### Indexing big colored image bank: Texture 3.0

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#### **Outline**

- 1 Introduction
- 2 Team presentation
- 3 User requirement
- Work achievement
- 6 Results and Discussion
- 6 Project Management
- Conclusion

# Image Indexing

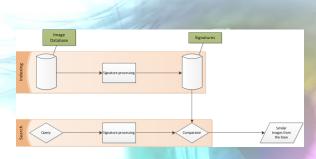


FIGURE: Online image indexing

### Descriptor

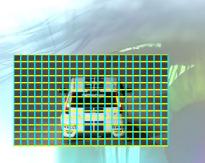


FIGURE: Dense grid keypoints

# Descriptor



FIGURE: Points of interest keypoints

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#### **Deadlines**

#### XLIM-SIC Laboratory of University of Poitiers

- Noel Richard (Researcher in Color images): Supervisor
- David Helbert ( Researcher in Signal-Image-Communications) : Supervisor
- Thierry Urruty (Researcher in Color images): Customer

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#### Software

- Design software programs : indexation of images database,calculate descriptor according to nature images
- Adapt the last up to date designed color and texture attributes to the current image classification
- Compare our results (using CLEF challenge metrics)
- Provide an abstract of the comparisons and a technical report

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### SIFT(Scale-Invariant Feature Transform)

#### Key-points detection $(x,y,\sigma)$

- Scale-space extrema detection
  Find the best locations which characterize well the image
- Key-point location
  Improve the position of the keypoints detected
- Orientation assignment
  Assign orientations to the key-points
- key-point descriptor
  Describe the key-point with with a vector of 128 dimension

### SIFT(Scale-Invariant Feature Transform)







FIGURE: SIFT test2

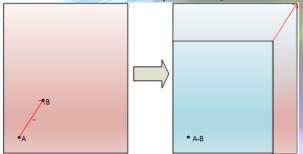
### $C_2O(1/3)$



- Conversion to L\*a\*b\* space
- C<sub>2</sub>O matrix calculation.
- C<sub>2</sub>O signature extraction.

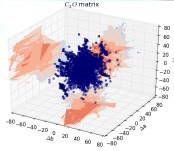
### $C_2O(2/3)$

- The C<sub>2</sub>O matrix
  - The color difference computation (in the  $L^*a^*b^*$  space).

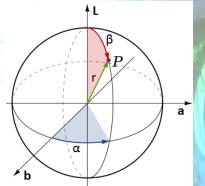


### $C_2O(2/3)$

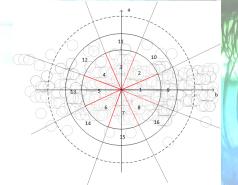
- The C2O matrix
  - The color difference computation (in the  $L^*a^*b^*$  space).
  - The C<sub>2</sub>O matrix in a 3-D repository.



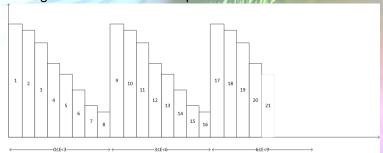
- The C2O feature extraction
  - Spherical from cartesian repository.



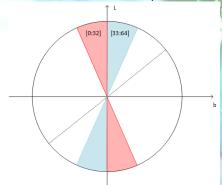
- The C<sub>2</sub>O feature extraction
  - Spherical from cartesian repository.
  - Quantization for one β interval.



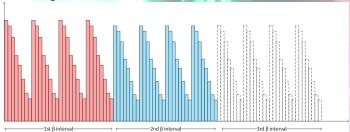
- The C<sub>2</sub>O feature extraction
  - Spherical from cartesian repository.
  - Quantization for one β interval.
  - Histogram obtained for one β interval.



- The C<sub>2</sub>O feature extraction
  - Spherical from cartesian repository.
  - Quantization for one β interval.
  - Histogram obtained for one β interval.
  - Quantization for each β interval.



- The C<sub>2</sub>O feature extraction
  - Spherical from cartesian repository.
  - Quantization for one β interval.
  - Histogram obtained for one β interval.
  - Quantization for each β interval.
  - Final signature obtained.



### Classification (Bag of words)

Reducing the number of points.

- K-means
  - Attribute the vectors to centroid vectors.

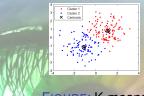
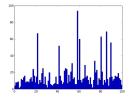


FIGURE: K-means



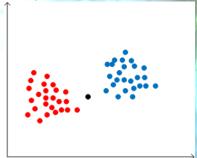
- Signature
  - Design histogram in function of assignment of the vectors.

FIGURE: Signature

### Classification (K-nn(1/2))

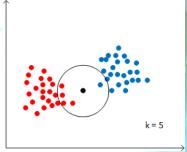
- The k nearest neighbor method

Comparison to the dictionary.



### Classification (K-nn(1/2))

- The k nearest neighbor method
  - Comparison to the dictionary .



- 4 Occurrences of the 'red' class , 1 occurrence of the 'blue' class
- The new point is attributed to the 'red' class

### Classification (K-nn(1/2))

- Application for image classification
  - More complex data.
  - Distances on signature vectors extracted from the K-mean method.
  - One most adapted distance type for each descriptor.

#### **CLEF**

- What is CLEF?
- What did we gained from enrolling?



FIGURE: Points of interest keypoints

benchmark

#### Process flow

- Main function which control all the process
  - Create the tree structure.
  - Allows the choice of descriptors.

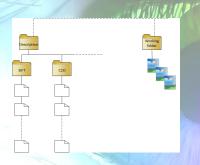


FIGURE: Tree structure

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#### Results

- Reduce data-base of 100 images composed of only 4 species.
- Compare the two descriptors SIFT and C<sub>2</sub>O.

TABLE: SIFT result

		A ROSENT REME TO AM		
ID	Training Base	Test Base	Correct	Accuracy
173	17	8	4	50%
1102	22	3	1	33%
1889	16	9	1	11%
2717	15	10	7	70%
Total	70	30	9	1

TABLE: C<sub>2</sub>O result

ID	Training Base	Test Base	Correct	Accuracy
173	17	8	1/1/1	12.5%
1102	22	3	1	33%
1889	16	9	0	0%
2717	15	10	7	70%
Total	70	30	9	1

#### Discussion

- Classification
  - To much reducing on the K-means (100 words).
  - Euclidean distance not the most efficient or adapt.
- C<sub>2</sub>O
  - The concatenation way is not optimal.

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### Project management (1/2)

- The scrum methodology
  - One sprint per week.
  - Daily scrum meeting.
  - Complete time repartition on the product backlog.



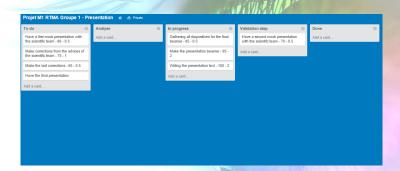
### Project management (2/2)

- The sprint backlog: Trello board
  - Progress on one sprint.



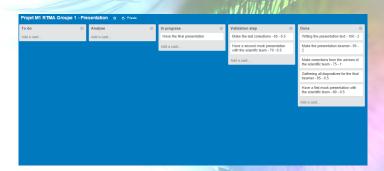
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