

# Underwater Organism Detection Vehicle

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#### Content



Background

Our works

Result

Timeline and Future works



#### underwater complex environment:

low temperature, dim vision, and high pressure

#### using underwater robots:

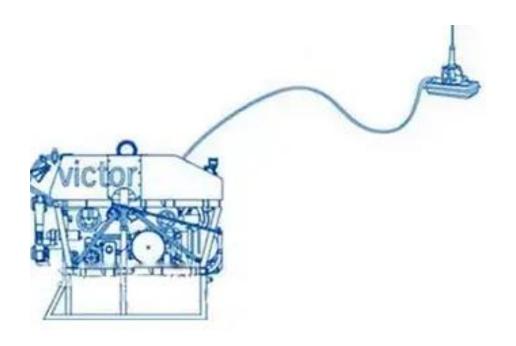
collecting the marine products



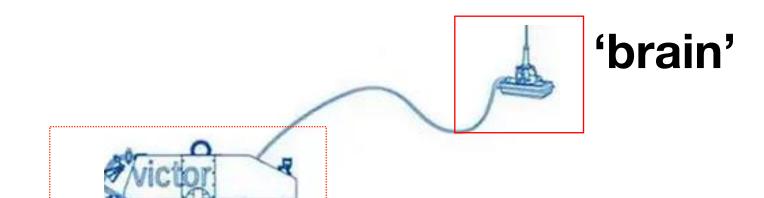
#### core technique of making an underwater robot:

detect target from underwater vision



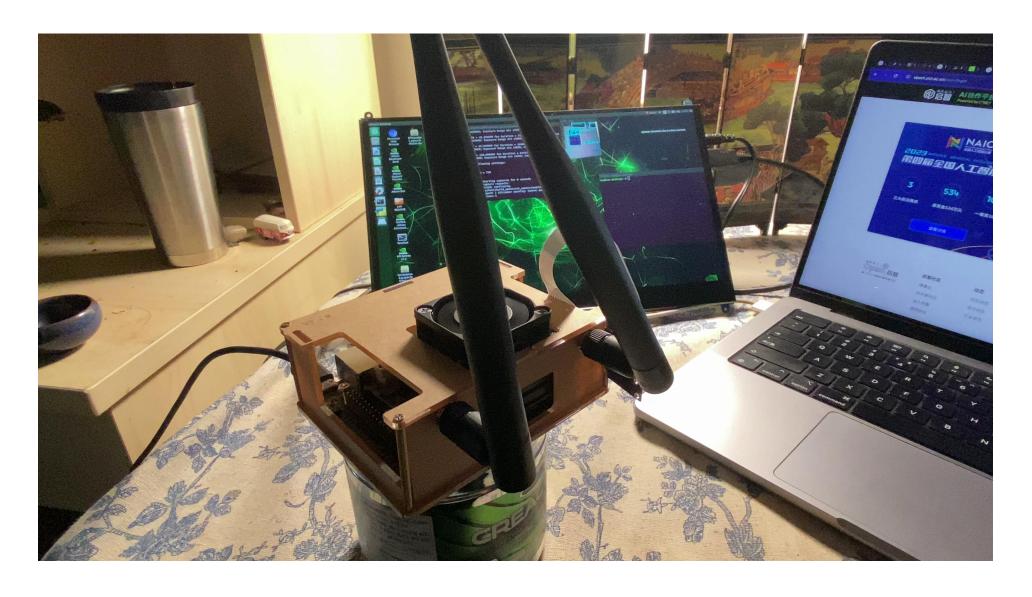




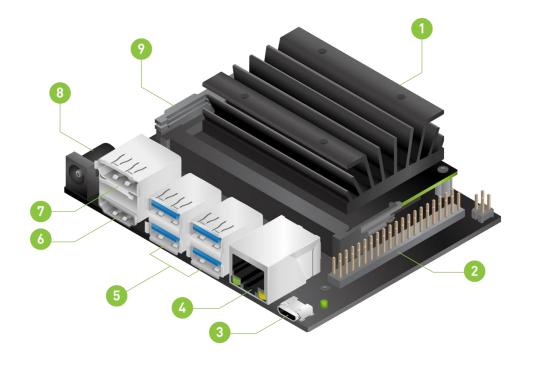


'eyes'











#### Remote communication







#### Deploying

```
while True:
    ret, frame = cap.read()
    if not ret:
        break

# Preprocess frame
    ori_imgs, framed_imgs, framed_metas = preprocess(frame, max_size=512)
```



Testing

### Result





#### **Future Works**



ROV(Remotely Operated Vehicle) development



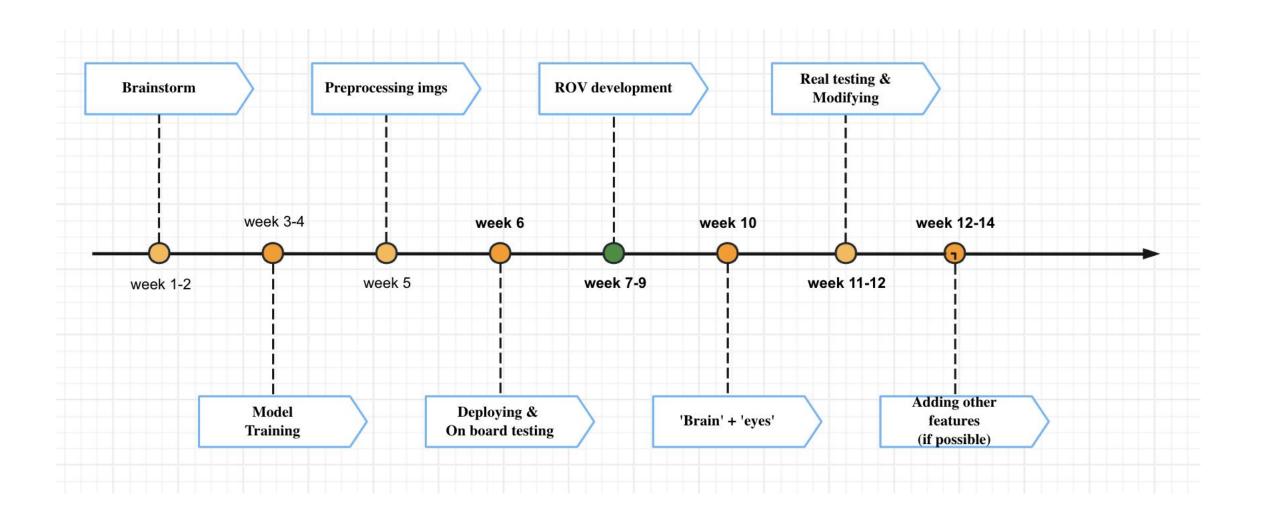
### **Future Works**



Do some real testing!

### Timeline







## Thank You!