



# EE 3101

## Digital Signal Processing

BS Electronic Systems programme

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*September – December 2024*

*September 16, 2024*



EE 3101Digital Signal ProcessingEE 3101Session 4

Session 4

Outline

Last session

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Week 1-2

- ✓ Introduction to sampling - Review of Signals and Systems; Basic operations on signals
- ✓ - Discrete time complex exponentials and other basic signals – system properties (linearity, time-invariance, memory, causality, BIBO stability) -- impulse response and convolution

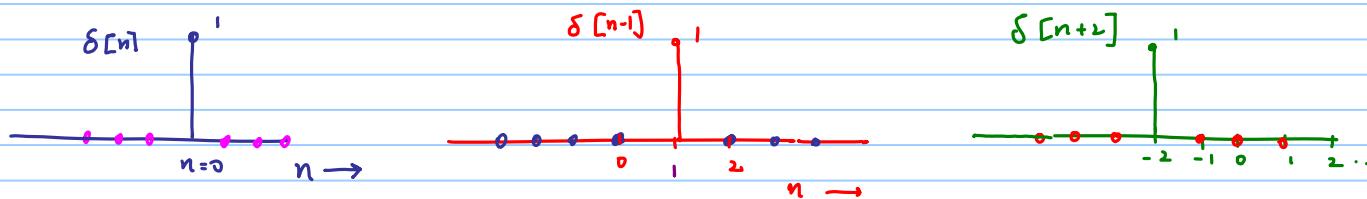
Reading Assignment

Oppenheim &amp; Schafer : Sec 2.0 - 2.3

Rawat

: Chapter 1

Unit sample



### Sequences

- \* Finite length, Infinite Length
- \* Causal, right-sided
- \* Anticausal, Left-sided
- \* Non-causal
- \* Length of finite length sequence  $N = N_2 - N_1 + 1$   $x[n]$  non-zero in the range  $[N_1, N_2]$

$$x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n-k]$$

Gen representation of  
any DT sequence  $x[n]$

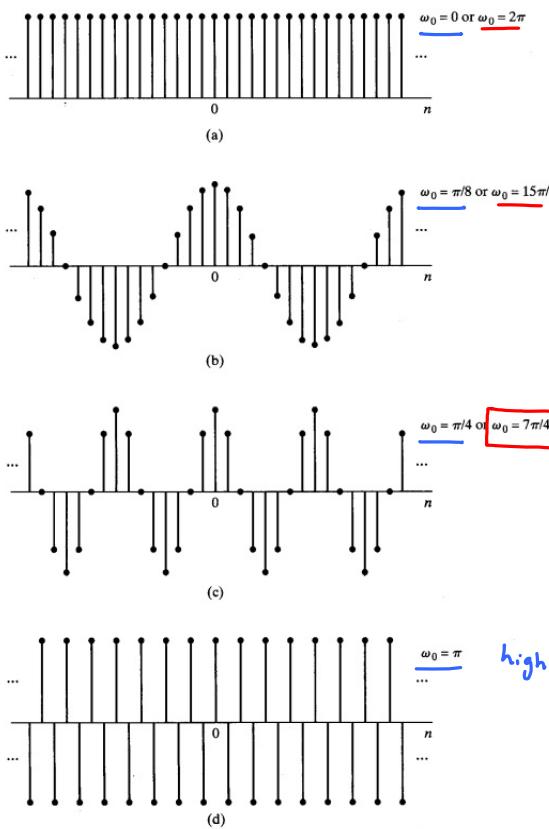
### DT Sinusoids

$$A \cos(\omega_0 n + \phi) = A \cos(\omega_0 n + 2\pi k n + \phi) = A \cos(\omega_0 n + \phi)$$

Periodicity in frequency for DT sinusoids with period =  $2\pi$

## Illustration

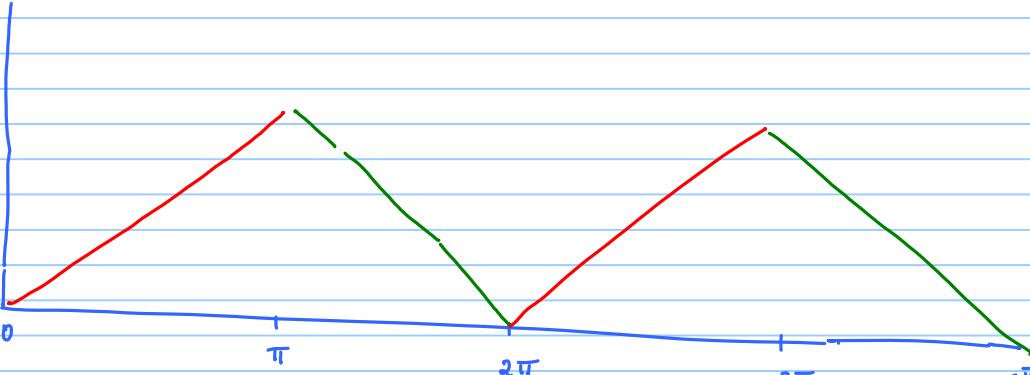
### DT sinusoids



Low freq

$$A \cos(\omega_0 n + \phi)$$

Rate of  
oscillation



high freq

$$A \cos(\omega_0 n + \phi)$$

$$\omega_0 = \pi$$

Observation #1 \*\*\*

DT sinusoids are periodic in frequency  
Period =  $2\pi$  or any multiple of  $2\pi$

### Time behaviour

$$CT \rightarrow \text{all sinusoids are periodic} \quad T = \frac{2\pi}{\omega_0}$$

$$DT \quad A \cos(\omega_0 n + \phi)$$

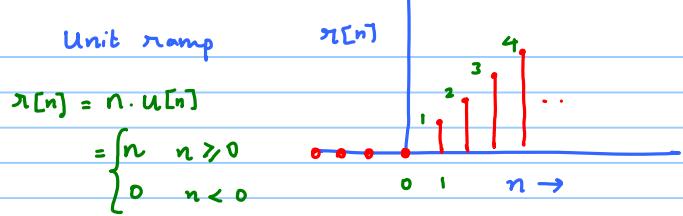
$$\text{If periodic with period } N \Rightarrow A \cos(\omega_0(n + KN) + \phi) = A \cos(\omega_0 n + \phi)$$
$$x[n + KN] = x[n] \quad \forall n$$

A DT sinusoid is periodic if

$$\boxed{\frac{2\pi}{\omega_0} = \frac{N}{m}}$$

Rational function  
 $N, m$  are integers

$N = \text{period of periodic seq}$

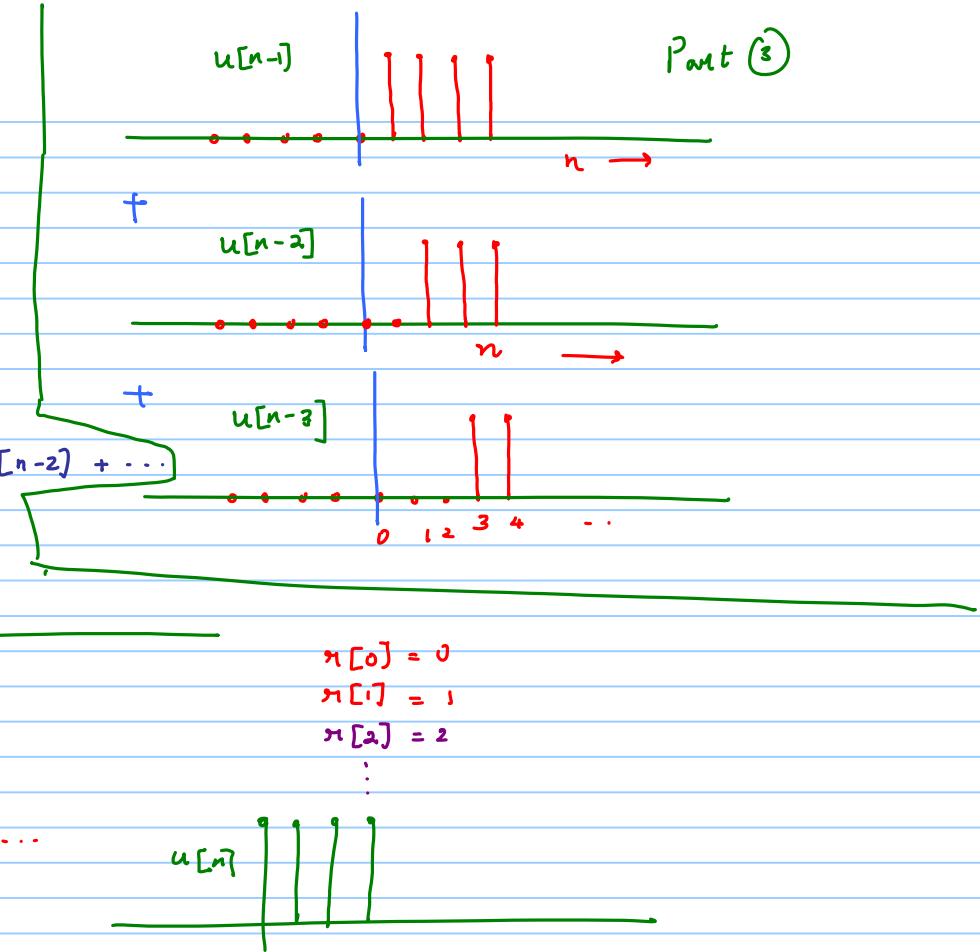


Show That

$$\textcircled{1} \quad r[n] = \sum_{k=0}^{\infty} k \delta[n-k] = 0 \cdot S[n] + 1 \cdot \delta[n-1] + 2 \delta[n-2] + \dots$$

$$\textcircled{2} \quad r[n] = \sum_{k=-\infty}^{n-1} u[k]$$

$$\textcircled{3} \quad r[n] = \sum_{m=1}^{\infty} u[n-m] = u[n-1] + u[n-2] + u[n-3] + \dots$$



### DT Sequence $x[n]$

Real valued

$\text{I}_b$	$x[n] = x[-n]$	even sequence
	$x[n] = -x[-n]$	odd sequence

Complex valued sequences

$$x[n] = x^*[ -n ] \quad \text{Conjugate symm}$$

$$x[n] = -x^*[ -n ] \quad \text{Conjugate antisymm}$$

Periodic signal

$$x[n] = x[n+N] \quad \forall n \quad \textcircled{1}$$

$$\ast \quad x[n] = x[n+2N]$$

\* Period of a periodic seq is the smallest integer satisfying  $\textcircled{1}$

$$x[n] = x_e[n] + x_o[n]$$

$$x_e[n] = \frac{1}{2} [x[n] + x[-n]]$$

$$x_o[n] = \frac{1}{2} [x[n] - x[-n]]$$

$$x_{cs}[n] = \frac{1}{2} [x[n] + x^*[-n]]$$

$$x_{ca}[n] = \frac{1}{2} [x[n] - x^*[-n]]$$

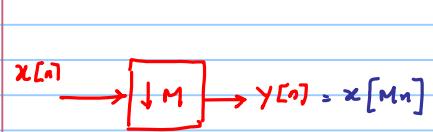
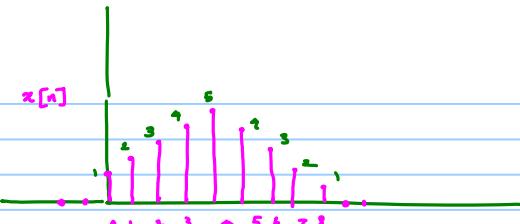
$$x[n] = x_{cs}[n] + x_{ca}[n]$$

### Time Scaling

$$x[n] = \{0, 0, \dots, 0, 1, 2, 3, 4, 5, 4, 3, 2, 1, 0, 0, \dots\}$$

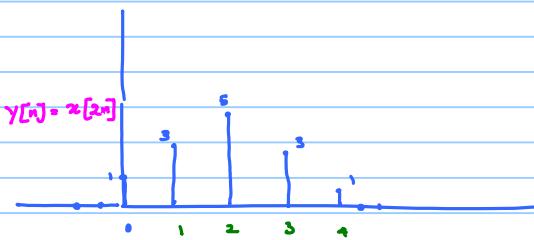
↑

$$y[n] = x[Mn]$$



M integer

Compression  
Down-sampling



Expansion or Upsampling  $\rightarrow \boxed{\uparrow 2} \rightarrow$

$$y[n] = \begin{cases} x\left[\frac{n}{2}\right] & \text{if } n = 0, \pm 2, \pm 4, \dots \\ 0 & \text{otherwise} \end{cases}$$

$$y[0] = x[0]$$

$$y[1] = 0$$

$$y[2] = x[1]$$

$$y[3] = 0$$

$$y[4] = x[2]$$

:

$$y[n] = \begin{cases} x\left[\frac{n}{N}\right] & \text{if } n = 0, \pm N, \pm 2N, \dots \\ 0 & \text{otherwise} \end{cases}$$

insertion of  $(N-1)$  zeros between every  
pair of samples

$$x[n] = \{ 0, 0, 0, 1, 2, 3, 4, 5, 4, 3, 2, 1, 0 \dots \}$$

$$y[n] = \{ \dots 0, 0, 0, 0, 1, 0, 2, 0, 3, 0, 4, 0, 5, 0, 4, 0, 3, 0, 2, 0, 1, 0 \dots \}$$

$$y_1[n] = \begin{cases} x\left[\frac{n}{3}\right] & \text{if } n = 0, \pm 3, \pm 6, \dots \\ 0 & \text{otherwise} \end{cases}$$

$$y_1[n] \{ \dots 0 0 1 0 0 2 0 0 3 \dots \}$$

$$x[n] \rightarrow \boxed{\downarrow M} \rightarrow x[Mn]$$

$$x[n] \rightarrow \boxed{\uparrow N} \rightarrow \begin{cases} x\left[\frac{n}{N}\right] & \text{if } n=0, \pm N, \pm 2N, \dots \\ 0 & \text{otherwise} \end{cases}$$

$$y[n] = x\left[\frac{M}{N}n\right]$$

- ① Upsampling  
② Downsampling

$$\underline{\text{HW}} \quad y[n] = x\left[-\frac{M}{N}n - n_0\right]$$

① Shift  
② Upsampling  
③ downsample

$$x_1[n] = x[n - n_0]$$

$$x_2[n] = \begin{cases} x_1\left[\frac{n}{N}\right] & \text{if } n=0, \pm N, \pm 2N, \dots \\ 0 & \text{otherwise} \end{cases}$$

$$x_3[n] = x_2[Mn] = \begin{cases} x_1\left[\frac{Mn}{N}\right] & \text{if } n=0, \pm N, \pm 2N, \dots \\ 0 & \text{otherwise} \end{cases}$$

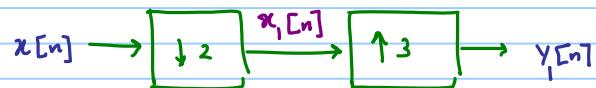
$$y[n] = x_3[-n] = x_2[-Mn] = \begin{cases} x_1\left[\frac{-Mn}{N}\right] & \text{if } n=0, \pm N, \dots \\ 0 & \text{otherwise} \end{cases}$$

$$= x\left[-\frac{Mn}{N} - n_0\right] \quad \begin{matrix} \text{if } n=0, \pm N, \dots \\ \text{otherwise} \end{matrix}$$

Shift  
time scaling  
Time reversal

### Example

$$1. \quad x[n] = \{ 1, 3, 4, -2, 5 \}$$



$$x_1[n] = \{ 0, 0, 1, 4, 5, 0 \dots \}$$



$$y_1[n] = \{ 0, 0, 0, 1, 0, 0, 4, 0, 0, 5, 0, 0 \dots \}$$

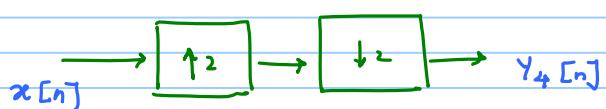
$$x_2[n] = \{ 0, 0, 1, 0, 0, 3, 0, 0, 4, 0, 0, -2, 0, 0, 5, 0, 0 \dots \}$$

$$y_2[n] = \{ 0, 1, 0, 0, 4, 0, 0, 0, 5, 0 \dots \}$$

$$y_2[n] = y_1[n]$$



$$y_3[n] = \{ 0, 1, 0, 4, 0, 5, 0 \dots \}$$



$$y_4[n] = \{ 0, 1, 3, 4, -2, 5, 0 \dots \}$$

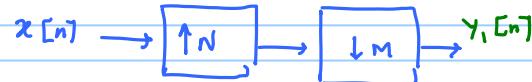
$$y_3[n] = x[n]$$

$$y_3[n] \neq y_4[n]$$

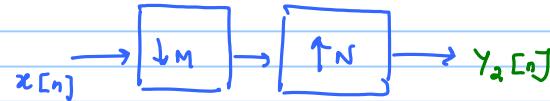
Important Results



$$y_1[n] = y_2[n]$$



if and only if  $N$  &  $M$  are relatively prime



$$\neq x[n] \rightarrow \boxed{\downarrow N} \rightarrow \boxed{\uparrow N} \rightarrow y_4[n]$$

$$y_3[n] \neq y_4[n]$$

### Example 2

$x_1[n]$  is periodic with period  $N_1$   
 $x_2[n]$  " period  $N_2$

Is  $x_1[n]x_2[n]$  periodic?

If periodic with period  $= N$

$$x[n] = x_1[n]x_2[n]$$

$$x[n+N] = \underbrace{x_1[n+N]}_{x_1[n]} \underbrace{x_2[n+N]}_{x_2[n]} = x[n]$$

$$N = pN_1$$

$$N = qN_2$$

### Application

$$N_1 = 90$$

$$N_2 = 54$$

$$\frac{N_1}{N_2} = \frac{90}{54} = \frac{5}{3}$$

$$N = pN_1 = 270$$

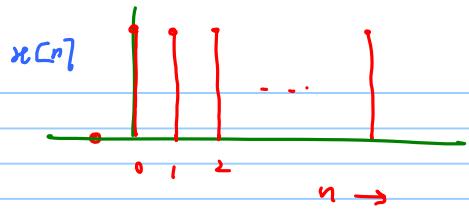
$$qN_2 = 270$$

$$\frac{N_1}{N_2} = \frac{q}{p}$$

$$\text{Period} = N = pN_1 = qN_2$$

$$x[n+N] = x_1[n+pN_1] x_2[n+qN_2]$$

① Is  $u[n]$  periodic?



$$x[n+N] \stackrel{?}{=} u[n]$$

$N=1$

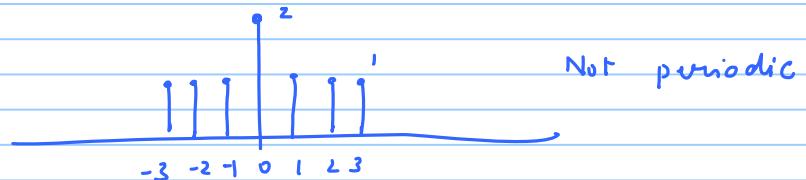
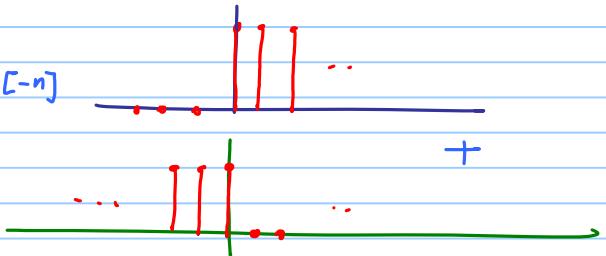
$$n=0 \quad x[0+1] = x[0] \quad \checkmark$$

$$n=1 \quad x[1+1] = x[1] \quad \checkmark$$

$$n=-2 \quad x[-1] = x[-2] \quad \checkmark$$

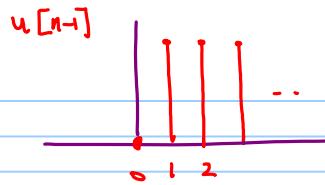
$$n=-1 \quad x[0] = x[-1] \quad \times$$

②  $x_1[n] = u[n] + u[-n]$



Not periodic

$$x_2[n] = u[n] + u[-n-1]$$

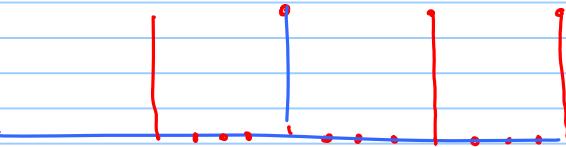


periodic seq

Period N=1

$$x_2[n] = x_2[n+1] \quad \forall n$$

$$\textcircled{3} \quad x_3[n] = \sum_{k=-\infty}^{\infty} \delta[n-4k] = \delta[n] + \delta[n-4] + \delta[n-8] + \dots + \delta[n+4] + \delta[n+8] + \dots$$



periodic = Yes.

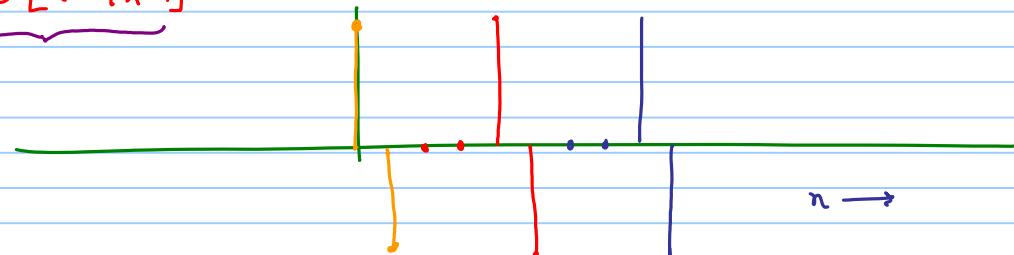
Period N=4.

$$x_4[n] = \sum_{k=-\infty}^{\infty} \delta[n-4k] - \underbrace{\delta[n-4k-1]}_{\text{Periodic Period=4}}$$

$$N = pN_1 = qN_2$$

$$N = \text{LCM}(N_1, N_2)$$

→ periodic, period =  $N = 4$



Even & Odd signals

$$x_1[n] = x_1[-n] \text{ even}$$

$$x_1[n] = -x_1[-n] \text{ odd}$$

Given

$x_1[n]$  odd signal  
 $x_2[n]$  even signal

$$x[n] = x_1[n] x_2[n]$$

$$x[-n] = \underbrace{x_1[-n]}_{-x_1[n]} \underbrace{x_2[-n]}_{x_2[n]}$$

$$x[-n] = -x_1[n] x_2[n]$$

$$x[-n] = -x[n]$$

$x[n]$  is odd

$x_1[n]$  even  
 $x_2[n]$  even

$x_1[n] x_2[n]$  even

$x_1[n]$  odd  
 $x_2[n]$  odd

$x_1[n] x_2[n]$  even

If  $x[n]$  is odd

$$x[n] = -x[-n]$$

$$\sum_{n=0}^{\infty} x[n] = -\sum_{n=-\infty}^{-1} x[n] + x[0] + \sum_{n=1}^{\infty} x[n]$$

$$\dots + x[-2] + \cancel{x[-1]} + x[-1]$$

$$x[1] + \cancel{x[2]} + \cancel{x[3]} + \dots$$

$$= 0$$

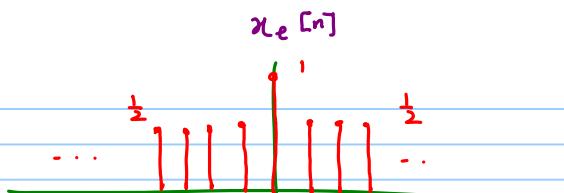
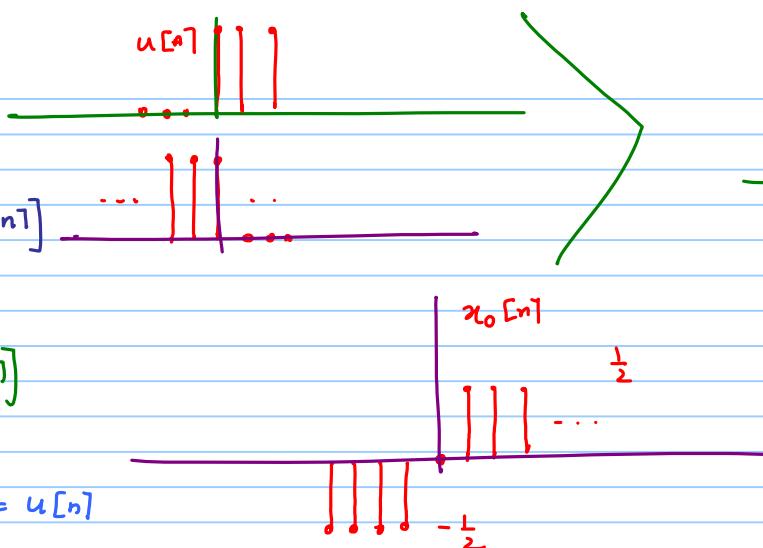
Example

$$x[n] = u[n]$$

$$x_e[n] = \frac{1}{2}[u[n] + u[-n]]$$

$$x_o[n] = \frac{1}{2}[u[n] - u[-n]]$$

✓  $x_e[n] + x_o[n] = x[n] = u[n]$



Example

$$x[n] = \{ 4, -2, 4, -6 \}$$

$$x_e[n] = \{ 2, -4, 4, -4, 2 \}$$

$$x_o[n] = \{ 2, 2, 0, -2, -2 \}$$

$$\underline{\text{Ex}} \quad x[n] = [0, 1+j4, -2+j3, 2-j4, -6-j5, 7, -j3]$$

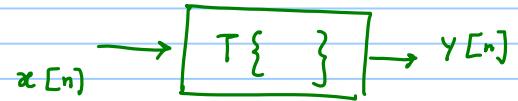
Verify

$$x_{cs}[n] = \frac{1}{2} [x[n] + x^*[-n]] = [j1.5 \quad 4+j2 \quad -4+j4 \quad 2 \quad -4-j4 \quad 4-j2 \quad -j1.5]$$

$$x_{ca}[n] = \frac{1}{2} [x[n] - x^*[-n]] = [-j1.5 \quad -3+j2 \quad 2-j \quad -j4 \quad -2-j \quad 3+j2 \quad -j1.5]$$

$$x[n] = x_{cs}[n] + x_{ca}[n]$$

DT System



Properties of DT Systems

1. Memoryless property

Output  $y[n]$  at every value of  $n$  depends only on the input  $x[n]$  at the same value of  $n$

## Linearity

Systems that satisfy principle of superposition

scaling

additivity

$$T\{x_1[n]\} = y_1[n]$$

$$x_1[n] \xrightarrow{T} y_1[n]$$

$$T\{x_2[n]\} = y_2[n]$$

Scaling  $T\{ax_1[n]\} = ay_1[n]$  homogeneity

Additivity  $T\{x_1[n] + x_2[n]\} = y_1[n] + y_2[n]$

DT System is **linear** if

$$T\{ax_1[n] + bx_2[n]\} = \underbrace{ay_1[n] + by_2[n]}_{\text{additivity}}$$

scaling

additivity

$$\boxed{\begin{array}{l} T\{ \} \\ x_1[n] \xrightarrow{T} y_1[n] \\ x_2[n] \xrightarrow{T} y_2[n] \end{array}}$$

Example

$$y[n] = 2x[n]$$

$$x_1[n] \longrightarrow y_1[n] = 2x_1[n]$$

$$x_2[n] \longrightarrow y_2[n] = 2x_2[n]$$

$$\alpha x_1[n] \longrightarrow y[n] = 2\alpha x_1[n] = \alpha y_1[n] \quad \text{Scaling ✓}$$

$$x_1[n] + x_2[n] \longrightarrow y[n] = 2(x_1[n] + x_2[n])$$

$$= 2x_1[n] + 2x_2[n]$$

$$= y_1[n] + y_2[n]$$

Verify

$$\alpha x_1[n] + \beta x_2[n] \xrightarrow{T\{\cdot\}} \alpha y_1[n] + \beta y_2[n]$$

Yes

Linear

$y[n] = 2x[n]$  straight line, slope 2  
passing through the origin

Input is 0, then output must be zero

$$y[n] = 2x[n] - 3$$

Linear

$$\text{I}_b \quad x[n]=0, \quad y[n]=-3$$

$$x_1[n] \longrightarrow y_1[n] = 2x_1[n] - 3$$

$$x_2[n] \longrightarrow y_2[n] = 2x_2[n] - 3$$

$$\alpha x_1[n] \longrightarrow y[n] = 2\cancel{\alpha} x_1[n] - 3 \quad \cancel{x}$$

$$\alpha y_1[n] = 2\cancel{\alpha} x_1[n] - 3\cancel{\alpha}$$

Scaling not satisfied  $\Rightarrow$  not linear

$$x_1[n] + x_2[n] \longrightarrow y[n] = 2(x_1[n] + x_2[n]) - 3 = 2\cancel{x_1[n]} + 2\cancel{x_2[n]} - 3 \quad \cancel{x}$$

$$y_1[n] + y_2[n] = (2x_1[n] - 3) + (2x_2[n] - 3) = 2\cancel{x_1[n]} + 2\cancel{x_2[n]} - 6 \quad \cancel{x}$$

Additivity not  
satisfied  
 $\Rightarrow$  Not linear

Example

Check the following DT for linearity

$$1. \quad y[n] = n x[n]$$

$$2. \quad y[n] = x^2[n]$$

$$3. \quad y[n] = \operatorname{Re}\{x[n]\}$$

$$4. \quad y[n] = x[n] x[n-1]$$

## Time Invariance

$$T\{x[n]\} \rightarrow y_1[n]$$

$$T\{x[n-n_0]\} \rightarrow y[n-n_0]$$

System is Time Invariant

### Example

$$y[n] = \sin(x[n])$$

Linear  $x$

$$x[n-n_0] \rightarrow y_1[n] = \sin(x[n-n_0])$$

$$y[n-n_0] = \sin(x[n-n_0]) = y_1[n]$$

Time/shift invariant

### Exercise

①  $y[n] = x[-n]$

②  $y[n] = ax[n]$

③  $y[n] = n x[n]$

④  $y[n] = x[2n]$

LTI

Linearity & Time Invariance

≡ Impulse Response

$$T\{a x_1[n] + b x_2[n]\} = a y_1[n] + b y_2[n]$$

$$T\{x_i[n-n_0]\} = y_i[n-n_0]$$

I  $x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n-k]$  ①  
unit impulses shifted in time

II  $y[n] = T\{x[n]\}$

From ①

$$y[n] = T\left\{ \sum_{k=-\infty}^{\infty} x[k] \delta[n-k] \right\}$$

superposition

$$= \sum_{k=-\infty}^{\infty} T\left\{ x[k] \delta[n-k] \right\}$$

scale factor

$$= \sum_{k=-\infty}^{\infty} x[k] T\left\{ \delta[n-k] \right\}$$

Shift invariance

$$= \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

$h[k+n]$

$T[\delta[n]] = h[n]$

unit impulse      impulse response

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] \underbrace{h[n-k]}_{\substack{\text{shift} \\ \text{Time reversal}}}$$

$$h[n] = T\{\delta[n]\} \quad \text{unit sample response}$$

### Computing the Output

- ① Obtain  $h[n]$  unit sample response
- ② Time reversal  $h[n]$
- ③ Shift the time-reversed seq

→ at each shift, obtain one output point

DT  
Convolution

$$y[n] = x[n] * h[n]$$

CT LTI characterized impulse response  $h(t)$

$$y(t) = x(t) * h(t)$$

Computed via integral

$$\int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$= h[n] * x[n]$$

DT LTI system DT impulse resp  $h[n]$

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

Ex LTI systems  $\Rightarrow$  impulse response

$$h[n] = a^n u[n]$$

$$0 < a < 1$$

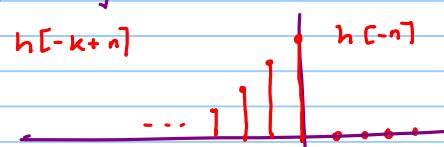
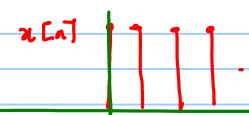
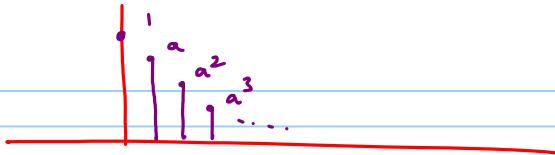
$$x[n] = u[n]$$

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

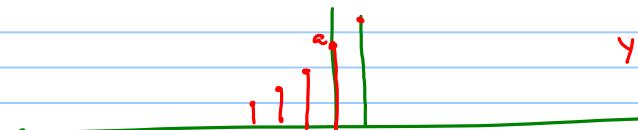
$$y[0] = \sum_{k=-\infty}^{\infty} x[k] h[-k]$$

$$= 1$$

$$y[1] = \sum_{k=-\infty}^{\infty} x[k] h[-k+1]$$



$$y[0] = 1$$



$$y[1] = 1 + a$$

$$y[2] = 1 + a + a^2$$

$$y[n] = 1 + a + a^2 + \dots + a^n u[n]$$

$$y[n] = \frac{1-a^{n+1}}{1-a} u[n]$$

$$y[-1] = 0$$

$$y[-2] = 0$$

⋮

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

$$n - k = l$$

$$y[n] = \sum_{l=-\infty}^{\infty} x[n-l] h[l]$$

$$y[n] = x[n] * h[n] = h[n] * x[n]$$

Flip  $x[n]$

Keep  $h[n]$  without flipping



$y[n]$  same as before

$$y[0] = 1$$

$$y[1] = 1 + \alpha$$

$$y[2] = 1 + \alpha + \alpha^2$$

.

### Causality

A DT system  $y[n] = T\{x[n]\}$  is causal if for every choice of  $n_0$ ,  
the output  $\text{e.g., } y[n_0]$  depends only on the input  $\text{e.g., values}$

$$x[n_0], x[n_0-1], x[n_0-2] \dots$$

$y[n]$  depends on  $x[n] \quad n \leq n_0$

Ex  
Averaging  
Filter

$$y[n] = \frac{1}{3} [x[n-1] + x[n] + x[n+1]]$$

Not causal

Linear?  $\swarrow$  scaling ✓  $\searrow$  additivity ✓  $\Rightarrow$  LTI  $\Rightarrow$  impulse response  
Time invariant ✓

$$y[n] = \sum_{k=-\infty}^{\infty} h[k] x[n-k] = h[0] x[n] + h[1] x[n-1] + h[-1] x[n+1]$$

$$h[n] = \left\{ \frac{1}{3}, \frac{1}{3}, \frac{1}{3} \right\}$$

↑

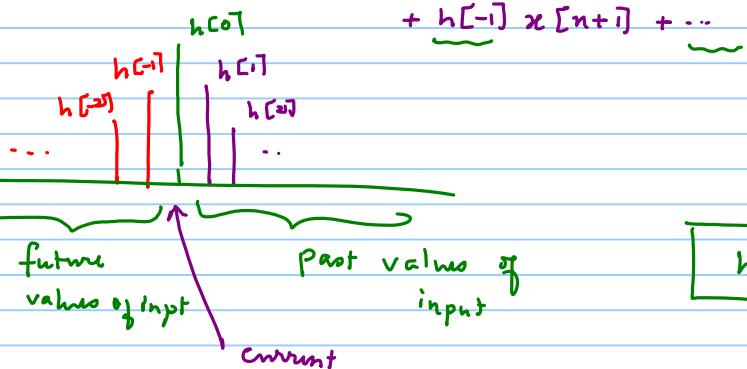
## Gen Averaging Filter

$$(\text{Moving Average Filter}) = y[n] = \frac{1}{N} \sum_{k=-M_1}^{M_2} x[n-k]$$

$$\sum_{k=-\infty}^{\infty} h[k] x[n-k] = h[0] x[n] + h[1] x[n-1] + \dots + h[-1] x[n+1] + \dots$$

$$h[M_2] x[n-M_2]$$

$$h[-M_1] x[n+M_1]$$



$$h[n] = 0 \quad n < 0$$

Causal seq,

Non Causal

Convert to a causal filter

$$h[n] = \frac{1}{N} \left\{ 0 \dots 0 \underset{-M_1}{|} 1 \dots 1 \underset{M_2}{|} 1 \dots 1 \dots 1 \right\}$$

$$y[n] = \frac{1}{M_2+1} \sum_{k=0}^{M_2} x[n-k] \quad \text{Causal version}$$