



Spring 2022							
EE1616 Electronic Workshop							
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May 2022							
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PIC Lab 1: Introduction to PIC

O Aims (5 Points)

- Preliminary understanding the architecture of PIC16F877A, instruction set and PICmicro assembly programming.
- Learn to use MPLAB X IDE to write assembly language and copy the code into the PIC board.

1 Task 1 (5 Points)

Table 1. Components and their connections

Component	PICmicro	8 Push buttons	LEDs	8-seg.	LCD 1602
Location numbers	1	13	5	12	20

2 Task 2 (35 Points)

2.1 Task 2.1 (5 Points)

- (1) What is the size of the program memory of the PIC16F877A? 8K 14 bit words
- (2) What is the size of the data memory of the PIC16F877A? 368 bytes.

2.2 Task 2.2 (10 Points)

(1) STATUS

03h, 83h, 103h, 183h

(2) PORTB

06h, 106h,

(3) TRISB

86h, 186h

2.3 Task 2.3 (10 Points)

(1) clear all PORTB pins

CLRF RORTB

(2) change the current memory to BANK1 (hint: STATUS register)

BSF STATUS, RP0

(3) PORTB is set up as output (hint: TRISB register)

CLRF TRISB

(4) change the current memory to BANK0 (hint: STATUS register) BCF STATUS,RP0

2.4 Task2.4 (10 Points)

(1) 0 (decimal value)

BCF PORTB,0

(2) 0xFF (hexadecimal value)

BSF PORTB.0

BSF PORTB,1

BSF PORTB.2

BSF PORTB,3

BSF PORTB,4

BSF PORTB,5

BSF PORTB,6

BSF PORTB,7

(3) 01010101 (binary value)

BSF PORTB,0

BCF PORTB,1

BSF PORTB,2

BCF PORTB,3

BSF PORTB,4

BCF PORTB,5

BSF PORTB,6

BCF PORTB,7

3 Task 3 (20 Points)

(1) This is my assembly code:

EQU H'06'; define PORTB register

TRISB

EQU H'86'; define TRISB register

COUNT1 EQU H'20'; define a new variable COUNT2 EQU H'21'; define a new variable

CLRF PORTB; clear all PORTB pins BSF STATUS,RP0; change to BANK1 CLRF TRISB; PORTB is set up as output BCF STATUS,RP0; change to BANK0

LOOPIT

BSF PORTB,0; set Port B pin 0

;CALL DELAY

BSF PORTB,1; set Port B pin 1

;CALL DELAY

BSF PORTB,2; set Port B pin 2

;CALL DELAY

BSF PORTB,3; set Port B pin 3

;CALL DELAY

BSF PORTB,4; set Port B pin 4

;CALL DELAY

BSF PORTB,5; set Port B pin 5

;CALL DELAY

BSF PORTB,6; set Port B pin 6

;CALL DELAY

BSF PORTB,7; set Port B pin 7

;CALL DELAY

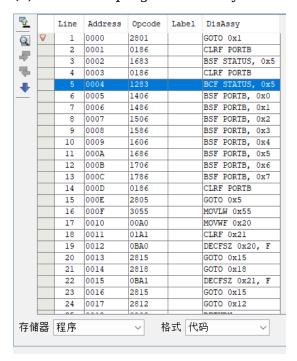
CLRF PORTB; clear all PORTB pins GOTO LOOPIT; go to address LOOPIT

DELAY MOVLW 255
MOVWF COUNT1
CLRF COUNT2
DELAY1 DECFSZ COUNT1,F
GOTO DELAY2
GOTO COMPLETE
DELAY2 DECFSZ COUNT2,F
GOTO DELAY2
GOTO DELAY1
COMPLETE RETURN
GOTO \$\(\); loop forever

END

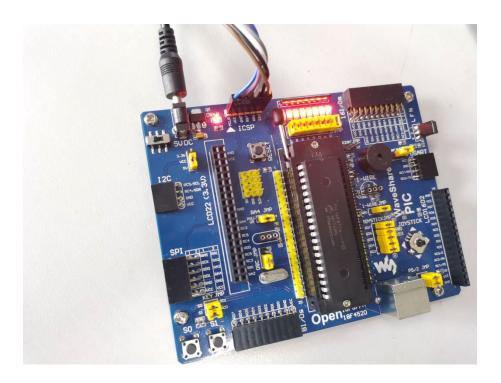
The location of the modified code has been highlighted. Then I debug it and find it is correct.

(2) This is the program memory which in my computer.



4 Task 4 (30 Points)

(1) Make the modification on the code by removing the ";" in every "CALL DELAY". then run the program on the PICmicro development board. This is my result.



(2) Then I modified the code with the pattern "01010101".

The assembly code is:

BSF PORTB,0

CALL DEALY

BCF PORTB,1

CALL DEALY

BSF PORTB,2

CALL DEALY

BCF PORTB,3

CALL DEALY

BSF PORTB,4

CALL DEALY

BCF PORTB,5

CALL DEALY

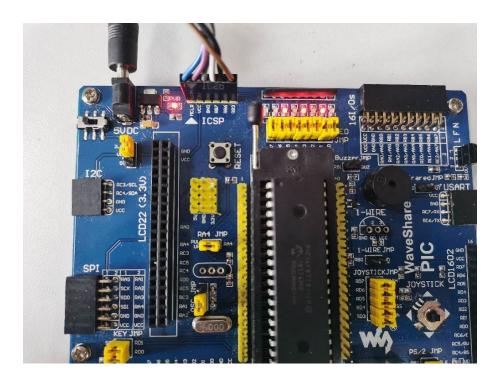
BSF PORTB,6

CALL DEALY

BCF PORTB,7

CALL DEALY

The result is:



Conclusions (5 Points)

In this seminar, I briefly understand the architecture of PIC16F877A and the assembly language. In assembly language, I know that "CLRF" can clear the data in the register like "CLRF PORTB". "BSF f,b" can set bit b of the f register to 1 and "BCF F,b" set bit b of the register to 0. Finally, copy the correct code on the PIC board and find the interesting LEDs flash.