Experiment No: 04

BECS 31421

INTERRUPT HANDLING WITH A PIC MICROCONTROLLER EXERCISE

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SOURCE CODE

```
// STEP 1: DECLARE THE MAIN FUNCTION
INT A = 50;
INT B = 200;
INT TEMP;
VOID MAIN()
  // STEP 2: INITIALIZE CONFIGURATION SETTINGS
  TRISB = 0X01; // HINT: SET RBO AS INPUT, OTHERS AS OUTPUT
  TRISA = 0X00; // HINT: SET ALL PORT A PINS AS OUTPUT
  CMCON = 0X07; // HINT: DISABLE COMPARATORS
  OPTION_REG = 0X00; // HINT: CONFIGURE OPTION REGISTER
  // STEP 3: ENABLE INTERRUPTS
  INTOON.GIE = 1; // HINT: ENABLE GLOBAL INTERRUPTS
  INTOONPEIE = 1; // HINT: ENABLE PERIPHERAL INTERRUPTS
  INTOONINTE = 1; // HINT: ENABLE RBO/INT INTERRUPT
  // STEP 4: DEFINE THE INFINITE LOOP
  WHILE (1){ // HINT: ENTER AN APPROPRIATE CONDITION FOR THE LOOP
    // STEP 5: SET INITIAL PORT VALUES
     PORTBRB2 = 0; // HINT: SET RB2 TO LOW
     PORTARAO = 1: // HINT: SET RAO TO HIGH
     PORTARA1 = 0; // HINT: SET RA1 TO LOW
     IF (A == 50) DELAY_MS(50);
     ELSE IF (A == 200) DELAY_MS(200);
     // STEP 6: TOGGLE PORT VALUES
     PORTARAO = 0; // HINT: SET RAO TO LOW
     PORTARA1 = 1; // HINT: SET RA1 TO HIGH
     IF (A == 50) DELAY_MS(50);
```

```
ELSE IF (A == 200) DELAY_MS(200);
     INTOONINTF = 0; // HINT: CLEAR THE EXTERNAL INTERRUPT FLAG
  }
}
  // STEP 7: INTERRUPT SERVICE ROUTINE
VOID INTERRUPT() {
IF (INTOONINTF) { // HINT: CHECK THE EXTERNAL INTERRUPT FLAG (INTOONINTF)
     // STEP 8: SET PORT VALUES UPON INTERRUPT
    PORTBRB1 = 1; // HINT: SET RB1 TO HIGH
    PORTB:RB2 = 0; // HINT: SET RB2 TO LOW
     IF (B == 50) DELAY_MS(50);
     ELSE IF (B == 200) DELAY_MS(200);
     // STEP 9: TOGGLE PORT VALUES
     PORTBRB1 = 0; // HINT: SET RB1 TO LOW
     PORTBRB2 = 1; // HINT: SET RB2 TO HIGH
     IF (B == 50) DELAY_MS(50);
     ELSE IF (B == 200) DELAY_MS(200);
     TEMP = A:
      A = B_{i}
      B = TEMP:
      INTOONINTF = 0; // HINT: CLEAR THE EXTERNAL INTERRUPT FLAG
  }
}
```

SIMULATION SCREENSHOTS







