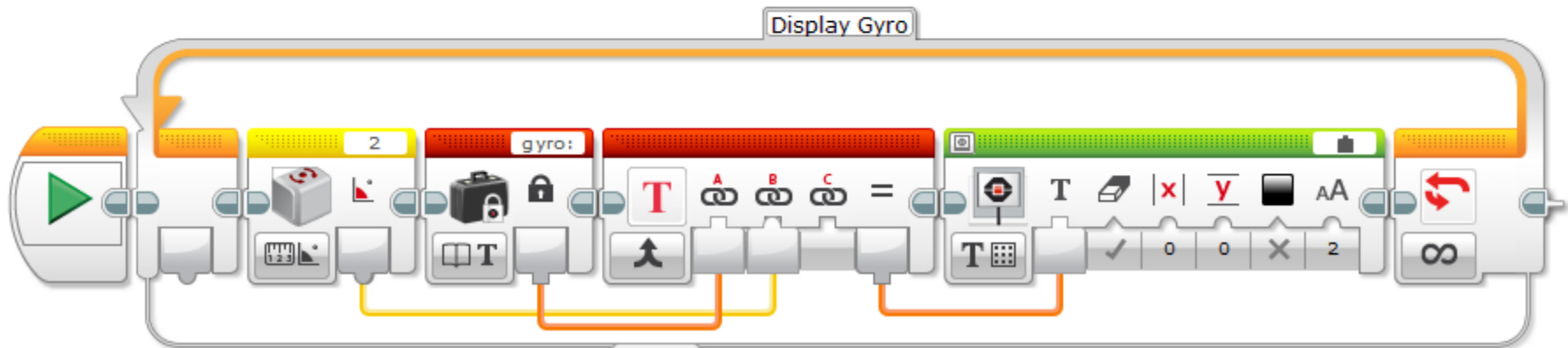


## Contents

001 .....	2
M11_EscapeVelocity .....	3
M13_Observatory .....	4
M10_FoodProduction .....	5
M12_SatelliteOrbits .....	6
ReturnToBase_M12_M00 .....	7
M02_SolarPanelArray .....	8
M01_SpaceTravel .....	9
M05_Extraction .....	10
M03_3DPrinting .....	12
SpaceTravelDump .....	14
OtherSPA .....	15
MENU .....	17

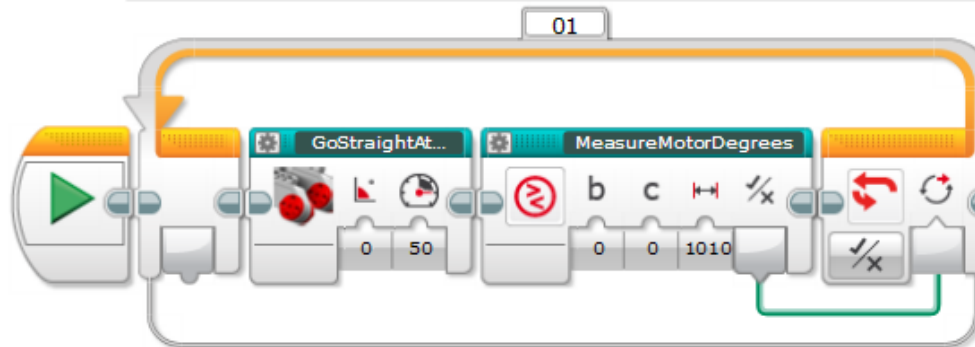


Display the Gyro Sensor's current angle on the screen for debugging purposes.

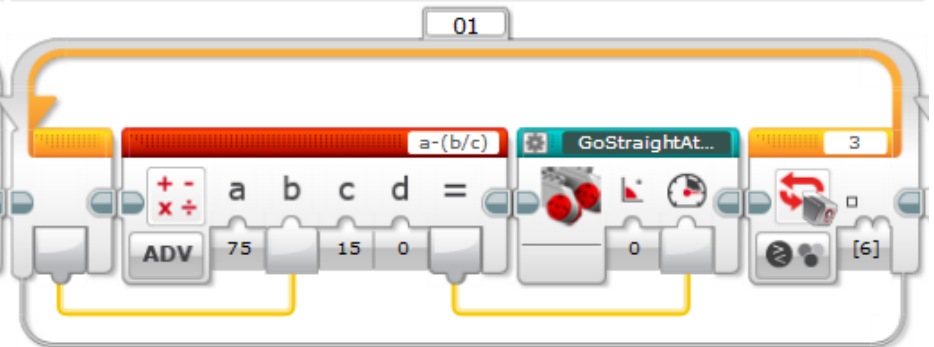


## M11\_EscapeVelocity

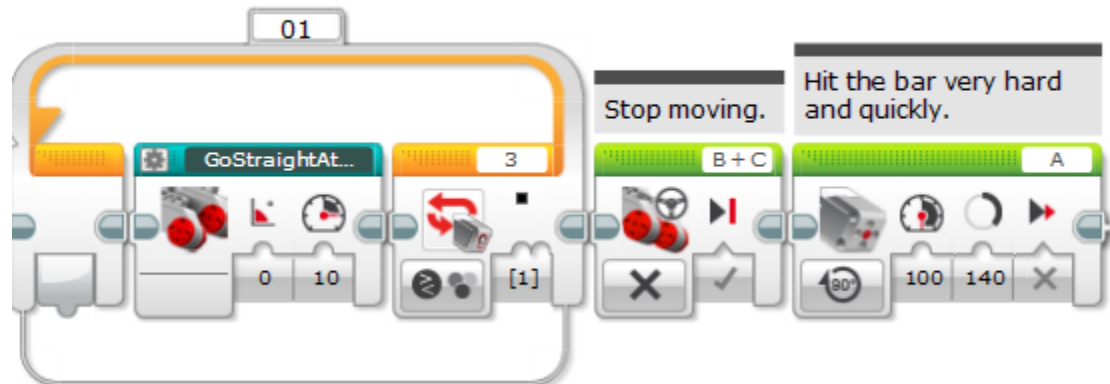
Make the robot go forward for 1010° rotation of the wheels.



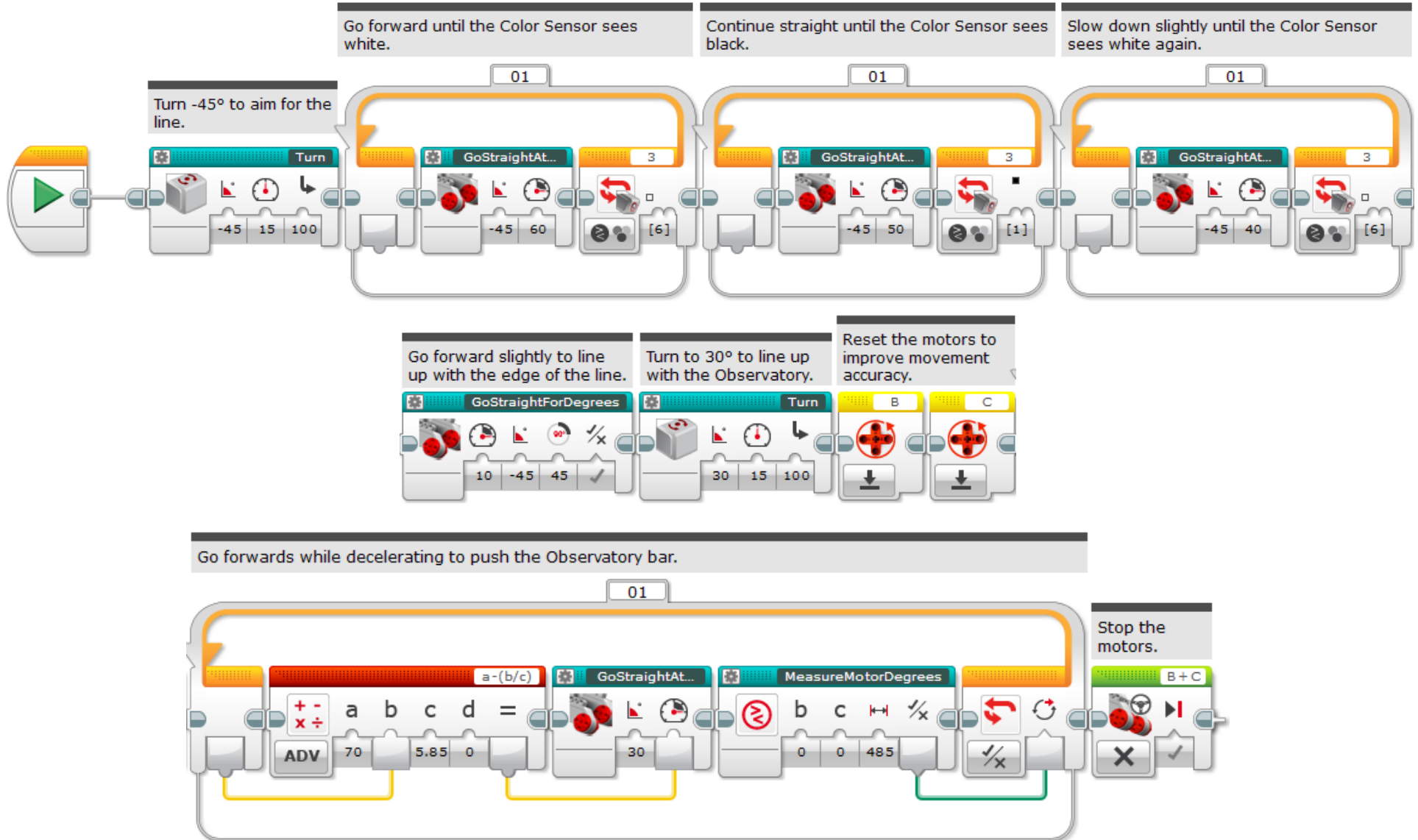
Go straight while deaccelerating until the Color Sensor sees white.



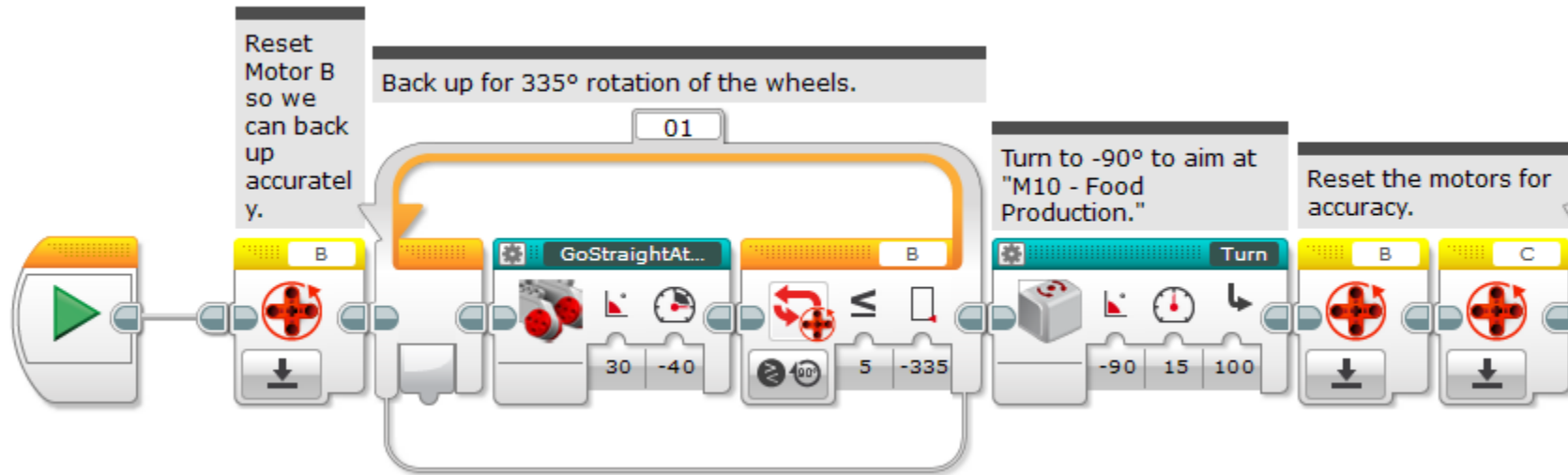
Go slower at 10% speed until the Color Sensor sees black.



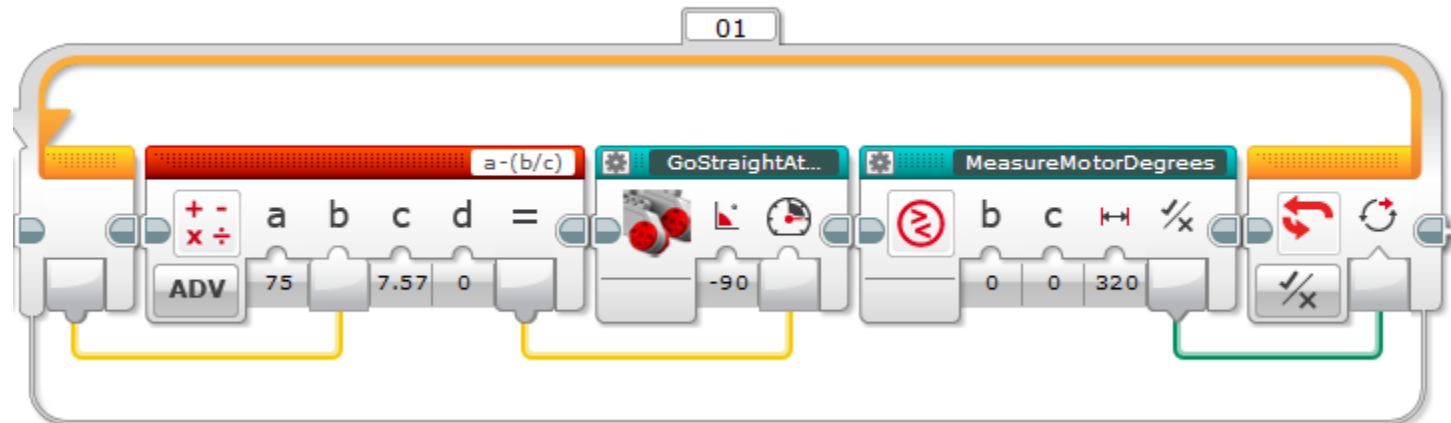
## M13\_Observatory



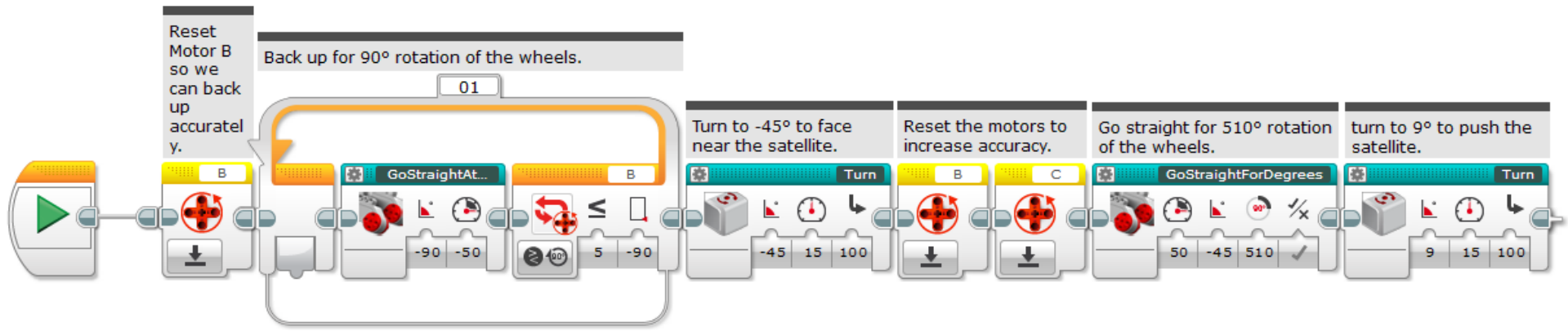
## M10\_FoodProduction



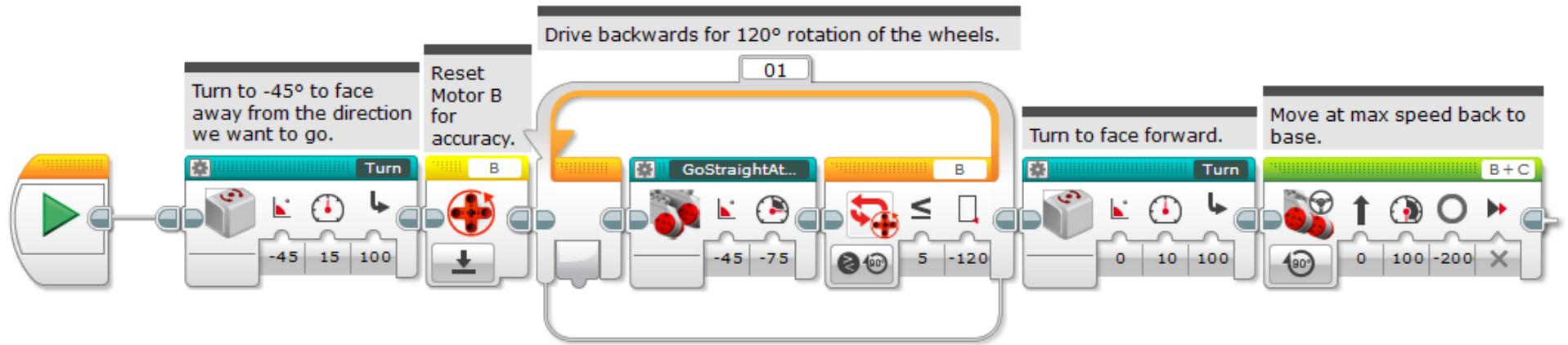
Go straight while decelerating for 320° rotation of the wheels to push the bar of "M10 - Food Production."



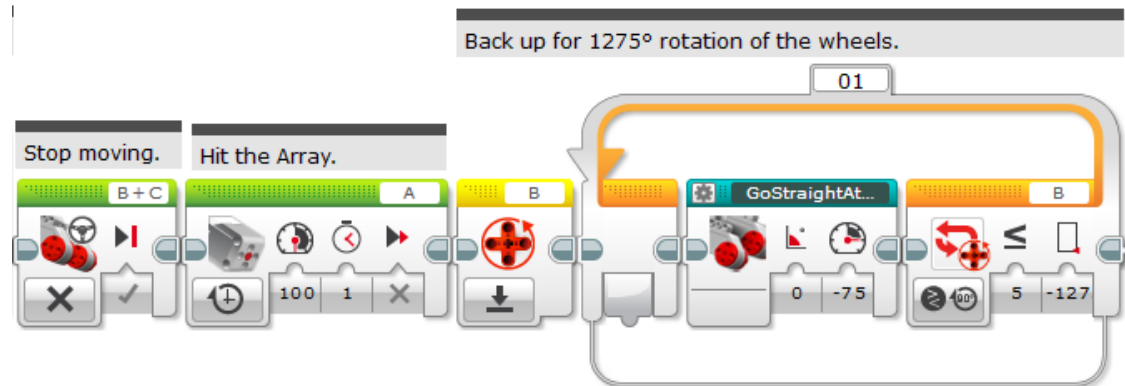
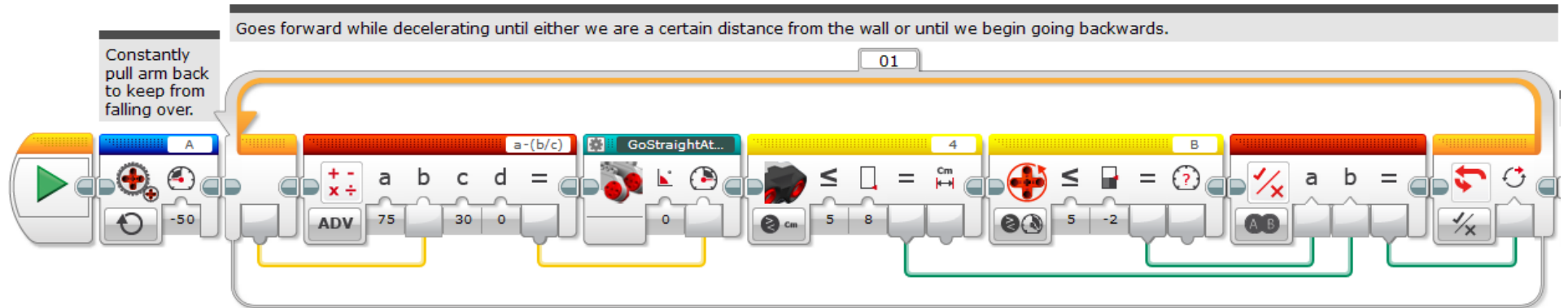
## M12\_SatelliteOrbits



## ReturnToBase\_M12\_M00

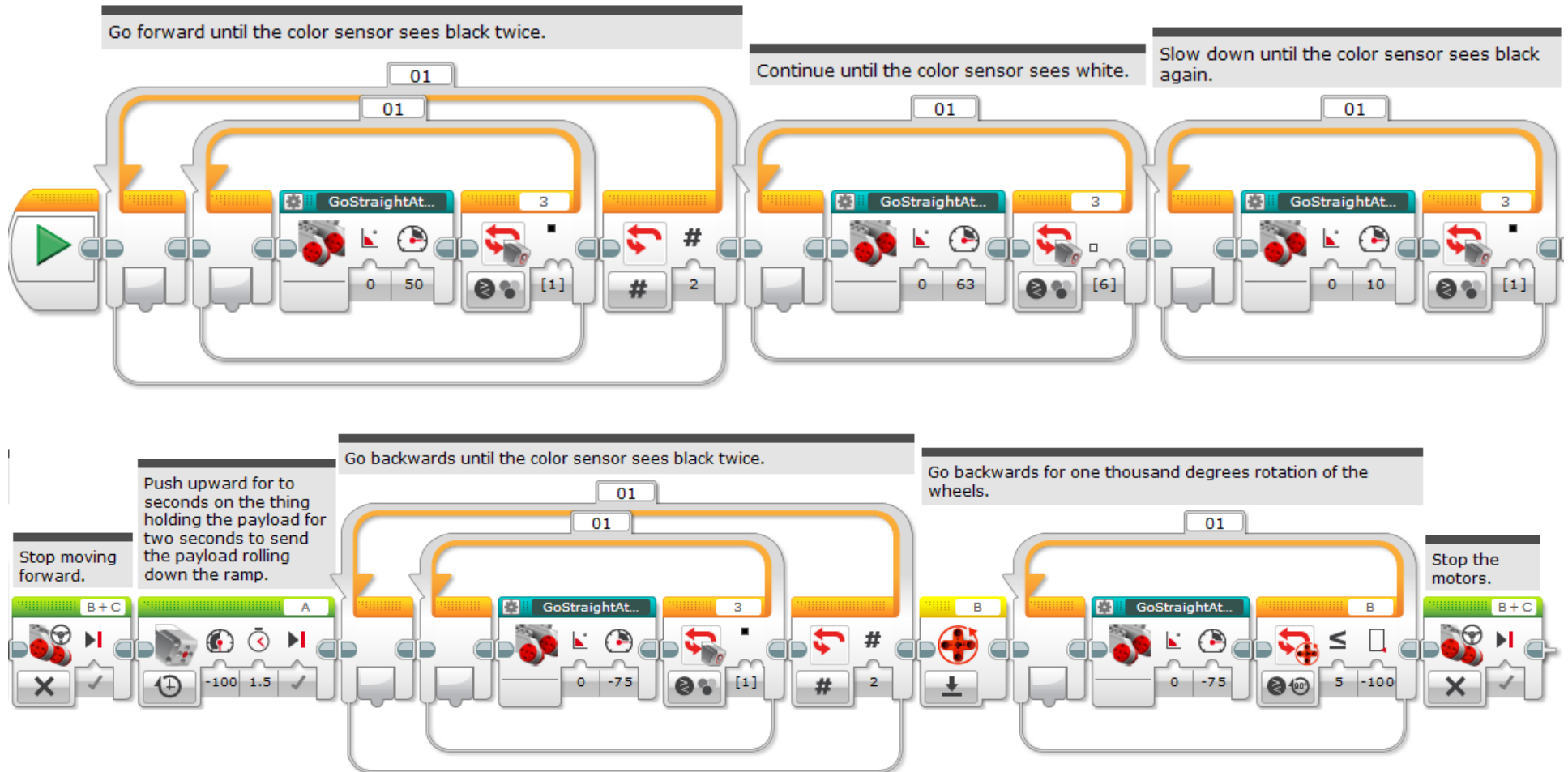


## M02\_SolarPanelArray



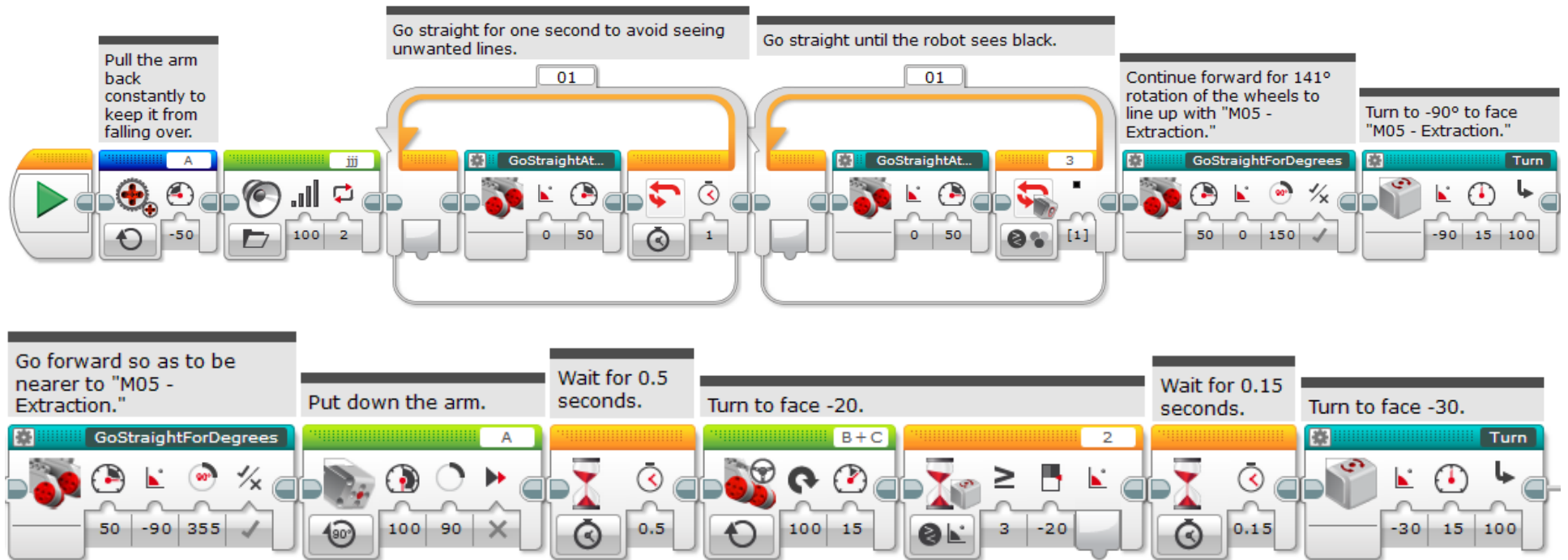


## M01\_SpaceTravel



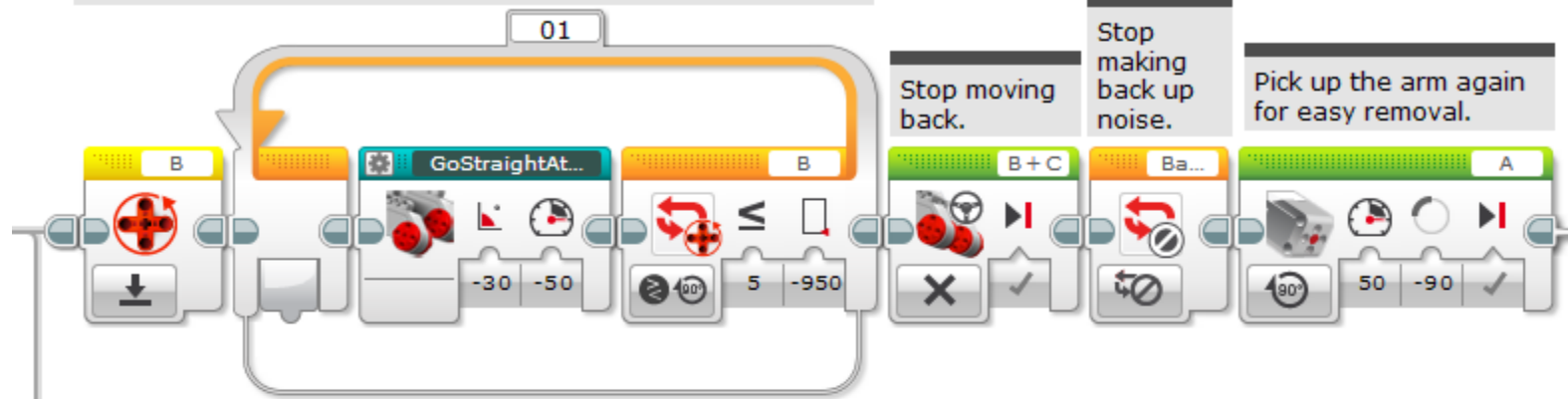
## M05\_Extraction

(page 1 of 2)



(continued on next page)

Back up for 950° rotation of the wheels.

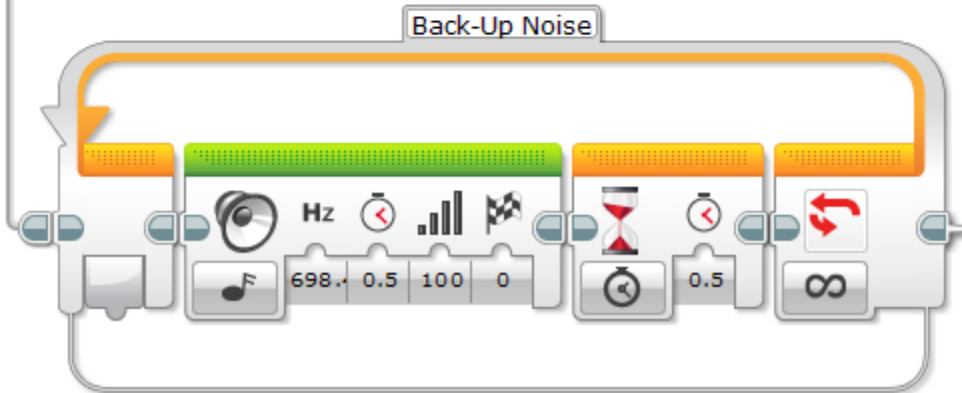


Stop moving back.

Stop making back up noise.

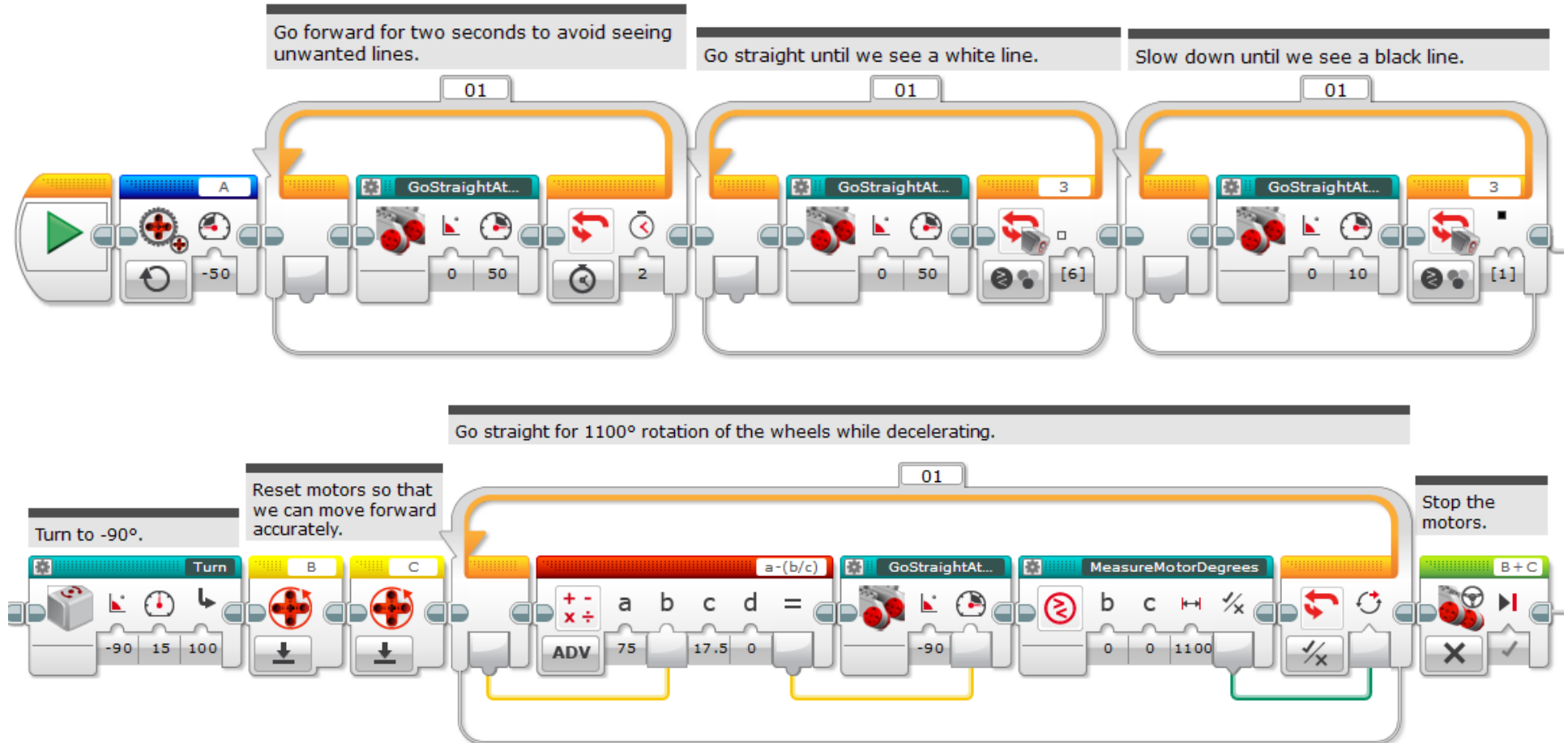
Pick up the arm again for easy removal.

Make back up noise while backing up.

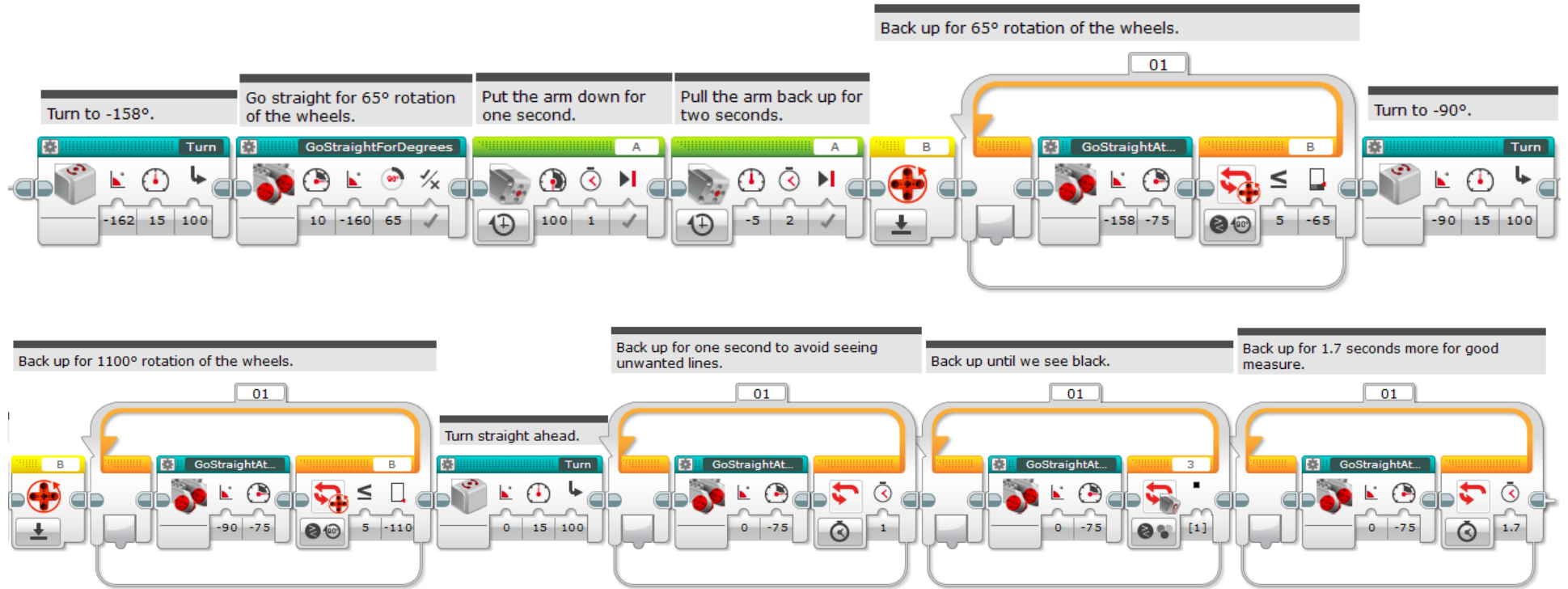


## M03\_3DPrinting

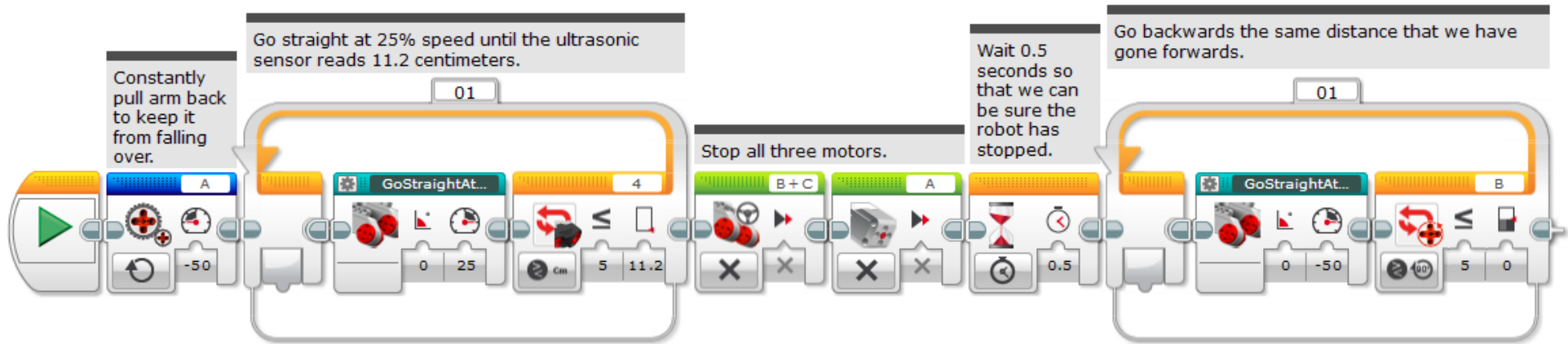
(page 1 of 2)



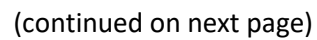
(continued on next page)

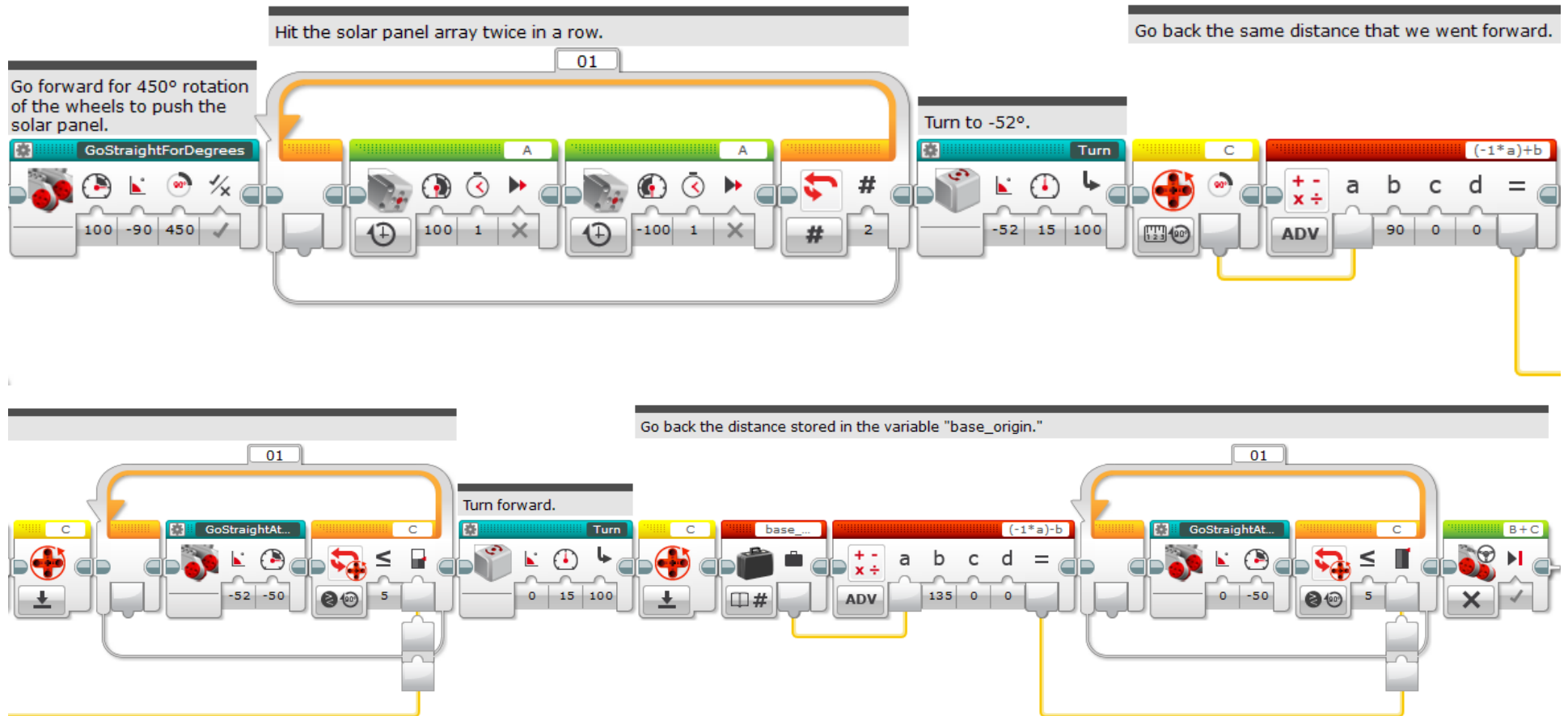


## SpaceTravelDump



(other team's Solar Panel Array, page 1 of 2)







(page 1 of 2)



(continued on next page)

