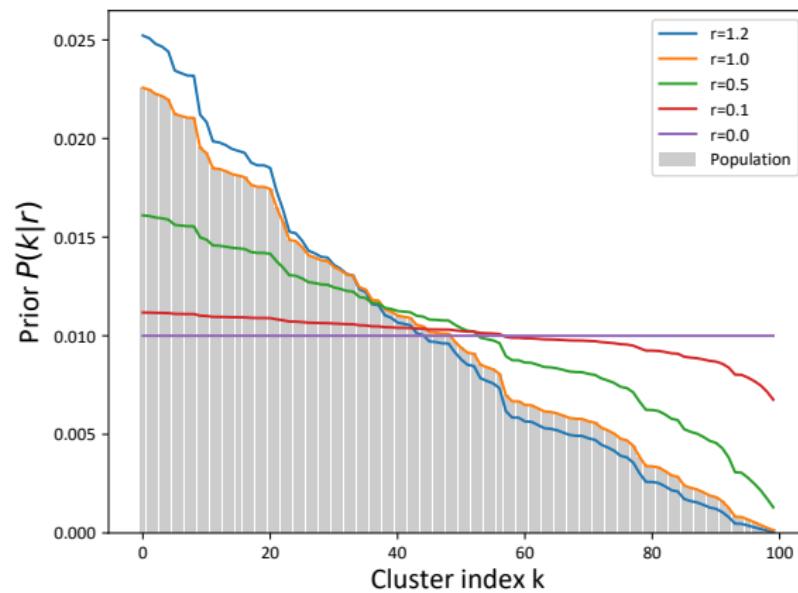
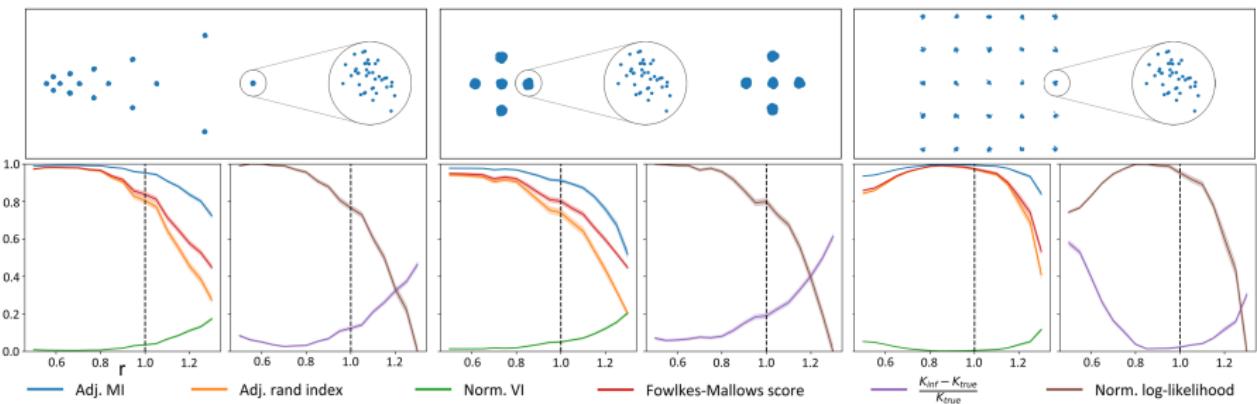


Figure 23: Prior probability for each of 100 clusters whose population is known (grey bars) w.r.t.  $r$

# Results

- Use as prior for IGMM
- DP not always the best prior



## Why is it relevant - Overlaps

- Often, a piece of information is more informative than the other:
  - Twitter: short texts (few textual information) but informative cascade dynamics (helpful temporal information)
- Happens often because of overlaps:

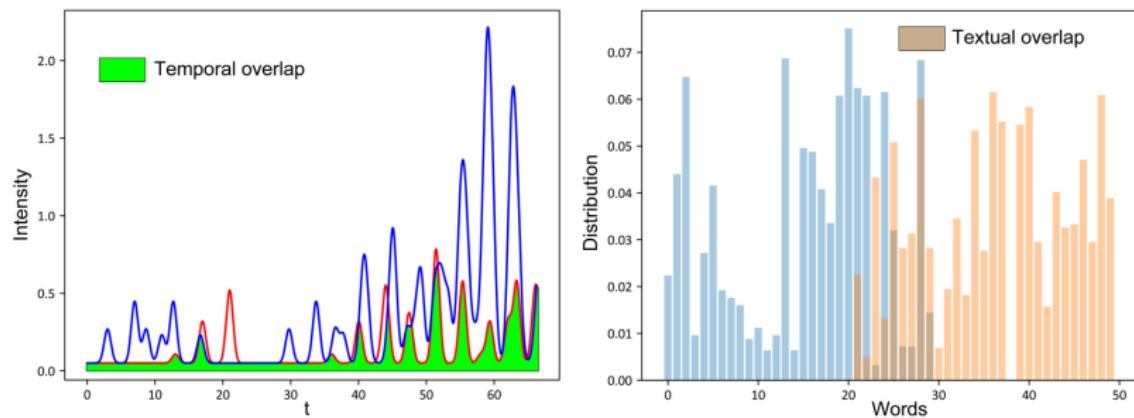
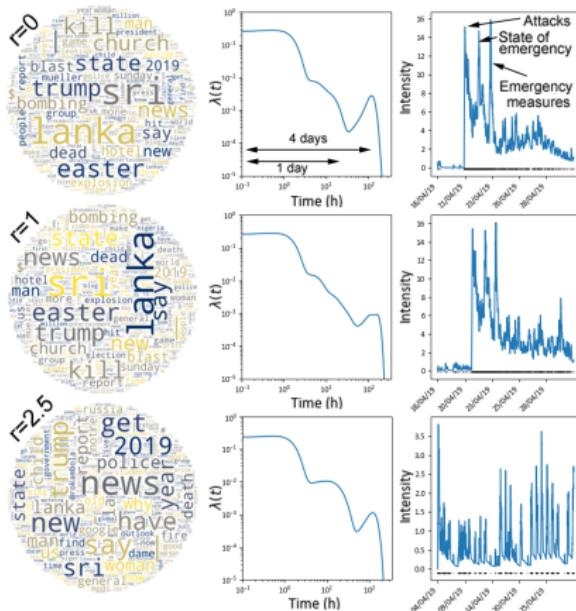


Figure 24: [Poux-Médard et al., 2021]

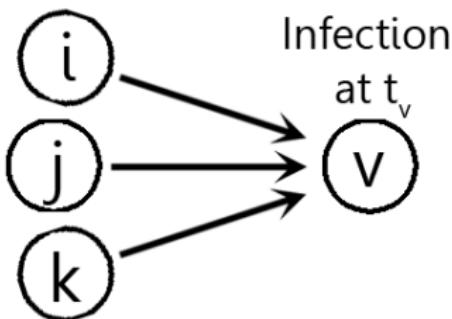
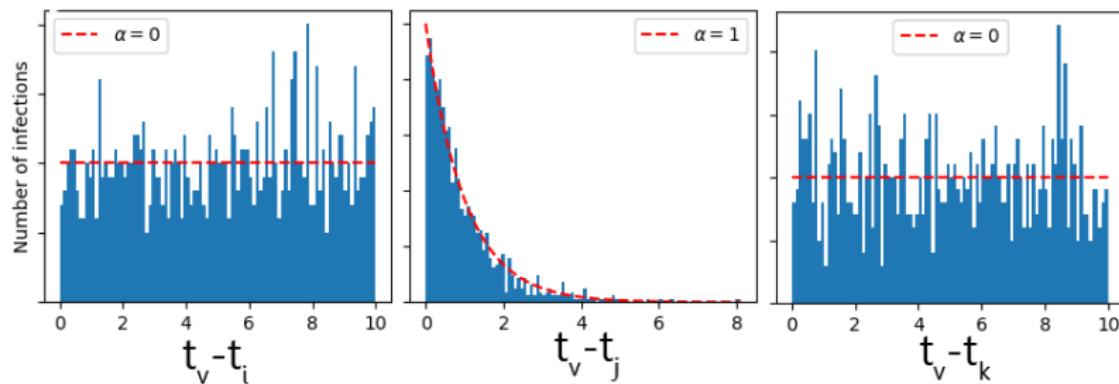
## Reddit r/news - Typical output



- Real world data: r/news
- Different clusters and dynamics for different  $r$ 
  - ◊ Small  $r$ : similar vocabulary
  - ◊ Large  $r$ : specific dynamics

Figure 25: [Poux-Médard et al., 2021]

## Network inference

Exponential model  $P(t) = a \cdot e^{-\alpha t}$ 

# Point process

- Network inference naturally embeds into point processes literature  
→ We can derive a temporal *and* structural Bayesian prior

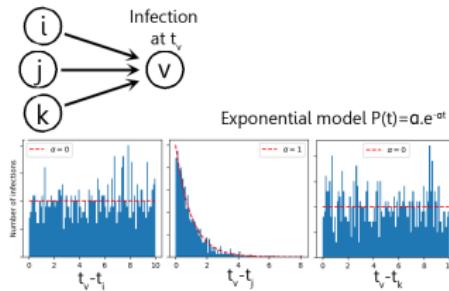


Figure 26: Survival process

Both are  
point  
processes  
 $\langle \approx \rangle$

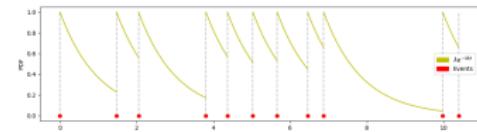
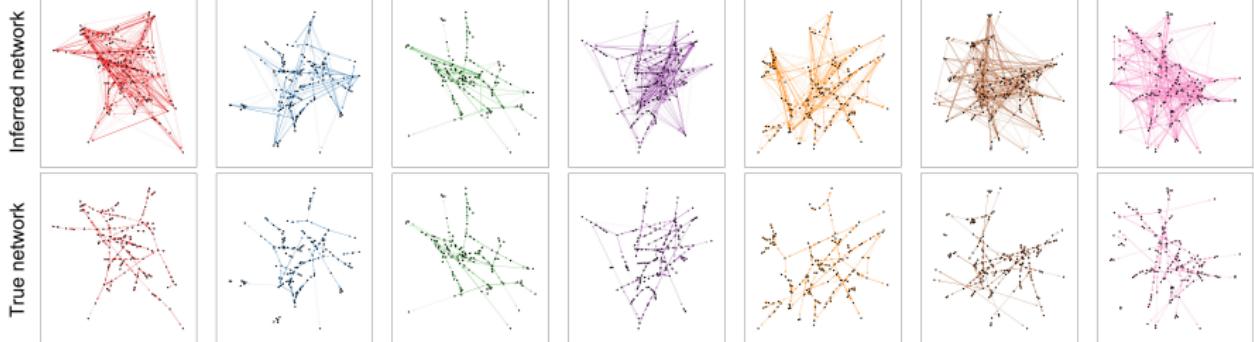


Figure 27: Hawkes process

## Results – Synthetic

- We simulate the spread of documents drawn from 5 topics, each with its own vocabulary and subnetwork



## Numerical results

		Houston	TC	DHP	NetRate
PL	NMI	<b>0.809</b>	0.669	0.449	-
	ARI	<b>0.688</b>	0.330	0.063	-
	AUC	<b>0.807</b>	0.719	-	0.731
	MAE	<b>0.267</b>	0.338	-	0.460
ER	NMI	<b>0.787</b>	0.711	0.638	-
	ARI	<b>0.631</b>	0.488	0.411	-
	AUC	<b>0.849</b>	0.800	-	0.659
	MAE	<b>0.229</b>	0.278	-	0.481
Blogs	NMI	<b>0.750</b>	0.668	0.372	-
	ARI	<b>0.609</b>	0.365	0.023	-
	AUC	<b>0.701</b>	0.613	-	<b>0.710</b>
	MAE	<b>0.374</b>	0.444	-	0.499