

Some Formulas

- **Line Equations:** The equation of the line segment connecting \mathbf{r}_0 and \mathbf{r}_1 :

$$\mathbf{r}(t) = (1 - t)\mathbf{r}_0 + t\mathbf{r}_1 \quad 0 \leq t \leq 1$$

The equation of the line containing \mathbf{r}_0 in the direction \mathbf{v} :

$$\mathbf{r}(t) = \mathbf{r}_0 + t\mathbf{v} \quad -\infty < t < \infty$$

- **Plane Equations:** The equation of the plane with normal vector \mathbf{n} and containing \mathbf{r}_0 :

$$\mathbf{n} \cdot (\mathbf{r} - \mathbf{r}_0) = 0$$

The equation of the plane in scalar form, when $\mathbf{n} = \langle a, b, c \rangle$ and $\mathbf{r} = \langle x, y, z \rangle$:

$$ax + by + cz + d = 0 \quad d \text{ constant.}$$

- **Arc Length Integrals:** The length of the curve C given by $\mathbf{r}(t)$ for $a \leq t \leq b$:

$$\int_a^b |\mathbf{r}'(t)| \, dt$$

An integral of a function f with respect to arc length on C is :

$$\int_a^b f(\mathbf{r}(t)) |\mathbf{r}'(t)| \, dt = \int_a^b f(x(t), y(t), z(t)) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} \, dt$$

where $\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$.

- **Tangent Planes to Surfaces:** If a surface S is of the form $z = g(x, y)$, the tangent plane at $P(x_0, y_0, z_0)$ is:

$$z - z_0 = g_x(x_0, y_0)(x - x_0) + g_y(x_0, y_0)(y - y_0).$$

If S is a level surface $f(x, y, z) = k$, the tangent plane at $\mathbf{r}_0 = \langle x_0, y_0, z_0 \rangle$ has normal vector ∇f , so the equation is:

$$f_x(x_0, y_0, z_0)(x - x_0) + f_y(x_0, y_0, z_0)(y - y_0) + f_z(x_0, y_0, z_0)(z - z_0) = 0, \quad \text{or} \quad \nabla f \cdot (\mathbf{r} - \mathbf{r}_0) = 0.$$

If S is parameterized in vector form by $\mathbf{r}(u, v)$, the tangent plane at $\mathbf{r}_0 = \mathbf{r}(u_0, v_0)$ has normal vector $\mathbf{r}_u \times \mathbf{r}_v$, so the equation is:

$$(\mathbf{r}_u \times \mathbf{r}_v) \cdot (\mathbf{r} - \mathbf{r}_0)$$

- **Implicit Function Theorem:** If a curve satisfies the equation $F(x, y) = 0$, if F_x and F_y are continuous, and $F_y \neq 0$, then

$$\frac{dy}{dx} = -\frac{F_x}{F_y}.$$

If a surface satisfies $F(x, y, z) = 0$ with F_x, F_y , and F_z continuous with $F_z \neq 0$, then

$$\frac{\partial z}{\partial x} = -\frac{F_x}{F_z} \quad \text{and} \quad \frac{\partial z}{\partial y} = -\frac{F_y}{F_z}$$

- **Cylindrical Coordinates:** Volume differential: $dV = r \, dr \, d\theta \, dz$

$$x = r \cos \theta, \quad y = r \sin \theta, \quad z = z, \quad x^2 + y^2 = r^2, \quad \tan \theta = \frac{y}{x}$$

- **Spherical Coordinates:** Volume differential: $dV = \rho^2 \sin \phi \, d\rho \, d\theta \, d\phi$

$$x = \rho \sin \phi \cos \theta, \quad y = \rho \sin \phi \sin \theta, \quad z = \rho \cos \phi, \quad \rho^2 = x^2 + y^2 + z^2$$

- **Line Integrals:** C a curve parameterized by $\mathbf{r}(t)$, $a \leq t \leq b$. $f(x, y, z)$ a function.

$$\int_C f(x, y, z) \, ds = \int_a^b f(\mathbf{r}(t)) |\mathbf{r}'(t)| \, dt$$

$\mathbf{F} = \langle P, Q, R \rangle$ a vector field:

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) \, dt = \int_C P \, dx + Q \, dy + R \, dz.$$

- **Surface Integrals:** S parameterized by $\mathbf{r}(u, v)$ where $(u, v) \in D$, $f(x, y, z)$ a function.

$$\iint_S f(x, y, z) \, dS = \iint_D f(\mathbf{r}(u, v)) |\mathbf{r}_u \times \mathbf{r}_v| \, dA.$$

\mathbf{F} a vector field:

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D \mathbf{F} \cdot (\mathbf{r}_u \times \mathbf{r}_v) \, dA.$$

- **Fundamental Theorem of Line Integrals:**

$$\int_C (\nabla f) \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$$

where the curve C is the curve given by $\mathbf{r}(t)$ where $a \leq t \leq b$.

- **Green's Theorem:** $\mathbf{F} = \langle P, Q \rangle$ is a 2-dimensional vector field.

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \oint_C P \, dx + Q \, dy = \iint_D (Q_x - P_y) \, dA$$

where C is the positively oriented boundary of the 2-dimensional region D .

- **Stokes' Theorem:** $\mathbf{F} = \langle P, Q, R \rangle$ is a 3-dimensional vector field.

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S \text{curl}(\mathbf{F}) \cdot d\mathbf{S}$$

where C is the positively oriented boundary of the oriented surface S in 3-dimensional space.

- **Divergence Theorem:** $\mathbf{F} = \langle P, Q, R \rangle$ is a vector field.

$$\oiint_S \mathbf{F} \cdot d\mathbf{S} = \iiint_E \text{div}(\mathbf{F}) \, dV$$

where S is the positively oriented boundary of the 3-dimensional region E .