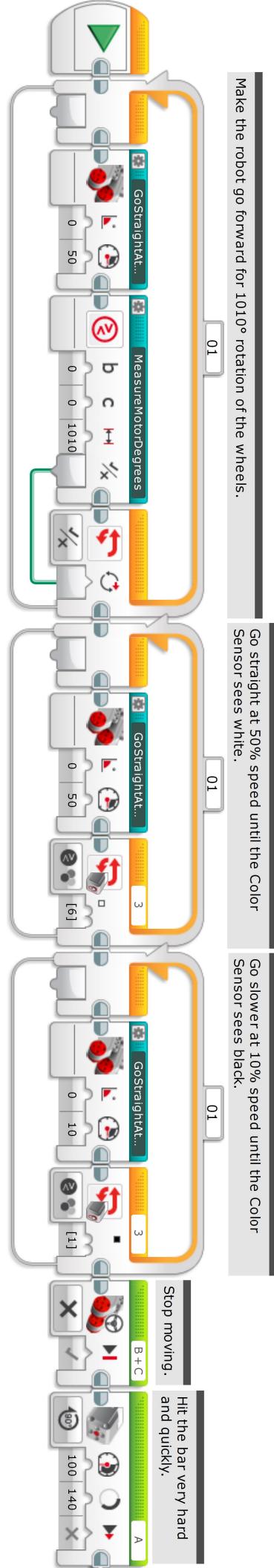
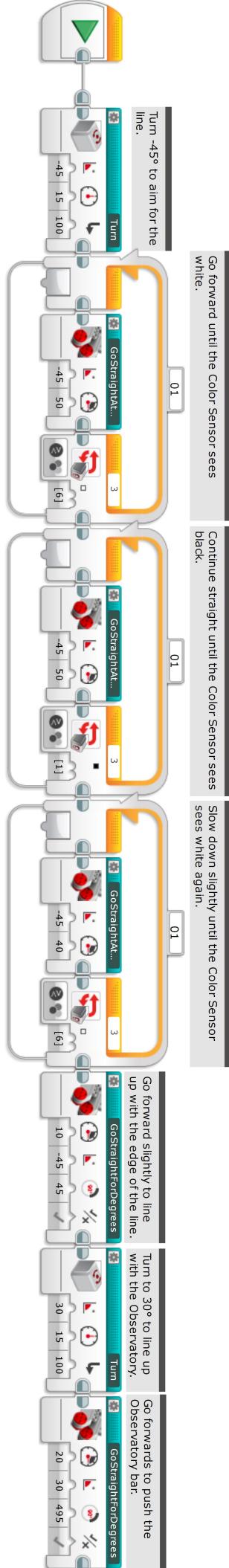
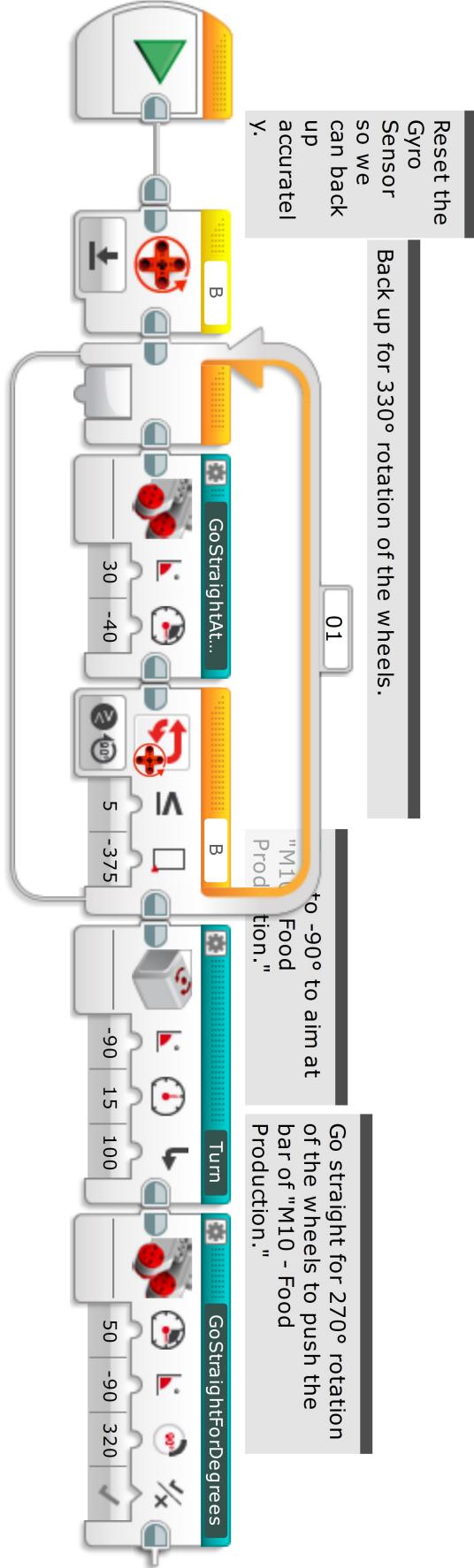
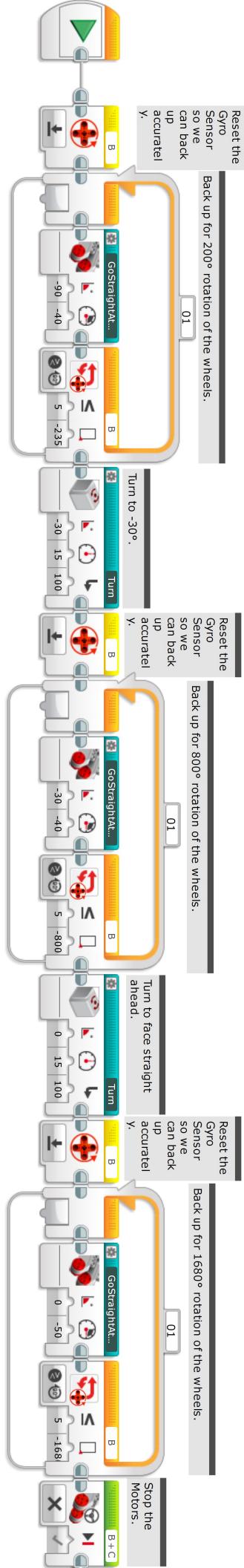


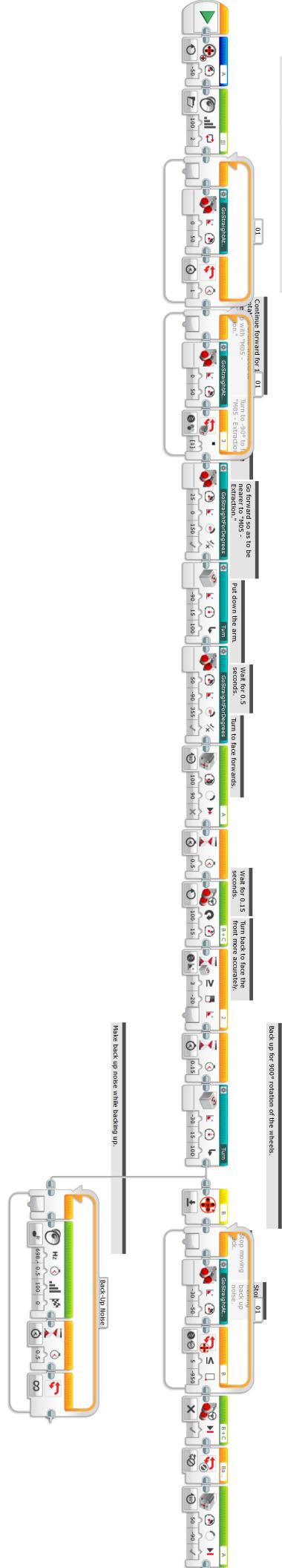
Display the Gyro Sensor's current angle on the screen for debugging purposes.





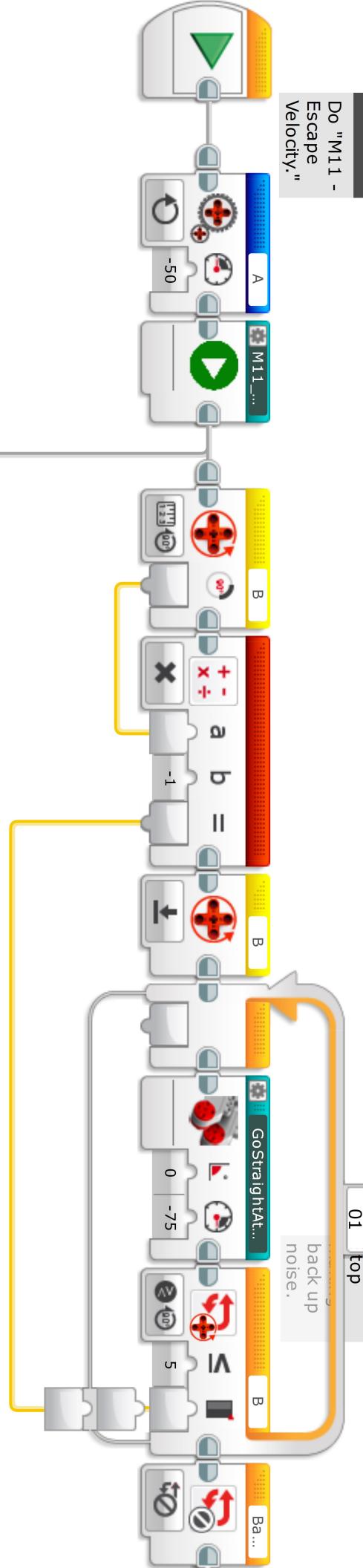






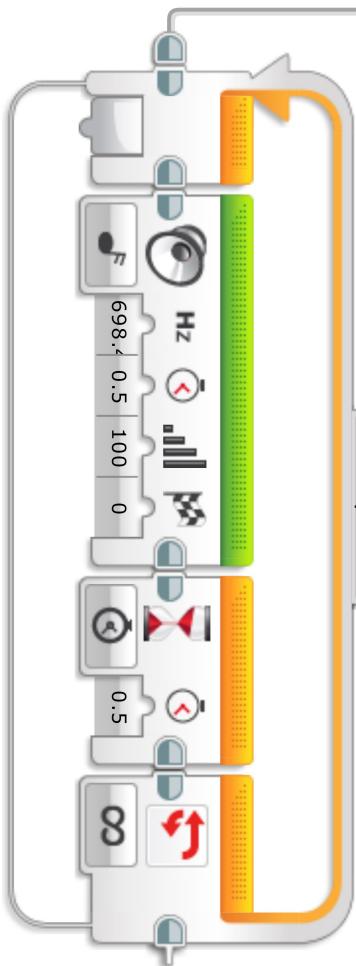
Back up the same distance we went forward.

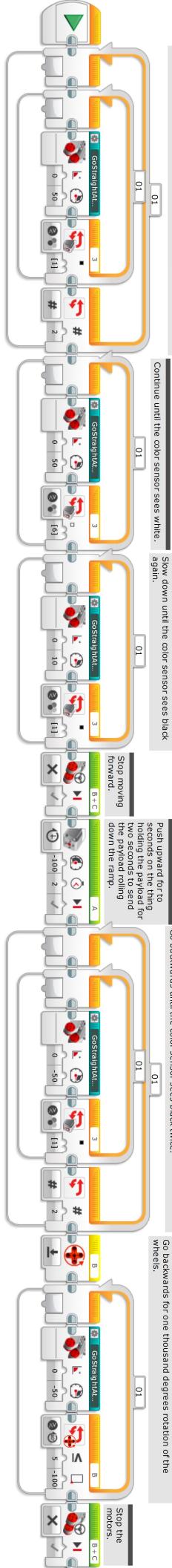
Do "M11 -  
Escape  
Velocity."



Make back up noise while backing up.

Back-Up Noise





Go forward until the color sensor sees black twice.

Continue until the color sensor sees white again.

Slow down until the color sensor sees black again.

Stop moving forward.

Go backwards until the color sensor sees black twice.

Go backwards for one thousand degrees rotation of the wheels.

Push upward for 10 seconds on the timer, then move the payload down the ramp.

Stop the motors.

