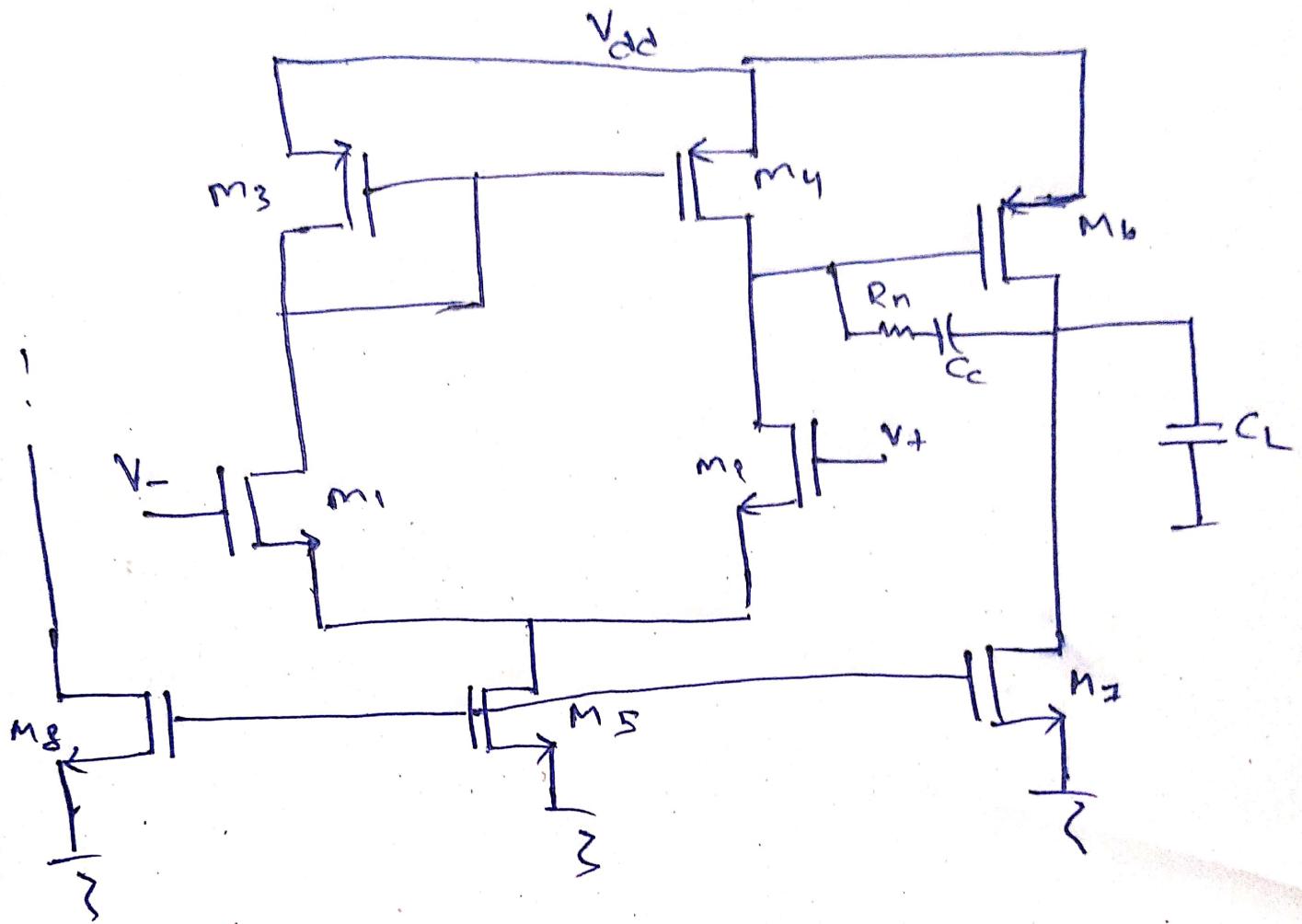


Two - stage - opamp:-



Design constraints,

$$C_L = 5 \text{ pF}$$

$$\text{Power consumption} < 0.5 \text{ mW}$$

$$\text{Unity Gain BW} > 10 \text{ MHz}$$

$$\text{Slew rate} = 15 \text{ V/μs}$$

$$\text{Gain} > 90 \text{ dB}$$

$$\text{PM} > 75^\circ$$

For $M_1 \& M_2$:-

$$g_{m_1} = 2\pi \times 6BW \times C_C$$

$$= 2\pi \times 10 \times 2$$

$$g_{m_1} = 125.6 \mu$$

$$\begin{cases} C_L = 5P \\ C_C = 4C_L \\ C_C = 2Pf \end{cases}$$

Consider
option

$$\text{Slow rate} = 15 \text{ mV/μs} \quad (\text{S.R} = \frac{I_o}{C_C})$$

$$\begin{aligned} I_{\text{Tail}} &= 15 \times 2 \\ &= 30 \mu \end{aligned}$$

$$I_{\text{Tail}} = 30 \mu$$

$$\begin{aligned} \left(\frac{\omega}{L}\right)_1 &= \frac{g_{m_1}^2}{\mu_n C_o \times 2 I_{\text{Tail}}} \\ &= \frac{(125.6)^2}{30 \times 2 \times 15} \\ &= 1.78 \mu \end{aligned}$$

$$\left(\frac{\omega}{L}\right)_{1/2} \approx 2 \mu$$

Using Miller Compensation:-

→ Let us assume that due to Miller compensation the ratio which is created due to Miller cap is 10 times bigger than $Z_1 \geq 10 \text{ GBP}$.

$$PM = 180 - \tan^{-1}\left(\frac{\text{GBP}}{Z}\right) - \tan^{-1}\left(\frac{\text{GBP}}{P_1}\right) - \tan^{-1}\left(\frac{\text{GBP}}{P_2}\right)$$

Let us assume that gain of the op amp is very high such that $\tan^{-1}(A_{DC})$ can go up to 90° .

$$PM = 180 - 95.17 + \tan^{-1}\left(\frac{\text{GBP}}{P_2}\right)$$

∴ We have considered, $PM = 70^\circ$

$$\therefore \tan^{-1} \frac{\text{GBP}}{P_2} = 14.29$$

$$\boxed{P_2 = 4 \text{ GBP}}$$

From this $C_C = \alpha H C_L$

For M_6 :

We have assumed

$$Z_1 = 10 \text{ GBP}$$

$$\frac{g_{m6}}{CC} \geq 10 \frac{g_{m1}}{CC}$$

$$g_{m6} \geq 10 g_{m1}$$

$$\therefore g_{m6} = 1250 \mu$$

But from the test circuit of g_{m1} ,
was found to be, ~~1250~~ 117μ

$$\therefore g_{m1} = 117 \mu$$

$$\therefore g_{m6} = 1170 \mu$$

$$\left(\frac{w}{t}\right)_6 = \frac{g_{m6}}{g_{m1}} \left(\frac{w}{t}\right)_4 \rightarrow \text{Also found from test circuit.}$$

$$= \frac{1170}{208.9} \times 11.63$$

$$= 268.8$$

$$\left(\frac{w}{t}\right)_6 \approx 269$$

$$\text{now } I_b = \frac{269}{11.63} \times 15$$

$$I_b = \frac{\left(\frac{w}{t}\right)_6}{\left(\frac{w}{t}\right)_n} \times I_4$$

$$I_b = 98.11 \mu A$$

For $M_7 \geq$

$$\left(\frac{w}{l}\right)_7 = \frac{I_S}{I_S} \times \left(\frac{w}{l}\right)_{S_5} \text{ (for rubber ratio)}$$

$$= \frac{98.41}{30} (20)$$

$$\left(\frac{w}{l}\right)_7 = 65.60$$

→ To increase the PM & GBP, we are using nulling resistor such that it will compensate the non-dominant pole and increase the gap between P_1 & P_3 such that PM will increase.

$$R_N = \left(\frac{C_C + C_L}{C_C} \right) \frac{1}{g_m b}$$
$$= \left(\frac{2+5}{2} \right) \frac{1}{1170}$$

$$R_N = 2.99 K$$

$$R_N \approx 3 K \Omega$$

After adding Miller Cap & nulling Res:-

$$w_{P_1} = \frac{1}{gm_1 R_1 R_2 C_C} \quad w_{P_2} = \frac{gm_2}{C_L}$$

$$w_{P_3} = \frac{1}{R_2 C_L} \quad w_{Z_1} = \frac{1}{C_C \left(\frac{1}{gm_3} L R_2 \right)}$$

Now, Since

$$\boxed{w_{Z_1} = w_{P_2}} \Rightarrow \text{For inc PM}$$

From this we get R_N

Tuning the parameters:

→ Since the square law method is an approximate method and we don't get exact results.

→ Tuning the parameters is important to get expected results.

After tuning:

For M_{1,2} :-

$$\left(\frac{w}{l}\right) = 2, \quad w = 4 \mu m \\ L = 2 \mu m$$

For M_{3,4} :-

$$\left(\frac{w}{l}\right) = 41 \quad w = 20.5 \mu m \\ L = 500 n$$

For M_{5,6} :-

$$\left(\frac{w}{l}\right) = 20 \quad w = 20 \mu m \\ L = 1 \mu m$$

For M₆ :-

$$\left(\frac{w}{l}\right) = 269 \quad w = 134.5 \mu m \\ L = 500 n$$

For M₇ :-

$$\left(\frac{w}{l}\right) = 65.6 \mu m \quad L = 1 \mu m$$

For nulling resistor, R_N = 2.29 k ohms after tuning.