Nonparametric methods

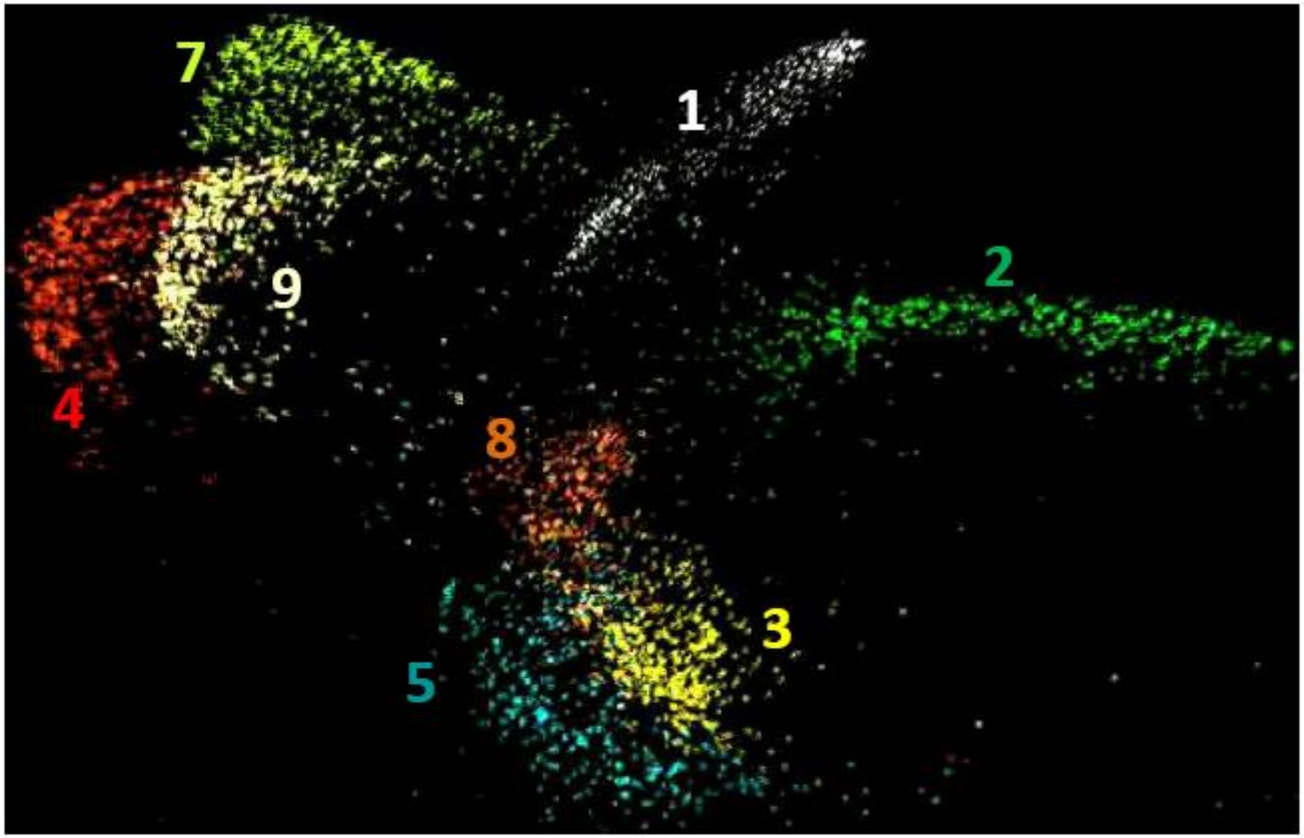
Parametric methods

- Assume some functional form (Gaussian, Bernoulli, Multinomial, logistic, Linear) for
  - $P(X_i|Y)$ and $P(Y)$ as in Naïve Bayes
  - $P(Y|X)$ as in Logistic regression

- Estimate parameters ($\mu,\sigma^2,\theta,w,\beta$) using MLE/MAP and plug in

- **Pro** – need few data points to learn parameters
- **Con** – Strong distributional assumptions, not satisfied in practice

Example



Hand-written digit images

projected as points on a two-dimensional (nonlinear) feature spaces

Non-Parametric methods

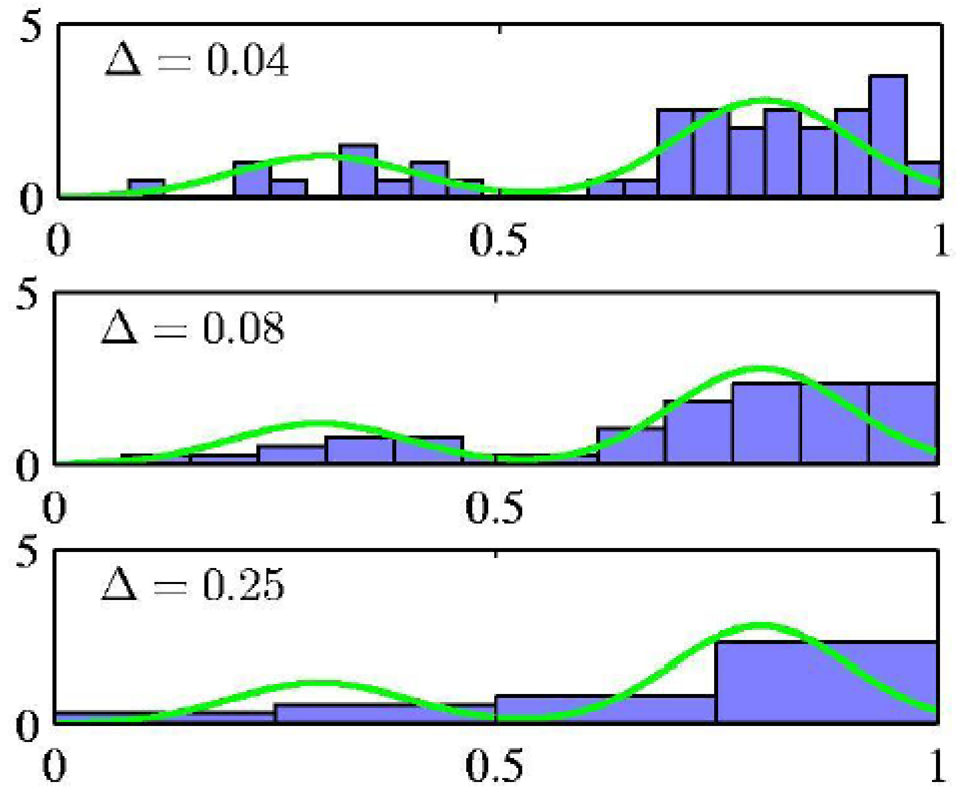
- Typically don’t make any distributional assumptions
- As we have more data, we should be able to learn more complex models
- Let number of parameters scale with number of training data
- Today, we will see some nonparametric methods for
  - Density estimation
  - Classification

Histogram density estimate

Partition the feature space into distinct bins with widths Δ_i and count the number of observations, n_i, in each bin.

$$\widehat{p}(x) = \frac{n_i}{n\Delta_i}\mathbf{1}_{x\in \mathrm{Bin}_i}$$

- Often, the same width is used for all bins, $\Delta_i = \Delta$.
- Δ acts as a smoothing parameter.

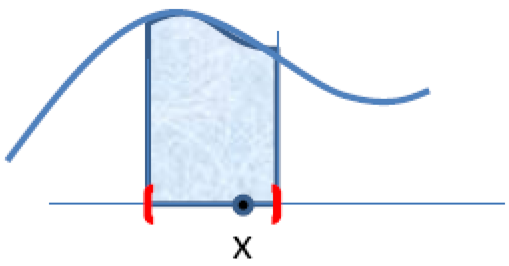


Effect of histogram bin width

$$\widehat{p}(x) = \frac{n_i}{n\Delta}\mathbf{1}_{x\in\mathrm{Bin}_i}$$

bins = 1/Δ

$$\widehat{p}(x) = \frac{1}{\Delta}\frac{\sum_{j=1}^{n}\mathbf{1}_{X_j\in\mathrm{Bin}_x}}{n}$$



Bias of histogram density estimate:

$$\mathbb{E}[\widehat{p}(x)] = \frac{1}{\Delta}P(X\in\mathrm{Bin}_x) = \frac{1}{\Delta}\int_{z\in\mathrm{Bin}_x} p(z)dz \approx \frac{p(x)\Delta}{\Delta} = p(x)$$

Assuming density it roughly constant in each bin
(holds true if Δ is small)

Bias-Variance tradeoff

- Choice of #bins

bins = $1/\Delta$

$$\mathbb{E}[\widehat{p}(x)] \approx p(x) \text{ if } \Delta \text{ is small}$$
(p(x) approx constant per bin)

$$\mathbb{E}[\widehat{p}(x)] \approx \widehat{p}(x) \text{ if } \Delta \text{ is large}$$
(more data per bin, stable estimate)

- **Bias** – how close is the mean of estimate to the truth
- **Variance** – how much does the estimate vary around mean

Small Δ, large #bins $\Leftrightarrow$ "**Small bias**, **Large variance**"

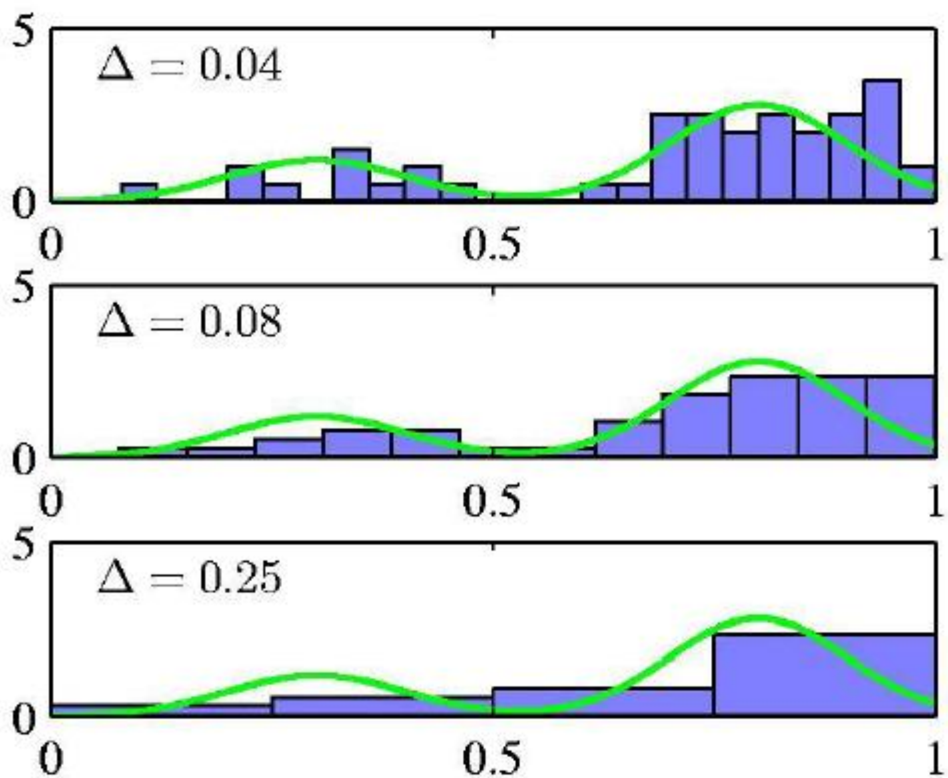
Large Δ, small #bins $\Leftrightarrow$ "**Large bias**, **Small variance**"

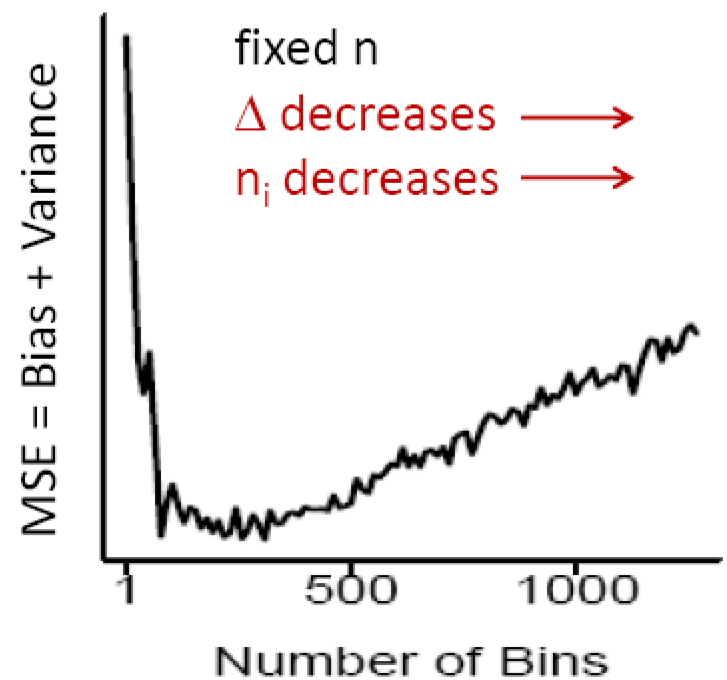
Bias-Variance tradeoff

Choice of #bins

$$\widehat{p}(x) = \frac{n_i}{n\Delta}\mathbf{1}_{x\in \mathrm{Bin}_i}$$

bins = $1/\Delta$





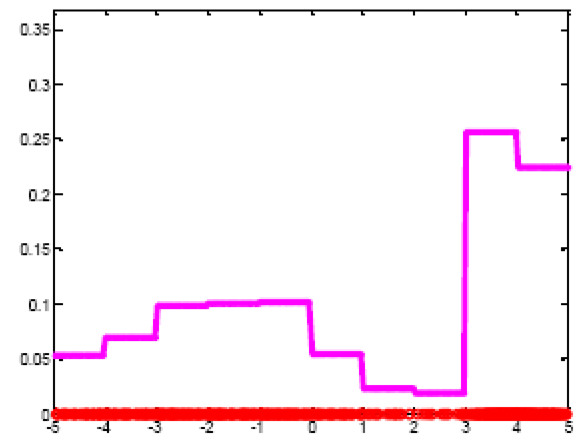
Histogram: Conclusion

- Pro-once computed, the data set itself can be discarded, advantageous if the data set is large; easily applied if the data points are arriving sequentially; a quick visualization of data in one or two dims
- Con-discontinuities on bin edge; $(\#bins)^D$
- Two hints: local; delta

Kernel density estimate

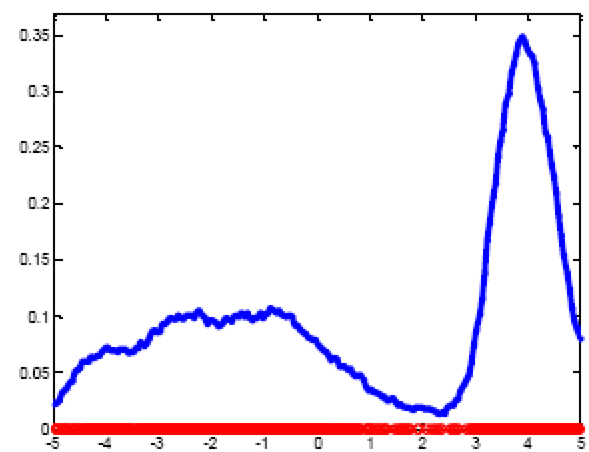
- Histogram – blocky estimate

$$\widehat{p}(x) = \frac{1}{\Delta}\frac{\sum_{j=1}^{n} \mathbf{1}_{X_j \in \text{Bin}_x}}{n}$$



- Kernel density estimate aka "Parzen/moving window method"

$$\widehat{p}(x) = \frac{1}{\Delta}\frac{\sum_{j=1}^{n} \mathbf{1}_{||X_j - x|| \leq \Delta}}{n}$$



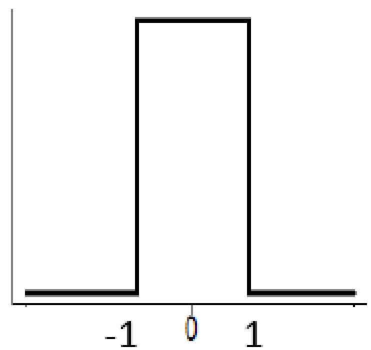
Kernel density estimate

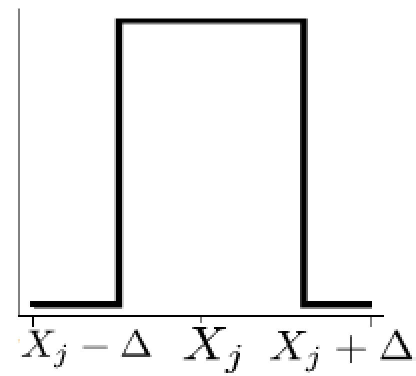
- $\widehat{p}(x) = \frac{1}{\Delta} \frac{\sum_{j=1}^{n} K\left(\frac{X_j - x}{\Delta}\right)}{n}$ more generally

$$K\left(\frac{X_j - x}{\Delta}\right)$$

boxcar kernel :

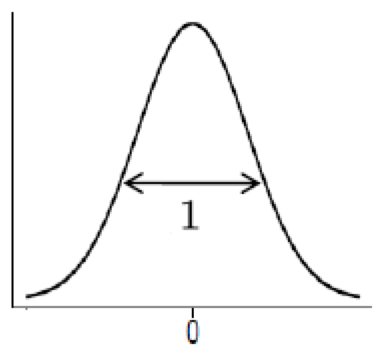
$$K(x) = \frac{1}{2} I(x),$$

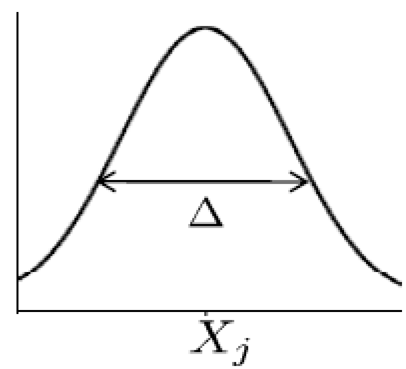




Gaussian kernel :

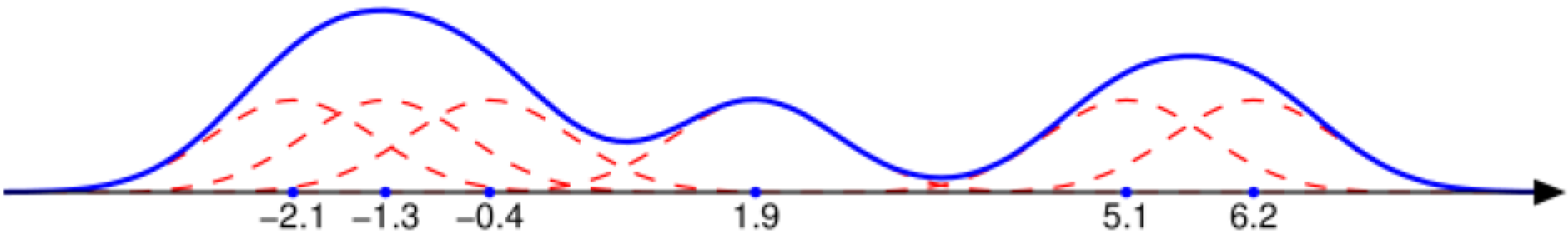
$$K(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$





Kernel density estimate

- Place small "bumps" at each data point, determined by the kernel function.
- The estimator consists of a (normalized) "sum of bumps".



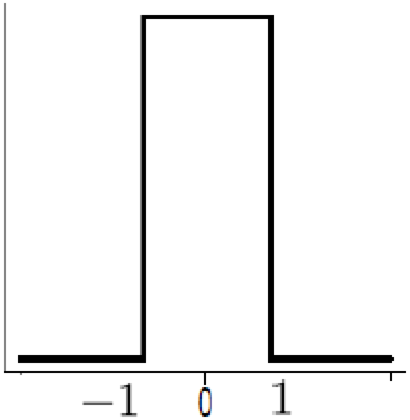
Gaussian bumps (red) around six data points and their sum (blue)

- Note that where the points are denser the density estimate will have higher values.

Kernels

boxcar kernel :

$$K(x) = \frac{1}{2} I(x),$$



Gaussian kernel :

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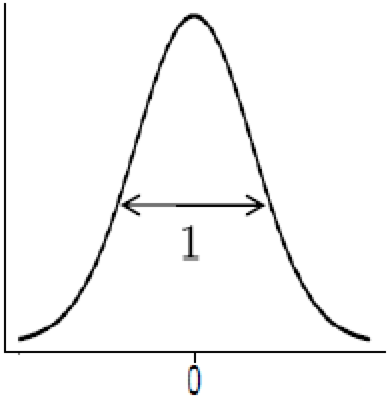


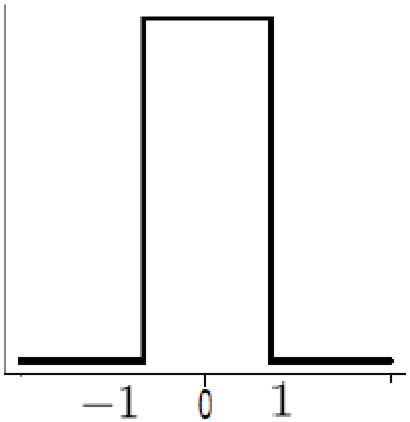
Any kernel function that satisfies

$$\begin{aligned} K(x) &\geq 0, \\ \int K(x)dx &= 1 \end{aligned}$$

Kernels

boxcar kernel :

$$K(x) = \frac{1}{2} I(x),$$

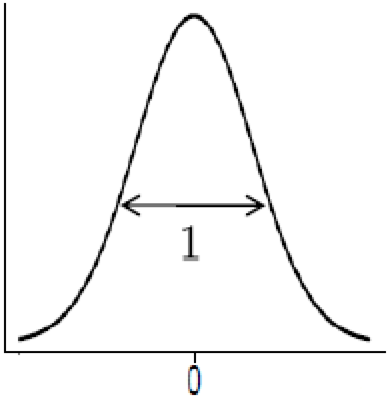


Finite support

– only need local points to compute estimate

Gaussian kernel :

$$K(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$

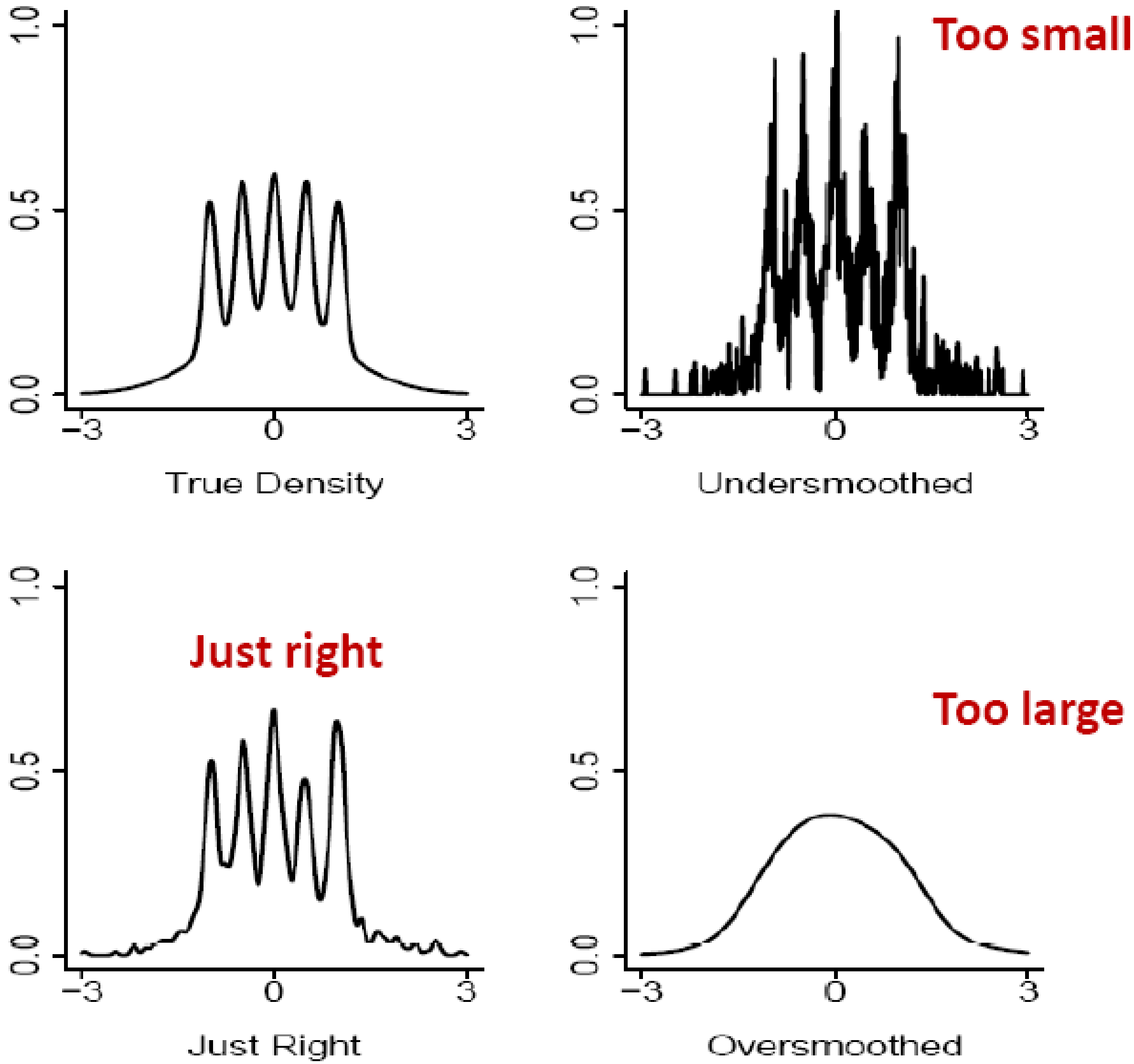


Infinite support

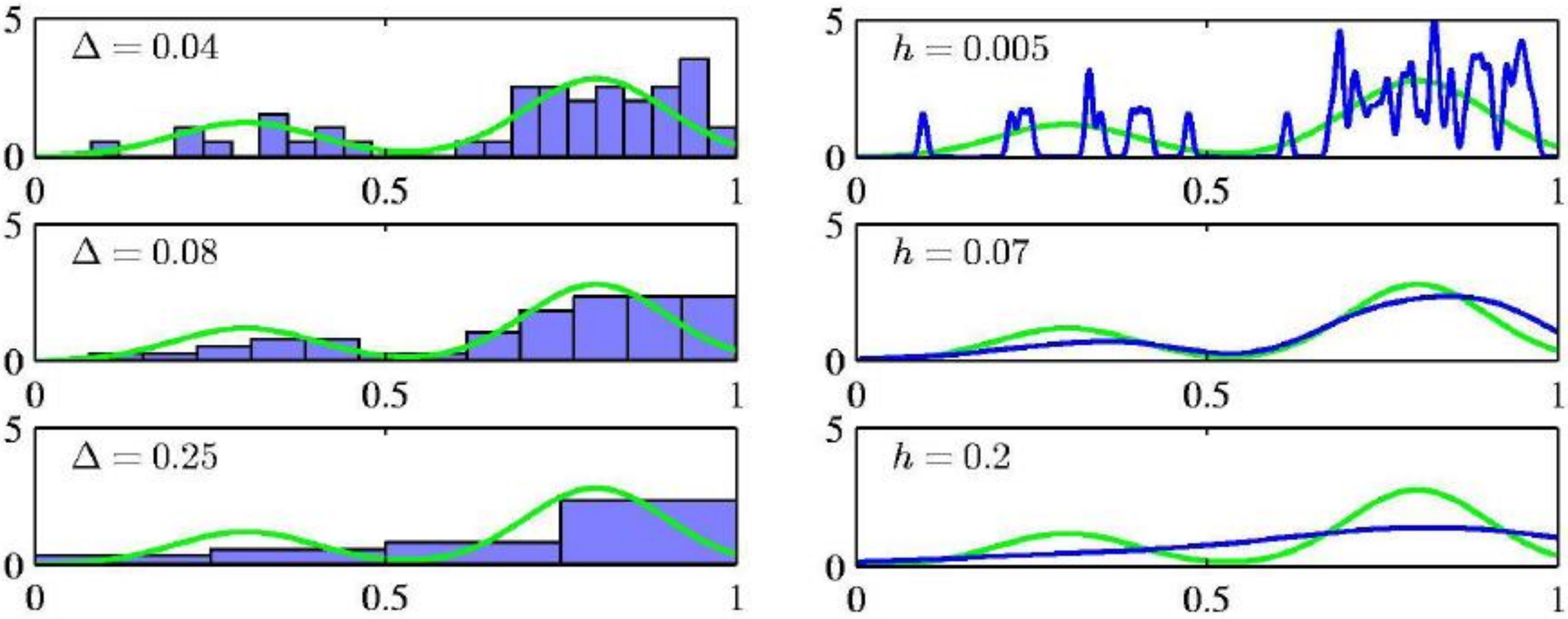
- need all points to compute estimate

-But quite popular since smoother

Choice of kernel bandwidth



Histograms vs. Kernel density estimation



$\Delta = h$ acts as a smoother.

K-NN(Nearest Neighbor) density estimation

- Histogram $$\widehat{p}(x) = \frac{n_i}{n\Delta}\mathbf{1}_{x\in \text{Bin}_i}$$
- Kernel density est $$\widehat{p}(x) = \frac{n_x}{n\Delta}$$

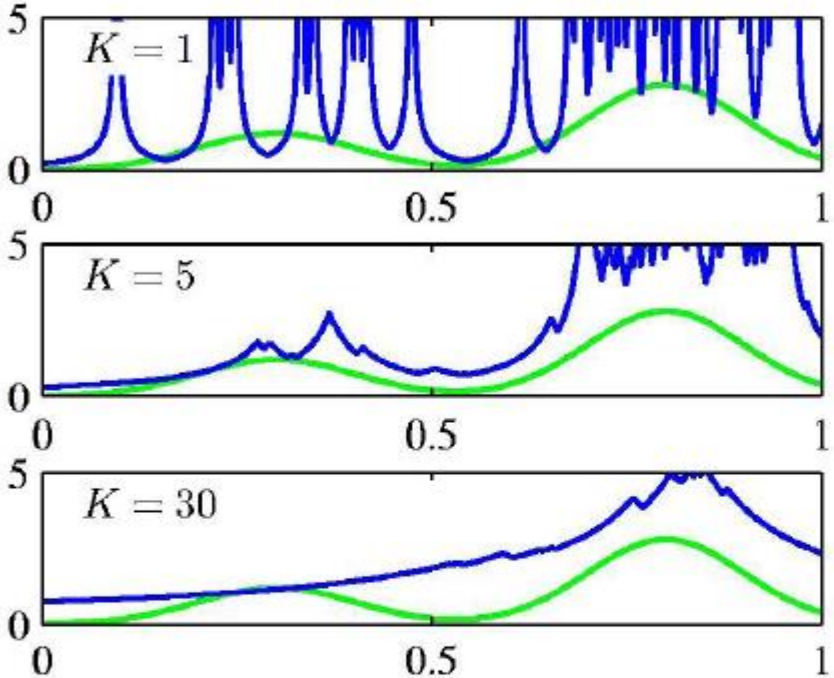
  Fix Δ, estimate number of points within Δ of x (n_i or n_x) from data

  Fix $n_x = k$, estimate Δ from data (volume of ball around x that contains k training pts)

- k-NN density est $$\widehat{p}(x) = \frac{k}{n\Delta_{k,x}}$$

K-NN density estimation

$$\widehat{p}(x) = \frac{k}{n\Delta_{k,x}}$$



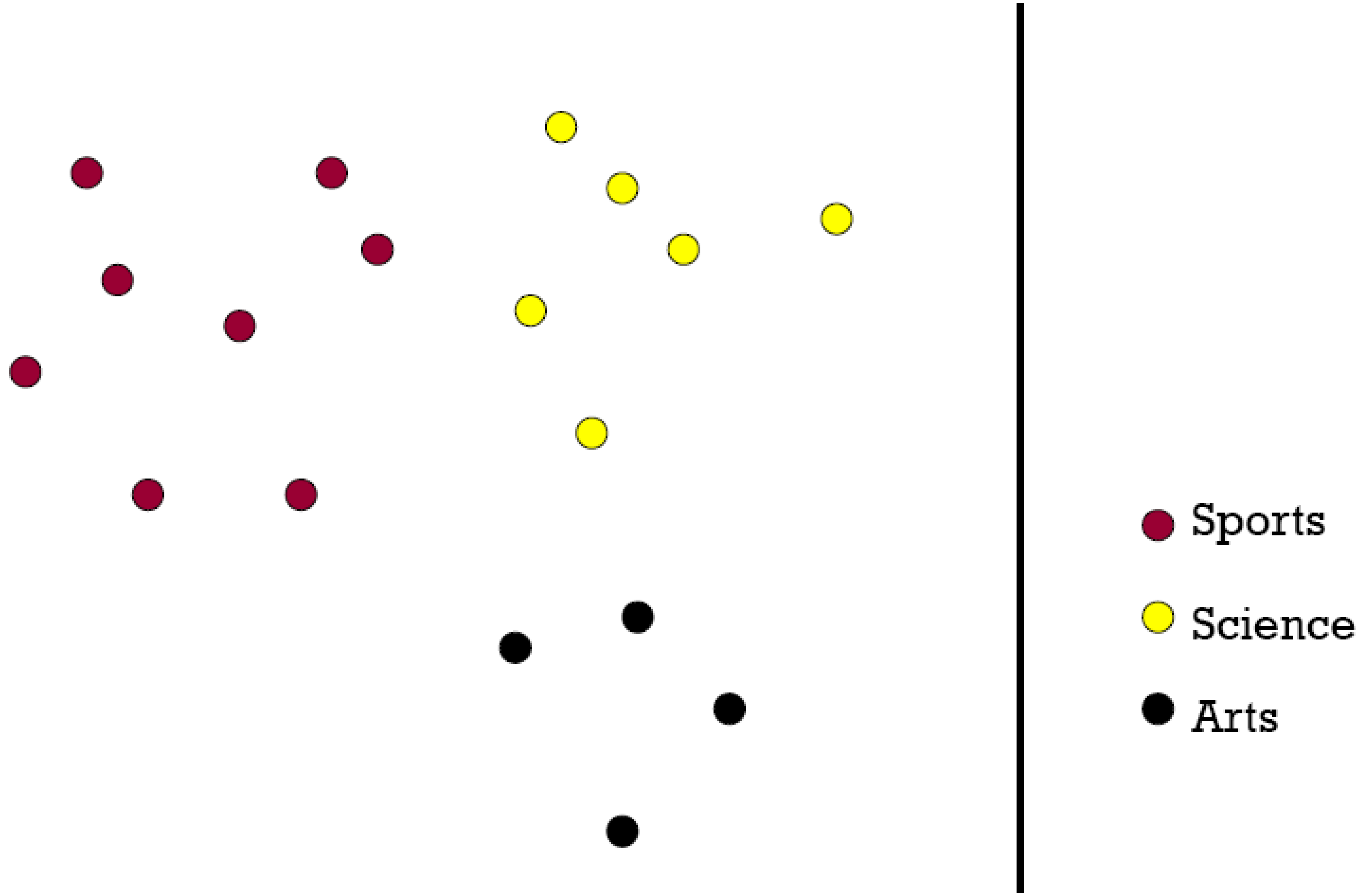
k acts as a smoother.

Not very popular for density estimation - expensive to compute, bad estimates

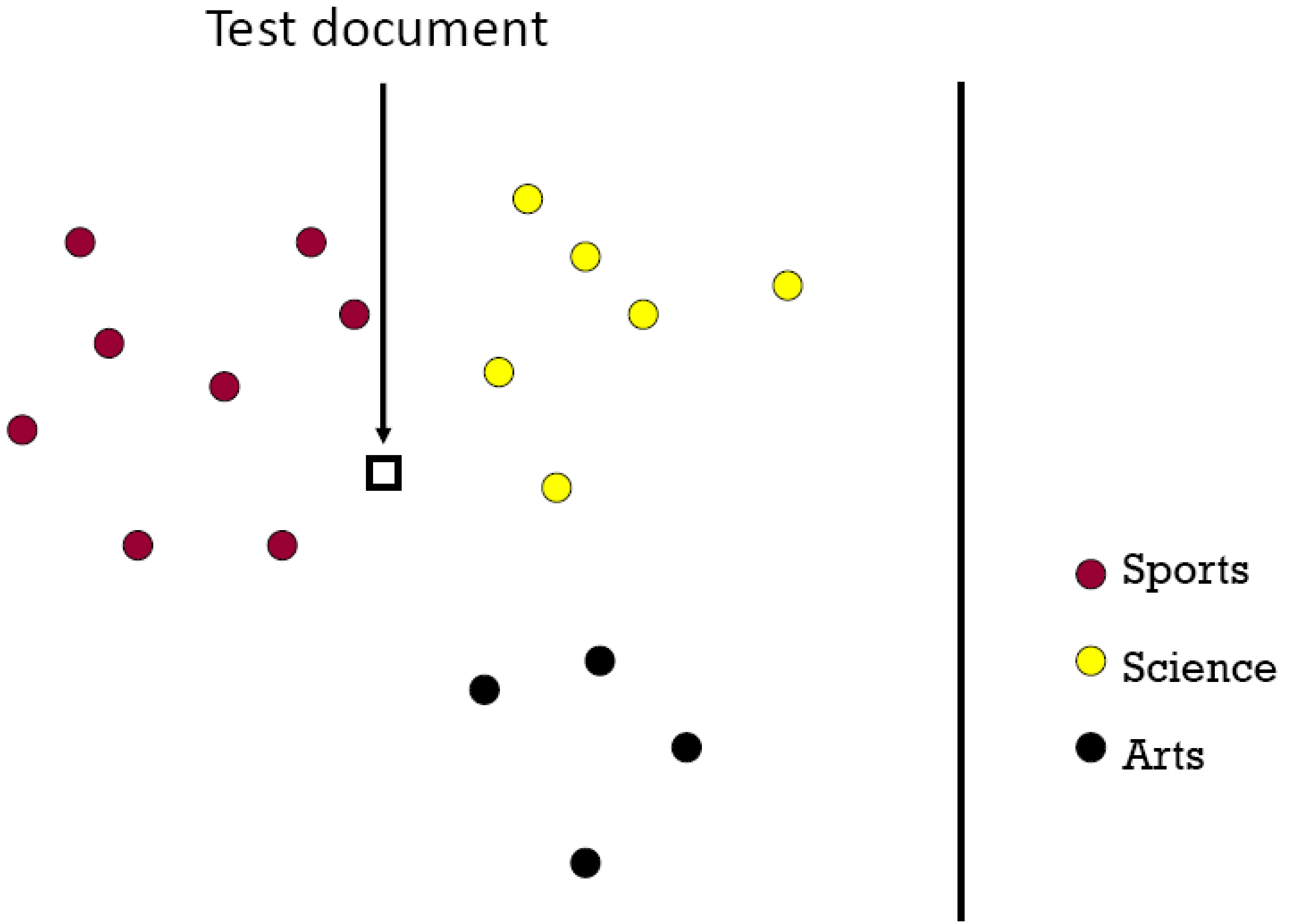
But a related version for classification quite popular …

From
Density estimation
to
Classification

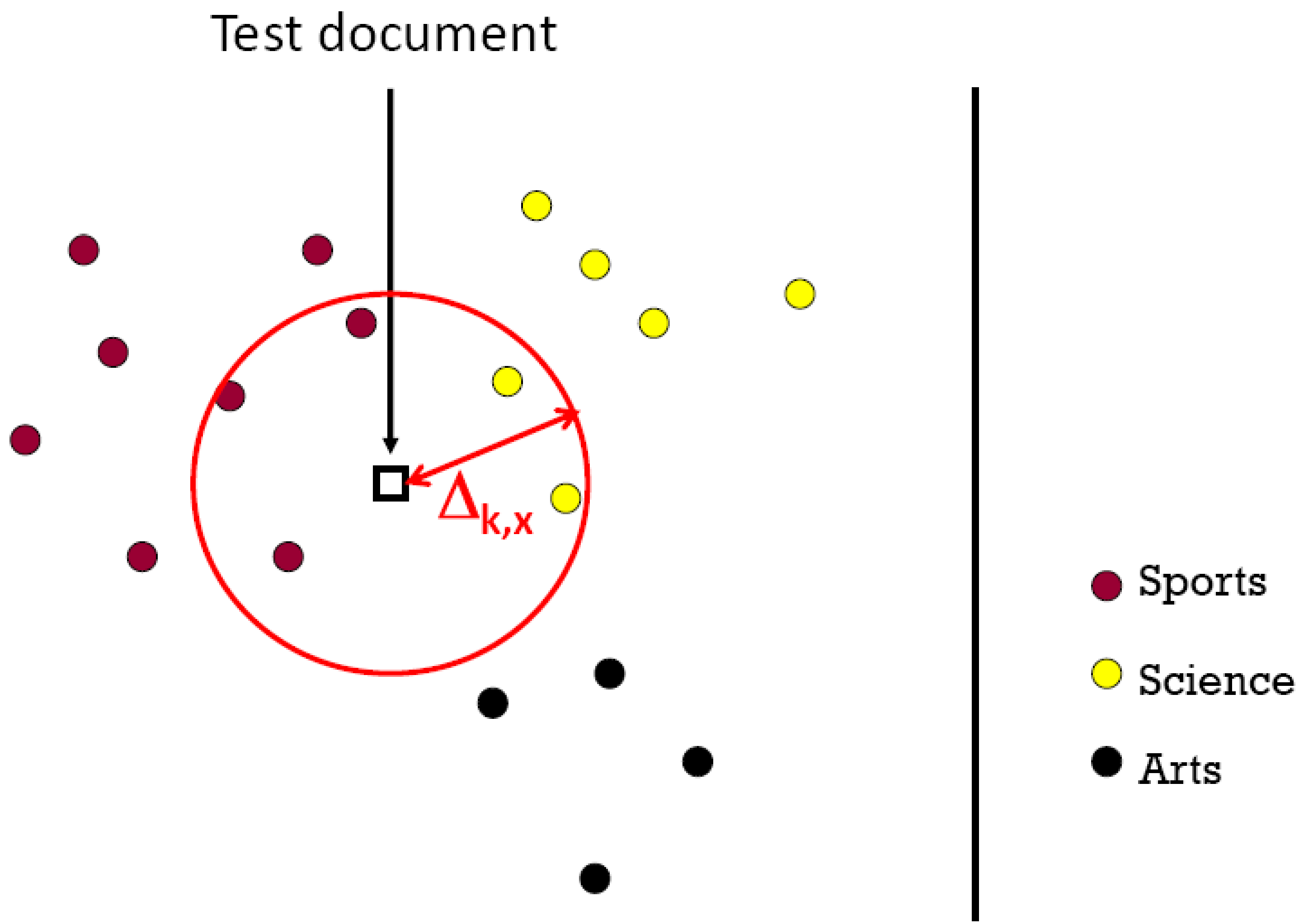
K-NN classifier



K-NN classifier



K-NN classifier (K=5)



What should we predict? ... Average? Majority? Why?

K-NN classifier

- Optimal Classifier: $$\begin{aligned} f^*(x) &= \arg\max_y P(y|x) \\ &= \arg\max_y p(x|y)P(y) \end{aligned}$$

- k-NN Classifier: $$\begin{aligned} \widehat{f}_{kNN}(x) &= \arg\max_y \ \widehat{p}_{kNN}(x|y)\widehat{P}(y) \\ &= \arg\max_y \ k_y \end{aligned}$$ (Majority vote)

$$\widehat{p}_{kNN}(x|y) = \frac{k_y}{n_y \Delta_{k,x}}$$

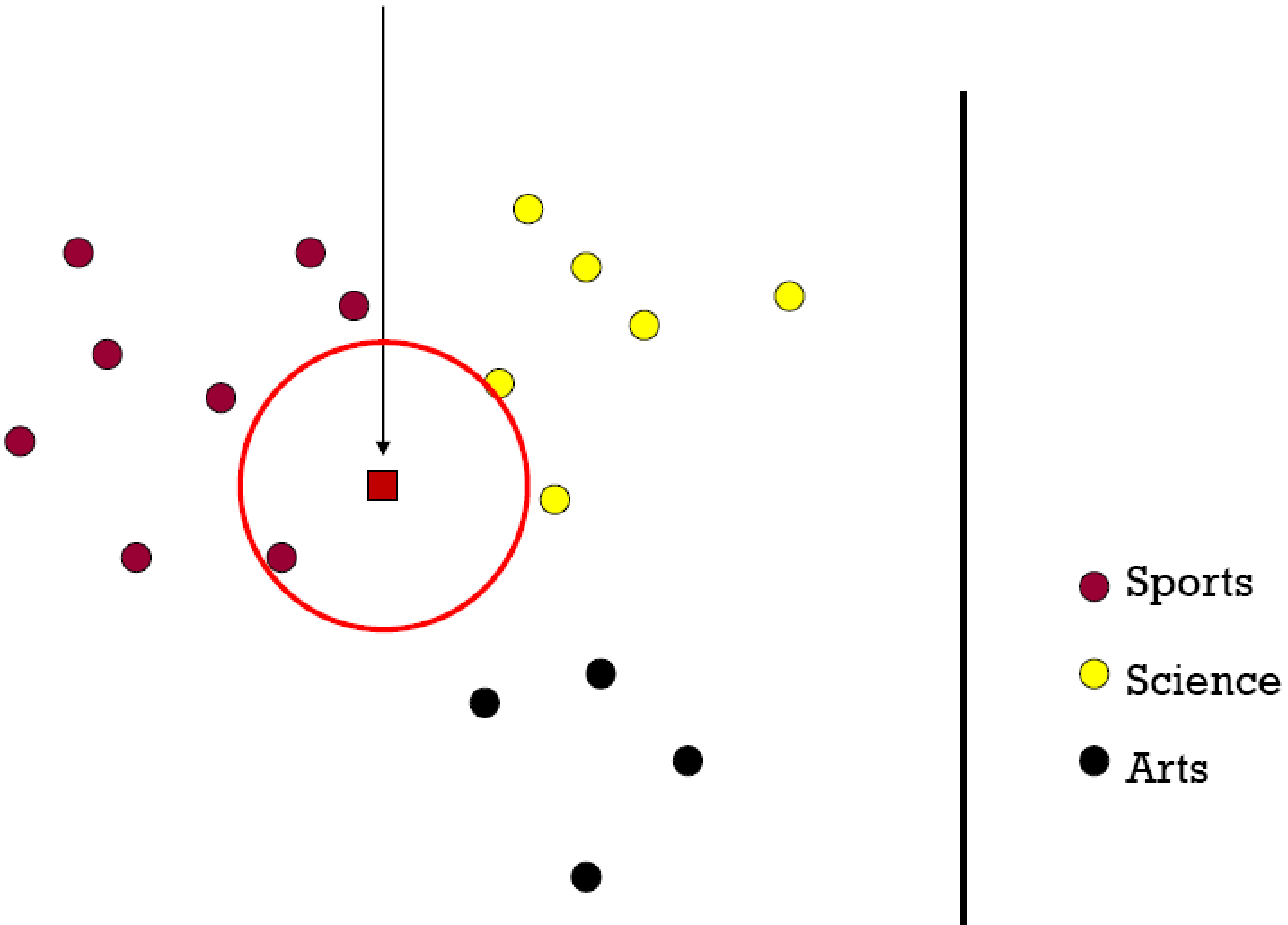
k_y: # training pts of class y that lie within Δ_k ball

n_y: # total training pts of class y

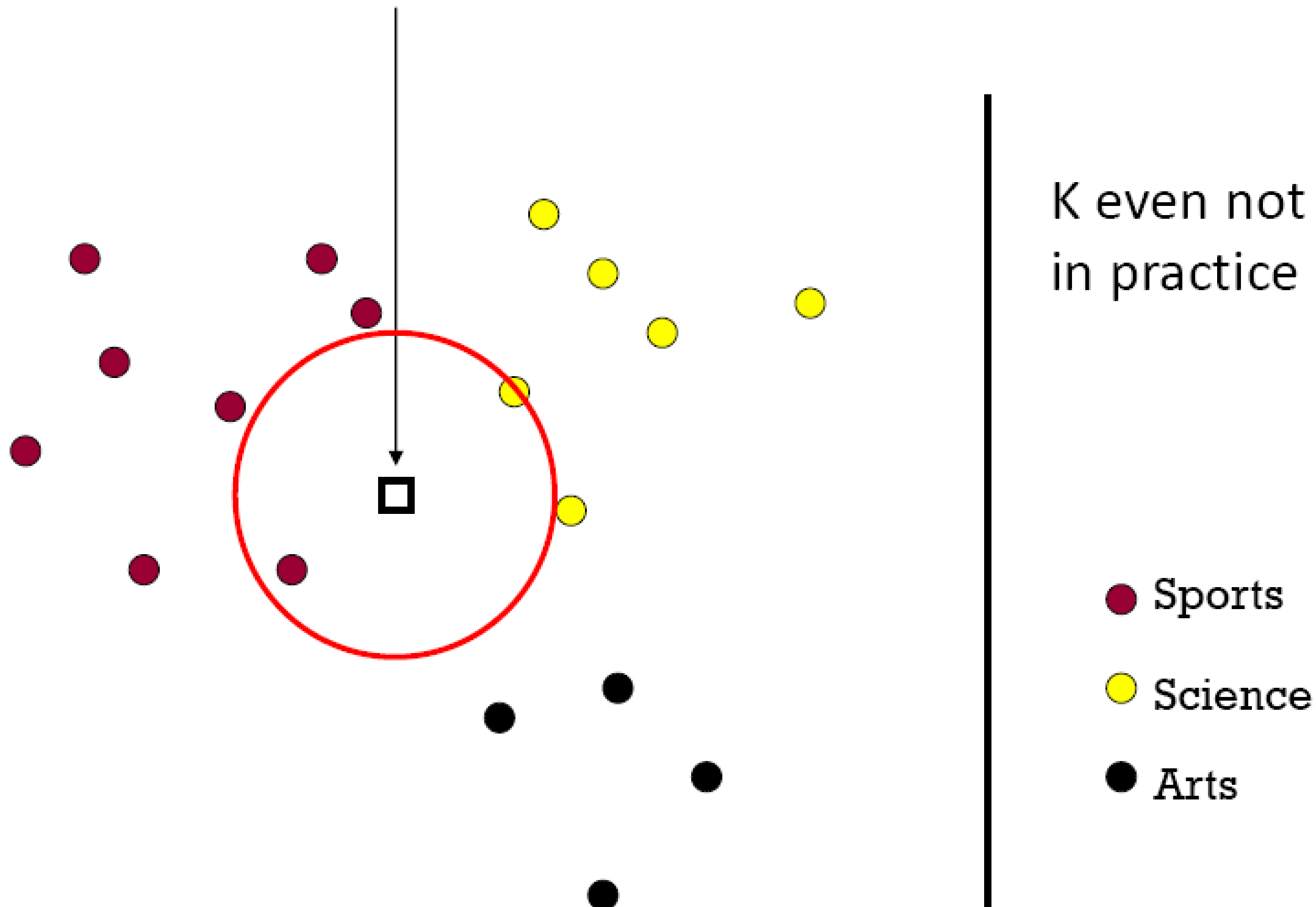
$$\sum_y k_y = k$$

$$\widehat{P}(y) = \frac{n_y}{n}$$

1-Nearest Neighbor (kNN) classifier

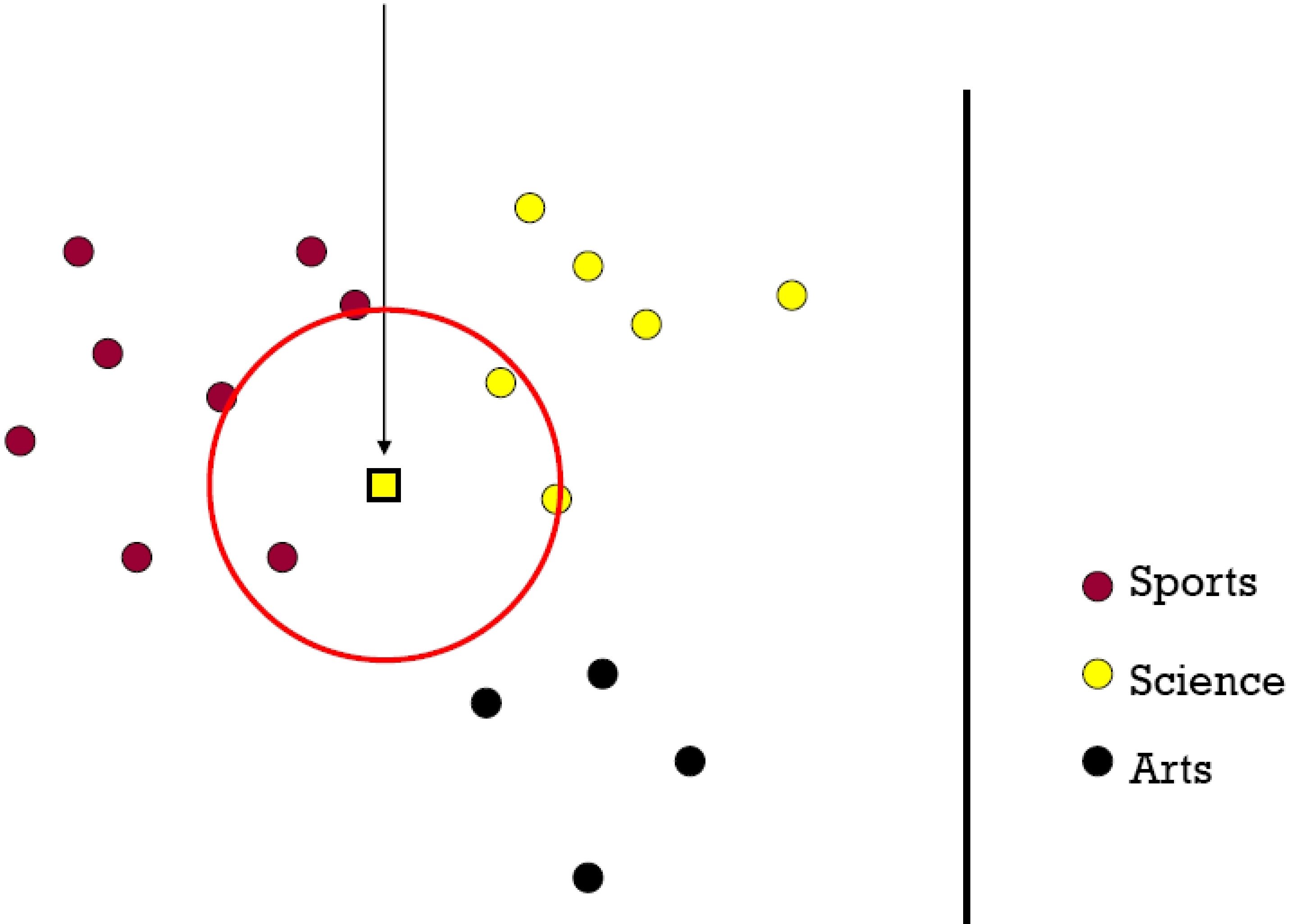


2-Nearest Neighbor (kNN) classifier

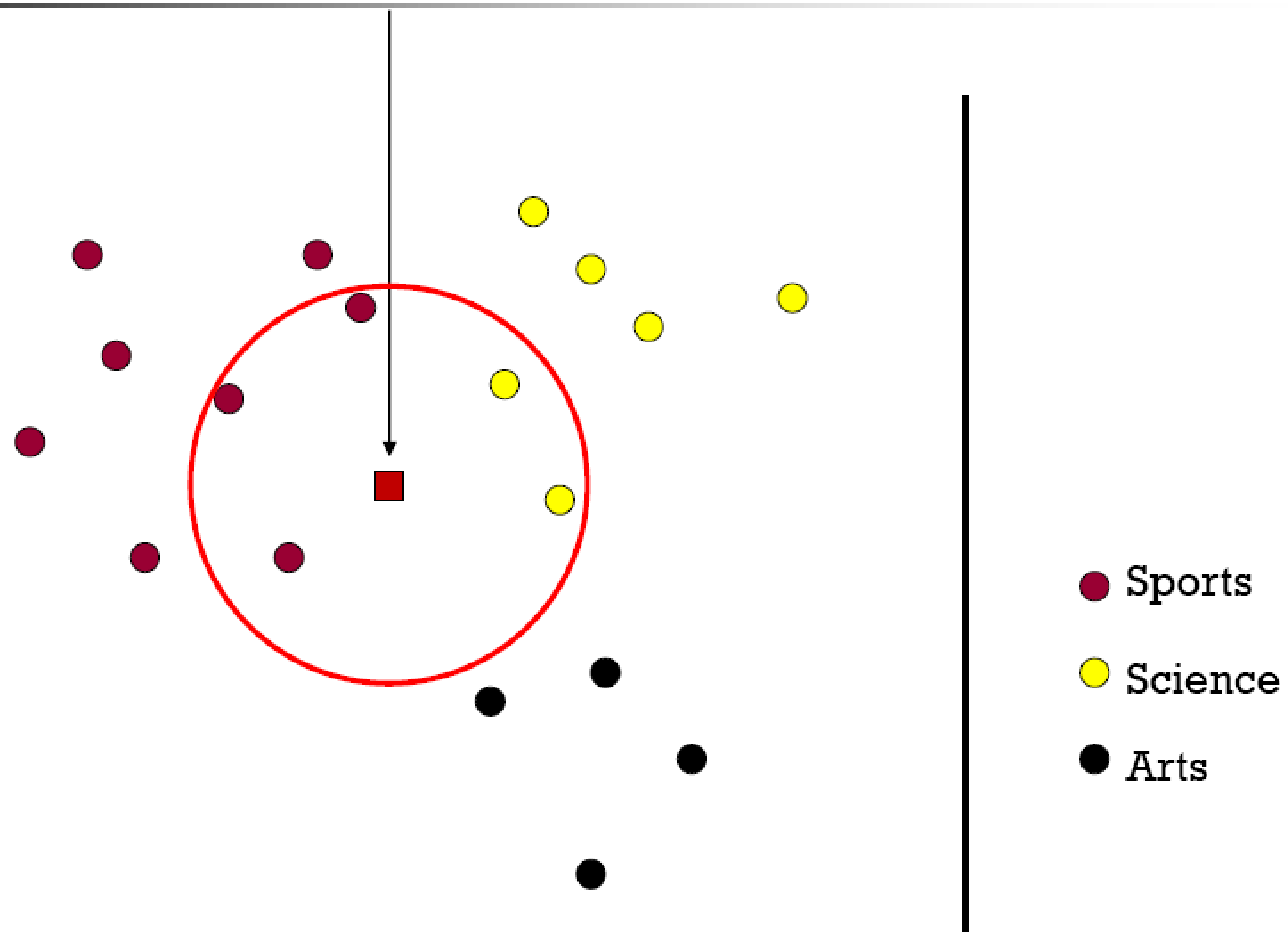


K even not used in practice

3-Nearest Neighbor (kNN) classifier



5-Nearest Neighbor (kNN) classifier



What is the best K?

Bias-variance tradeoff

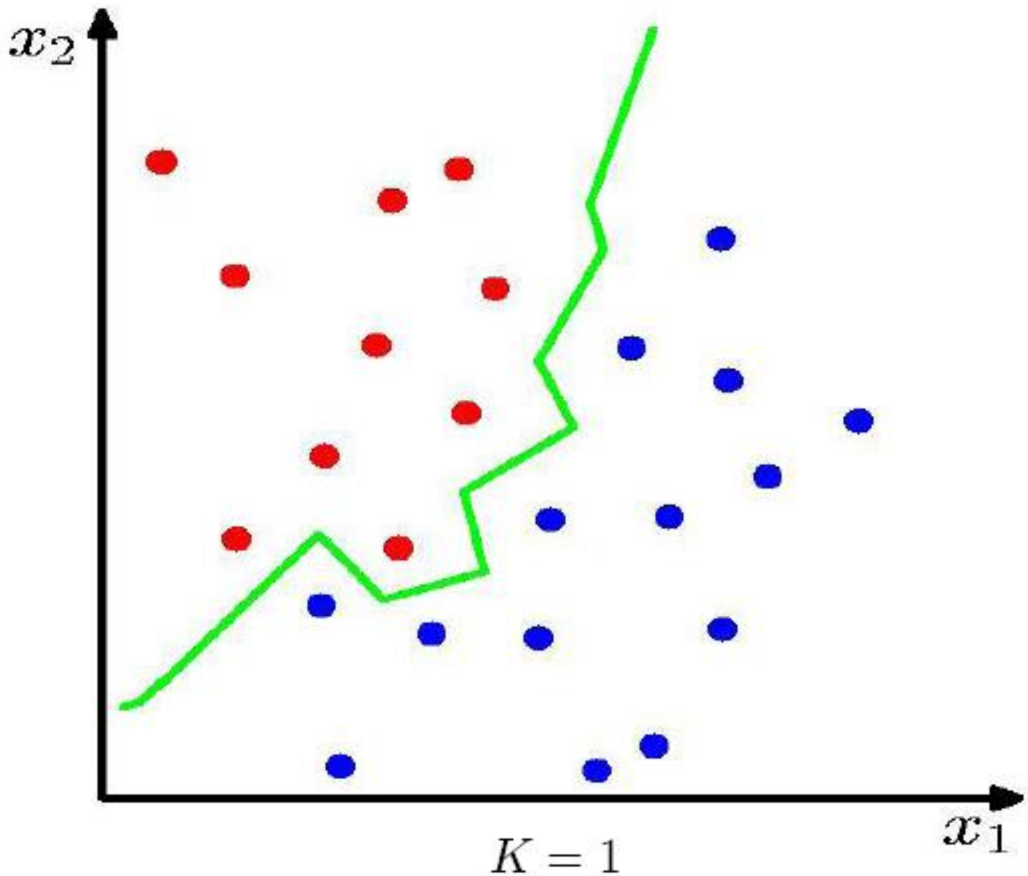
Larger K => predicted label is more stable

Smaller K => predicted label is more accurate

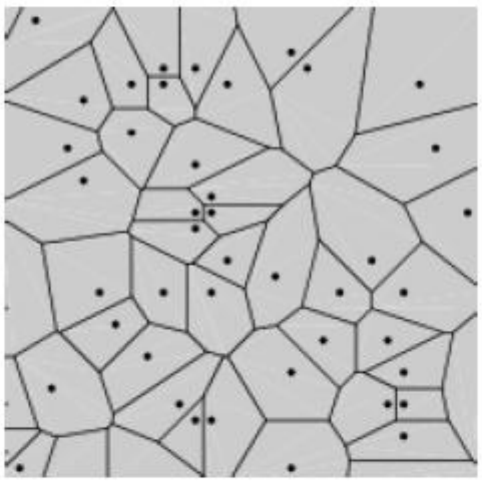
Similar to density estimation

Choice of K - in next class ...

1-NN classifier – decision boundary

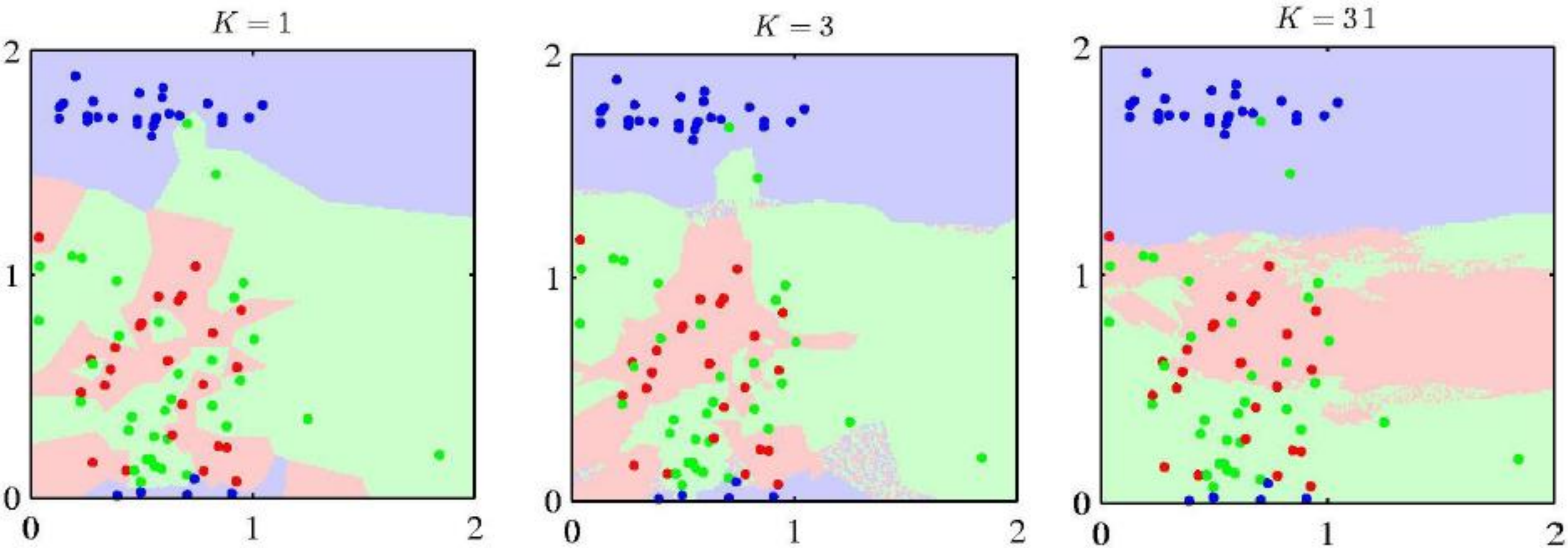


Voronoi Diagram



- Guarantee: For $n \to \infty$, the error rate of the 1-nearest-neighbour classifier is never more than twice the optimal error.

k-NN classifier – decision boundary



- K acts as a smoother (Bias-variance tradeoff)

Case Study: kNN for Web Classification

- Dataset
  - 20 News Groups (20 classes)
  - Download :(http://people.csail.mit.edu/jrennie/20Newsgroups/)
  - 61,118 words, 18,774 documents
  - Class labels descriptions

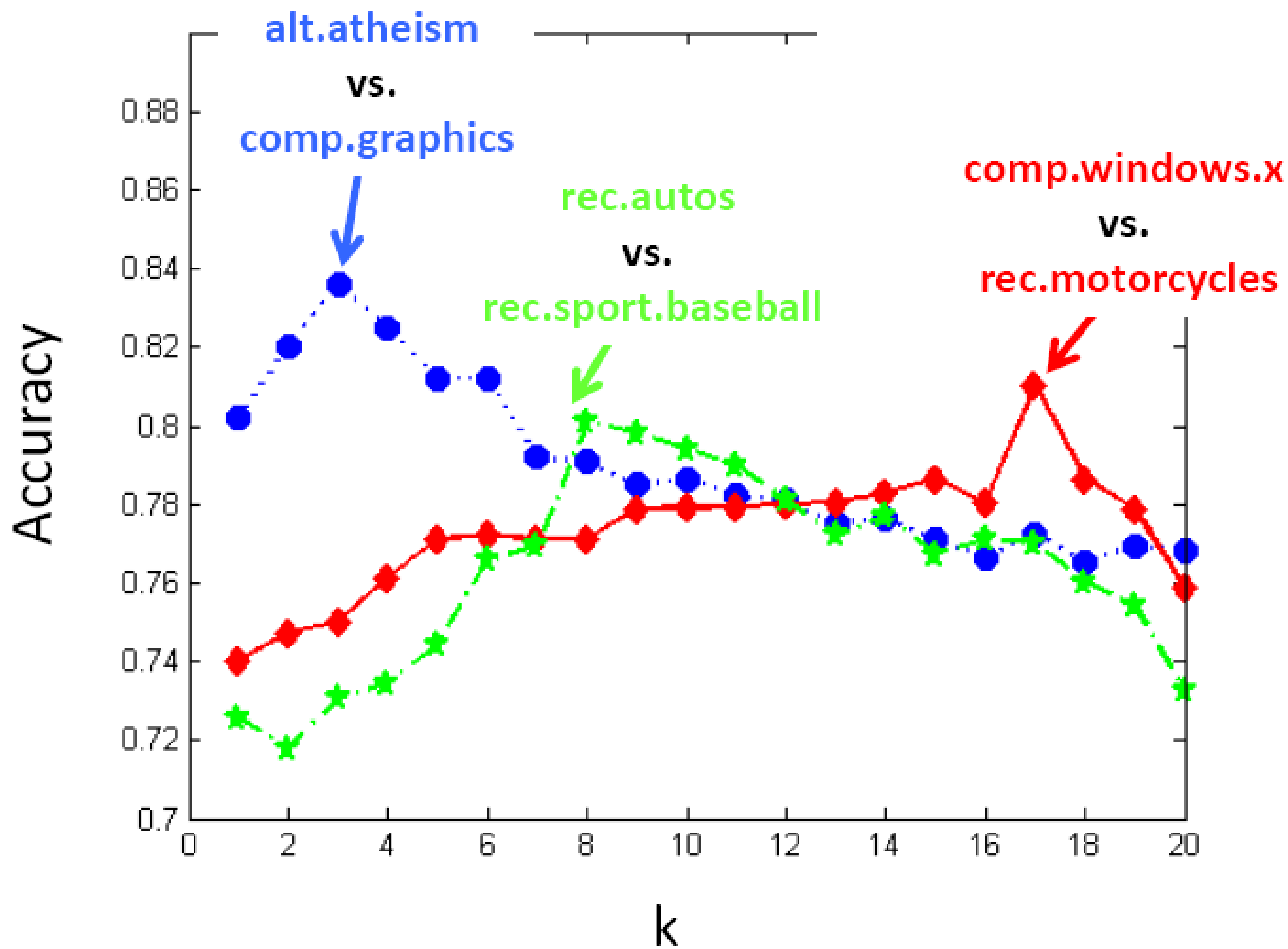
comp.graphics comp.os.ms-windows.misc comp.sys.ibm.pc.hardware comp.sys.mac.hardware comp.windows.x	rec.autos rec.motorcycles rec.sport.baseball rec.sport.hockey	sci.crypt sci.electronics sci.med sci.space
misc.forsale	talk.politics.misc talk.politics.guns talk.politics.mideast	talk.religion.misc alt.atheism soc.religion.christian

Experimental Setup

- Training/Test Sets:
  - 50%-50% randomly split.
  - 10 runs
  - report average results
- Evaluation Criteria:

$$Accuracy = \frac{\sum_{i \in test\ set} \mathrm{I}(predict_i == true\ label_i)}{\#\ of\ test\ samples}$$

Results: Binary Classes



Summary

- Instance based/non-parametric approaches

Four things make a memory based learner:

1. *A distance metric, dist(x,X_i)*

   Euclidean (and many more)

2. *How many nearby neighbors/radius to look at?*

   k, Δ/h

3. *A weighting function (optional)*

   W based on kernel K

4. *How to fit with the local points?*

   Average, Majority vote, Weighted average, Poly fit

Summary

- Parametric vs Nonparametric approaches
  - Nonparametric models place very mild assumptions on the data distribution and provide good models for complex data

    Parametric models rely on very strong (simplistic) distributional assumptions

  - Nonparametric models (not histograms) requires storing and computing with the entire data set.

    Parametric models, once fitted, are much more efficient in terms of storage and computation.

What you should know…

- Histograms, Kernel density estimation
  - Effect of bin width/ kernel bandwidth
  - Bias-variance tradeoff

- K-NN classifier
  - Nonlinear decision boundaries