# Bayesian nonparametrics in machine learning

Rémi Bardenet 1

<sup>1</sup>CNRS & CRIStAL, Univ. Lille, France





### **Supervised learning with Gaussian Processes**

From linear regression to GPs [2, Chapter 2]

Basic theory: Existence and conditioning for GPs [1, Chapter 4]

Modeling with GPs [2, Chapter 4]

Inferring GPs [2, Chapter 5]

Some more applications

References and open issues

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]

Basic theory: Existence and conditioning for DPs [1, Chapter 2]

Modeling with DPs [1, Chapter 2]

Fitting a DP mixture model [1, Chapter 2]

Some applications

# Supervised learning with Gaussian Processes

From linear regression to GPs [2, Chapter 2]

Basic theory: Existence and conditioning for GPs [1, Chapter 4]

Modeling with GPs [2, Chapter 4]

Inferring GPs [2, Chapter 5

Some more applications

References and open issues

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]

Basic theory: Existence and conditioning for DPs [1, Chapter 2]

Modeling with DPs [1, Chapter 2

Fitting a DP mixture model [1, Chapter 2]

Some applications

### **Supervised learning with Gaussian Processes**

From linear regression to GPs [2, Chapter 2

Basic theory: Existence and conditioning for GPs [1, Chapter 4]

Modeling with GPs [2, Chapter 4]

interring GPS [2, Chapter

Some more applications

References and open issues

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]

Basic theory: Existence and conditioning for DPs [1, Chapter 2]

Modeling with DPs [1, Chapter 2]

Fitting a DP mixture model [1, Chapter 2]

Some applications

# **Supervised learning with Gaussian Processes**

From linear regression to GPs [2, Chapter 2]

Basic theory: Existence and conditioning for GPs [1, Chapter 4]

# Modeling with GPs [2, Chapter 4]

Inferring GPs [2, Chapter 5]

Some more applications

References and open issues

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]

Basic theory: Existence and conditioning for DPs [1, Chapter 2]

Modeling with DPs [1, Chapter 2]

Fitting a DP mixture model [1, Chapter 2]

Some applications

#### Commonly-used kernels

covariance function	expression	S	ND
constant	$\sigma_0^2$		
linear	$egin{array}{l} \sum_{d=1}^D \sigma_d^2 x_d x_d' \ (\mathbf{x} \cdot \mathbf{x}' + \sigma_0^2)^p \end{array}$		
polynomial	$(\mathbf{x} \cdot \mathbf{x}' + \sigma_0^2)^p$		
squared exponential	$\exp(-\frac{r^2}{2\ell^2})$		$\checkmark$
Matérn	$\left  \begin{array}{c} rac{1}{2^{ u-1}\Gamma( u)} \left(rac{\sqrt{2 u}}{\ell}r ight)^ u K_ u \left(rac{\sqrt{2 u}}{\ell}r ight) \end{array}  ight.$		$\checkmark$
exponential	$\exp(-\frac{r}{\ell})$		$\checkmark$
$\gamma$ -exponential	$\exp\left(-\left(\frac{r}{\ell}\right)^{\gamma}\right)$		$\checkmark$
rational quadratic	$\left(1 + \frac{r^2}{2\alpha\ell^2}\right)^{-\alpha}$		$\checkmark$
neural network	$\sin^{-1}\left(\frac{2\tilde{\mathbf{x}}^{\top}\Sigma\tilde{\mathbf{x}}'}{\sqrt{(1+2\tilde{\mathbf{x}}^{\top}\Sigma\tilde{\mathbf{x}})(1+2\tilde{\mathbf{x}}'^{\top}\Sigma\tilde{\mathbf{x}}')}}\right)$		$\checkmark$

Table 4.1: Summary of several commonly-used covariance functions. The covariances are written either as a function of  $\mathbf{x}$  and  $\mathbf{x}'$ , or as a function of  $r = |\mathbf{x} - \mathbf{x}'|$ . Two columns marked 'S' and 'ND' indicate whether the covariance functions are stationary and nondegenerate respectively. Degenerate covariance functions have finite rank, see section 4.3 for more discussion of this issue.

# **Supervised learning with Gaussian Processes**

From linear regression to GPs [2, Chapter 2]

Basic theory: Existence and conditioning for GPs [1, Chapter 4]

Modeling with GPs [2, Chapter 4]

# Inferring GPs [2, Chapter 5]

Some more applications

References and open issues

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]

Basic theory: Existence and conditioning for DPs [1, Chapter 2]

Modeling with DPs [1, Chapter 2]

Fitting a DP mixture model [1, Chapter 2]

Some applications

### **Supervised learning with Gaussian Processes**

From linear regression to GPs [2, Chapter 2

Basic theory: Existence and conditioning for GPs [1, Chapter 4]

Modeling with GPs [2, Chapter 4]

Inferring GPs [2, Chapter 5]

#### Some more applications

References and open issues

### Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]

Basic theory: Existence and conditioning for DPs [1, Chapter 2]

Modeling with DPs [1, Chapter 2]

Fitting a DP mixture model [1, Chapter 2

Some applications

#### **Emulators of expensive models**



RESEARCH ARTICLE

#### Bayesian Sensitivity Analysis of a Cardiac Cell Model Using a Gaussian Process Emulator

Eugene TY Chang<sup>1,2</sup>, Mark Strong<sup>3</sup>, Richard H Clayton<sup>1,2</sup>\*

1 Insigneo Institute for in-silico Medicine, University of Sheffield, Sheffield, United Kingdom, 2 Department of Computer Science University of Sheffield, Sheffield, United Kingdom, 3 School of Health and Related Research, University of Sheffield, Sheffield, United Kingdom

\* r.h.clayton@sheffield.ac.uk



OPEN ACCESS

Citation: Chang ETY, Strong M, Clayton RH (2015)

#### Abstract

Models of electrical activity in cardiac cells have become important research tools as they can provide a quantitative description of detailed and integrative physiology. However, cardiac cell models have many parameters, and how uncertainties in these parameters affect the model output is difficult to assess without undertaking large numbers of model runs. In this study we show that a surrogate statistical model of a cardiac led model (the Luo-Rudy 1991 model) ran be huitt used.

#### Nonparametric fits

# ro-ph.CO] 10 Jul 2012

#### Gaussian Process Cosmography

Arman Shafieloo<sup>1</sup>, Alex G. Kim<sup>2</sup>, Eric V. Linder<sup>1,2,3</sup>
Institute for the Early Universe WCU, Ewha Womans University, Seoul, Korea

<sup>2</sup> Lawrence Berkeley National Laboratory, Berkeley, CA 94720, USA and

<sup>3</sup> University of California, Berkeley, CA 94720, USA

(Dated: July 11, 2012)

Gaussian processes provide a method for extracting cosmological information from observations without assuming a cosmological model. We carry out cosmography — mapping the time evolution of the cosmic expansion —in a model-independent manner using kinematic variables and a geometric probe of cosmology. Using the state of the art supernova distance data from the Union2.1 compilation, we constrain, without any assumptions about dark energy parametrization or matter density, the Hubble parameter as a function of redshift. Extraction of these relations is tested successfully against models with features on various coherence scales, subject to certain statistical cautions.

#### I. INTRODUCTION

Cosmic acceleration is a fundamental mystery of great interest and importance to understanding cosmology, gravitation, and high energy physics. The cosmic expansion rate is slowed down by gravitationally attractive matter and speed up by some other, unknown contribution to the dynamical equations. While great effort is being put into identifying the source of this extra dark energy contribution, the overall expansion behavior also holds important clues to origin, evolution, and present ing procedures have been suggested, e.g. [6], but tend to induce bias in the function reconstruction due to parametric restriction of the behavior or to have poor error control. Using a general orthonormal basis or principal component analysis is another approach, to describe the distance-redshift relation (e.g. [7]) or the deceleration parameter [8], or using a correlated prior for smoothness on the dark energy equation of state [9], but in practice a finite (and small) number of modes is significant beyond the prior, essentially reducing to a parametric approach. Gaussian processes [10] offer an interesting possibility for

#### Natural language processing

# Using Gaussian Processes for Rumour Stance Classification in Social Media

MICHAL LUKASIK, University of Sheffield KALINA BONTCHEVA, University of Sheffield TREVOR COHN, University of Melbourne ARKAITZ ZUBIAGA, University of Warwick MARIA LIAKATA, University of Warwick ROB PROCTER, University of Warwick

Social media tend to be rife with rumours while new reports are released piecemeal during breaking news. Interestingly, once an mine multiple reactions expressed by social media uses in those situations, exploring their stance towards rumours, ultimately enabling the flagging of highly disputed rumours as being potentially false. In this work, we set out to develop an automated, supervised classifier that uses multi-task learning to classify the stance expressed in each individual tweet in a rumourous conversation as either supporting, denying or questioning the rumour. Using a classifier based on Gaussian Processes, and exploring its effectiveness on two datasets with very different characteristics and varying distributions of stances, we show that our approach consistently outperforms competitive baseline classifiers. Our classifier is especially effective in estimating the distribution of different types of stance associated with a given rumour, which we set forth as a desired characteristic for a rumour-tasking system that will warn both ordinary users of Twitter and professional news practitioners when a rumour is being rebutted.

#### 1. INTRODUCTION

There is an increasing need to interpret and act upon rumours spreading quickly through social media during breaking news, where new reports are released piecemeal and often have an unverified

s.CL] 7 Sep 2016

#### Bayesian optimization for hyperparameter tuning

#### **Algorithms for Hyper-Parameter Optimization**

James Bergstra The Rowland Institute Harvard University

bergstra@rowland.harvard.edu

Yoshua Bengio

Dépt. d'Informatique et Recherche Opérationelle Université de Montréal yoshua.bengio@umontreal.ca

Rémi Bardenet

Laboratoire de Recherche en Informatique Université Paris-Sud bardenet@lri.fr

#### Balázs Kégl

Linear Accelerator Laboratory Université Paris-Sud. CNRS balazs.kegl@gmail.com

#### Abstract

Several recent advances to the state of the art in image classification benchmarks have come from better configurations of existing techniques rather than novel approaches to feature learning. Traditionally, hyper-parameter optimization has been the job of humans because they can be very efficient in regimes where only a few

# **Supervised learning with Gaussian Processes**

From linear regression to GPs [2, Chapter 2]
Basic theory: Existence and conditioning for GPs [1, Chapter 4]
Modeling with GPs [2, Chapter 4]
Inferring GPs [2, Chapter 5]
Some more applications

References and open issues

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]

Basic theory: Existence and conditioning for DPs [1, Chapter 2]

Modeling with DPs [1, Chapter 2]

Fitting a DP mixture model [1, Chapter 2]

Some applications

#### References

- ► Textbook by C. Rasmussen and C. Williams [2],
  - great for understanding, methods, pointers to ML and stats.
- ► Similar videolecture by C. Rasmussen.
- ▶ lecture notes by P. Orbanz [1].
  - ▶ mathematically clean, without losing the focus on ML.

#### Some open issues

- Fully Bayesian scalable approaches!
- Natural approaches to constrained GPs.
- Links with other models based on Gaussians and geometry.

# Supervised learning with Gaussian Processes

From linear regression to GPs [2, Chapter 2]
Basic theory: Existence and conditioning for GPs [1, Chapter 4]
Modeling with GPs [2, Chapter 4]
Inferring GPs [2, Chapter 5]

References and open issues

.

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]

Basic theory: Existence and conditioning for DPs [1, Chapter 2]

Modeling with DPs [1, Chapter 2]

Fitting a DP mixture model [1, Chapter 2]

Some applications

#### The Dirichlet distribution

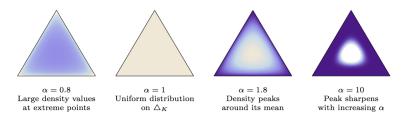


FIGURE A.1. Dirichlet distribution on  $\triangle_3$ , with uniform expectation, for various concentration parameters (dark colors = small density values).

Figure: Taken from [1, Appendix 4]

# Supervised learning with Gaussian Processes

From linear regression to GPs [2, Chapter 2]

Basic theory: Existence and conditioning for GPs [1, Chapter 4]

Modeling with GPs [2, Chapter 4]

Interring GPs [2, Chapter 5

Some more applications

References and open issues

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]

Basic theory: Existence and conditioning for DPs [1, Chapter 2]

Modeling with DPs [1, Chapter 2

Fitting a DP mixture model [1, Chapter 2]

Some applications

# Supervised learning with Gaussian Processes

From linear regression to GPs [2, Chapter 2]

Basic theory: Existence and conditioning for GPs [1, Chapter 4

Modeling with GPs [2, Chapter 4]

Interring GPs [2, Chapter 5

Some more applications

References and open issues

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]

Basic theory: Existence and conditioning for DPs [1, Chapter 2]

# Modeling with DPs [1, Chapter 2]

Fitting a DP mixture model [1, Chapter 2]

Some applications

# Supervised learning with Gaussian Processes

From linear regression to GPs [2, Chapter 2]

Basic theory: Existence and conditioning for GPs [1, Chapter 4]

Modeling with GPs [2, Chapter 4]

Inferring GPs [2, Chapter 5

Some more applications

References and open issues

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]

Basic theory: Existence and conditioning for DPs [1, Chapter 2]

Modeling with DPs [1, Chapter 2

Fitting a DP mixture model [1, Chapter 2]

Some applications

### Supervised learning with Gaussian Processes

From linear regression to GPs [2, Chapter 2]
Basic theory: Existence and conditioning for GPs [1, Chapter 4
Modeling with GPs [2, Chapter 4]
Inferring GPs [2, Chapter 5]
Some more applications
References and open issues

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]
Basic theory: Existence and conditioning for DPs [1, Chapter 2]
Modeling with DPs [1, Chapter 2]
Fitting a DP mixture model [1, Chapter 2]

#### Some applications

#### **Hierarchical Dirichlet Processes**

Yee Whye Teh tehyw@comp.nus.edu.sg
Department of Computer Science, National University of Singapore,
Singapore 117543

Michael I. Jordan jordan@eecs.berkeley.edu
Computer Science Division and Department of Statistics,
University of California at Berkeley, Berkeley CA 94720-1776, USA

Matthew J. Beal mbeal@cse.buffalo.edu
Department of Computer Science & Engineering,
State University of New York at Buffalo, Buffalo NY 14260-2000, USA

David M. Blei blei@eecs.berkeley.edu
Department of Computer Science, Princeton University,
Princeton, NI 08544, USA

November 15, 2005

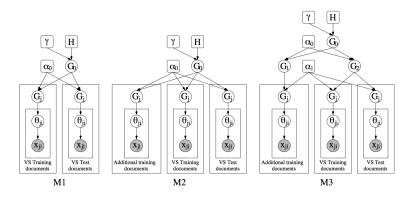


Figure 4: Three models for the NIPS data. From left to right: M1, M2 and M3.

Figure: Taken from [3]

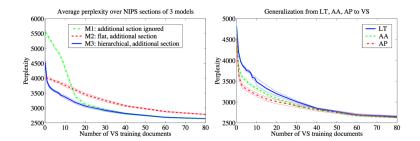
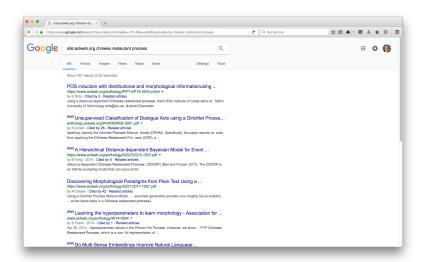


Figure: Taken from [3]

cs	task representation pattern processing trained representations three process unit patterns examples concept similarity bayesian hypotheses generalization numbers positive classes hypothesis		
NS	cells cell activity response neuron visual patterns pattern single fig visual cells cortical orientation receptive contrast spatial cortex stimulus tuning		
LT	signal layer gaussian cells fig nonlinearity nonlinear rate eq cell large examples form point see parameter consider random small optimal		
AA	algorithms test approach methods based point problems form large paper distance tangent image images transformation transformations pattern vectors convolution simard		
IM	processing pattern approach architecture single shows simple based large control motion visual velocity flow target chip eye smooth direction optical		
SP	visual images video language image pixel acoustic delta lowpass flow signals separation signal sources source matrix blind mixing gradient eq		
AP	approach based trained test layer features table classification rate paper image images face similarity pixel visual database matching facial examples		
CN	ii tree pomdp observable strategy class stochastic history strategies density policy optimal reinforcement control action states actions step problems goal		

# DP and CRP are also popular in Natural language processing (NLP)



# Supervised learning with Gaussian Processes

From linear regression to GPs [2, Chapter 2]
Basic theory: Existence and conditioning for GPs [1, Chapter 4
Modeling with GPs [2, Chapter 4]
Inferring GPs [2, Chapter 5]
Some more applications
References and open issues

# Density estimation and clustering with Dirichlet processes

From finite mixture models to DPs [1, Chapter 2]
Basic theory: Existence and conditioning for DPs [1, Chapter 2]
Modeling with DPs [1, Chapter 2]
Fitting a DP mixture model [1, Chapter 2]
Some applications

#### References

- ▶ My primary source is P Orbanz' 2014 BNP lecture notes again, with a great overview of relevant theory.
- ► Chapters 1, 2, 5, 6 of the 2010 book edited by N. Hjort et al.
  - This book is a collection of dense independent chapters and not really a textbook, more of a state-of-the-art with a lot of pointers. There is ample material for those who want to read further on BNP.
- ▶ There is an upcoming book by YW Teh and M Jordan that should become the reference ML textbook that [2] is to GPs, keep an eye open!
  - Meanwhile, check out recent videolectures by the authors YW Teh and M Jordan.

#### Some open issues

- Lots of potential applications in other fields such as signal processing.
- ► Fast variational vs slow "exact" approaches.
- ▶ Characterize models for which efficient Gibbs is possible.
- Discover/build new models and name them after your favourite food source.

#### References I

- P. Orbanz.
   Lecture notes on Bayesian nonparametrics, 2014.
- [2] C. E. Rasmussen and C. K. I. Williams. Gaussian Processes for Machine Learning. MIT Press, 2006.
- [3] Y. W. Teh, M. I. Jordan, M. J. Beal, and D. M. Blei. Hierarchical dirichlet processes.
  In Advances in Neural Information Processing Systems (NIPS).