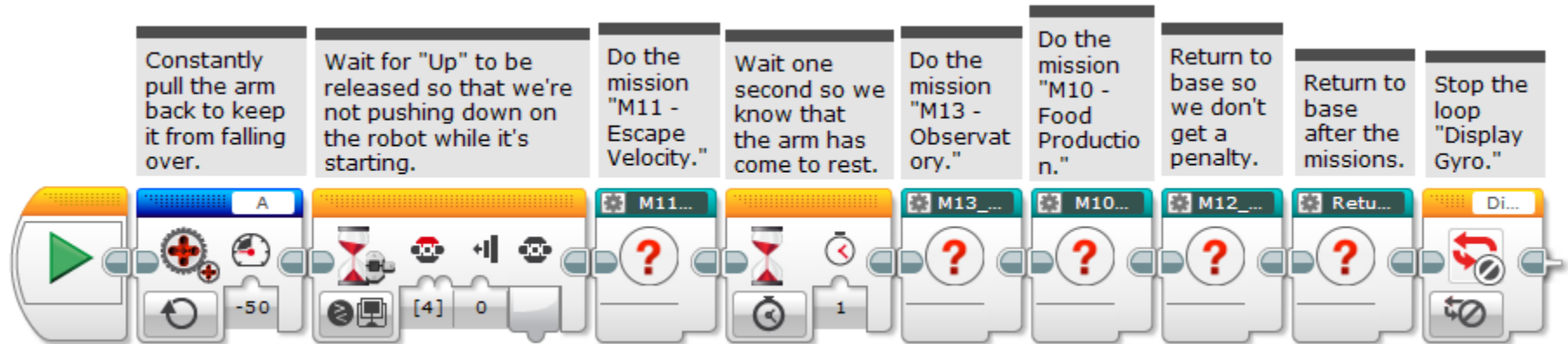
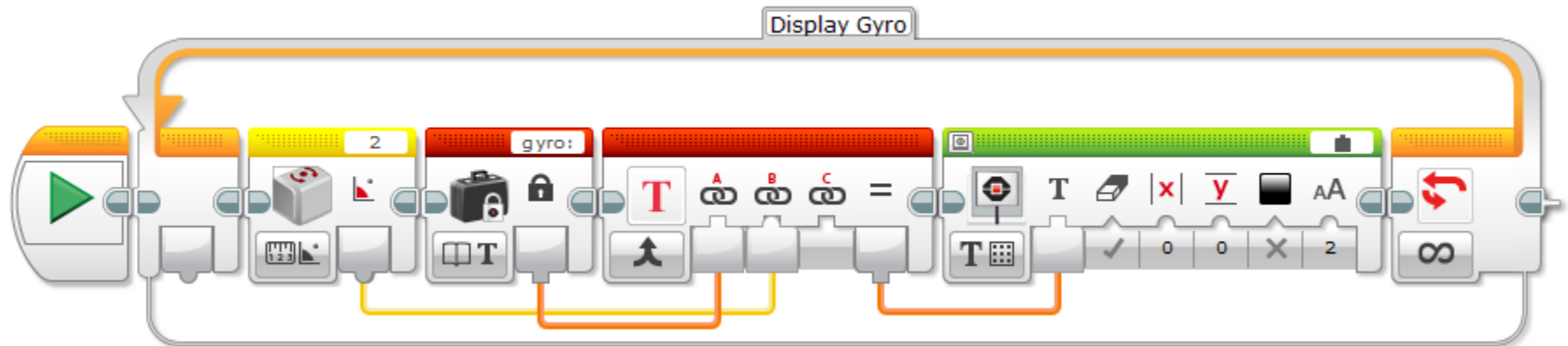


## Contents

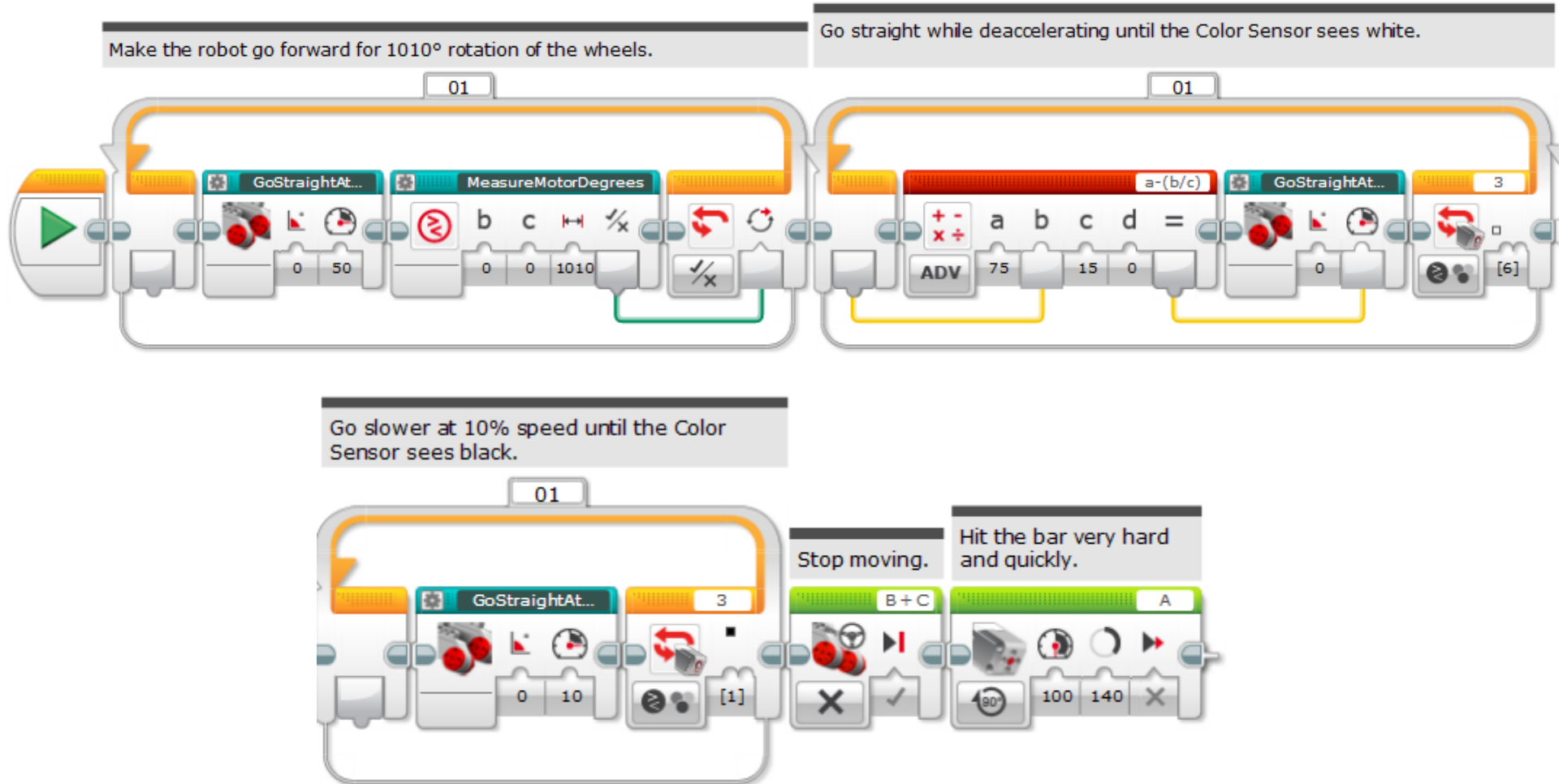
001 .....	2
M11_Escape_Velocity .....	3
M13_Observatory .....	4
M10_Food_Production .....	5
M12_Satellite_Orbits .....	6
ReturnToBase_M12_M00 .....	7
Escape_Velocity_2 .....	8
Observatory_2 .....	9
Return_to_Base_M10_M00 .....	10
Food_Production_2 .....	11
M02_Solar_Panel_Array .....	12
M01_SpaceTravel .....	13
M05_Extraction .....	14
M03_3DPrinting .....	16
Other SPA (other team's Solar Panel Array) .....	18
MENU .....	20



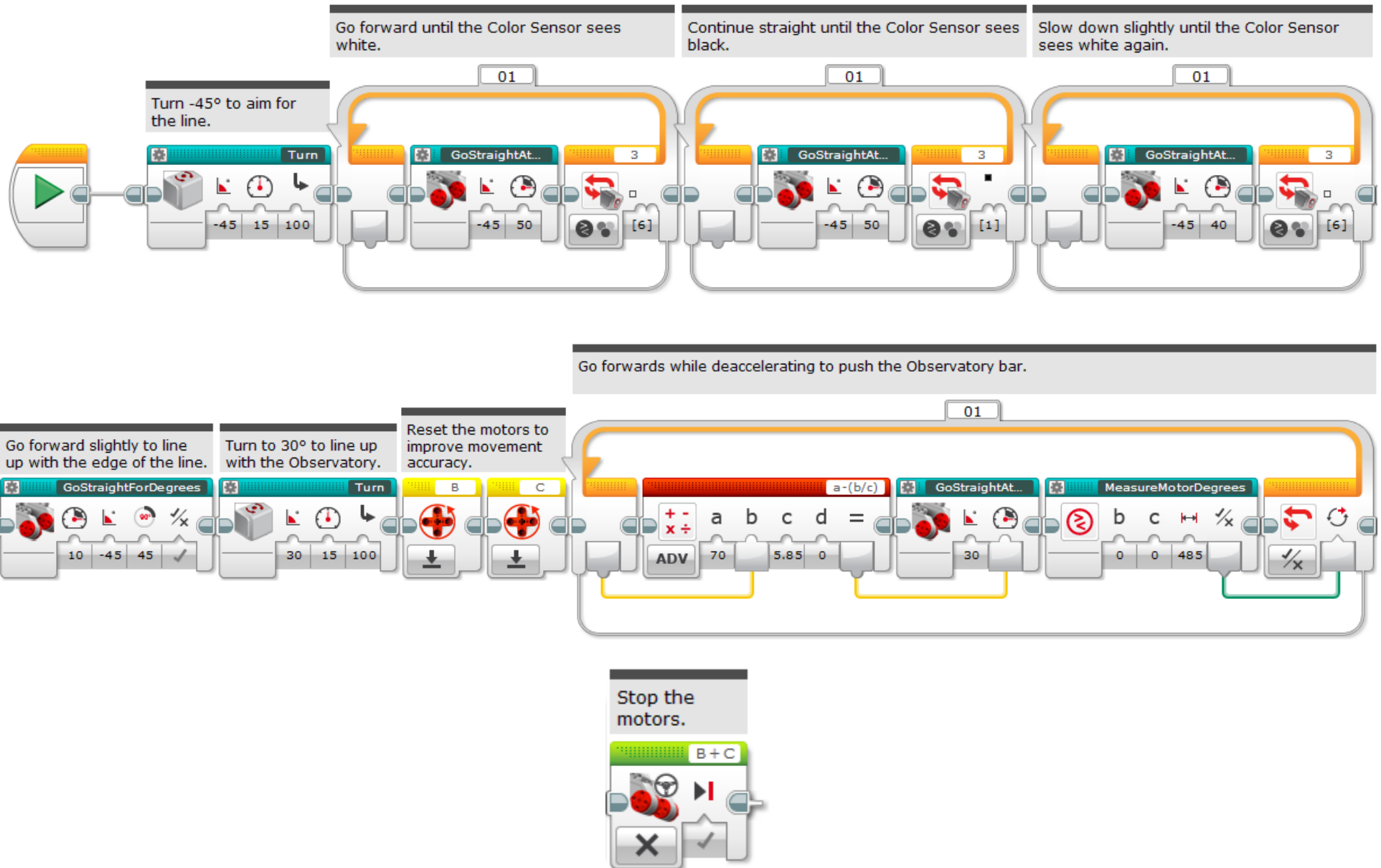
Display the Gyro Sensor's current angle on the screen for debugging purposes.



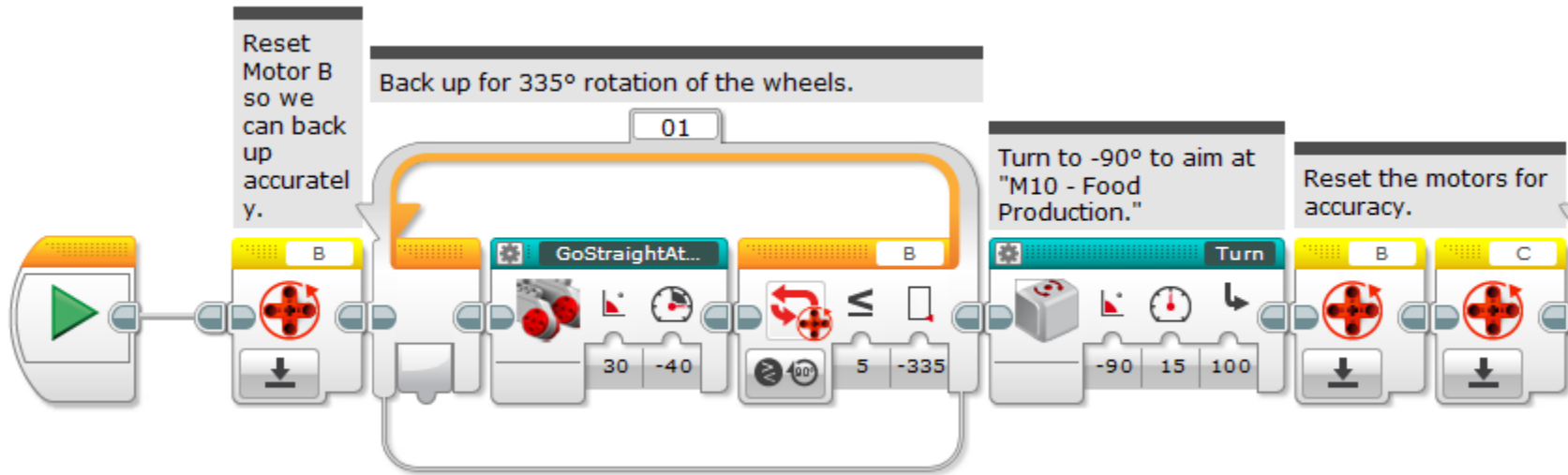
## M11\_Escape\_Velocity



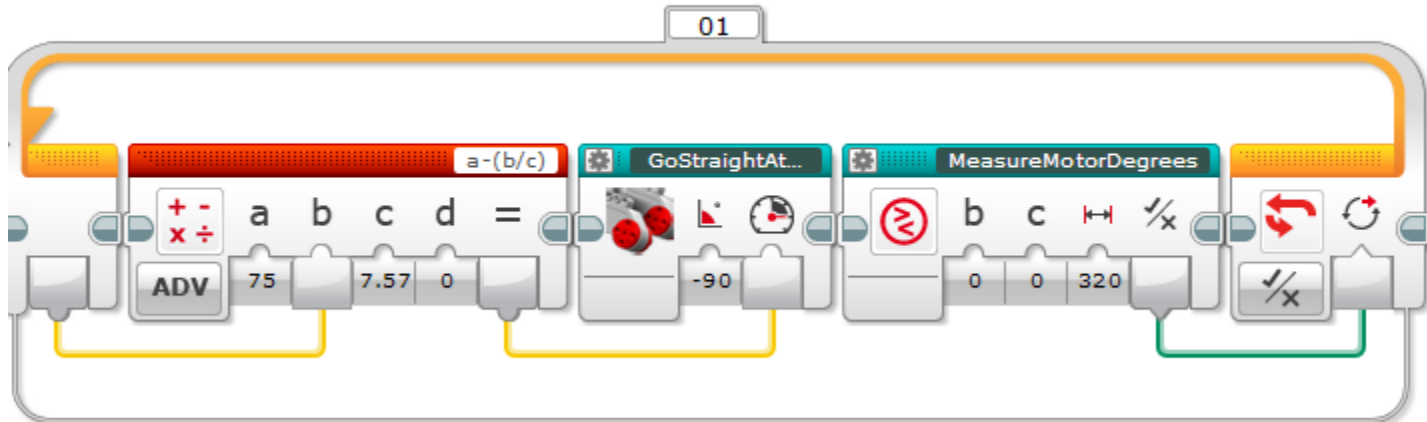
## M13\_Observatory



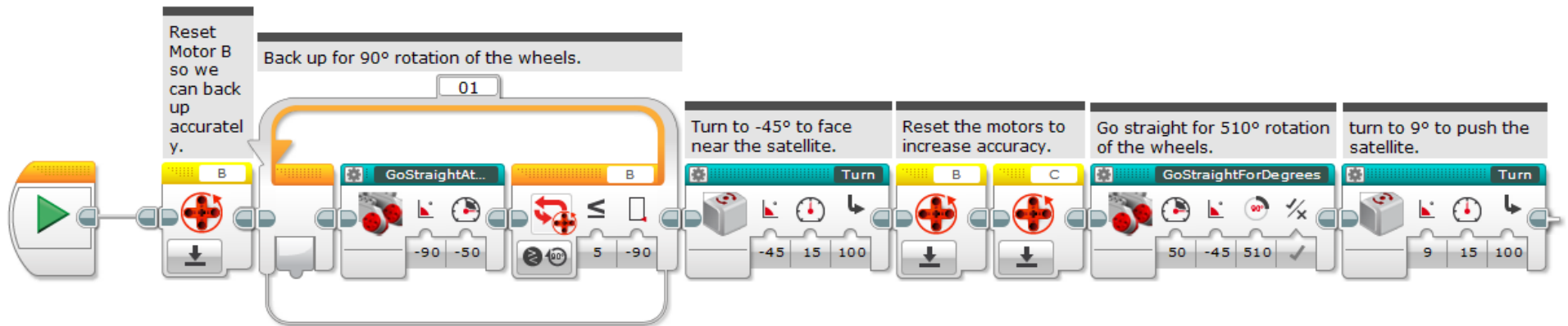
## M10\_Food\_Production



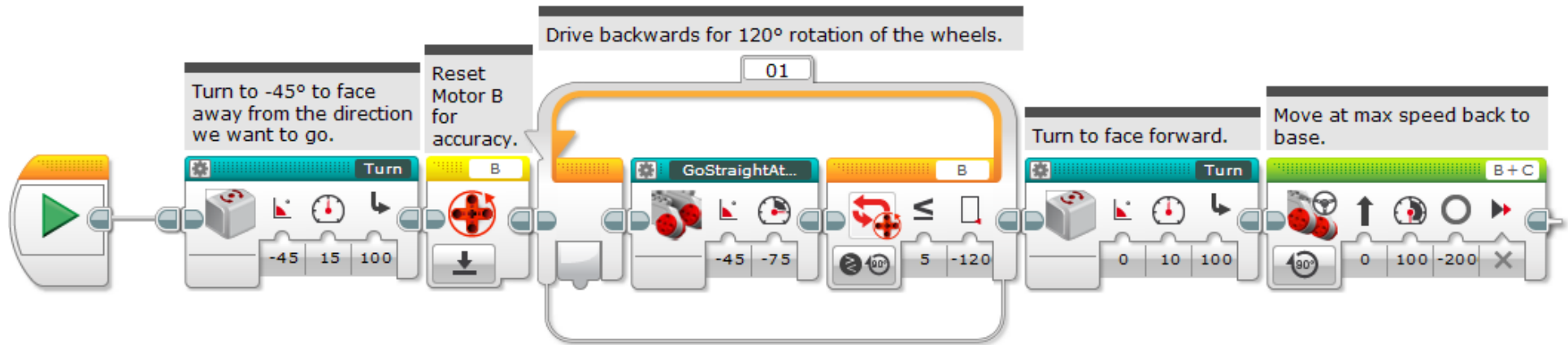
Go straight while deaccelerating for 320° rotation of the wheels to push the bar of "M10 - Food Production."



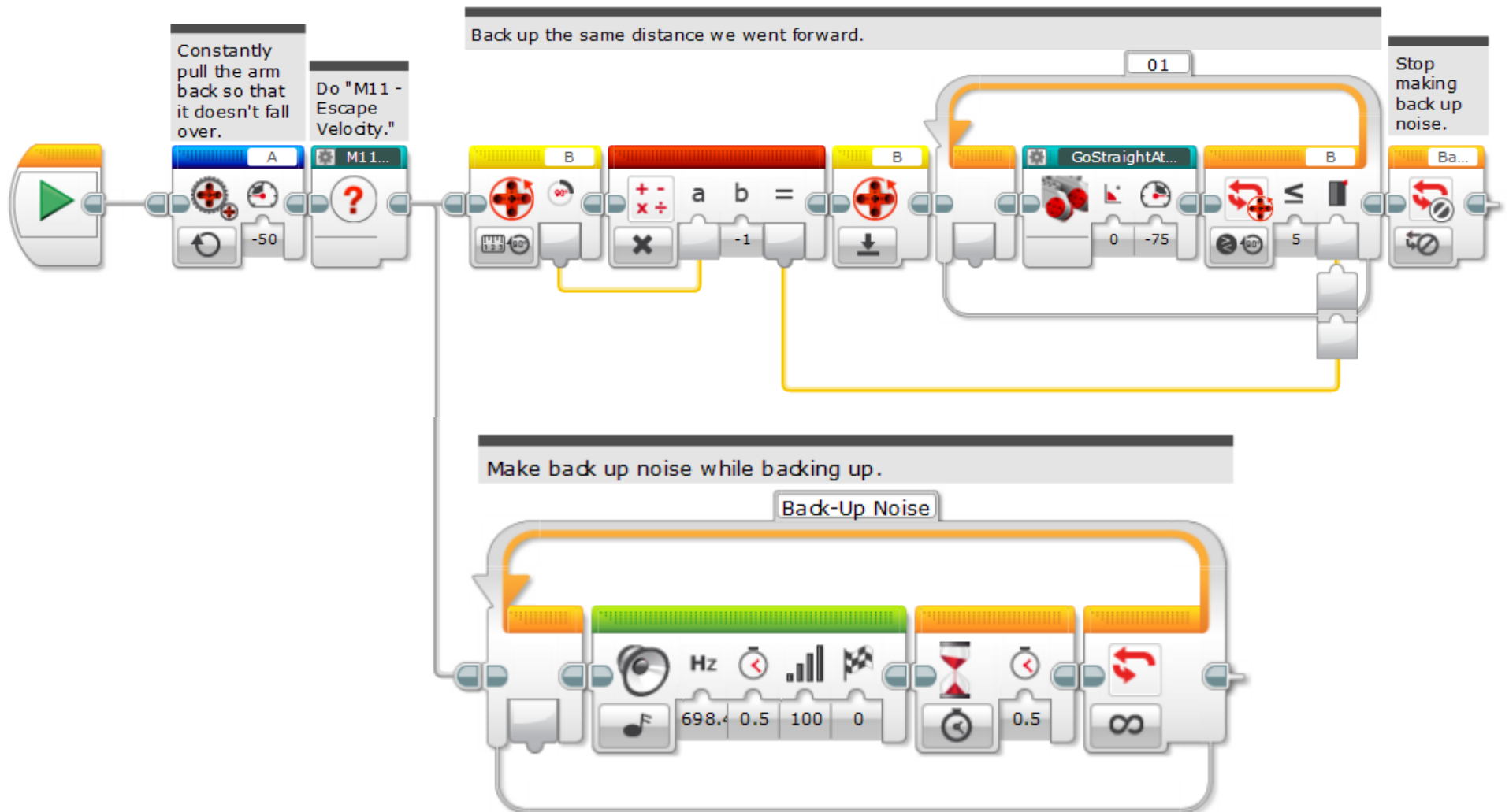
## M12\_Satellite\_Orbits



## ReturnToBase\_M12\_M00

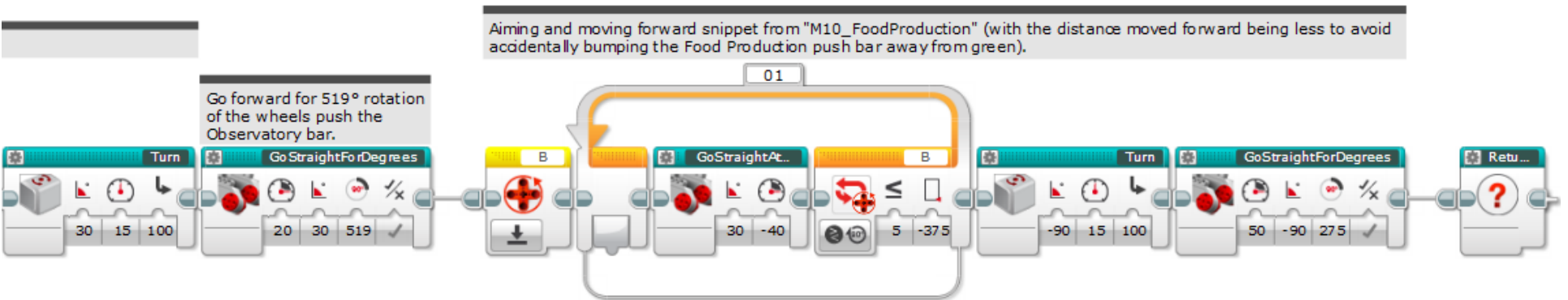
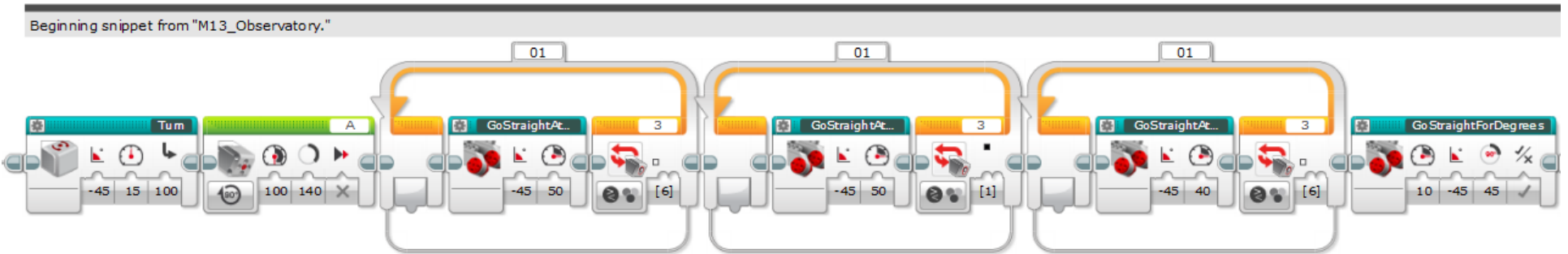
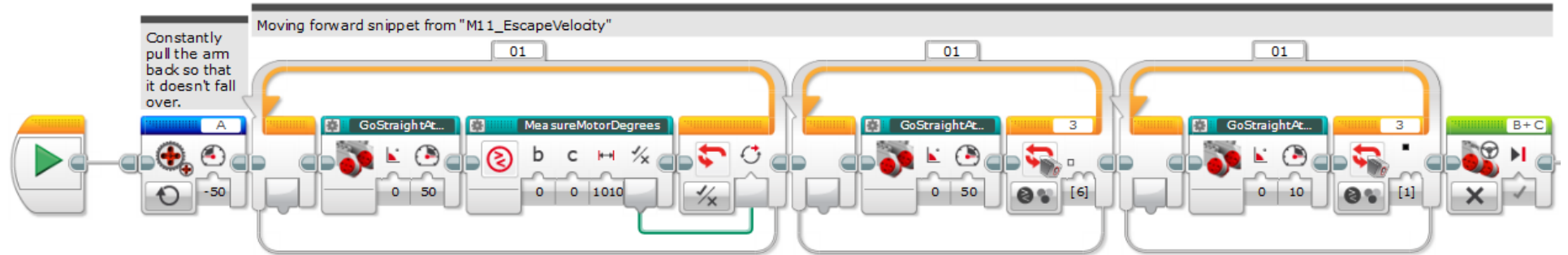


## Escape\_Velocity\_2

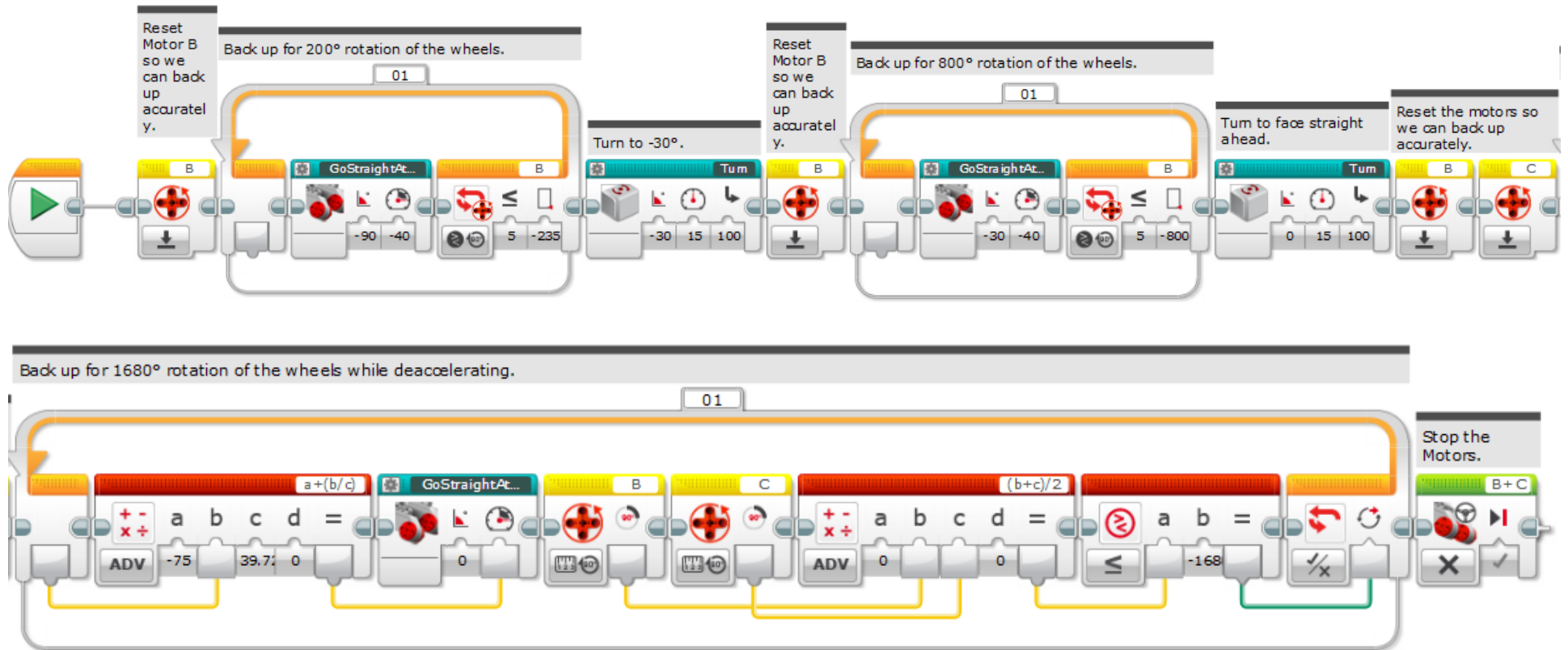




## Observatory\_2

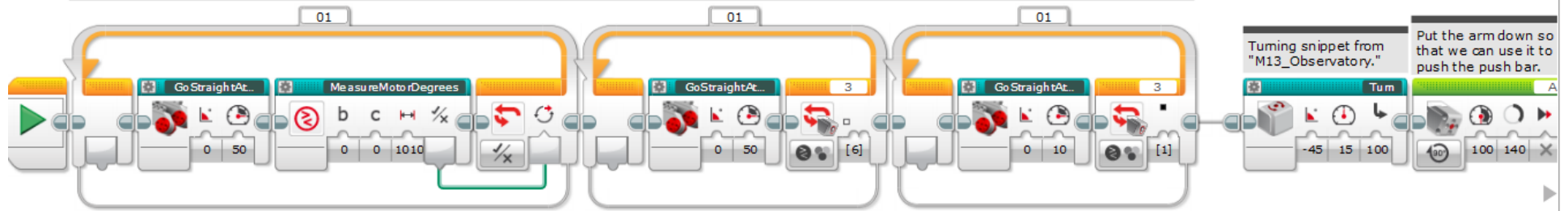


## Return\_to\_Base\_M10\_M00

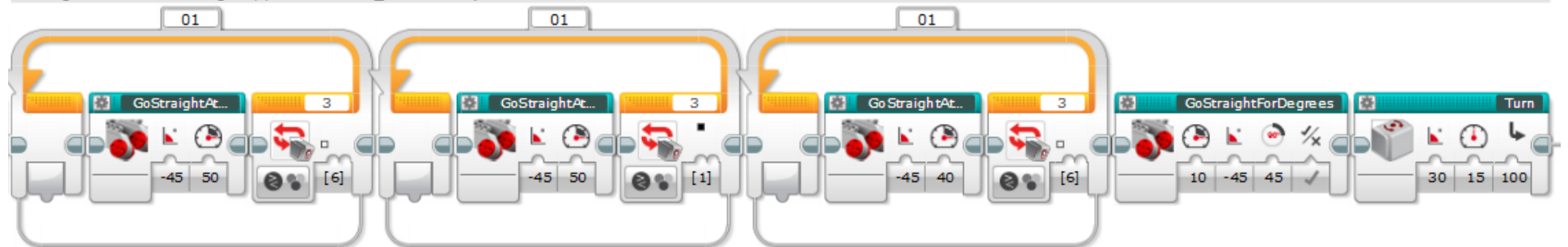


## Food\_Production\_2

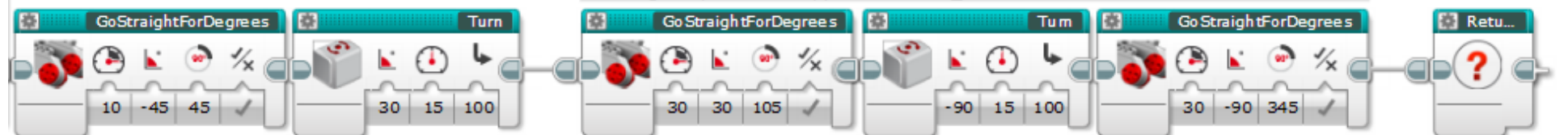
Moving forward snippet from "M11\_EscapeVelocity."



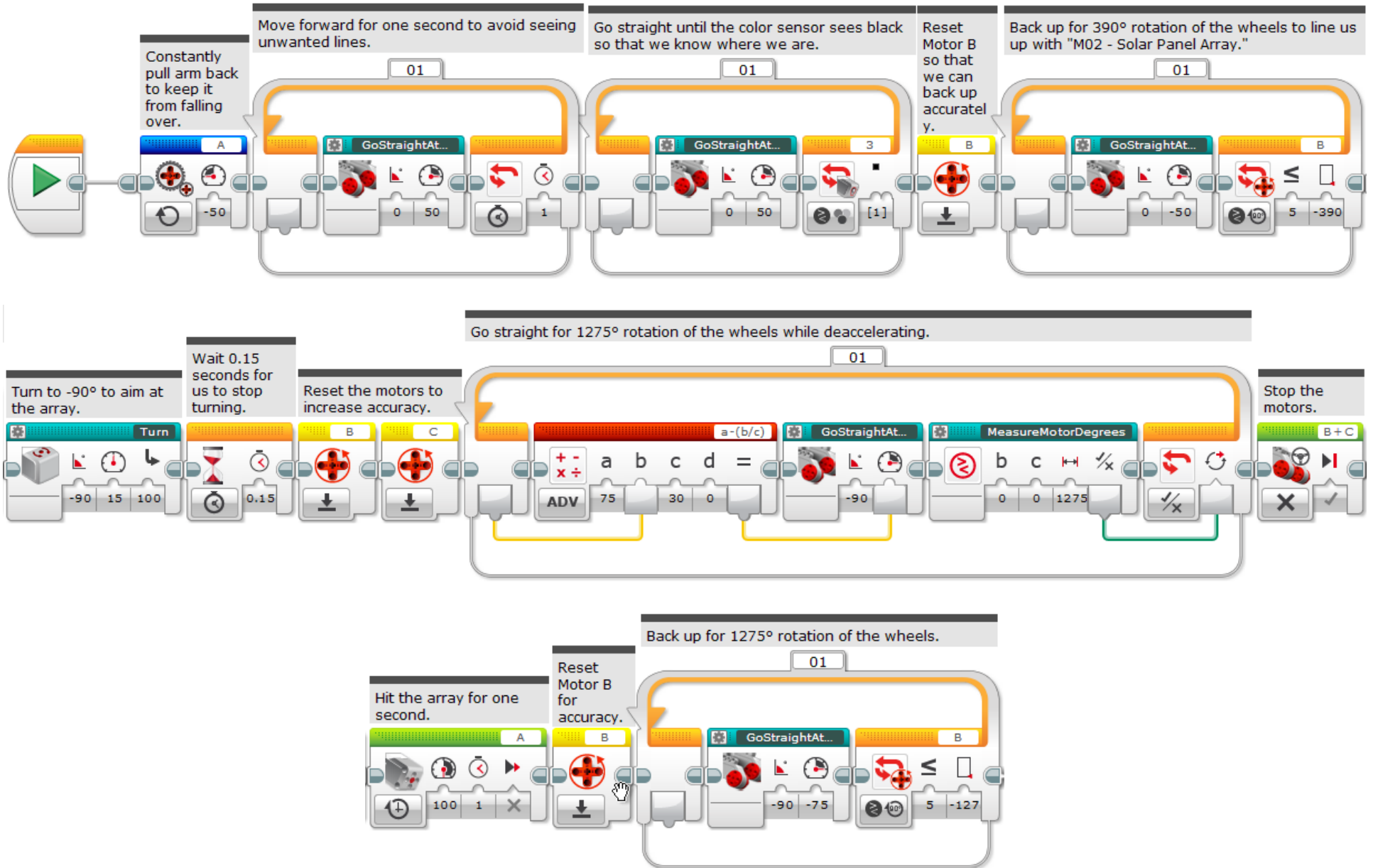
Moving forward and aiming snippet from "M13\_Observatory."



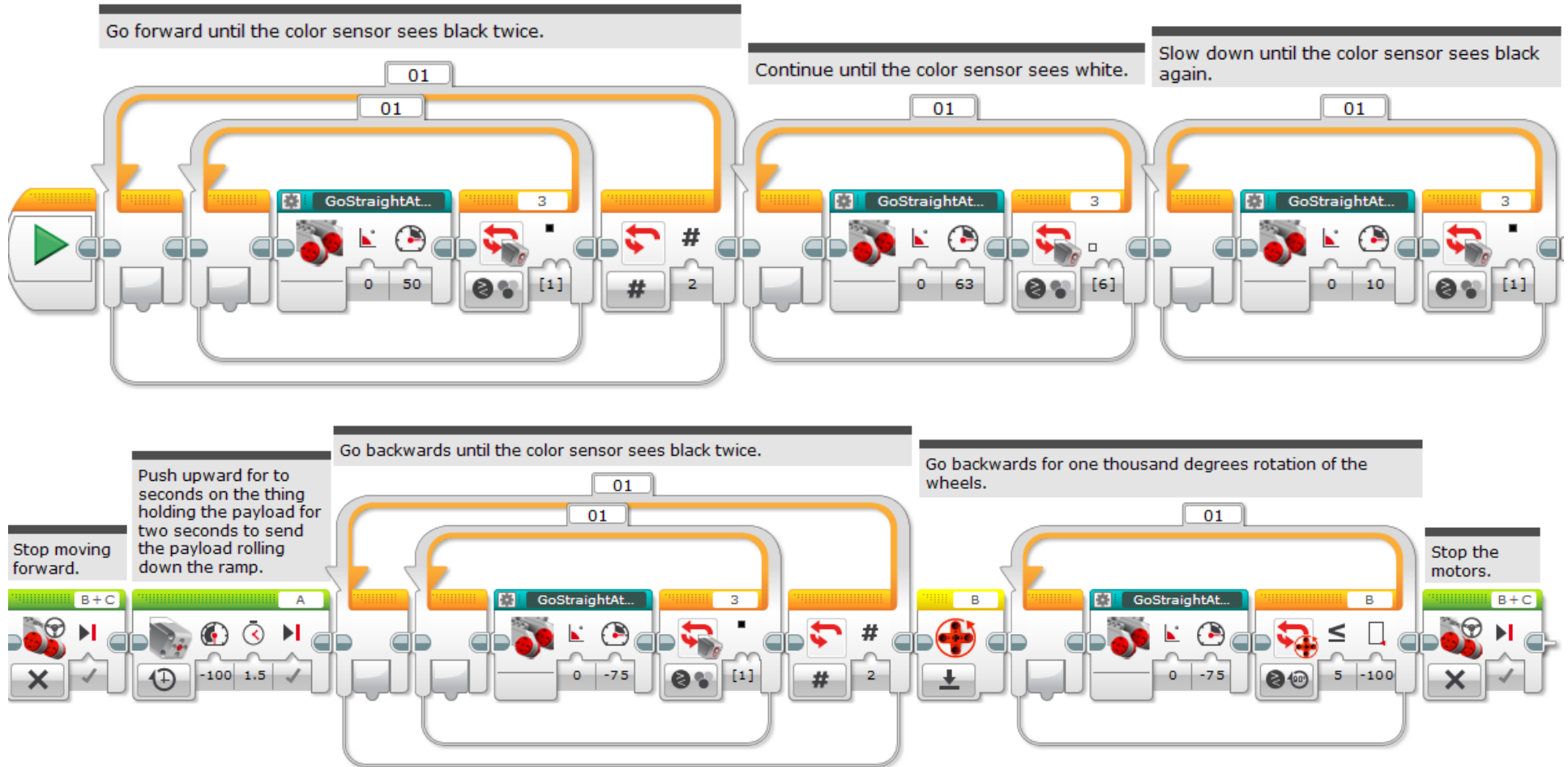
Pushing the push bar snippet from "M10\_FoodProduction."



## M02\_Solar\_Panel\_Array

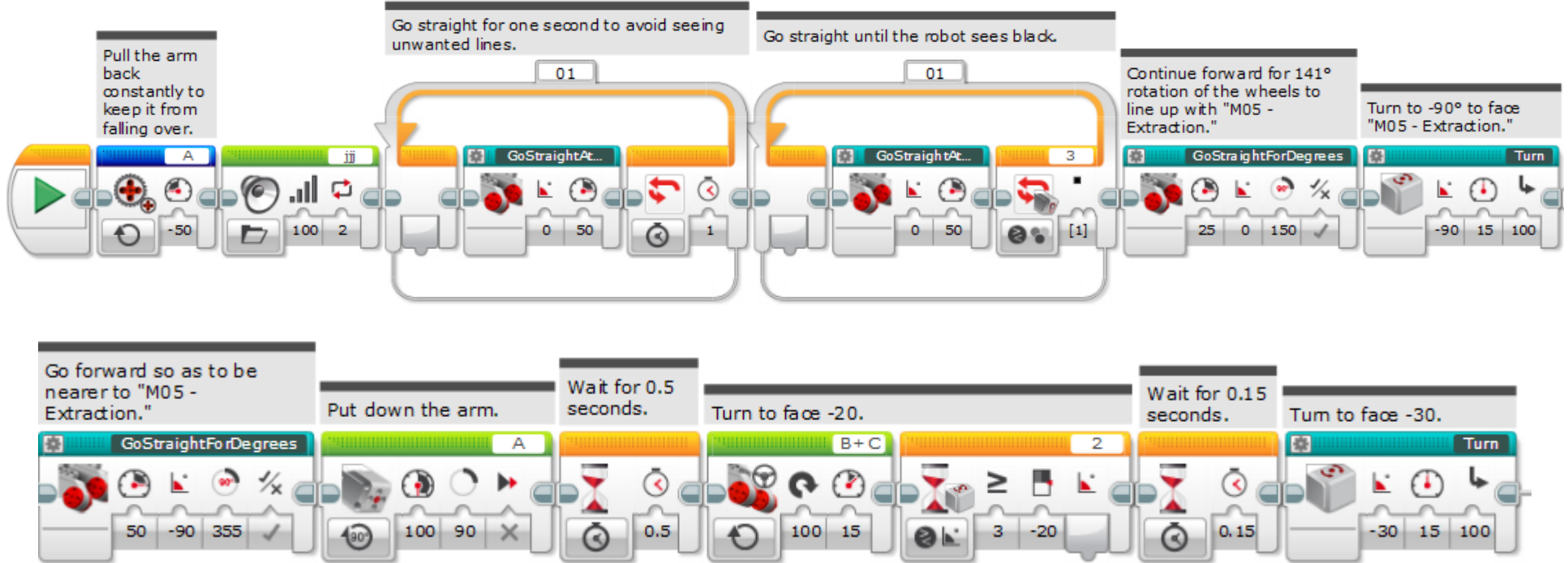


## M01\_SpaceTravel

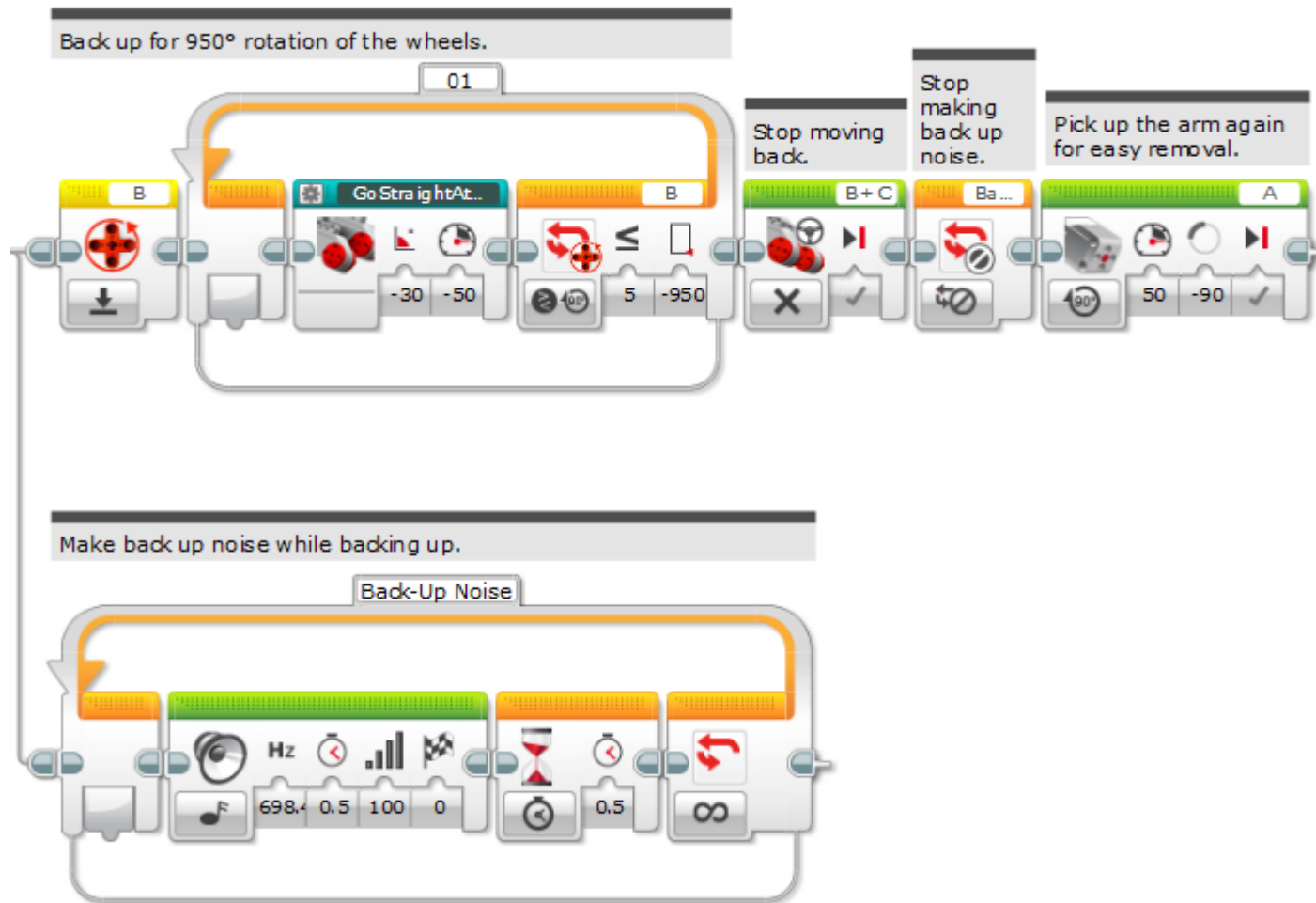


## M05\_Extraction

(page 1 of 2)



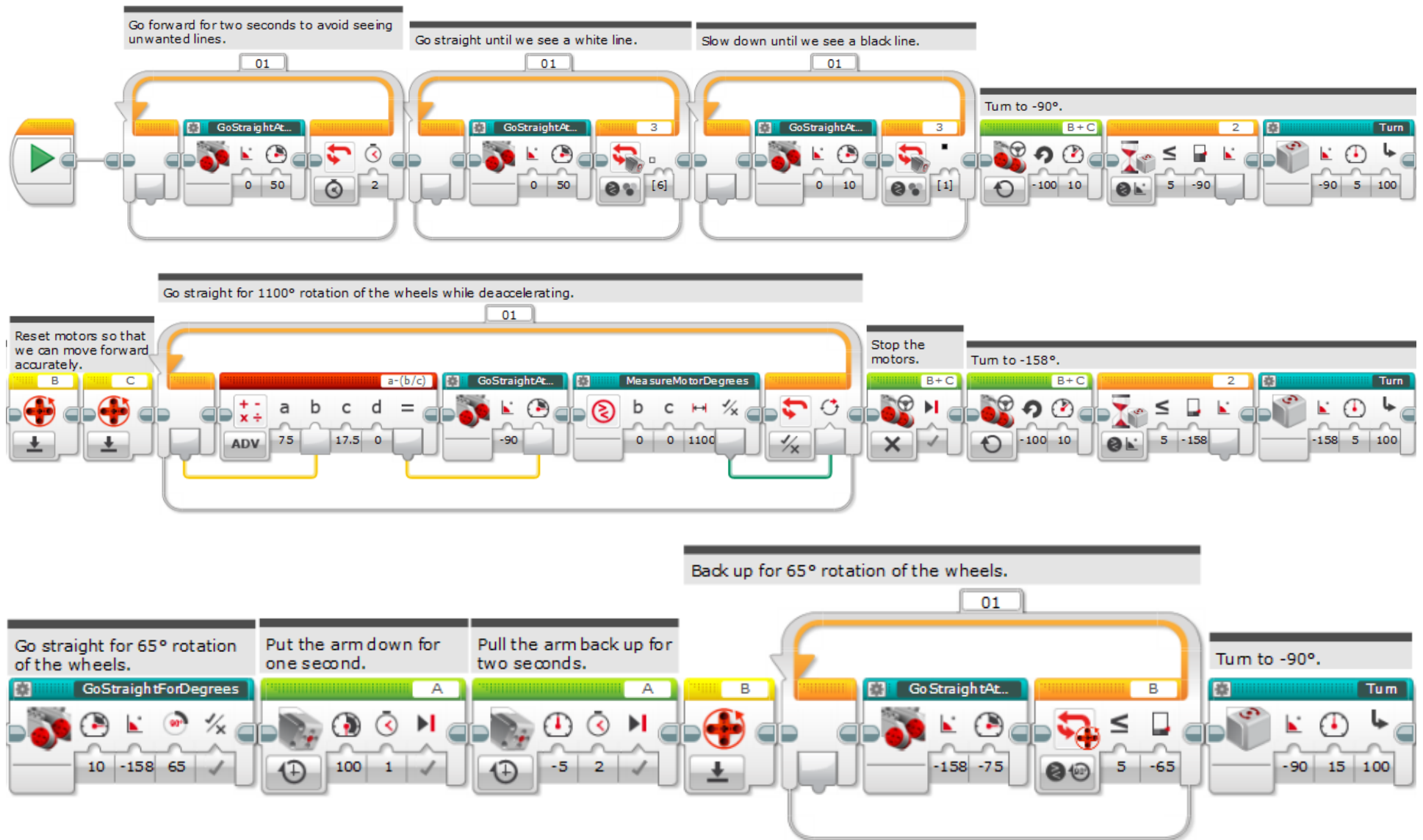
(continued on next page)





# M03\_3DPrinting

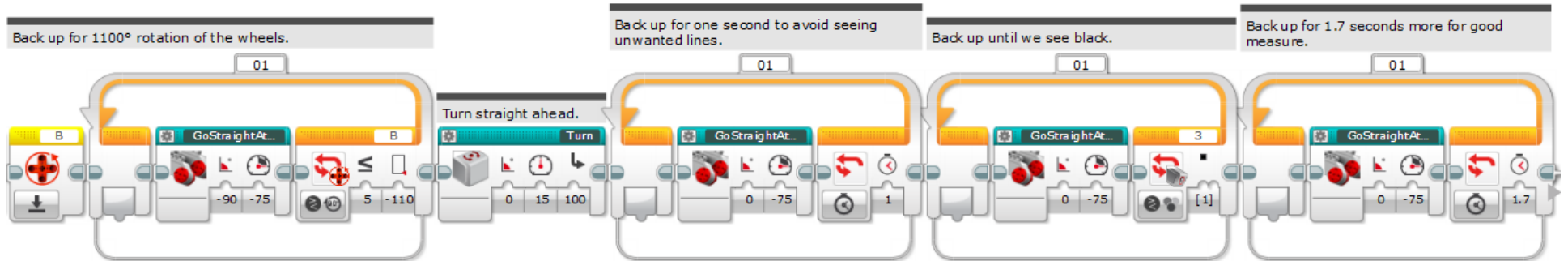
(page 1 of 2)



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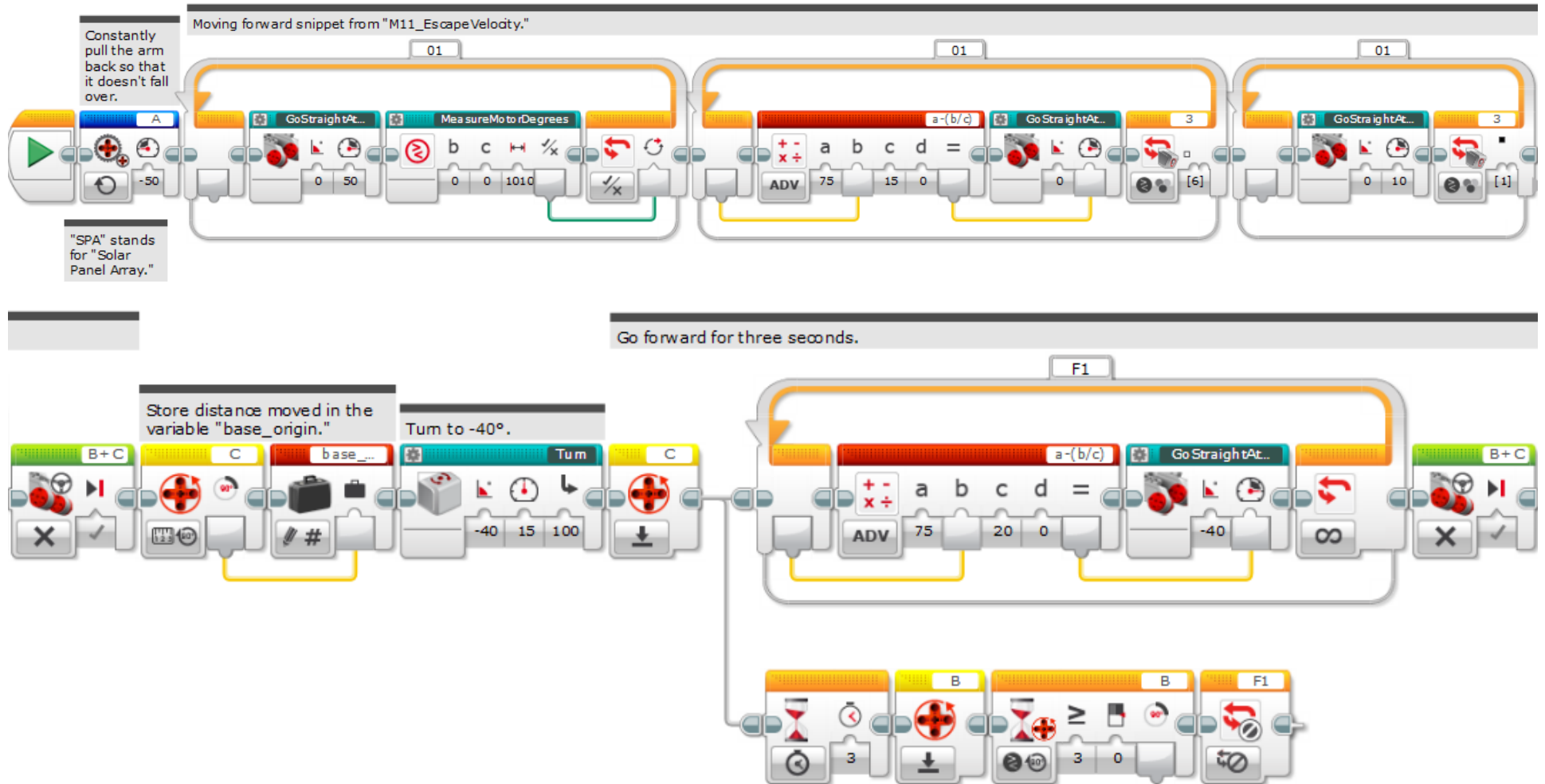


M03\_3DPrinting (page 2 of 2)



## Other SPA (other team's Solar Panel Array)

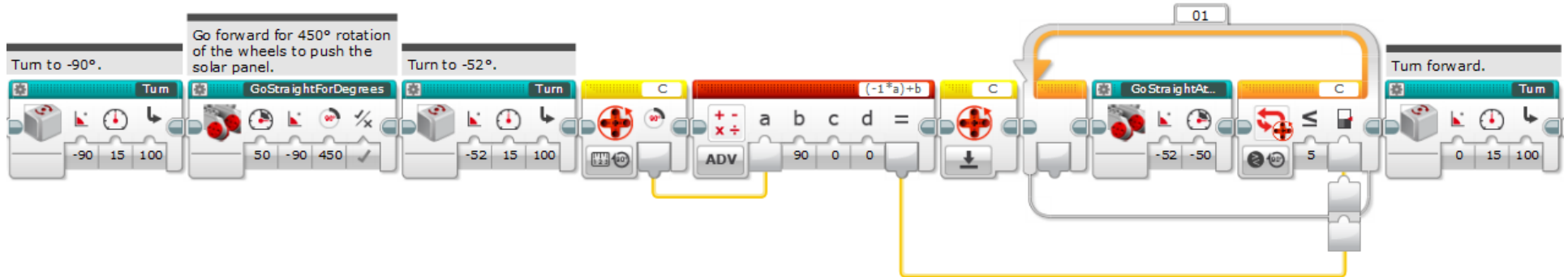
(page 1 of 2)



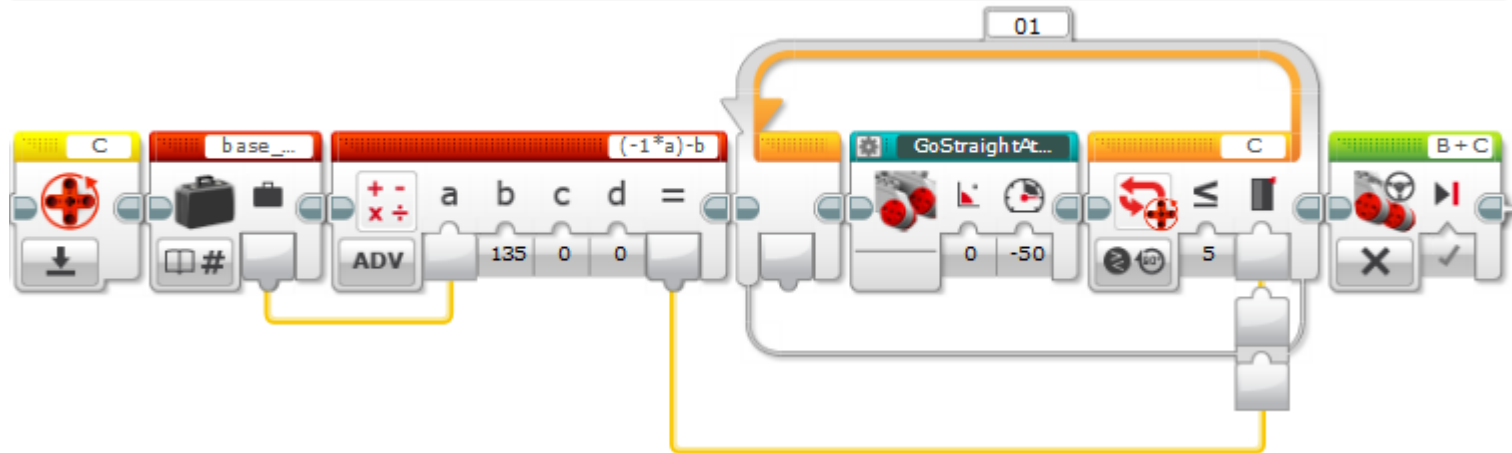
(continued on next page)

Other SPA (page 2 of 2)

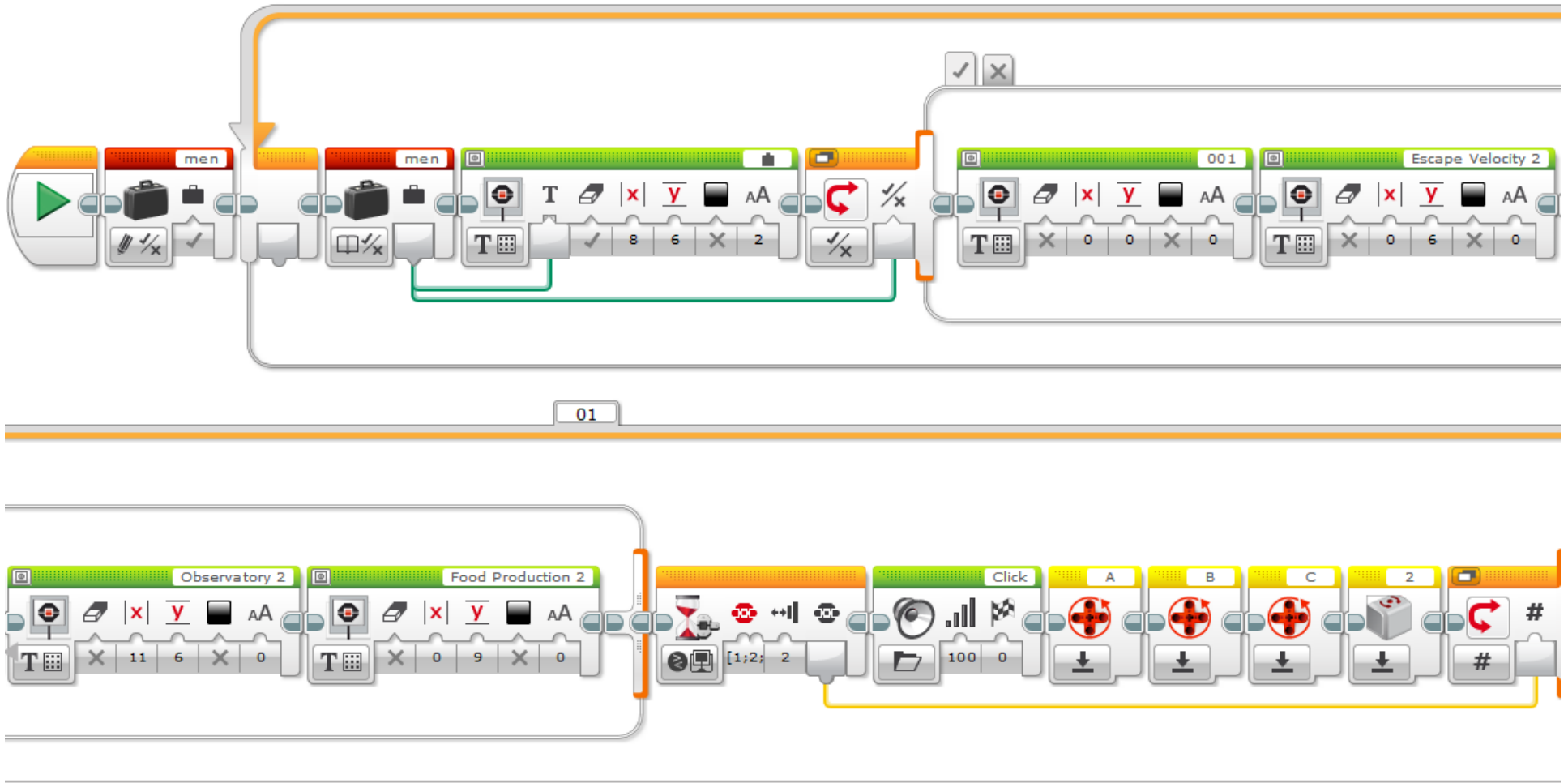
Go back the same distance that we went forward.



Go back the distance stored in the variable "base\_origin."



MENU  
(page 1 of 2)



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