# Krótkie wprowadzenie do metody FDTD (cz. 2(2D))

### Równania Maxwella

$$ullet \frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}$$



$$\bullet \frac{\partial E_{\mathcal{X}}}{\partial t} = \frac{1}{\varepsilon} \left( \frac{\partial H_{\mathcal{Z}}}{\partial y} - J_{\mathcal{X}} \right)$$

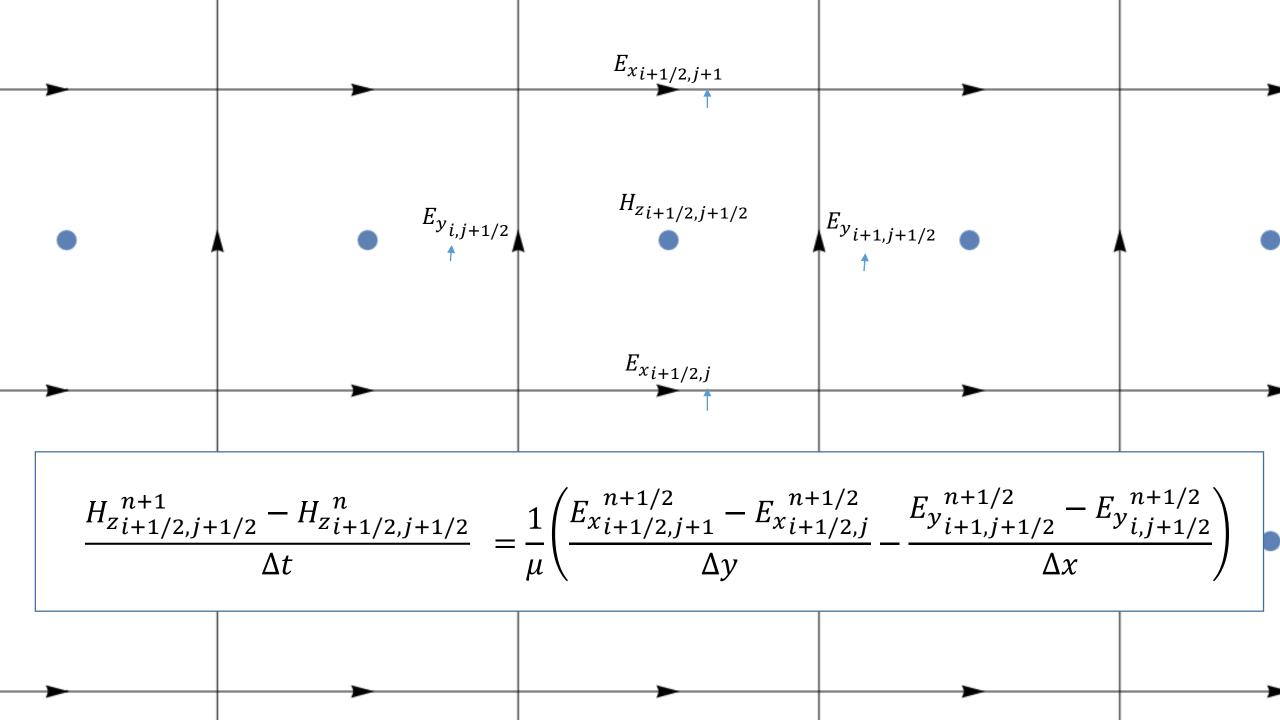
• 
$$\frac{\partial E_y}{\partial t} = \frac{1}{\varepsilon} \left( -\frac{\partial H_z}{\partial x} - J_y \right)$$

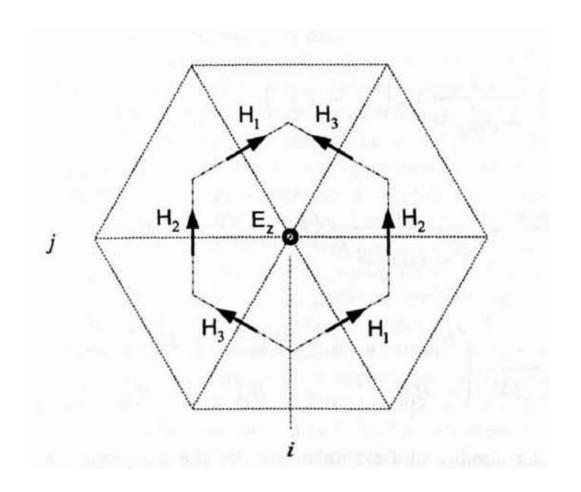
$$\frac{\partial H_Z}{\partial t} = \frac{1}{\mu} \left( \frac{\partial E_X}{\partial y} - \frac{\partial E_Y}{\partial x} \right)$$

$$\boldsymbol{J} = \boldsymbol{J}_{source} + \sigma \boldsymbol{E}$$

Źródło prądu

Mikroskopowe prawo Ohma





źr: Allen Taflove, Susan C. Hagness, Computational electrodynamics – FDTD method

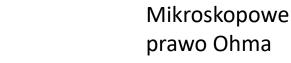
### Równania Maxwella

$$\frac{\partial \mathbf{B}}{\partial x} = -\nabla \times \mathbf{E}$$



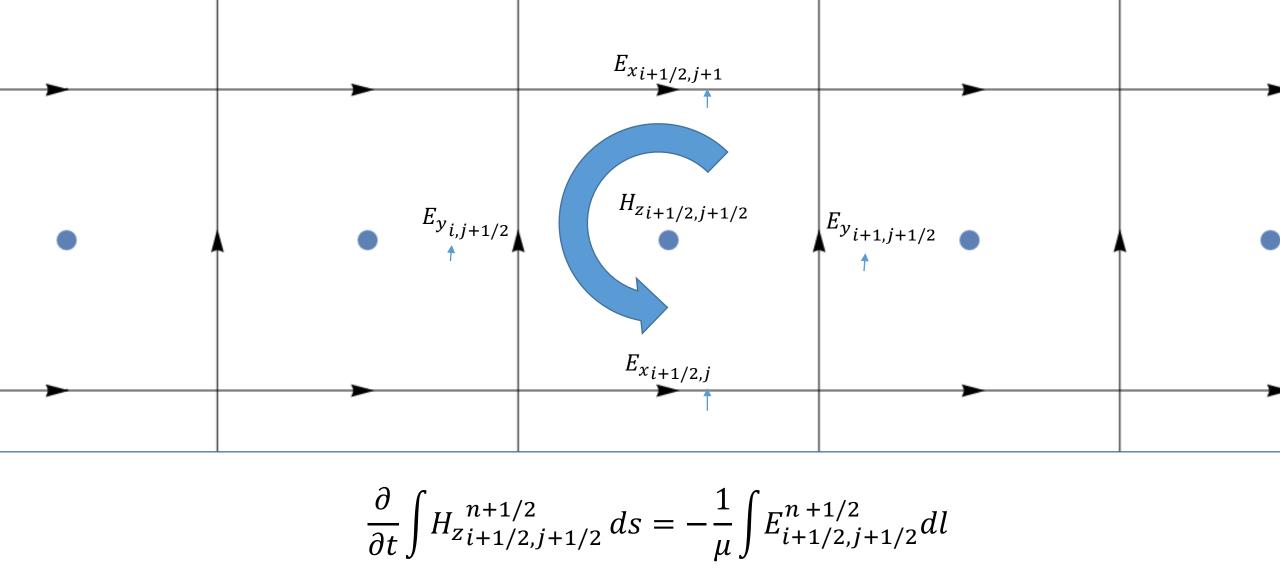
• 
$$\frac{\partial}{\partial t} \int_{S} \mathbf{D} \cdot d\mathbf{s} = \int_{C} \mathbf{H} \cdot d\mathbf{l} - \mathbf{I}$$

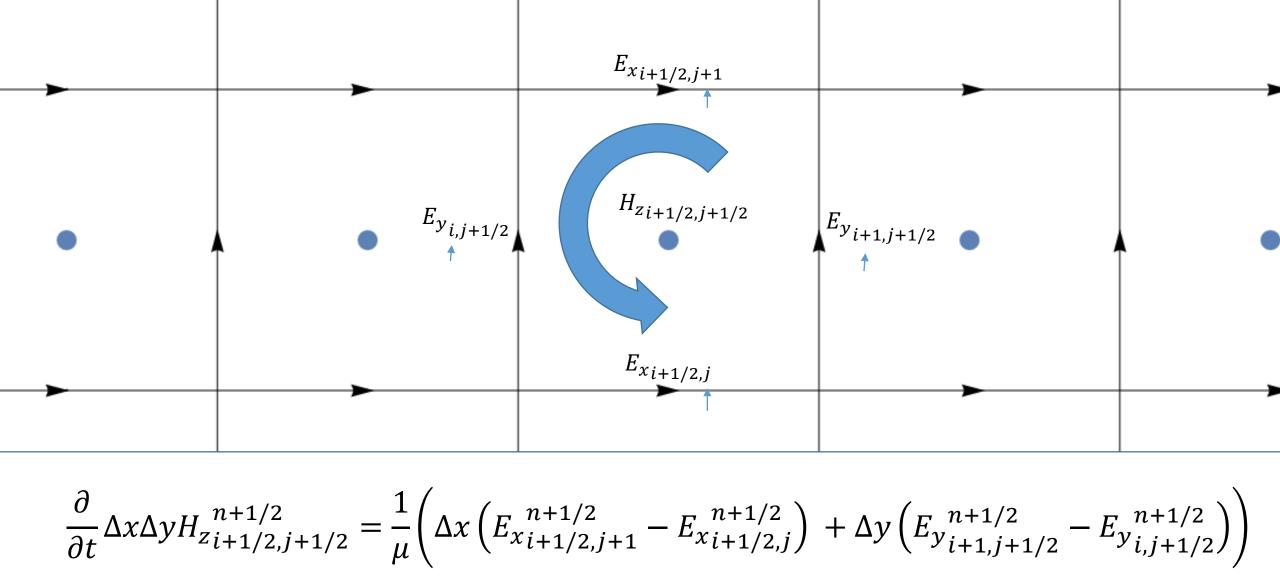
$$\boldsymbol{J} = \boldsymbol{J}_{source} + \sigma \boldsymbol{E}$$

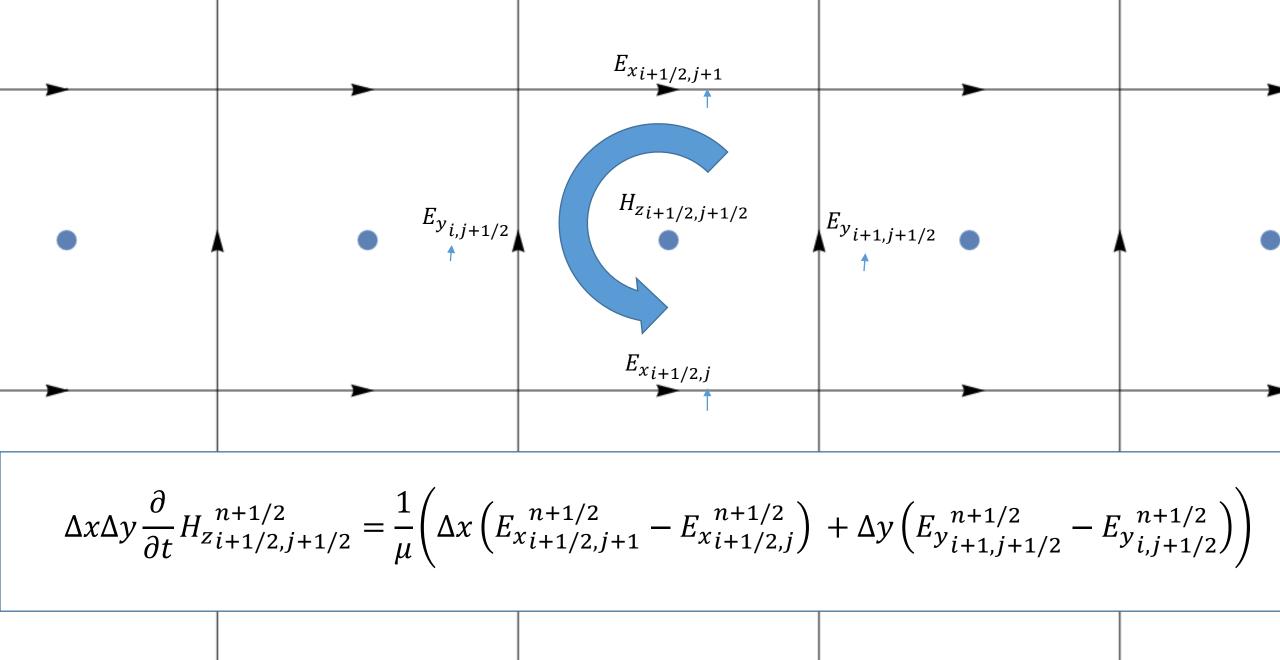


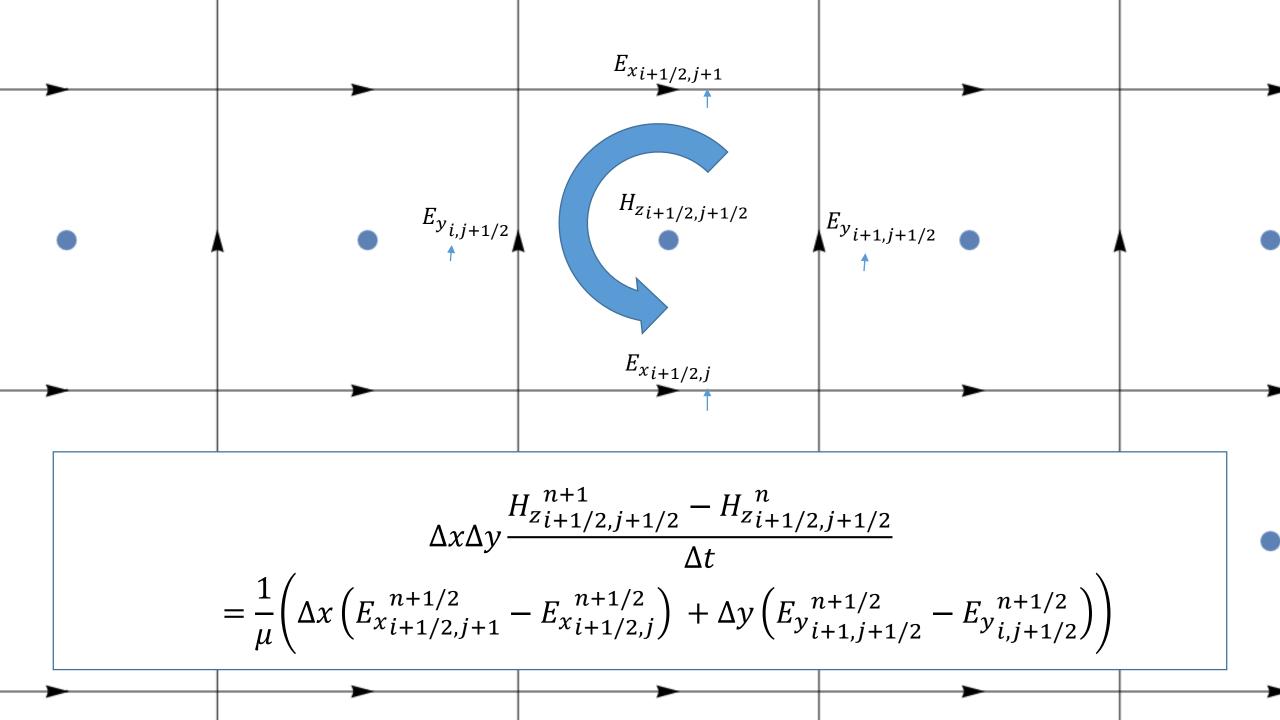
Źródło prądu

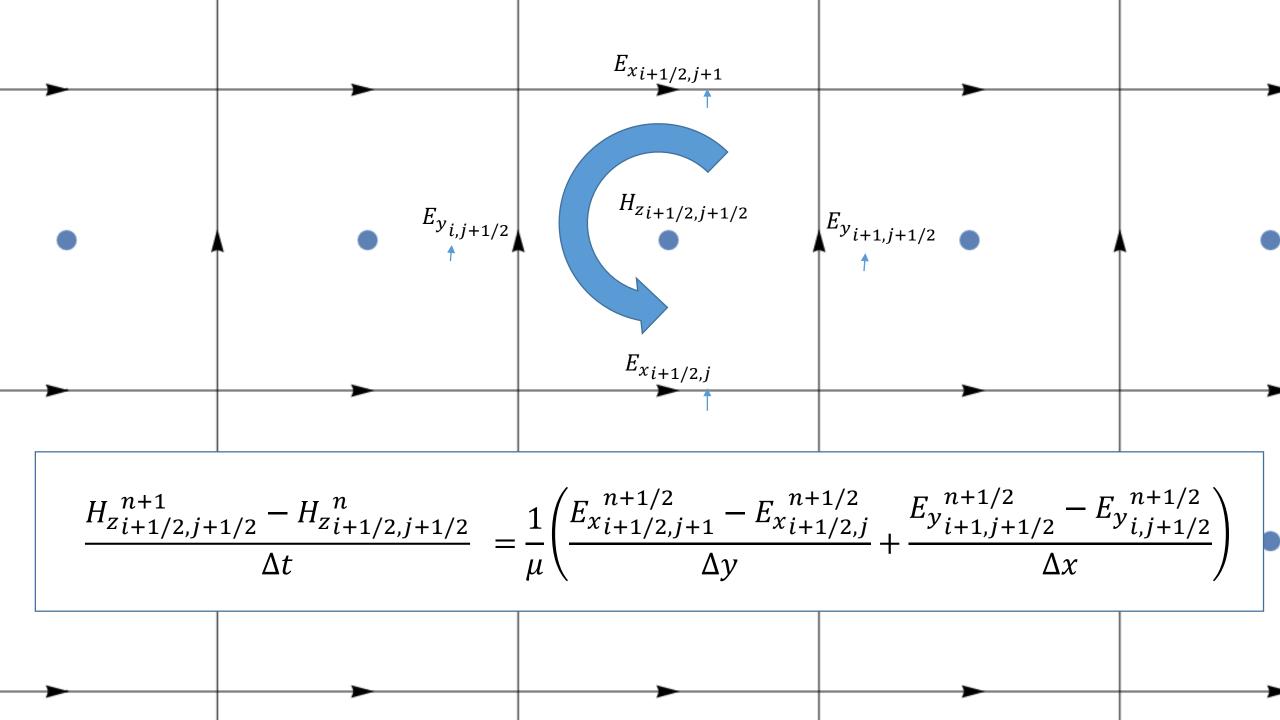
$$I = \int_{S} J \cdot ds$$





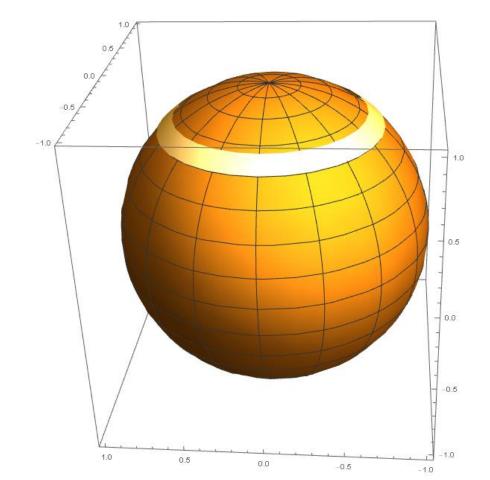




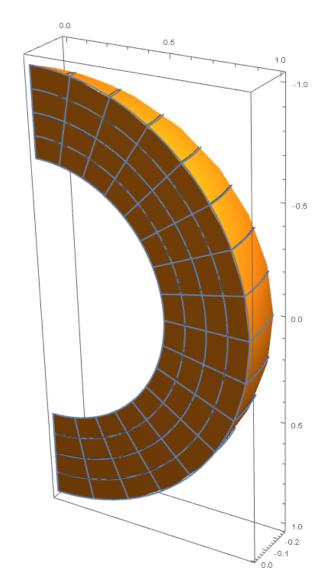


# Modelowanie wnęki sferycznej

Zakładamy symetrię ze względu na  $\varphi$  => brak gradientu ze względu na  $\varphi$ 







# Modelowanie wnęki sferycznej

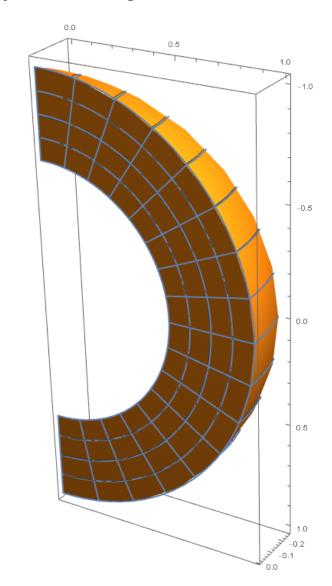
Zakładamy symetrię ze względu na  $\varphi$   $\Rightarrow$  brak gradientu ze względu na  $\varphi$ 

$$\varepsilon \frac{\partial E_r}{\partial t} = \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \theta} (\sin \theta H_{\varphi}) - \frac{\partial H_{\theta}}{\partial \varphi} \right]$$

$$\varepsilon \frac{\partial E_{\theta}}{\partial t} = \frac{1}{r \sin \theta} \frac{\partial H_r}{\partial \varphi} - \frac{1}{r} \frac{\partial}{\partial r} (r H_{\varphi})$$

$$\varepsilon \frac{\partial E_{\varphi}}{\partial t} = \frac{1}{r} \left[ \frac{\partial}{\partial r} (r H_{\theta}) - \frac{\partial H_r}{\partial \theta} \right]$$

$$\begin{split} \mu \frac{\partial H_r}{\partial t} &= -\frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \theta} (\sin \theta E_{\varphi}) - \frac{\partial E_{\theta}}{\partial \varphi} \right] \\ \mu \frac{\partial H_{\theta}}{\partial t} &= -\frac{1}{r \sin \theta} \frac{\partial E_r}{\partial \varphi} + \frac{1}{r} \frac{\partial}{\partial r} (r E_{\varphi}) \\ \mu \frac{\partial H_{\varphi}}{\partial t} &= -\frac{1}{r} \left[ \frac{\partial}{\partial r} (r E_{\theta}) - \frac{\partial E_r}{\partial \theta} \right] \end{split}$$



# Modelowanie wnęki sferycznej

Zakładamy symetrię ze względu na  $\varphi$   $\Rightarrow$  brak gradientu ze względu na  $\varphi$ 

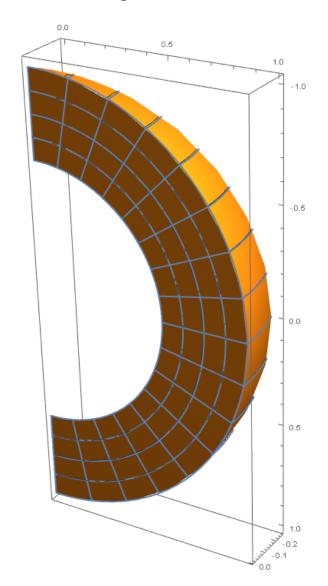
$$\mathbf{Q} \varepsilon \frac{\partial E_r}{\partial t} = \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \theta} (\sin \theta H_{\varphi}) - \frac{\partial H_{\theta}}{\partial \varphi} \right]$$

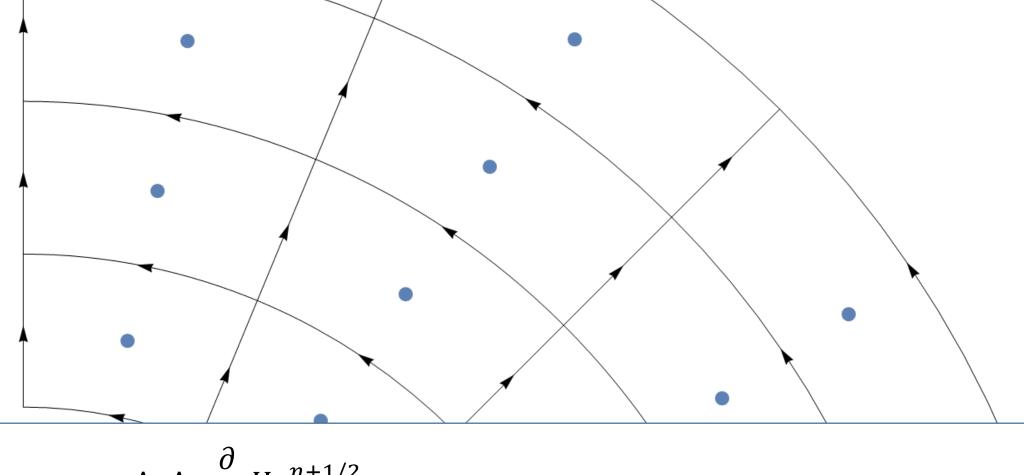
$$\varepsilon \frac{\partial E_{\theta}}{\partial t} = \frac{1}{r \sin \theta} \frac{\partial H_r}{\partial \varphi} - \frac{1}{r} \frac{\partial}{\partial r} (r H_{\varphi})$$

$$\varepsilon \frac{\partial E_{\varphi}}{\partial t} = \frac{1}{r} \left[ \frac{\partial}{\partial r} (rH_{\theta}) - \frac{\partial H_{r}}{\partial \theta} \right]$$

$$\mathbf{D} \quad \mu \frac{\partial H_r}{\partial t} = -\frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \theta} (\sin \theta E_{\varphi}) - \frac{\partial E_{\theta}}{\partial \varphi} \right]$$

$$\Phi \mu \frac{\partial H_{\theta}}{\partial t} = -\frac{1}{r \sin \theta} \frac{\partial E_r}{\partial \varphi} + \frac{1}{r} \frac{\partial}{\partial r} (r E_{\varphi})$$





$$\Delta x \Delta y \frac{\partial}{\partial t} H_{\varphi_{i+1/2,j+1/2}}^{n+1/2}$$

$$= \frac{1}{\mu} \left( \frac{\Delta r \left( E_{r_{i+1/2,j+1}}^{n+1/2} - E_{r_{i+1/2,j}}^{n+1/2} \right) + \sum_{i=1}^{n+1/2} \left( -r_{i} E_{\theta_{i,j+1/2}}^{n+1/2} - r_{i} E_{\theta_{i,j+1/2}}^{n+1/2} \right) \right)$$