

# Sensors

# Sensors

- While smartphones differ from other devices in terms of their computation power and battery limitations they do have one significant advantage
  - They generally come packed with sensors
  - Used to measure various aspects of the current environment
  - In this lecture we will introduce the various sensor types, coordinate systems and also the issues that surround sensors

# Why sensors are useful

- Sensors permit a device to collect data about its current environment
  - While the data is basic in nature it can be used to provide useful information about what a user is doing at any given time
  - Examples in the latest android devices include support for heart rate monitors and step counters
  - To be able to track users and inform them how to improve their health
  - This is only one example but there is many more

# Scalar sensors

- Sensors in android are divided into two specific types
  - The first type we deal with are scalar sensors
  - A scalar sensor is a sensor that reads a single property about the environment
  - That property has no directional component. e.g. ambient temperature has no direction
  - Android has four main types of sensor here

# Light sensors

- The light sensor is used to measure the ambient light level in an environment
  - Light levels are measured in units of lux
  - 0 represents complete darkness while increasing values represent increasing brightness. A well lit room will approximately be 300 to 500 lux
  - One of the main uses of a sensor like this is to automatically adjust screen brightness to adapt to the overall lighting level

# Temperature sensors

- The temperature sensor is used to measure the ambient temperature of the current environment
  - A sensor type that is not found very often on devices
  - Temperature is measured in celcius or farhenheit
  - While there is no direct use for something like this. A possible idea for its use is to use lots of distributed temperature sensors to map local fluctuations in temperature

# Proximity sensors

- Proximity sensors measure how close an object is to the sensor
  - Unit of measurement here is the centimeter
  - Generally used to disable/enable a touchscreen when a user moves the device to their ear or away from their ear
  - Also used when a device is put face down on a table to silence the device from accepting any calls

# Barometric sensors

- Barometric sensors are used to measure atmospheric pressure
  - Like the temperature sensors they are not found on many devices
  - The unit of measurement here is the millibar, higher values indicate a higher pressure
  - Similar to the temperature sensors it only really makes sense if there are many of them in use for mapping local changes in air pressure



# Vector sensors

- Vector sensors are sensors that measure data in more than one dimension
  - All vector sensors in Android will measure data in three dimensions
  - These sensors tend to be the most common in android devices
  - As they provide much information about the environment

# Accelerometers

- An accelerometer is used to measure accelerations in all three directions
  - Acceleration being the rate in change of velocity. Higher absolute values here state that the device is undergoing quicker changes in speed
  - The SI unit here is meters per second squared ( $\text{ms}^{-2}$ ) but it is also common to use G-force units as well ( $1g = 9.81 \text{ ms}^{-2}$ )
  - There are many uses for a sensor like this a few examples of which will be covered later

# Gyroscopes

- Gyroscopes are used to measure the speed of rotation of the device
  - The unit measurement here is radians per second. Higher absolute values represent faster device rotation.
  - Another of the common sensors provided on Android devices
  - Generally used in combination with the accelerometer to generate a device orientation

# Magnetic field sensors

- Magnetic field sensors are used to detect the magnetic field strength of the earth in all three axis
  - The unit of measurement here is the micro-Tesla ( $\mu\text{T}$ ), higher values here will mean that the magnetic field is stronger.
  - Generally something like this is used for getting device orientation if the gyroscope is not available
  - However more recent uses include magnetic covers for devices such that a high magnetic value is screen off and a reduction in magnetic value is screen on.

# Virtual sensors

- Using sensors like the accelerometer directly may not be the best approach.
  - In the case of the accelerometer you will always have a gravity component that you may not need in your application.
  - In this case android provides a series of virtual sensors that will provide filtered versions of data and common combinations of sensors
  - Here we look at the gravity, linear acceleration, and rotation vector virtual sensors

# Linear accelerometer

- The linear accelerometer is a high pass filter applied to the values that come back from the accelerometer
  - The high pass filter will remove the gravity component from the accelerometer as it is constant and has a frequency of zero
  - This will only leave the accelerations on the device that are caused by the user
  - This is generally used in place of the raw accelerometer

# Gravity sensor

- The gravity sensor on the other hand is the accelerometer with a low pass filter applied
  - Thus removing all of the user induced accelerations on the device
  - Generally there will not be much in the way of use for a sensor like this, although one use could be to create a bubble application to check if things are level
  - Generally more interested in removing this

# Rotation vector

- The rotation vector is a combination of the accelerometer and gyroscope that is used to determine a three axis orientation of a device
  - Has a different coordinate system to the other sensors (will be explained later)
  - Will produce a set of values that will enable the device to determine its compass bearing
  - And also the pitch and roll of the device



# Location sensors

- Perhaps some of the most important sensors within a device like this are the location sensors
  - To be able to locate a device on the surface of the planet
  - Generally used for navigation purposes
  - Also used for anti-theft measures

# GPS

- The most accurate of the location sensors that uses the Global Positioning System satellite signals
  - Can provide accuracy to within a few meters
  - Generally used for navigation however is generally assisted by the rotation vector for compass information
  - However, does not work indoors

# Network location

- “location system” that uses a database that google maintains of network access points (wifi and mobile)
  - Provides an approximation of the location of the device.
  - However unlike GPS it works both indoors and outdoors
  - Generally the two will be combined to provide a full location for the device indoor and outdoor

# How sensors are managed in android

- Sensors are all managed through a series of sensor classes
  - To hide the individual differences in how each sensor is managed and to present a unified interface to the developer
- All applications must register interest in sensors directly with the Android OS.
  - Again in an effort to reduce battery usage android will deliver updates at the rate requested by each individual listener rather than having each application poll the sensor continuously

# Permissions

- Getting access to the majority of sensors does not require any form of permissions
  - Very difficult to do any kind of malicious activity just by reading gyroscopes and accelerometers
- However, for the location sensors there is explicit permissions required
  - As an application can track the user's location and that information a user may not wish to disclose to an application.

# Sensors need to be queried

- You are not guaranteed that a specific sensor will appear on any device.
  - While a lot of sensors appear on a majority of devices there will be some like temperature sensors and barometric sensors that have very little use and may not be in a certain device
- As a result you are expected to query if a given sensor is on a device.
  - The test to do this is to ask for a default sensor of the type you are interested in. If a value of null is returned then the device has no sensors of that type

# Sensor manager class

- The class that you must interface with in order to access sensors and to register listeners with sensors
  - You will query this service for all of the sensors you require in your application
  - Once you have determined what sensors you require you will register listeners for those sensors with this service
  - It will then take responsibility for triggering your listeners whenever a new sensor value is obtained

# Sensor class

- Contains all the information about each sensor that a device has
  - Includes all the constants that differentiate between the different sensor types
  - You can use this to query the specification of individual sensors and for comparing them
    - Generally you will do this if you have access to more than a single type of sensor and you are looking for the best one



# Sensor listeners

- Small segments of java code that you provide for reacting to a change in a sensor
  - Changes include new values in which case you may need to update your application and the UI
  - Also will include changes in the accuracy of the sensor.
    - Gives you the opportunity to change to another sensor if there is another one available or to change your UI to take account of the loss in accuracy

# Sensor delay types

- There are three main sensor delay types that are used in application development. It is possible for you to define your own rates as well
  - `SENSOR_DELAY_FASTEST`: get updates from the sensor as fast as the sensor can physically provide them
  - `SENSOR_DELAY_GAME`: get updates from a sensor at a rate that is appropriate for game processing
  - `SENSOR_DELAY_UI`: get updates from a sensor at a rate that is suitable for updating a display

# Where sensors fit with the activity life cycle

- It is generally recommended that you should only register interest in sensors when your application is not in the stopped state
  - Generally a user is not interested in the sensor values that your application is tracking if the application is not active
  - Thus we usually deregister our listeners in the `onStop()` method and reregister in the `onStart()` method as a way of conserving battery power
  - Unless you have a good reason to keep a sensor active while your application is not active

# GPS and the activity life cycle

- The same advice would also apply to the location sensors with a few minor exceptions
  - The main exception being navigation
  - This is because if a navigation application is interrupted and removes location listeners it will have to wait about 5 to 10 seconds before the listener will get a new location after being reregistered
  - Otherwise you should deregister interest as GPS does consume battery power

# Issues to consider with sensors

- While sensors do provide a lot of information about the environment and your user there are issues to consider with their use
  - These must be considered carefully
  - As they will affect the trust of your users and also the amount of information you collect on them
  - And also the performance of your application and the device it is running on

# User tracking

- One of the most important ones is the use of location sensors to track the users location
  - While there are legitimate and common sense uses for these sensors it is not uncommon to see abuses of this data
  - As it is easily possible to track a user's full movements throughout a long period of time
  - If you are going to track your user you must inform them up front and give them a chance to opt out

# Clarity on data use

- Like permissions you should be fully clear on what data you use from sensors and for what use.
  - Applications that do this are generally not malicious and are more likely to be trusted by users.
  - If you collect such data from your user particularly location data and store it on a server somewhere you must provide secure storage for that data
  - Generally anonymising and scrubbing identifying information away from data collected is a good step to take

# Battery usage

- You must play a delicate balancing act between sensor accuracy and performance and battery power
  - The more you query a sensor the quicker you will receive updates and will likely improve the accuracy of your application.
  - The downside however is that your application will consume more battery power as a result
  - If you go the opposite way you will save battery power with the potential loss of accuracy



# Sensor accuracy

- Another issue to consider is that every sensor will have different accuracies and also value ranges
  - e.g. the proximity sensor in the HTC One X is a very basic sensor that only provides two values 0cm and 8cm
  - Other sensors will provide a higher accuracy but they will come at a higher expense
  - Don't assume anything with regards to the accuracy and error rates of any sensor you use on an android device

# When to use multiple sensors of the same type

- Some devices will provide more than one of the same sensor type
  - It is possible to register interest in more than one sensor of the same type
  - Generally you will only need to do this if you need a higher accuracy than you could get from a single sensor
  - By averaging or filtering between two or more sensors

# Sensor values are not absolute

- As you saw with the proximity sensor example earlier the values you get from the sensor will not be absolute
  - While a sensor measures a continuous variable in general the sensor will represent them in discrete values.
  - Thus there will be an error associated between what the sensor reports and the actual value of that property in the environment
  - Usually more expensive sensors will have more discrete levels leading to a larger values that can be represented

# Sensor coordinate system

- Most sensors with the exception of the location and rotation vector sensors will use the same coordinate system
  - Where the Z axis is coming out of the device screen
  - The Y axis is coming out of the top of the device
  - And the X axis is coming out of the right hand side of the device

# Rotation coordinate system

- As the rotation vector provides a series of rotations it uses a different coordinate system
  - The z axis is perpendicular to the ground and rotation around this axis is the compass direction
  - The X axis is pointing out from the right of the device and rotations around this axis represent the pitch of the device
  - The Y axis is pointing out of the top of the device and rotations around this axis represent the roll of the device

# Location coordinate system

- The location sensors take advantage of the world standard latitude and longitude system of surface coordinates
  - Takes the earth and maps the surface as a 2D plane
  - With latitude representing how far south or north the device is  $[-90, +90]$
  - And longitude representing how far west or east the device is  $[-180, +180]$