

## 4.7 EXERCISES

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1. Let  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$  and  $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}$  be bases for a vector space  $V$ , and suppose  $\mathbf{b}_1 = 6\mathbf{c}_1 - 2\mathbf{c}_2$  and  $\mathbf{b}_2 = 9\mathbf{c}_1 - 4\mathbf{c}_2$ .
  - a. Find the change-of-coordinates matrix from  $\mathcal{B}$  to  $\mathcal{C}$ .
  - b. Find  $[\mathbf{x}]_{\mathcal{C}}$  for  $\mathbf{x} = -3\mathbf{b}_1 + 2\mathbf{b}_2$ . Use part (a).
2. Let  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$  and  $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}$  be bases for a vector space  $V$ , and suppose  $\mathbf{b}_1 = -\mathbf{c}_1 + 4\mathbf{c}_2$  and  $\mathbf{b}_2 = 5\mathbf{c}_1 - 3\mathbf{c}_2$ .
  - a. Find the change-of-coordinates matrix from  $\mathcal{B}$  to  $\mathcal{C}$ .
  - b. Find  $[\mathbf{x}]_{\mathcal{C}}$  for  $\mathbf{x} = 5\mathbf{b}_1 + 3\mathbf{b}_2$ .



3. Let  $\mathcal{U} = \{\mathbf{u}_1, \mathbf{u}_2\}$  and  $\mathcal{W} = \{\mathbf{w}_1, \mathbf{w}_2\}$  be bases for  $V$ , and let  $P$  be a matrix whose columns are  $[\mathbf{u}_1]_{\mathcal{W}}$  and  $[\mathbf{u}_2]_{\mathcal{W}}$ . Which of the following equations is satisfied by  $P$  for all  $\mathbf{x}$  in  $V$ ?

(i)  $[\mathbf{x}]_{\mathcal{U}} = P[\mathbf{x}]_{\mathcal{W}}$       (ii)  $[\mathbf{x}]_{\mathcal{W}} = P[\mathbf{x}]_{\mathcal{U}}$

4. Let  $\mathcal{A} = \{\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3\}$  and  $\mathcal{D} = \{\mathbf{d}_1, \mathbf{d}_2, \mathbf{d}_3\}$  be bases for  $V$ , and let  $P = \begin{bmatrix} [\mathbf{d}_1]_{\mathcal{A}} & [\mathbf{d}_2]_{\mathcal{A}} & [\mathbf{d}_3]_{\mathcal{A}} \end{bmatrix}$ . Which of the following equations is satisfied by  $P$  for all  $\mathbf{x}$  in  $V$ ?

(i)  $[\mathbf{x}]_{\mathcal{A}} = P[\mathbf{x}]_{\mathcal{D}}$       (ii)  $[\mathbf{x}]_{\mathcal{D}} = P[\mathbf{x}]_{\mathcal{A}}$

5. Let  $\mathcal{A} = \{\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3\}$  and  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$  be bases for a vector space  $V$ , and suppose  $\mathbf{a}_1 = 4\mathbf{b}_1 - \mathbf{b}_2$ ,  $\mathbf{a}_2 = -\mathbf{b}_1 + \mathbf{b}_2 + \mathbf{b}_3$ , and  $\mathbf{a}_3 = \mathbf{b}_2 - 2\mathbf{b}_3$ .

- a. Find the change-of-coordinates matrix from  $\mathcal{A}$  to  $\mathcal{B}$ .  
b. Find  $[\mathbf{x}]_{\mathcal{B}}$  for  $\mathbf{x} = 3\mathbf{a}_1 + 4\mathbf{a}_2 + \mathbf{a}_3$ .

6. Let  $\mathcal{D} = \{\mathbf{d}_1, \mathbf{d}_2, \mathbf{d}_3\}$  and  $\mathcal{F} = \{\mathbf{f}_1, \mathbf{f}_2, \mathbf{f}_3\}$  be bases for a vector space  $V$ , and suppose  $\mathbf{f}_1 = 2\mathbf{d}_1 - \mathbf{d}_2 + \mathbf{d}_3$ ,  $\mathbf{f}_2 = 3\mathbf{d}_2 + \mathbf{d}_3$ , and  $\mathbf{f}_3 = -3\mathbf{d}_1 + 2\mathbf{d}_3$ .

- a. Find the change-of-coordinates matrix from  $\mathcal{F}$  to  $\mathcal{D}$ .  
b. Find  $[\mathbf{x}]_{\mathcal{D}}$  for  $\mathbf{x} = \mathbf{f}_1 - 2\mathbf{f}_2 + 2\mathbf{f}_3$ .

In Exercises 7–10, let  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$  and  $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}$  be bases for  $\mathbb{R}^2$ . In each exercise, find the change-of-coordinates matrix from  $\mathcal{B}$  to  $\mathcal{C}$  and the change-of-coordinates matrix from  $\mathcal{C}$  to  $\mathcal{B}$ .

7.  $\mathbf{b}_1 = \begin{bmatrix} 7 \\ 5 \end{bmatrix}$ ,  $\mathbf{b}_2 = \begin{bmatrix} -3 \\ -1 \end{bmatrix}$ ,  $\mathbf{c}_1 = \begin{bmatrix} 1 \\ -5 \end{bmatrix}$ ,  $\mathbf{c}_2 = \begin{bmatrix} -2 \\ 2 \end{bmatrix}$

8.  $\mathbf{b}_1 = \begin{bmatrix} -1 \\ 8 \end{bmatrix}$ ,  $\mathbf{b}_2 = \begin{bmatrix} 1 \\ -5 \end{bmatrix}$ ,  $\mathbf{c}_1 = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$ ,  $\mathbf{c}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

9.  $\mathbf{b}_1 = \begin{bmatrix} -6 \\ -1 \end{bmatrix}$ ,  $\mathbf{b}_2 = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$ ,  $\mathbf{c}_1 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$ ,  $\mathbf{c}_2 = \begin{bmatrix} 6 \\ -2 \end{bmatrix}$

10.  $\mathbf{b}_1 = \begin{bmatrix} 7 \\ -2 \end{bmatrix}$ ,  $\mathbf{b}_2 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$ ,  $\mathbf{c}_1 = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$ ,  $\mathbf{c}_2 = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$

In Exercises 11 and 12,  $\mathcal{B}$  and  $\mathcal{C}$  are bases for a vector space  $V$ . Mark each statement True or False. Justify each answer.

11. a. The columns of the change-of-coordinates matrix  ${}_{\mathcal{C}}P_{\mathcal{B}}$  are  $\mathcal{B}$ -coordinate vectors of the vectors in  $\mathcal{C}$ .

- b. If  $V = \mathbb{R}^n$  and  $\mathcal{C}$  is the standard basis for  $V$ , then  ${}_{\mathcal{C}}P_{\mathcal{B}}$  is the same as the change-of-coordinates matrix  $P_{\mathcal{B}}$  introduced in Section 4.4.

12. a. The columns of  ${}_{\mathcal{C}}P_{\mathcal{B}}$  are linearly independent.

- b. If  $V = \mathbb{R}^2$ ,  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$ , and  $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}$ , then row reduction of  $[\mathbf{c}_1 \ \mathbf{c}_2 \ \mathbf{b}_1 \ \mathbf{b}_2]$  to  $[I \ P]$  produces a matrix  $P$  that satisfies  $[\mathbf{x}]_{\mathcal{B}} = P[\mathbf{x}]_{\mathcal{C}}$  for all  $\mathbf{x}$  in  $V$ .

13. In  $\mathbb{P}_2$ , find the change-of-coordinates matrix from the basis  $\mathcal{B} = \{1 - 2t + t^2, 3 - 5t + 4t^2, 2t + 3t^2\}$  to the standard basis  $\mathcal{C} = \{1, t, t^2\}$ . Then find the  $\mathcal{B}$ -coordinate vector for  $-1 + 2t$ .

14. In  $\mathbb{P}_2$ , find the change-of-coordinates matrix from the basis  $\mathcal{B} = \{1 - 3t^2, 2 + t - 5t^2, 1 + 2t\}$  to the standard basis. Then write  $t^2$  as a linear combination of the polynomials in  $\mathcal{B}$ .

Exercises 15 and 16 provide a proof of Theorem 15. Fill in a justification for each step.

15. Given  $\mathbf{v}$  in  $V$ , there exist scalars  $x_1, \dots, x_n$ , such that

$$\mathbf{v} = x_1\mathbf{b}_1 + x_2\mathbf{b}_2 + \cdots + x_n\mathbf{b}_n$$

because (a) \_\_\_\_\_. Apply the coordinate mapping determined by the basis  $\mathcal{C}$ , and obtain

$$[\mathbf{v}]_{\mathcal{C}} = x_1[\mathbf{b}_1]_{\mathcal{C}} + x_2[\mathbf{b}_2]_{\mathcal{C}} + \cdots + x_n[\mathbf{b}_n]_{\mathcal{C}}$$

because (b) \_\_\_\_\_. This equation may be written in the form

$$[\mathbf{v}]_{\mathcal{C}} = \begin{bmatrix} [\mathbf{b}_1]_{\mathcal{C}} & [\mathbf{b}_2]_{\mathcal{C}} & \cdots & [\mathbf{b}_n]_{\mathcal{C}} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \quad (8)$$

by the definition of (c) \_\_\_\_\_. This shows that the matrix  ${}_{\mathcal{C}}P_{\mathcal{B}}$  shown in (5) satisfies  $[\mathbf{v}]_{\mathcal{C}} = {}_{\mathcal{C}}P_{\mathcal{B}}[\mathbf{v}]_{\mathcal{B}}$  for each  $\mathbf{v}$  in  $V$ , because the vector on the right side of (8) is (d) \_\_\_\_\_.

16. Suppose  $Q$  is any matrix such that

$$[\mathbf{v}]_{\mathcal{C}} = Q[\mathbf{v}]_{\mathcal{B}} \quad \text{for each } \mathbf{v} \text{ in } V \quad (9)$$

Set  $\mathbf{v} = \mathbf{b}_1$  in (9). Then (9) shows that  $[\mathbf{b}_1]_{\mathcal{C}}$  is the first column of  $Q$  because (a) \_\_\_\_\_. Similarly, for  $k = 2, \dots, n$ , the  $k$ th column of  $Q$  is (b) \_\_\_\_\_ because (c) \_\_\_\_\_. This shows that the matrix  ${}_{\mathcal{C}}P_{\mathcal{B}}$  defined by (5) in Theorem 15 is the only matrix that satisfies condition (4).

17. [M] Let  $\mathcal{B} = \{\mathbf{x}_0, \dots, \mathbf{x}_6\}$  and  $\mathcal{C} = \{\mathbf{y}_0, \dots, \mathbf{y}_6\}$ , where  $\mathbf{x}_k$  is the function  $\cos^k t$  and  $\mathbf{y}_k$  is the function  $\cos kt$ . Exercise 34 in Section 4.5 showed that both  $\mathcal{B}$  and  $\mathcal{C}$  are bases for the vector space  $H = \text{Span}\{\mathbf{x}_0, \dots, \mathbf{x}_6\}$ .

- a. Set  $P = \begin{bmatrix} [\mathbf{y}_0]_{\mathcal{B}} & \cdots & [\mathbf{y}_6]_{\mathcal{B}} \end{bmatrix}$ , and calculate  $P^{-1}$ .  
b. Explain why the columns of  $P^{-1}$  are the  $\mathcal{C}$ -coordinate vectors of  $\mathbf{x}_0, \dots, \mathbf{x}_6$ . Then use these coordinate vectors to write trigonometric identities that express powers of  $\cos t$  in terms of the functions in  $\mathcal{C}$ .

See the Study Guide.

18. [M] (Calculus required)<sup>3</sup> Recall from calculus that integrals such as

$$\int (5 \cos^3 t - 6 \cos^4 t + 5 \cos^5 t - 12 \cos^6 t) dt \quad (10)$$

are tedious to compute. (The usual method is to apply integration by parts repeatedly and use the half-angle formula.) Use the matrix  $P$  or  $P^{-1}$  from Exercise 17 to transform (10); then compute the integral.

<sup>3</sup> The idea for Exercises 17 and 18 and five related exercises in earlier sections came from a paper by Jack W. Rogers, Jr., of Auburn University, presented at a meeting of the International Linear Algebra Society, August 1995. See "Applications of Linear Algebra in Calculus," *American Mathematical Monthly* 104 (1), 1997.



19. [M] Let

$$P = \begin{bmatrix} 1 & 2 & -1 \\ -3 & -5 & 0 \\ 4 & 6 & 1 \end{bmatrix},$$

$$\mathbf{v}_1 = \begin{bmatrix} -2 \\ 2 \\ 3 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} -8 \\ 5 \\ 2 \end{bmatrix}, \mathbf{v}_3 = \begin{bmatrix} -7 \\ 2 \\ 6 \end{bmatrix}$$

- a. Find a basis  $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  for  $\mathbb{R}^3$  such that  $P$  is the change-of-coordinates matrix from  $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  to the basis  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ . [Hint: What do the columns of  ${}_{C \leftarrow B}^P$  represent?]

- b. Find a basis  $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$  for  $\mathbb{R}^3$  such that  $P$  is the change-of-coordinates matrix from  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  to  $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$ .

20. Let  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$ ,  $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}$ , and  $\mathcal{D} = \{\mathbf{d}_1, \mathbf{d}_2\}$  be bases for a two-dimensional vector space.

- a. Write an equation that relates the matrices  ${}_{C \leftarrow B}^P$ ,  ${}_{D \leftarrow C}^P$ , and  ${}_{D \leftarrow B}^P$ . Justify your result.
- b. [M] Use a matrix program either to help you find the equation or to check the equation you write. Work with three bases for  $\mathbb{R}^2$ . (See Exercises 7–10.)