

Feature importance measures for Random Forests: the problem of Mean Decrease Impurity, solutions and alternatives

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- 1 Introduction & Problem Statement
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- 3 Unifying Framework
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- Explain the impact of a feature on a model
- To understand the output
- Important for biology, finance, patient care
- Subjective notion

Two key considerations

- 1 Marginal vs Conditional:** Do we want unique information?
- 2 Model vs Data:** Are we explaining the model or the underlying process?

Decision Tree

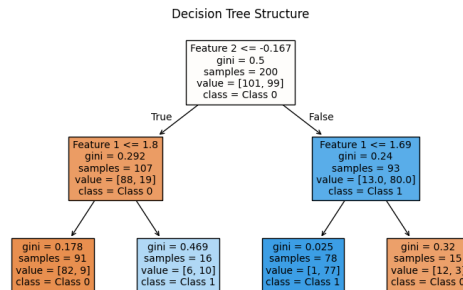
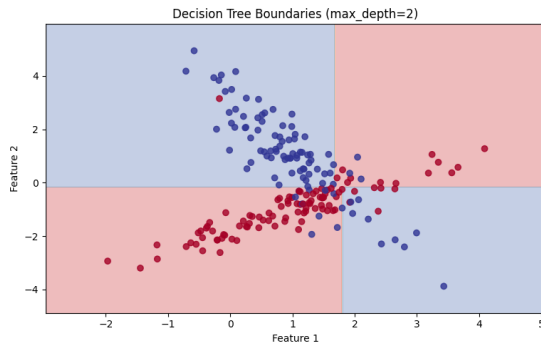


Figure: Visualization of a simple decision tree and its decision function.

Mean Decrease in Impurity

Definition (MDI, [Breiman \(2001\)](#))

For feature j :

$$\text{MDI}(j) = \frac{1}{T} \sum_{t \in F} \sum_{\substack{m \in \text{inter}(t) \\ j_m = j}} [\omega_m H(m) - \omega_{l_m} H(l_m) - \omega_{r_m} H(r_m)]$$

where $\omega_m = \frac{n_m}{n}$ and H is the impurity function.

The Problem with MDI

Three main issues:

- 1 Positive bias:** Assigns non-zero importance to irrelevant features
- 2 Cardinality bias:** Favors high-cardinality features
- 3 Overfitting amplification:** Deeper trees = more bias

Despite that it is widely used, which causes a problem for `scikit-learn`.

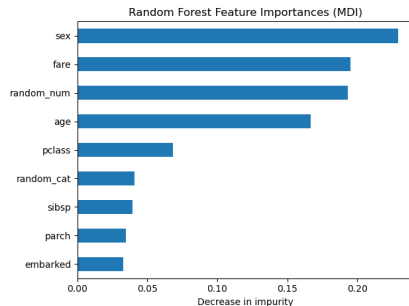


Figure: MDI assigns significant importance to random features

1. Conditional Inference Trees ([Strobl et al. 2008](#))

- Replace CART ([Breiman et al. 1984](#)) with conditional inference trees ([Hothorn, Hornik, and Zeileis 2006](#))
- Eliminates selection bias
- **Cost:** 25-35x slower training

2. Out-of-Bag Corrections

- UFI ([Zhou and Hooker 2021](#))
- MDI-oob ([Li et al. 2019](#))
- Use oob samples to reduce overfitting bias
- Presented in different ways, we show they are very close

Algorithm Permutation Importance

Require: Fitted model f , validation dataset \mathcal{D} , scoring function Score

- 1: Compute reference score $s_0 \leftarrow \text{Score}(f, \mathcal{D})$
 - 2: **for** each feature j **do**
 - 3: $\tilde{\mathcal{D}}^{(j)} \leftarrow \text{RandomlyShuffle}(\mathcal{D}, \text{column } j)$
 - 4: $s_j \leftarrow \text{Score}(f, \tilde{\mathcal{D}}^{(j)})$
 - 5: **end for**
 - 6: $PI(j) \leftarrow s_0 - s_j$
-

- **Pros:** Model-agnostic, suitable for feature selection ([Reyero-Lobo, Neuvial, and Thirion 2025](#))
- **Cons:** Computationally expensive, issues with correlated features

Definition (Shapley Additive Global Importance)

$$\text{SAGE}(j) = \frac{1}{p} \sum_{\substack{s \subseteq \{1, \dots, p\} \\ j \notin s}} \binom{p-1}{|s|}^{-1} (v(s \cup \{j\}) - v(s))$$

Satisfies four axioms: Efficiency, Symmetry, Dummy, Linearity

- **Pros:** Additive decomposition, game-theoretic foundation
- **Cons:** Exponential complexity, poor for feature selection ([Reyero-Lobo, Neuval, and Thirion 2025](#))
- **Note:** Converges to MDI in categorical settings ([Sutera et al. 2021](#))

Rewriting MDI as Loss Decomposition

Key insight: MDI can be written as feature contributions to training loss improvement.

Saabas (2017) show that for any prediction $f_t(x)$:

$$f_t(x) = v_0 + \sum_{j=1}^p f_{t,j}(x)$$

This leads to:

$\text{MDI}(j)$ = contribution of feature j to training score improvement

Definition (Training Score)

$$S_{\text{train}} = \frac{1}{n} \sum_{i=1}^n [l(y_i, v_0) - l(y_i, f_t(x_i))] = \sum_{j=1}^p S_{\text{train},j} = \sum_{j=1}^p \text{MDI}(j)$$

Proposed Method: oob-score

Instead of using training samples, use out-of-bag samples:

$$S_{\text{oob}} = \frac{1}{n'} \sum_{i=1}^{n'} [l(y'_i, v_0) - l(y'_i, f_t(x'_i))] = \sum_{j=1}^p S_{\text{oob},j}$$

Definition (oob-score)

$$\text{oob-score}(j) = S_{\text{oob},j} = \sum_{\substack{m \in \text{inter}(t) \\ j_m = j}} \omega'_m H'(m) - \omega'_{l_m} H'(l_m) - \omega'_{r_m} H'(r_m)$$

where $H'(m)$ is the cross-impurity: OOB targets with in-bag node values

Advantage: Additive decomposition of risk reduction for single trees: S_{oob} approximates the risk improvement

$$S := \mathbb{E}_{x,y \sim P} [l(y, v_0) - l(y, f_t(x))].$$

Unifying UFI and MDI-oob

Summary of the Impurity measures

- $H(m) = \frac{1}{n_m} \sum_{\substack{i \in \{1, \dots, n\} \\ x_i \in R_m}} I(y_i, v_m)$
- $H'(m) = \frac{1}{n'_m} \sum_{\substack{i \in \{1, \dots, n'\} \\ x'_i \in R_m}} I(y'_i, v_m)$
- $H''(m) = \frac{1}{n'_m} \sum_{\substack{i \in \{1, \dots, n'\} \\ x'_i \in R_m}} I(y'_i, v'_m)$

Method	Impurity function	Weights
MDI	H	in-bag
oob-score	H'	out-of-bag
naive-oob	H''	out-of-bag
UFI	$\frac{H+H'}{2}$	in-bag
MDI-oob	$\frac{H+H'}{2}$	out-of-bag

Table: Summary of impurity-based methods

Key elements:

- UFI and MDI-oob are nearly identical (different weights)
- All methods converge asymptotically
- UFI has theoretical guarantee: $X_j \perp\!\!\!\perp Y$ in every hyperrectangle $\Rightarrow \mathbb{E}[\text{UFI}(j)] = 0$

Experimental Setup

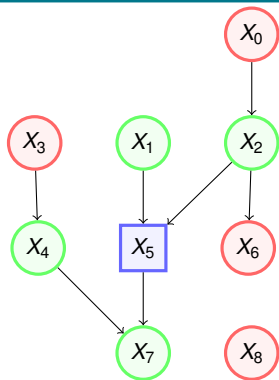


Figure: Feature relationships.
 Blue = Target, Green = Feature in Markov blanket, Red = Feature not in Markov blanket

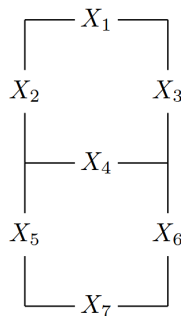


Figure: 7-segment display

y	x_1	x_2	x_3	x_4	x_5	x_6	x_7
0	1	1	1	0	1	1	1
1	0	0	1	0	0	1	0
2	1	0	1	1	1	0	1
3	1	0	1	1	0	1	1
4	0	1	1	1	0	1	0
5	1	1	0	1	0	1	1
6	1	1	0	1	1	1	1
7	1	0	1	0	0	1	0
8	1	1	1	1	1	1	1
9	1	1	1	1	0	1	1

Figure: Possible values of (X_1, \dots, X_7, Y)

Noise Detection Results

$\mathcal{H}_0 : X_8$ has zero importance

vs.

$\mathcal{H}_1 : X_8$ has non-zero importance.

Method	Mean importance	Rejects H_0 (t-test)
MDI	0.0480	YES
naive-oob	0.0435	YES
UFI	0.0007	NO
MDI-OOB	-0.0048	YES
oob-score	-0.0475	YES
Permutation	0.0003	NO
SAGE	-0.0018	YES

Only UFI and Permutation Importance correctly identify irrelevant features.

Feature Selection Performance

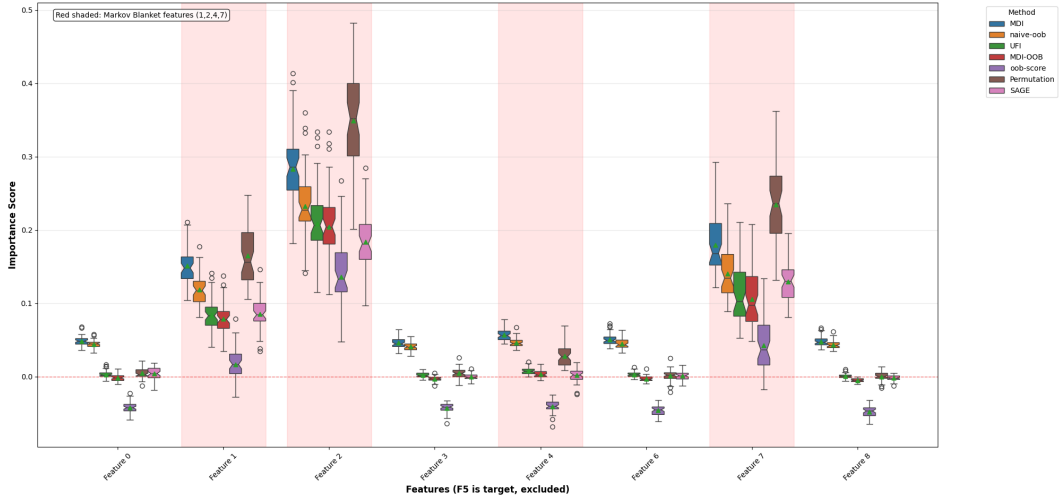
Task: Rank top 4 features to match Markov blanket

Method	Success rate
MDI	30/50 (60%)
naive-oob	14/50 (28%)
oob-score	15/50 (30%)
UFI	31/50 (62%)
MDI-OOB	33/50 (66%)
Permutation	46/50 (92%)
SAGE	13/50 (26%)

Permutation importance dominates, UFI and MDI-oob improve over MDI

Visualization

Feature Importance Comparison Across Methods



Computational Cost

Method	Time (500 pts)	Time (1000 pts)
MDI (retrieval)	16.8 ms	17.4 ms
UFI (high-level)	5506.7 ms	13606.6 ms
UFI (optimized)	192.6 ms	355.1 ms
Permutation	872.8 ms	1294.8 ms
SAGE	2835.7 ms	7028.1 ms

Key takeaway: Optimized UFI is 4x faster than Permutation, 14-20x faster than SAGE

Asymptotic Convergence of Impurity methods

Convergence of impurity-based feature importance measures for Random Forest

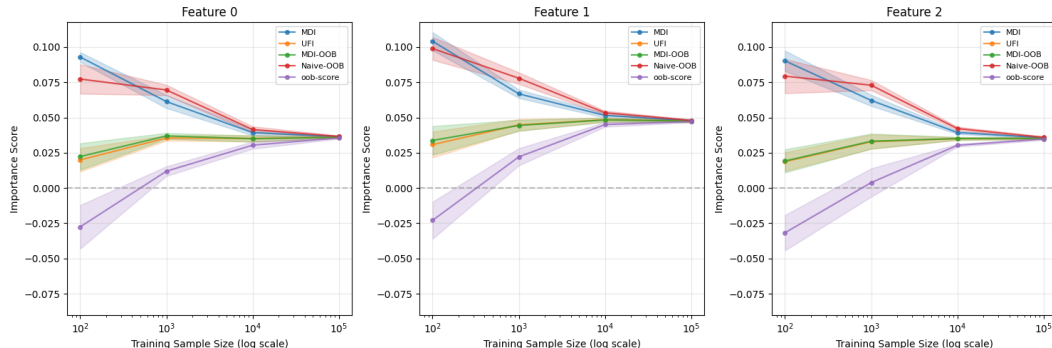


Figure: Evolution of the impurity based feature importance measures on the `noised_led` dataset as sample size increases, for the first 3 features.

Asymptotic Convergence of MDI to SAGE

Convergence of SAGE and MDI for Extra Trees

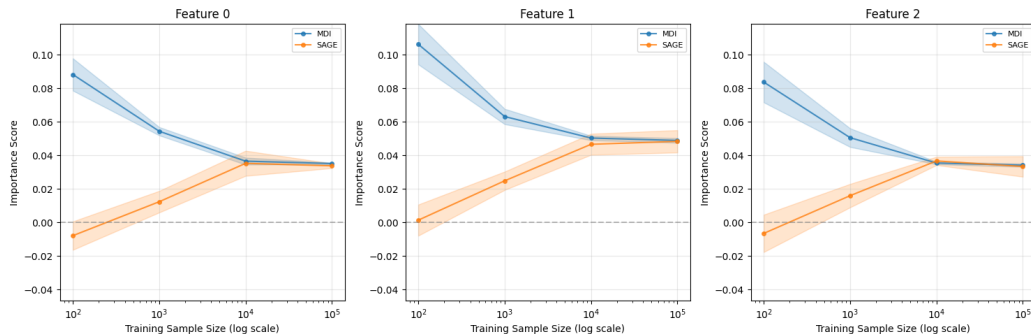


Figure: Convergence of the feature importance of SAGE and MDI in the categorical setting for Totally randomized trees, on the `noised_led` dataset, for the first 3 features.

- 1 **Unified framework** for all impurity-based methods
- 2 **New method (oob-score)** with additive decomposition property
- 3 **Extended UFI/MDI-oob** to arbitrary loss functions
- 4 **Evaluation** of feature selection capability
- 5 **Fast implementation** of UFI in Cython

For scikit-learn's replacement of MDI

UFI is the best choice:

- Fast computation during training with Cython implementation
- Theoretical guarantee for noise detection
- Significant improvement over MDI









For feature selection tasks

Permutation Importance:

- Best performance for feature selection
- Already available in scikit-learn
- Worth the computational cost for critical applications

- Prove or disprove $\text{UFI}(j) = 0 \implies X_j \perp\!\!\!\perp Y | X_{-j}$
- Formal proof that MDI is strictly positive in finite samples
- Adapt UFI to Gradient Boosting

Thank you for your attention.

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