

## EXAM QUESTION PAPER

<b>College/ Institute</b>	Engineering, Design and Physical Sciences		
<b>Department</b>	Electronic and Electrical Engineering		
<b>Exam Author(s)</b>	Dr Mingliang Deng		
<b>Module Code</b>	EE2637		
<b>Module Title</b>	Digital Signal Processing		
<b>Month</b>	January	<b>Year</b>	2024/25
<b>Exam Type</b>	Full/Resit	<b>Format</b>	
<b>Duration</b>	Two Hours		
<b>Number of questions</b>	Five		
<b>Question Instructions</b>	Answer all FIVE questions		
<b>Are calculators permitted</b>	Yes		
<b>Make/Model number of permitted calculators.</b>	None		
<b>Can students include drawings/ diagrams?</b>	No		
<b>Any permitted reference materials</b>	None		
<b>Required Stationery / Equipment</b>			

By continuing beyond this point, you confirm that you have read the information and instructions above, and understand the conditions of this examination.

1. Consider a causal LTI system where the input  $x[n]$  and the output  $y[n]$  are related by the linear constant coefficient difference equation below

$$y[n] = 0.9y[n-1] + x[n] + 0.9x[n-1]$$

[100%]

- a) Determine the transfer function  $H(z)$  of this system.

[20%]

- b) Determine the unit sample response  $h[n]$  of this system.

[20%]

- c) Determine the frequency response and plot the magnitude response.

[20%]

- d) Use the frequency response c) to determine the response to an input of  $e^{j\omega n}$ .

[40%]

2. Assume that there are two four-point sequences  $x[n]$  and  $h[n]$  as follows

$$x[n] = \cos\left(\frac{\pi n}{2}\right), n = 0, 1, 2, 3$$

$$h[n] = 2^n, n = 0, 1, 2, 3$$

[100%]

- a) Calculate the four-point DFT  $X[k]$  for  $x[n]$ .

[33%]

- b) Calculate the four-point DFT  $H[k]$  for  $h[n]$ .

[33%]

- c) Calculate  $y[n]$  by multiplying the DFTs of  $x[n]$  and  $h[n]$  and performing an IDFT.

[33%]

3. Consider a discrete-time linear causal system defined by the difference equation

$$y[n] - \frac{3}{4}y[n-1] + \frac{1}{8}y[n-2] = x[n] + \frac{1}{3}x[n-1]$$

Draw a signal flow graph to implement this system in each of the following forms

[100%]

a) Direct form I.

[20%]

b) Direct form II (Canonic form).

[20%]

c) Cascade form.

[30%]

d) Parallel form.

[30%]

For the cascade and parallel forms, only use the first-order sections.

4. Write down the features of unit sample response for four types of linear phase FIR filters. Determine whether the following unit sample response corresponds to a linear phase FIR filter. If it is, state its type, explain why and calculate its phase response and group delay.

$$\begin{cases} 1, & 0 \leq n \leq 3 \\ 0, & \text{others} \end{cases}$$

[100%]

5. Design a causal linear phase FIR system to approximate an ideal low-pass digital filter with a cut-off frequency of  $0.3\pi$  and satisfying

$$\begin{aligned} 0.95 < H(e^{j\omega}) < 1.05, & \quad 0 \leq |\omega| \leq 0.25\pi \\ -0.1 < H(e^{j\omega}) < 0.1, & \quad 0.35\pi \leq |\omega| \leq \pi \end{aligned}$$

[100%]

a) What kinds of windows can be used to meet this specification and why? Here, Kaiser window is NOT considered.

[20%]

- b) For each window obtained in Table 1, give the minimum filter length required. [25%]
- c) Determine the impulse response of the low-pass FIR filter with the minimum design complexity and passband/stopband ripples. [30%]
- d) Calculate the impulse response of a linear phase high-pass FIR filter with a cut-off frequency and a filter length of the low-pass filter obtained in (c). Here, rectangular window is only considered. [25%]

## Appendix

Table 1 Characteristics of Various Window Functions (The filter length is  $M+1$ .)

Type of Window	Peak Side-Lobe Amplitude (Relative) ( $r_p$ )	Approximate Width of Main Lobe ( $\Delta\omega_m$ )	Peak Approximation Error ( $e_p = 20\log_{10} \delta$ )	Transition Widths ( $\Delta\omega$ )	Equivalent Kaiser Window ( $\beta$ )
Rectangular	-13	$4\pi T(M+1)$	-21	$1.81\pi TM$	0
Bartlett	-25	$8\pi TM$	-25	$2.37\pi TM$	1.33
Hanning	-31	$8\pi TM$	-44	$5.01\pi TM$	3.86
Hamming	-41	$8\pi TM$	-53	$6.27\pi TM$	4.86
Blackman	-57	$12\pi TM$	-74	$9.19\pi TM$	7.04