

Assignment 5a (chapter2-part2)

2.16

For each of the following statements, determine whether it is true or false (justify your answers).

(a). If $x[n] = 0$ for $n < T_1$ and $h[n] = 0$ for $n < N_2$, then $x[n] * h[n] = 0$ for $n < N_1 + N_2$.

TRUE.

We can see that $h[n]$ has to move toward the right by $N_1 + N_2$ units before $x[n]$ and $h[n]$ overlap with the non-zero areas. So that $x[n] * h[n] = 0$ for $n < N_1 + N_2$.

(b). If $y[n] = x[n] * h[n]$, then $y[n - 1] = x[n - 1] * h[n - 1]$.

FALSE.

Consider:

$$y[n] = x[n] * h[n]$$

$$y[n] = \sum_{k=-\infty}^{\infty} x[k]h[n - k]$$

From this,

$$y[n - 1] = \sum_{k=-\infty}^{\infty} x[k]h[n - 1 - k]$$

$$y[n] = x[n] * h[n - 1]$$

This shows that the given statement is false.

(c). If $y[n] = x[n] * h[n]$, then $y(-t) = x(-t) * h(-t)$.

TRUE.

Consider:

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau)h(t - \tau)d\tau$$

From this,

$$y(-t) = \int_{-\infty}^{\infty} x(\tau)h(-t - \tau)d\tau$$

$$y(-t) = \int_{-\infty}^{\infty} x(-\tau)h(-t + \tau)d\tau$$

$$y(-t) = x(-t) * h(-t)$$

This shows that the given statement is true.

(d). If $x(t) = 0$ for $t > T_1$ and $h(t) = 0$ for $t > T_2$, then $x(t) * h(t) = 0$ for $t > T_1 + T_2$.

TRUE.

This can be explained by considering:

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau)h(t - \tau)d\tau$$

In Figure S2.16, we plot $x(\tau)$ and $h(t - \tau)$ under the assumptions that (1) $x(t) = 0$ for $t > T_1$ and (2) $h(t) = 0$ for $t > T_2$. Clearly, the product $x(\tau)h(t - \tau)$ is zero if $t - T_2 > T_1$. Therefore, $y(t) = 0$ for $t > T_1 + T_2$.

2.18

Consider a causal LTI system whose input $x[n]$ and output $y[n]$ are related by the difference equation

$$y[n] = \frac{1}{4}y[n-1] + x[n]$$

Determine $y[n]$ if $x[n] = \delta[n-1]$

Since the system is causal, $y[n] = 0$ for $n < 1$. Now,

$$y[1] = \frac{1}{4}y[0] + x[1] = 0 + 1 = 1$$

$$y[2] = \frac{1}{4}y[1] + x[2] = \frac{1}{4} + 0 = \frac{1}{4}$$

$$y[3] = \frac{1}{4}y[2] + x[3] = \frac{1}{16} + 0 = \frac{1}{16}$$

$$\dots y[m] = \left(\frac{1}{4}\right)^{m-1} \dots$$

Therefore,

$$y[n] = \left(\frac{1}{4}\right)^{n-1}u[n-1]$$

2.19

Consider the cascade of the following two system S_1 and S_2 , as depicted in Figure P2.19:

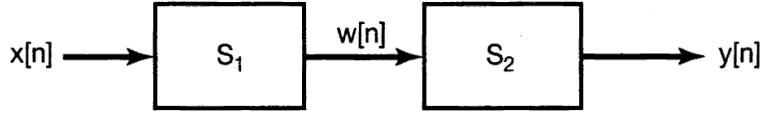


Figure P2.19

S_1 : causal LTI,

$$w[n] = \frac{1}{2}w[n-1] + x[n];$$

S_2 : causal LTI,

$$y[n] = \alpha y[n-1] + \beta w[n].$$

The difference equation relating $x[n]$ and $y[n]$ is:

$$y[n] = \frac{1}{8}y[n-2] + \frac{3}{4}y[n-1] + x[n].$$

(a). Determine α and β .

$$y[n] = \alpha y[n-1] + \beta w[n]$$

$$w[n] = \frac{1}{\beta}y[n] - \frac{\alpha}{\beta}y[n-1]$$

$$w[n-1] = \frac{1}{\beta}y[n-1] = \frac{\alpha}{\beta}y[n-1]$$

$$w[n] = \frac{1}{2}w[n-1] = \frac{1}{\beta}y[n] - \frac{\alpha}{\beta}y[n-1] - \frac{1}{2\beta}y[n-1] + \frac{\alpha}{2\beta}y[n-2]$$

$$\frac{1}{\beta}y[n] - \frac{\alpha}{\beta}y[n-1] - \frac{1}{2\beta}y[n-1] + \frac{\alpha}{2\beta}y[n-2] = x[n]$$

$$y[n] = (\alpha + \frac{1}{2})y[n-1] - \frac{\alpha}{2}y[n-2] + \beta x[n]$$

$$\alpha = \frac{1}{4}, \beta = 1$$

(b). Show the impulse response of the cascade connection of S_1 and S_2 .

$$w[n] = \frac{1}{2}w[n-1] + x[n] \text{ and } y[n] = \frac{1}{4}y[n-1] + w[n]$$

$$h_1[n] = \left(\frac{1}{2}\right)^n u[n]$$

$$h_2[n] = \left(\frac{1}{4}\right)^n u[n]$$

$$h[n] = h_1[n] * h_2[n] = \sum_{k=-\infty}^{\infty} h_1[k] h_2[n-k]$$

$$h[n] = \sum_{k=0}^{\infty} \left(\frac{1}{2}\right)^k \left(\frac{1}{4}\right)^{n-k} u[n-k]$$

$$h[n] = \sum_{k=0}^{\infty} \left(\frac{1}{2}\right)^k \left(\frac{1}{4}\right)^{n-k} = \sum_{k=0}^n \left(\frac{1}{2}\right)^{2(n-k)}$$

$$h[n] = \left[2\left(\frac{1}{2}\right)^n - \left(\frac{1}{4}\right)^n\right] u[n]$$

2.24

Consider the cascade interconnection of three causal LTI systems, illustrated in Figure P2.24(a).

The impulse response $h_2[n]$ is

$$h_2[n] = u[n] - u[n-2],$$

and the overall impulse response is as shown in Figure P2.24(b).

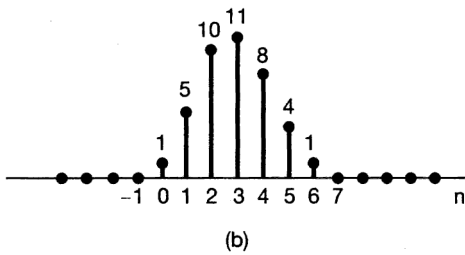
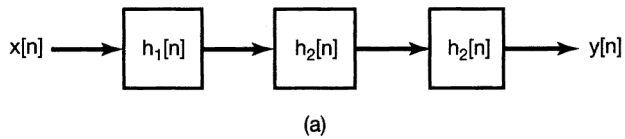


Figure P2.24

(a). Find the impulse response $h_1[n]$

$$h_2[n] = \delta[n] + \delta[n-1]$$

$$h_2[n] * h_2[n] = \delta[n] + 2\delta[n-1] + \delta[n-2]$$

$$h[n] = h_1[n] * [h_2[n] * h_2[n]]$$

$$h[n] = h_1[n] + 2h_1[n-1] + h_1[n-2]$$

$$h[0] = h_1[0] \Rightarrow h_1[0] = 1$$

$$h[1] = h_1[1] + 2h_1[0] \Rightarrow h_1[1] = 3$$

$$h[2] = h_1[2] + 2h_1[1] + h_1[0] \Rightarrow h_1[2] = 3$$

$$h[3] = h_1[3] + 2h_1[2] + h_1[1] \Rightarrow h_1[3] = 2$$

$$h[4] = h_1[4] + 2h_1[3] + h_1[2] \Rightarrow h_1[4] = 1$$

$$h[5] = h_1[5] + 2h_1[4] + h_1[3] \Rightarrow h_1[5] = 0$$

$$h_1[n] = 0 \text{ for } n < 0 \text{ and } n \geq 5$$

(b). Find the response of the overall system to the input $x[n] = \delta[n] - \delta[n-1]$.

$$y[n] = x[n] * h[n] = h[n] - h[n-1]$$

2.31

Consider the LTI system initially at rest and described by the difference equation

$$y[n] + 2y[n-1] = x[n] + 2x[n-2]$$

Find the response of this system to the input depicted in Figure P2.31 by solving the difference equation recursively.

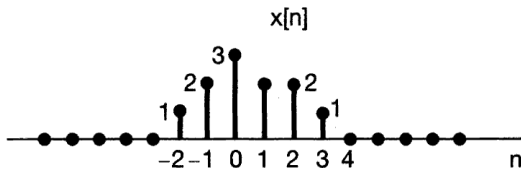


Figure P2.31

$$y[n] = 0 \text{ for } n < -2$$

$$y[n] = x[n] + 2x[n-2] - 2y[n-1]$$

$$y[-2] = 1, y[-1] = 0, y[0] = 5, y[1] = -4, y[4] = 56, y[5] = -110(-2)^{n-5} \text{ for } n \geq 5$$