Chord: A Scalable Peerto-peer Lookup Protocol for Internet Applications

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About Chord

- Protocol and algorithm for distributed hash table (DHT)
- Structured-decentralized P2P overlay network

About Chord

- Supports just one operation: lookup(key)
 - Given a key, it maps the key onto a node
 - Returns the IP-address of the node
- Associate a value with each key and store the pair on the resulting node:
 - Distributed hash table
- Uses consistent hashing for this operation

Chord properties (1)

- Load balancing:
 - spreads keys evenly over nodes
- Decentralized:
 - fully distributed, all nodes equally important
 - does not take into account heterogeneity of nodes

Chord properties (2)

- Scalability:
 - lookup cost: O(log(N))
- Availability:
 - automatically updates lookup tables as nodes join, leave, fail
- Flexible naming:
 - Flat key-space, no constraint on structure of keys

Traditional hashing

- Given an object, assign it to a bin from a set of N bins
- Each bin: roughly same amount of objects
- Problem:
 - If N changes, all objects need to be reassigned

Consistent hashing

- Evenly distributes K objects across N bins, about K/N each
- When N changes:
 - Not all objects need to be moved
 - Only O(K/N) need to
- Uses a base hash function, such as SHA-1

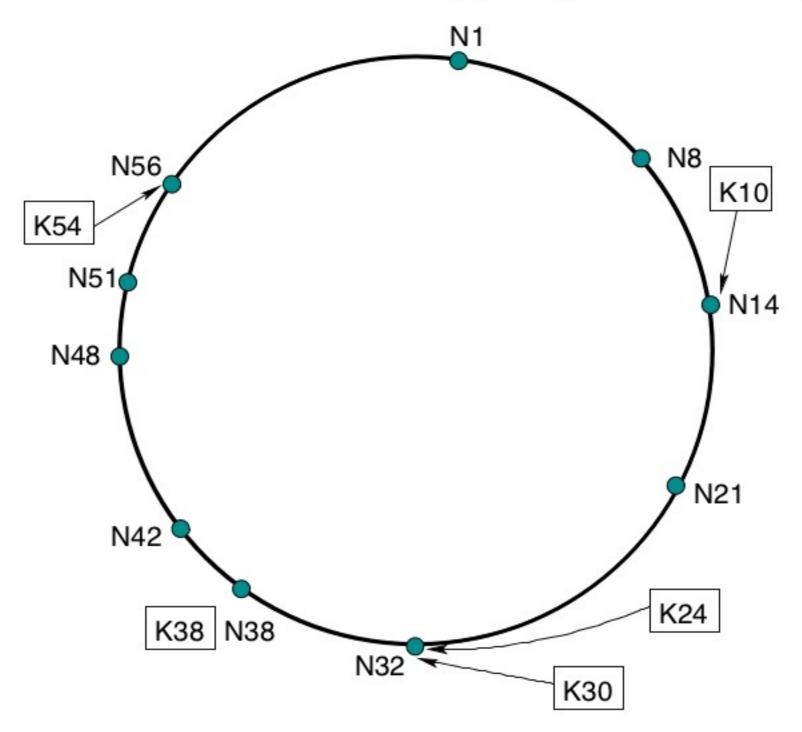
Chord protocol

- Assign each node and key an m-bit identifier using SHA-1:
 - node: hash the IP-address
 - key: hash the key
- Identifiers are ordered on an identifier circle module 2^m, the Chord ring:
 - circle of numbers from 0 to 2^{m-1}

Assigning keys to nodes

- Assigning key k to a node:
 - first node whose identifier is equal to or follows the identifier of key k in the identifier space
 - successor node of k: successor(k)
 - first node clockwise from k on Chord ring

Chord ring (m=6)



Minimal disruption

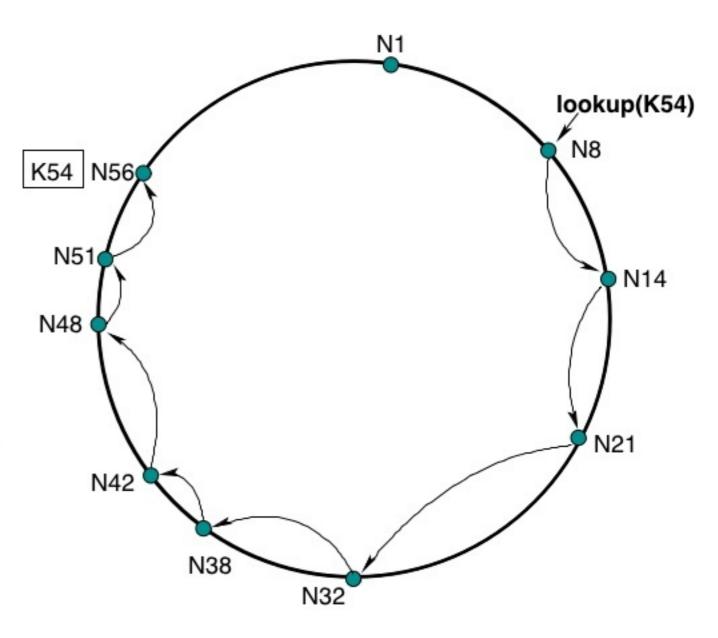
- Minimal disruption when node joins/leaves
- *n* joins:
 - certain keys assigned to successor(n) are now assigned to n
- n leaves:
 - all keys assigned to n are now assigned to successor(n)

Simple Chord lookup

- Simplest Chord lookup algorithm:
 - Each node only needs to know its successor on Chord ring
 - Query for identifier id is passed around Chord ring until successor(id) is found
 - Result returned along reverse path
- Easy but not efficient: # messages O(N)

Simple Chord lookup

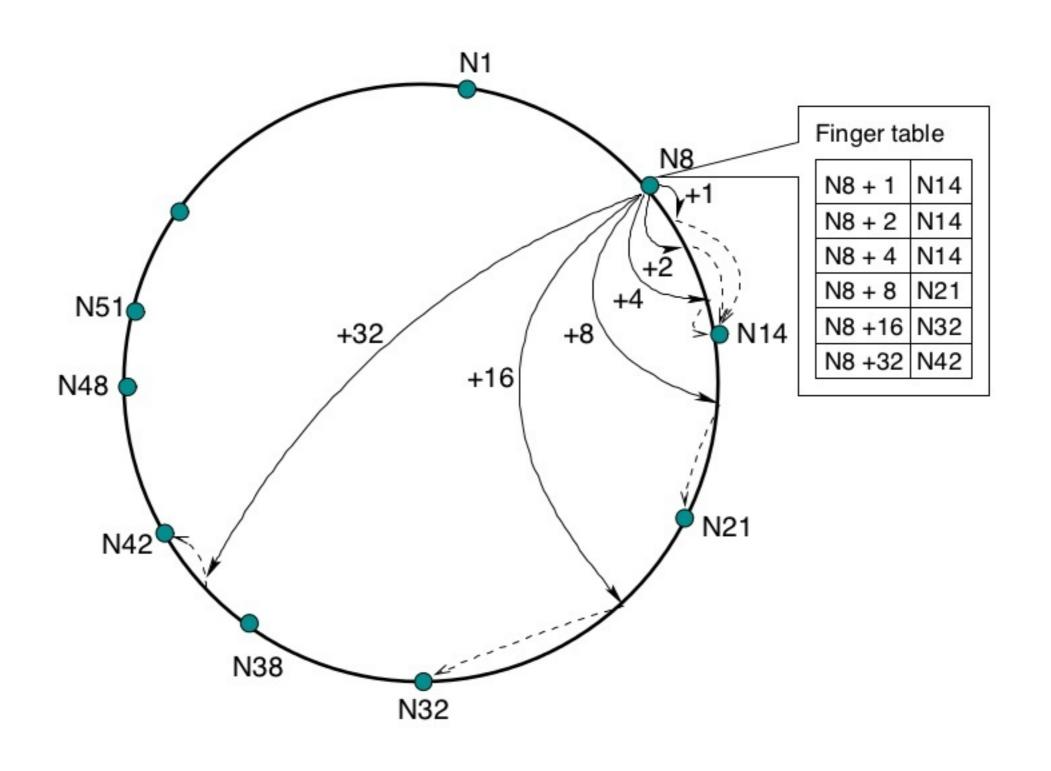
```
// ask node n to find the successor
// of id
n.find_successor(id)
  if (id ∈ (n, successor])
    return successor;
  else
    // forward the query around the
    // circle
    return successor.find_successor(id);
```



Finger table

- Chord maintains additional routing info:
 - not essential for correctness
 - but allows acceleration of lookups
- Each node maintains finger table with m entries:
 - $n.finger[i] = successor(n + 2^{i-1})$

Finger table



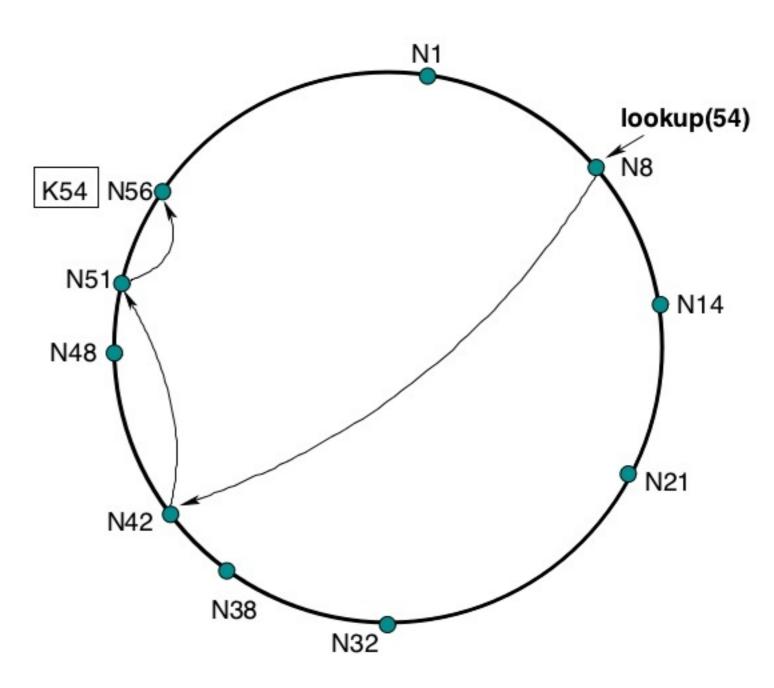
Improved lookup

- Lookup for id now works as follows:
 - If id falls between n and successor(n), successor(n) is returned
 - Otherwise, lookup is performed at node n', which is the node in the finger table of n that most immediately precedes id
- Since each node has finger entries at power of two intervals around the identifier circle, each node can forward a query at least halfway along the remaining distance between the node and the target identifier.
- Thus O(log(N)) nodes need to be contacted

Chord protocol

```
// ask node n to find the successor
// of id
n.find_successor(id)
if (id ∈ (n, successor])
    return successor;
else
    n' = closest_preceding_node(id);
    return n'.find_successor(id);

// search the local table for the
// highest predecessor of id
n.closest_preceding_node(id)
    for i = m downto 1
        if (finger[i] ∈ (n, id))
            return finger[i];
    return n;
```

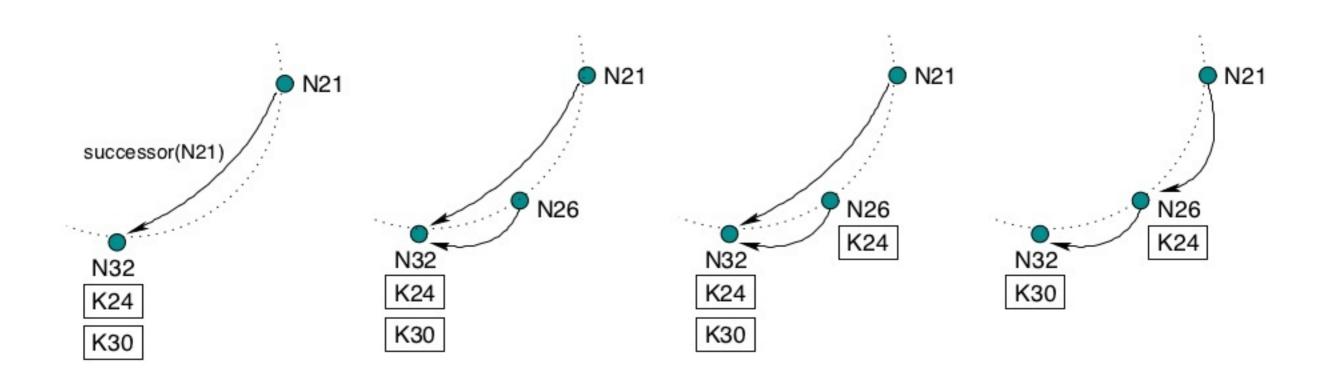


- Essential that successor pointers stay up to date
- Each node periodically runs stabilization protocol which updates Chord's successor pointers and finger tables
- For node n to join, it must know a node n' of the Chord ring

- To join, n performs join()
 - node n asks n' to find_successor(n), which n sets as its sucessor
- Each node periodically performs stabilize() to learn about newly joined nodes
 - n asks his successor s for s' predecessor p
 - decides whether p should be n's successor instead

- stabilize() also notifies n's successor s of n's existence
 - s might change it's predecessor to n
- Each node periodically calls fix_fingers()
 - makes sure fingers are up to date
 - is how new nodes acquire finger table
 - is how old nodes add new nodes to their tables

```
// n' thinks it might be our
//join a Chord ring containing node n'.
                                         // predecessor.
n.join(n')
                                         n.notify(n')
  predecessor = nil;
                                           if (predecessor is nil or
  successor = n'.find successor(n);
                                                    n' ∈ (predecessor, n))
                                             predecessor = n';
// called periodically. verifies n's
// immediate successor, and tells the
// successor about n.
                                         // called periodically. refreshes
n.stabilize()
                                         // finger table entries. next stores
  x = successor.predecessor;
                                         // the index of the next finger to fix.
  if (x \in (n, successor))
                                         n.fix fingers()
    successor = x;
                                           next = next + 1;
  successor.notify(n);
                                           if (next > m)
                                             next = 1;
                                           finger[next] = find_successor(n+2next-1);
```



- Lookup will only fail if successor pointers are not up to date => retry after a pause
- As soon as successor pointers are correct, lookup will work
 - over time, finger tables will be up to date and linear search is no longer needed
- Old finger tables can still be used and in general lookup will remain O(log(N)) even if not all finger tables are up to date

Successor list

- Lookup fails if a node doesn't know its correct successor
 - can occur when nodes fail
- Solution: each node maintains a successor list:
 - contains the node's first r successors
 - if first successor does not respond, try the rest of the list

Replication

- Successor list can also be used for replication
 - application on top of Chord might store replicas of data associated with a key on k nodes from n's successor list
 - Chord can inform application when this successor list changes, so application can create new replicas

Chord in practice

- In practice, Chord ring will never be in stable state:
 - Joins and leaves occur continuously
 - Interleaved by stabilization algorithm
 - Not enough time to stabilize before new change
- If stabilization is run at a certain rate:
 - Chord ring will be continuously "almost stable" and lookup will be fast and correct

Virtual nodes

- Chord load balancing can be improved through virtual nodes:
 - node ids do not uniformly cover entire id space
 - to make (# keys / node) more uniform, associate keys with virtual nodes
 - map r virtual nodes, with unrelated ids, to each real node
- Tradeoff: each real node needs r times as much space to store finger table

Network latency

- Chord path length is O(log(N)), but latency can be quite large
 - Nodes close in id space can be far away in the underlying network
- Idea:
 - choose next-hop finger based on progress in id space and latency in network
 - maximize progress in id space
 - minimize latency

Network latency

- Different approach to improving latency:
 - each entry in finger table can point to list of nodes instead of a single node
 - nodes have similar ids and are equivalent for routing purposes
 - latency of the nodes could be different
 - use closest node in terms of network distance in the underlying network

Applications of Chord

- Chord File System (CFS):
 - Chord locates storage blocks
- Distributed indexes:
 - solves Napster's central server issue
- Large-scale combinatorial search:
 - candidate solutions are keys, Chord maps these to machines which test them
- Cooperative mirroring:
 - Uses Chord to provide load balancing
- Time-shared storage:
 - Uses Chord to provide availability

