NETWORK TOPOLOGY

Topology refers to the way in which the network of computers is connected. Each topology is suited to specific tasks and has its own advantages and disadvantages.

The choice of topology is dependent upon

- type and number of equipment being used
- planned applications and rate of data transfers
- required response times
- cost

There are FOUR major competing topologies

- Bus
- Ring
- Star
- FDDI

Most networking software supports all topologies.

Bus Topology

- all workstations connect to the same cable segment
- commonly used for implementing Ethernet at 10mbps
- the cable is terminated at each end
- wiring is normally done point to point
- a faulty cable or workstation will take the entire LAN down
- two wire, generally implemented using coaxial cable during the 1980's

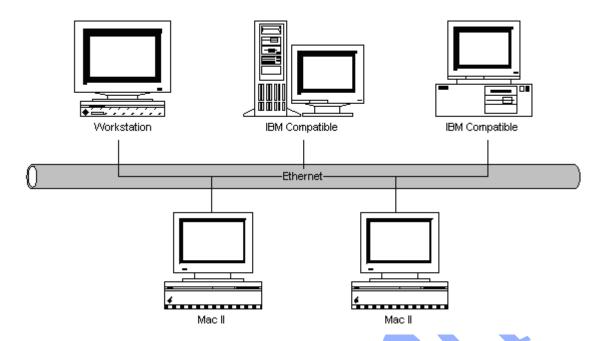
The bus cable carries the transmitted message along the cable. As the message arrives at each workstation, the workstation computer checks the destination address contained in the message to see if it matches it's own. If the address does not match, the workstation does nothing more.

If the workstation addresses matches that contained in the message, the workstation processes the message. The message is transmitted along the cable and is visible to all computers connected to that cable.

There are THREE common wiring implementations for bus networks

- 10Base2 (thin-net, CheaperNet) 50-ohm cable using BNC T connectors, cards provide transceiver
- 10Base5 (ThickNet) 50-ohm cable using 15-pin AUI D-type connectors and external transceivers
- 10BaseT (UTP) UTP cable using RJ45 connectors and a wiring centre

Physical Implementation of a Bus Network



The above diagram shows a number of computers connected to a Bus cable, in this case, implemented as Thin Ethernet. Each computer has a network card installed, which directly attaches to the network bus cable via a T-Connector.

It is becoming common to use 10BaseT (UTP) for implementing Ethernet LANS. Each workstation is wired in star fashion back to a concentrator wiring centre (hub). The hub is a multi-port device supporting up to about 32 ports. One of these ports is connected to a server, or the output of the hub can be connected to other hubs.

Ethernet 802.3: Carrier Sense Multiple Access with Collision Detection (CSMA/CD)

This protocol is commonly used in bus (Ethernet) implementations.

Multiple accesses refers to the fact that in bus systems, each station has access to the common cable.

Carrier sense refers to the fact that each station listens to see if no other station is transmitting before sending data.

Collision detection refers to the principle of listening to see if other stations are transmitting whilst we are transmitting.

In bus systems, all stations have access to the same cable medium. It is therefore possible that a station may already be transmitting when another station wants to transmit. Rule 1 is that a station must listen to determine if another station is transmitting before initiating a transmission. If the network is busy, then the station must back off and wait a random interval before trying again.

Rule 2 is that a station which is transmitting must monitor the network to see if another station has begun transmission. This is a collision, and if this occurs, both stations must back off and retry after a random time interval. As it takes a finite time for signals to travel down the cable, it is possible for more than one station to think that the network is free and both grab it at the same time.

CSMA/CD models what happens in the real world. People involved in group conversation tend to obey much the same behavior.

Physical Bus Cable Limits

10Base2 THIN ETHERNET NETWORK LAYOUT

Limitations

- maximum number of trunk segments = 5
- maximum trunk segment length = 607 feet (185 meters)
- maximum network trunk cable = 3035 feet (925 meters)
- maximum number of stations on a trunk segment = 30
- minimum distance between T connectors = 1.5 feet (0.5 meters)

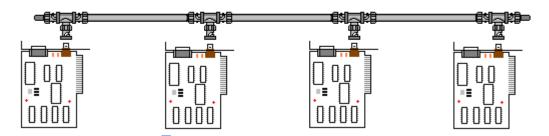
Rules

- each end of the trunk segment is terminated in 50-ohms
- one of the terminators is grounded
- connector splices are kept to a minimum

Cabling

- BNC-T type connectors
- RG58-AU 50-ohm cable, 0.2"





10Base5 THICK ETHERNET NETWORK LAYOUT Limitations

- maximum number of trunk segments = 5
- maximum trunk segment length = 1640 feet (500 meters)
- maximum network trunk cable = 8200 feet (2500 meters)
- maximum number of stations on a trunk segment = 100
- minimum distance between transceivers = 8 feet (2.5 meters)
- maximum transceiver cable length = 165 feet (50 meters)

Rules

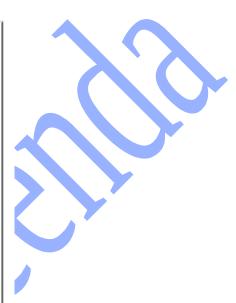
- each end of the trunk segment is terminated in 50-ohm
- one of the terminators is grounded
- Connector splices are kept to a minimum

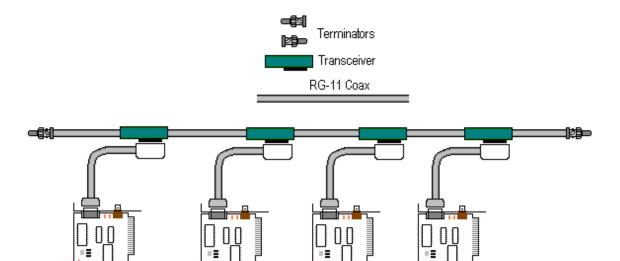
Cabling

- Transceivers 802.3
- 50-ohm cable RG-11
- Male DIX connector

Wiring of the DIX Connector

Pin	Ethernet	IEEE 802.3	
1	Shield	Control-in	Shield
2	Collision presence+	Control-in	A
3	Transmit+	Data-out	A
4	Reserved	Data-in	Shield
5	Receive+	Data-in	A
6	Power return	Voltage	common
7	Reserved	Control-out	A
8	Reserved	Control-out	Shield
9	Collision presence-	Control-in	В
10	Transmit-	Data-out	В
11	Reserved	Data-out	Shield
12	Receive-	Data-in	В
13	Power	Voltage	
14	Reserved	Voltage	Shield
15	Reserved	Control-out	В
Shell		Protective	Ground





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10BaseT UTP NETWORK LAYOUT Limitations

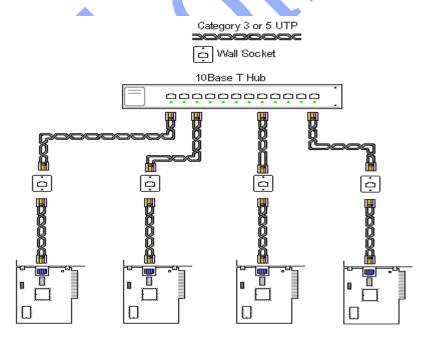
- Maximum segment length of 100 Meters
- Hub to Hub or repeater to repeater links limited to 100 Meters

Rules

- star topology
- 4 repeater/5 segment rule of 10Base5 is retained
- only two nodes per segment are allowed

Cabling

- RJ-45 Connectors
- Category 3 UTP minimum, preferably Category 5

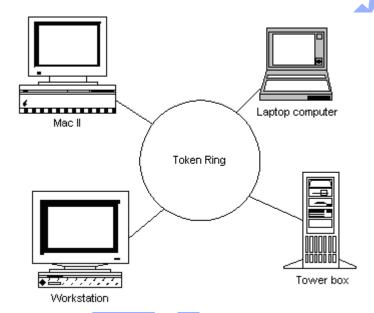


Bus Network Topology Summary

Advantages	Disadvantages	
Easy to implement Limits on cable length and Workstation numbers		
Low Cost	Difficultto isolate network faults	
	A cable fault affects all workstations	
	As the number of workstations increase, the speed of the network slows down	

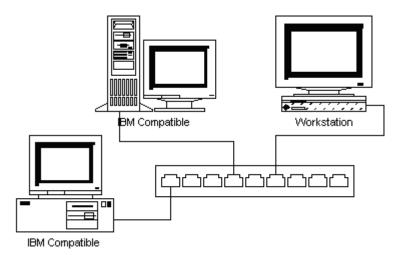
Ring Topology

- workstations connect to the ring
- faulty workstations can be bypassed
- more cabling required than bus
- the connectors used tend to cause a lot of problems
- commonly used to implement token ring at 4 and 16mbps
- four wire, generally STP or UTP



Physical Implementation Of A Ring Network

Each workstation is connected back to a Multiple Access Unit (MAU), which supports up to eight workstations. Additional MAU are cascaded to provide greater workstation numbers.



Wiring is performed in a physical star fashion, with cables wired directly from each workstation back to the MAU.

IEEE 802.5 Token Ring

This protocol is widely used in ring networks for controlling station access to the ring. A short message (called a token) is circulated around the ring, being passed from station to station (it originates from a controller or master station which inserts it onto the ring).

A station which wants to transmit waits for the token to arrive. When the token arrives, the station changes it from a token to a connector message, and appends its message. This new message is then placed on the outgoing side of the ring.

Each station passes on received tokens if they have nothing to transmit. They monitor connector messages to see if the message is addressed to them. If connector messages are addressed to them, they copy the message, modify it to signify its receipt, then send it on around the ring. Connector messages which are not addressed to them are passed directly on to the next station in the ring.

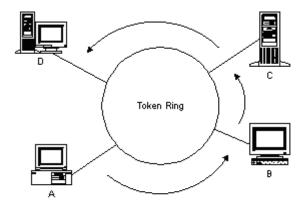
When the connector message travels full circle and arrives at the original sending station, it checks the message to see if it's been received. It then discards the message and replaces it with a token.

Token Ring

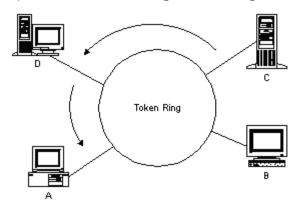
B

Assume that A wishes to transmit data to C

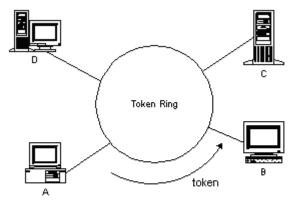
A waits for receipt of control token from its previous neighbour on the ring, D



A transmits frame onto ring, B retransmits frame to C, C copies frame into buffer, then sends frame back on ring with acknowledge bit set in frame.

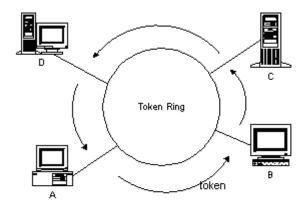


A waits for start of frame, but does not repeat it thereby removing it.



When the last bit of the frame has been received by A, it generates and passes on the token; it then processes the response bits at the tail of the frame.





When the last bit of the frame has been transmitted by A, it passes on the token - early release.

Physical Ring Cable Limits

TOKEN RING NETWORK LAYOUT Limitations

- maximum number of workstations = 96
- maximum number of 8228 MAU's = 12
- maximum patch cable distance between an 8228 MAU and a station (not including 8' adapter cable) = 150 feet (45 meters)
- maximum patch cable distance between two 8228's = 150 feet (45 meters)
- maximum patch cable connecting all 8228's = 400 feet (120 meters)

Rules

- stations are connected into the jacks of the 8228 units
- patch cables interconnect RO to RI for 8228 units.
- The last RO is connected to the first RI to form a ring.

Cable

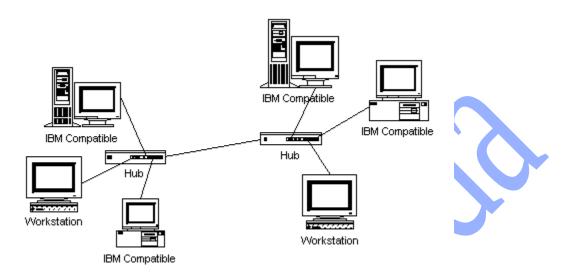
- patch cables generally type 6 (26 awg) or 1 (22 awg)
- type 1 for lengths > 66 feet (20 meters)
- IBM 8310574 MIC connectors
- alternatively, UTP with RJ45 connectors

Ring Topology: Summary

Advantages	Disadvantages
Cable failures affect limited users	Costly Wiring
Equal access for all users	DifficultConnections
Each workstation has full access speed to the ring	Expensive Adaptor Cards
As workstation numbers increase performance diminishes slightly	

Star Topology

- all wiring is done from a central point (the server or hub)
- has the greatest cable lengths of any topology (and thus uses the most amount of cable)
- generally STP or UTP, four wire

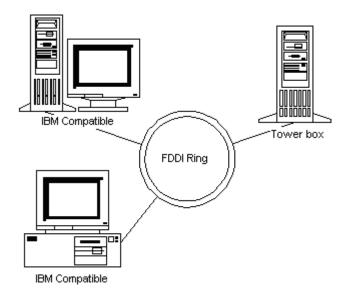


▲ Star Topology: Summary

Advantages	Disadvantages
HEACA TO AUU HEM MALKETATIONS	Hub failure cripples all workstations connected to that hub
Centralized control	Hubs are slighty more expensive than thin-Ethernet
Centralized network/hub monitoring	

FDDI Topology

- 100mbps
- normally implemented over fiber optic (fast-Ethernet, UTP)
- dual redundancy built in by use of primary and secondary ring
- automatic bypassing and isolation of faulty nodes



Fiber Distributed Data Interface

FDDI is based on two counter rotating 100-Mbit/sec token-passing rings. The rings consist of point to point wiring between nodes which repeat the data as it is received.

The primary ring is used for data transmission; the secondary is used for data transmission or to back up the primary ring in the event of a link or station failure. FDDI supports a sustained transfer rate of about 80Mbps, a maximum of 1000 connections (500 nodes) and a total distance of 200 kilometers end to end. There is a maximum distance of 2 kilometers between active nodes.

FDDI Station Types

There are two main types of stations, class A which attach directly to dual rings; or class B which attach to a station acting as a concentrator.

A concentrator is a specialized workstation that attaches to the ring and has multiple ports that allow attachment of other devices in a physical star configuration. These may be cascaded.

Logical Networks versus Physical Networks

A logical network describes how the network operates. A physical network describes how the network has been cabled. It is thus possible to have a physical star, logical bus network. In other words, the network operates as a bus network, but the cabling has been implemented using star topology.

