

MATH 4441 HW 8

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10.12

By Leibniz's rule, $D_i \langle F, G \rangle = \langle D_i F, G \rangle + \langle F, D_i G \rangle = 0$, so $\langle D_i F, G \rangle = -\langle F, D_i G \rangle$

10.13

Apply a rigid motion so that p coincides with the origin and $T_p M$ coincides with the x-y plane, then we can use a Monge patch around p , with the mapping

$$X(u^1, u^2) = (u^1, u^2, f(u^1, u^2))$$

Since the surface is tangent to x-y plane at the origin, $D_1 f(0, 0) = D_2 f(0, 0) = 0$. So

$$D_1 X(0, 0) = (1, 0, D_1 f(0, 0)) = (1, 0, 0) := e_1$$

$$D_2 X(0, 0) = (0, 1, D_2 f(0, 0)) = (0, 1, 0) := e_2$$

$$g_{ij}(0, 0) = \langle D_i X(0, 0), D_j X(0, 0) \rangle = \langle e_i, e_j \rangle = \delta_{ij}$$

Therefore $[g_{ij}(0, 0)] = [\delta_{ij}] = I$

10.15

For any γ , since γ lies on the surface, $\langle \gamma'(t), n(\gamma(t)) \rangle = 0$. Taking the derivative at $t = 0$,

$$\langle \gamma'(t), n(\gamma(t)) \rangle' |_{t=0} = \langle \gamma''(0), n(p) \rangle + \langle \gamma'(0), (n \circ \gamma)'(0) \rangle = 0$$

Therefore

$$\langle \gamma''(0), n(p) \rangle = -\langle \gamma'(0), (n \circ \gamma)'(0) \rangle = \boxed{-\langle v, dn_p(v) \rangle}$$

which is independent of γ .

10.17

$$\Pi_p(v, w) = \langle S_p(v), w \rangle = \left\langle \sum_i v_i S_p(e_i), \sum_j w_j e_j \right\rangle = \sum_{i,j} v_i w_j \langle S_p(e_i), e_j \rangle = \sum_{i,j} v_i w_j l_{ij}$$

Similarly

$$\Pi_p(w, v) = \sum_{i,j} v_i w_j l_{ji}$$

l_{ij} is symmetric since mixed derivatives are interchagable:

$$l_{ij} = \langle D_{ij}, N \rangle = \langle D_{ji}, N \rangle = l_{ji}$$

Therefore, $\Pi_p(v, w) = \Pi_p(w, v)$.

10.18

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By bilinearity and symmetry of Π_p

$$\begin{aligned} \Pi_p(v, v) &= \Pi_p(\cos \theta e_1 + \sin \theta e_2, \cos \theta e_1 + \sin \theta e_2) \\ &= \cos^2 \theta \Pi_p(e_1, e_1) + 2 \cos \theta \sin \theta \Pi_p(e_1, e_2) + \sin^2 \theta \Pi_p(e_2, e_2) \end{aligned}$$

Since we have chosen the unit eigenvectors of S_p to be the basis vectors,

$$\Pi_p(e_1, e_1) = \langle S_p(e_1), e_1 \rangle = \langle \lambda_1 e_1, e_1 \rangle = \lambda_1, \text{ similarly, } \Pi_p(e_2, e_2) = \lambda_2$$

$$\Pi_p(e_1, e_2) = \Pi_p(e_2, e_1) = \langle \lambda_1 e_1, e_2 \rangle = 0$$

Plug the values into the first equation,

$$\Pi_p(v, v) = \cos^2 \theta \lambda_1 + \sin^2 \theta \lambda_2$$

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$$\frac{d}{d\theta} \Pi_p(v, v) = -2 \cos \theta \sin \theta \lambda_1 + 2 \sin \theta \cos \theta \lambda_2 = 2(\lambda_2 - \lambda_1) \sin \theta \cos \theta$$

Since $\lambda_1 \neq \lambda_2$, the derivative vanishes when

$$\cos \theta = 0, \sin \theta = \pm 1 \text{ or } \sin \theta = 0, \cos \theta = \pm 1$$

which correspond to the extrema

$$\min \Pi_p(v, v) = 1\lambda_1 + 0\lambda_2 = \lambda_1$$

$$\max \Pi_p(v, v) = 0\lambda_1 + 1\lambda_2 = \lambda_2$$