## **Introduction to dynamics**

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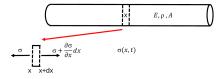
#### **Outline**

Context: continuum mechanics, small deformation, linear elasticity

Objectives: quickly brush up wave dynamics concepts to later interpret physics of dynamic fracture

- 1D (fragment) wave propagation; c-t diagram
- Wave reflection and transmission
- 3D dynamics; fundamental waves
- (Crack) Surface wave; Rayleigh

# 1D wave propagation: In an infinite elastic bar



Newton's second law:

$$\left(\sigma + \frac{\partial \sigma}{\partial x}dx\right)A - \sigma A = \rho A dx \frac{\partial^2 u}{\partial^2 x}$$

With constitutive law:

$$\sigma = E\epsilon = E\frac{\partial u}{\partial x}$$

Gives wave equation:

$$\frac{\partial^2 u}{\partial^2 t} = \frac{E}{\rho} \frac{\partial^2 u}{\partial^2 x} = c^2 \frac{\partial^2 u}{\partial^2 x}$$

with 
$$c = \sqrt{\frac{E}{\rho}}$$

Solution: left and right propagating waves

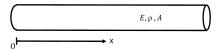
$$u(x,t) = f(x+ct) + g(x-ct)$$

Boundary conditions  $\operatorname{set} f$  and g

Rq: Particle velocity **is not** wave velocity ( $v = \dot{u} \ll c$ )

# 1D wave propagation

Space-Time (ct) diagram



Initial conditions:

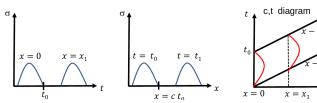
$$u(x, 0) = 0$$
  $v(x, 0) = 0$ 

Boundary conditions:

$$\sigma(0, t) = \sigma_0 h(t)$$
  $\forall t < t_0$ 

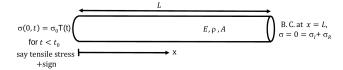
Right propagation:

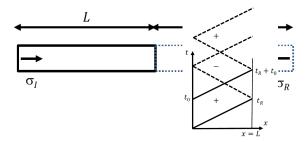
$$\sigma(x,t) = f(x - ct) = \sigma_0 h(t - x/c)$$



## Finite size bar; reflection

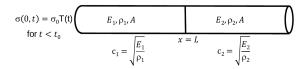
Incident and reflected wave

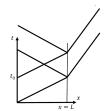




#### Interaction with interfaces

bimaterials: Incident, reflected, and transmitted waves





$$\sigma_I = f_I(x - c_1 t)$$

$$\sigma_R = f_R(x - L + c_1(t - t_R))$$

$$\sigma_T = f_T(x - L - c_2(t - t_R))$$

**Continuity:** 
$$f_T = \frac{2R}{1+R} f_I$$
 and  $f_R = \frac{R-1}{1+R} f_I$ 

$$\forall t, \text{ at } x = L$$
 $\sigma_I + \sigma_R = \sigma_T$ 

 $\sigma_I + \sigma_R = \sigma_T$  $u_I + u_R = u_T$ 

or

$$v_I + v_R = v_T$$

with *R* the impedance ratio  $R = \frac{\rho_2 c_2}{\rho_1 c_1}$ 

# 3D wave propagation: In elastic isotropic medium

Equations of motion:

$$div(\sigma) = \rho \ddot{\mathbf{u}}$$

With constitutive law:

$$\sigma = \lambda t r(\epsilon) I + 2\mu \epsilon$$

Kinematics:

$$\epsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{i,i})$$

Planar waves solutions:

$$u(\mathbf{x}, t) = f(\mathbf{p} \cdot \mathbf{x} - ct)\mathbf{d}$$

with

- d: direction of displacement
- p: direction of propagation
- · c: wave velocity
- $\mathbf{p} \cdot \mathbf{p} = 1$

Equation of motion yields an eigenvalue/eigenvector problem of accoustic tensor:

$$[(\lambda + \mu)\mathbf{p} \otimes \mathbf{p} + \mu(\mathbf{p} \cdot \mathbf{p})\mathbf{I}] \mathbf{d} = \rho c^2 \mathbf{d}$$

# Solutions of acoustic tensor: Two solutions

Solution 1: 
$$\mathbf{d} = d\mathbf{p} \Rightarrow c_L = \sqrt{\frac{\lambda + 2\mu}{\rho}}$$

Longitudinal waves, P-waves, or Push waves.

Pressure waves, L waves, Primary waves (earthquake warning)

**Solution 2:** 
$$\mathbf{d} \cdot \mathbf{p} = 0 \Rightarrow c_S = \sqrt{\frac{\mu}{\rho}}$$

Shear waves ≡ S-wave

Two possible directions for **p** 





animations from Wikipedia

# Fundamental waves: Helmoltz decomposition

One can show (with Helmoltz decomposition) that all waves can be decomposed as a sum of  $c_L$  and  $c_T$  waves.

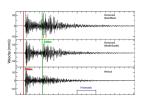
## Rayleigh waves: surface waves

- Rayleigh waves (often called «ground roll») are of particular interest to seismologists
  - o Decay slower than bulk waves: carry energy over long distances

Ratio of celerities:



- If  $\nu = 0$  ,  $\frac{c_L}{c_S} = \sqrt{2}$
- In all cases:  $c_S < \sqrt{2}c_L$



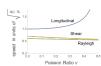
- Useful to localize earthquakes
- Emergence of «peculiar» waves: such as Love, Lamb, Stoneley and Rayleigh waves
- Rayleight wave speed  $c_R$

$$c_R < c_S < c_L$$

• Freund:

$$\frac{c_R}{c_S} = \sqrt{\frac{0.862 + 114\nu}{1 + \nu}}$$
Rayleigh Wave





images from Wikipedia

### **Conclusions**

- ullet Existence of P-Waves and S-Waves, propagating at  $c_s$   $c_T$
- Surface Rayleigh waves propagate at  $c_R < c_s$

• Waves propagating along cracks are concerned